IEEE P802.22b™/D1.0 Draft Standard for Wireless Regional Area Networks Part 22: Cognitive Wireless RAN Medium Access Control (MAC) and Physical Layer (PHY) specifications: Policies and procedures for operation in the TV Bands - Amendment: Enhancement for broadband services and monitoring applications

Prepared by the IEEE 802.22 Working Group of the

LAN/MAN Standards Committee of the **IEEE Society**

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Abstract: This standard specifies alternate Physical Layer (PHY) and necessary Medium Access Control Layer (MAC) enhancements to IEEE std. 802.22-2011 for operation in Very High Frequency (VHF)/ Ultra High Frequency (UHF) TV broadcast bands between 54 MHz and 862 MHz to support enhanced broadband services and monitoring applications. The standard supports aggregate data rates greater than the maximum data rate supported by the IEEE Std. 802.22-2011. This standard defines new classes of 802.22 devices to address these applications and supports more than 512 devices in a network. This standard also specifies techniques to enhance communications among the devices and makes necessary amendments to the cognitive, security $\&$ parameters and connection management clauses. This amendment supports mechanisms to enable coexistence with other 802 systems in the same band.

Keywords: broadband wireless access network, enhanced broadband services, monitoring applications, high throughput, high capacity, WRAN standards

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1. Overview

1.1 Scope

 This amendment specifies alternate Physical Layer (PHY) and necessary Medium Access Control Layer (MAC) enhancements to IEEE std. 802.22-2011 for operation in Very High Frequency (VHF) / Ultra High IEEE

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 Frequency (UHF) TV broadcast bands between 54 MHz and 862 MHz to support enhanced broadband services and monitoring applications. The standard supports aggregate data rates greater than the maximum data rate supported by the IEEE Std. 802.22-2011. This standard defines new classes of 802.22 devices to address these applications and supports more than 512 devices in a network. This standard also specifies techniques to enhance communications among the devices and makes necessary amendments to the cognitive, security $\&$ parameters and connection management clauses. This amendment supports mechanisms to enable coexistence with other 802 systems in the same band.

1.2 Purpose

The purpose of this amendment is to enhance the MAC and define an alternate PHY to accommodate broadband extensions and monitoring use cases for IEEE 802.22 devices operating is VHF/UHF TV broadcast bands between 54 MHz and 862 MHz.

2. Normative references

The following referenced documents are indispensable for the application of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments or corrigenda) applies.

3. Definitions

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7. MAC Common Part sublayer

Change the paragraph as follows:

5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 This clause describes the MAC layer used by the IEEE 802.22 WRAN point-to-multipoint medium access control standard and the IEEE 802.22b multihop relay WRAN (MR-WRAN) multihop relay medium access control standard. The MAC provides tools for protection of TV bands incumbent services as well as for coexistence. The MR-WRAN MAC provides all functionalities of the WRAN MAC, and additionally supports multihop relay operations, multiple channel operations, multiple input multiple output (MIMO) operations, etc. The MAC is The both WRAN and MR-WRAN MACs are connection-oriented and provides flexibility in terms of QoS support. The MAC regulatesThe WRAN MAC and the MR-WRAN MAC regulate downstream medium access by TDM, while the upstream is managed by using a DAMA/OFDMA system. In the WRAN MAC, the BS manages all the activities within its IEEE 802.22 cell and the associated CPEs are under the control of the BS. The MR-WRAN MAC provides point-to-multipoint connections and relay connections between the multihop relay base station (MR-BS) and the CPEs within an MR-BS's cell as well as supports to configure a local cell consisting of a distributed scheduling relay CPE (R-CPE) and subscriber CPEs (S-CPEs). A relay CPE (R-CPE) shall operate one of two modes of centralized scheduling mode and distributed scheduling mode depending on capability or network situations. The R-CPE on the centralized scheduling mode (called a centralized scheduling R-CPE) provides relay connections for the subscriber CPEs (S-CPEs) under the management of the MR-BS. On the other hand, the R-CPE on the distributed scheduling mode (called a distributed scheduling R-CPE) may configure a local cell, and has the similar functionalities of MR-BS and manages S-CPEs within the local cell. The MR-BS manages the MR-WRAN cell containing CPEs and local cells.

7.1 General

Insert the following paragraph as the second paragraph of section [7.1](#page-22-1):

35 36 37 38 39 40 41 42 43 44 45 46 In an MR-WRAN cell consisting of CPEs (e.g., R-CPEs and S-CPEs), all R-CPEs and multiple S-CPEs are managed by a single MR-BS, and other S-CPEs are managed by distributed scheduling R-CPEs. The downstream is TDM where the MR-BS transmits and the CPEs receive. The upstream transmissions, where the CPEs transmit and the MR-BS receives, are shared by the CPEs on a demand basis, according to a DAMA/ OFDMA scheme. Within a local cell consisting of a distributed scheduling R-CPE and S-CPEs, multiple S-CPEs are managed by the distributed scheduling R-CPE. The downstream within a local cell is TDM where the distributed scheduling R-CPE transmits and the S-CPEs receive. The upstream transmissions within a local cell, where the S-CPEs transmit and the distributed scheduling R-CPE receives, are shared by the S-CPEs on a demand basis, according to a DAMA/OFDMA scheme.

Change the second and third paragraphs as follows:

50 51 52 53 54 55 56 57 The both WRAN MAC and MR-WRAN MAC implements a combination of access schemes that efficiently control contention between CPEs within a cell and overlapping cells sharing the same channel while at the same time attempting to meet the latency and bandwidth requirements of each user application. This is accomplished through four different types of upstream scheduling mechanisms that are implemented using: unsolicited bandwidth grants, polling, and two contention procedures (i.e., MAC header and CDMA based). The use of polling simplifies the access operation and attempts to allow applications to receive service on a deterministic basis if it is required.

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60 61 62 63 64 65 The both WRAN MAC and MR-WRAN MAC isare connection-oriented, and as such, connections are a key component that require active maintenance and hence can be dynamically created, deleted, and changed as the need arises. A connection defines both the mapping between convergence processes at CPEs and BS-or MR-BS and the related service flow (one connection per service flow). For the purposes of mapping to services on CPEs and associating varying levels of QoS, all data communications are instantiated in the context of a connection and this provides a mechanism for upstream and downstream QoS management. In particular, the QoS parameters are integral to the bandwidth allocation process as the CPE requests upstream bandwidth on a per connection basis (implicitly identifying the service flow). The BS, MR-BS or the distributed scheduling R-CPE, in turn, grants bandwidth to a CPE as an aggregate of grants in response to per-connection requests from the CPE.

7.2 Addressing and connections

Insert the following paragraph after the first paragraph in section [7.2](#page-23-0):

Each MR-BS and CPE shall have a 48-bit universal MAC address, as defined in IEEE Std 802-2001. This address uniquely defines the MR-BS and CPE from within the set of all possible vendors and equipment types. It is used as part of the authentication process by which the MR-BS and CPE each verify the identity of the other at the time of network association. It is used as part of the authentication process by which the MR-BS and CPE each verify the identity of the other at the time of network association. The MR-BS MAC address is broadcast by the MR-BS on superframe control header (SCH) on PHY Mode 1 (Clause 9) or frame control header (FCH) on PHY Mode 2 (Clause 9a) and is present in every CBP burst. Each MR-WRAN device regularly broadcasts a CBP burst containing its Device ID and Serial Number. This is done as part of the device's self-identification process that helps identify potential interference sources to incumbent services and for coexistence purposes.

26 27 *Change the second paragraph as follows:*

28 29 (Note 1: Increasing SID to support a larger number of CPEs in an MR-WRAN)

30 (Note 2: Local cell ID defines a local cell identification for an MR-WRAN)

31 32 (Note 3: Separation of downstream FID and upstream FID to support different services for downstream and upstream)

33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 Connections are identified by two three items, a 8-bit local cell ID (LCID), a 913-bit station ID (SID) and a 38-bit flow ID (FID). The LCID uniquely identify a local cell within an MR-WRAN cell that is under the control of the distributed scheduling R-CPE. The SID uniquely identifies a station that is under the control of the BS, the MR-BS or the distributed scheduling R-CPE. A SID can be for a unicast station, when referencing a single CPE, or for a multicast station, when referencing a multicast group (of CPEs). A FID identifies a particular traffic flow assigned to a CPE. A 4bit LSB of FID defines downstream flow ID, while a 4bit MSB of FID defines upstream flow ID. The tuple of LCID, SID and FID (LCID | SID | FID) forms a connection identifier (CID) that identifies a connection for the CPE. The LCID and SID is sare signaled in the DS/ US- MAP allocation, and the FID is signaled in the generic MAC header (GMH) of a MAC PDU. This allows for a total of up to $\frac{5128192}{2}$ stations in each local cell up to 255, each with a maximum of eight sixteen flows that can be supported within each downstream and upstream channel. LCID with all zero shall be allocated for the WRAN and MR-WRAN cells.

49 50 *Change the third paragraph as follows:*

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51 52 53 54 55 56 57 58 59 60 61 62 63 64 65 At CPE initialization, three flows shall be dedicated for management connections (see 12.2) for the purpose of carrying MAC management messages and data between a CPE and the BS/MR-BS or the distributed scheduling R-CPE. The three flows reflect the fact that there are inherently three different levels of QoS for traffic sent on management connections between a CPE and the BS/MR-BS or the distributed scheduling R-CPE. The basic flow is used by the BS/MR-BS MAC or the distributed scheduling R-CPE MAC and CPE MAC to exchange short, time- urgent MAC management messages; whereas, the primary management flow is used by the BS/MR-BS or the distributed scheduling R-CPE MAC and CPE MAC to exchange longer, more delay-tolerant MAC management messages (Table 19 specifies which MAC management messages are transferred on which type of connections). Finally, the secondary management flow is used by the BS/MR-BS or the distributed scheduling R-CPE and CPE to transfer more delay tolerant, standards-based (e.g., DHCP, TFTP, and SNMP) messages that are carried in IP datagrams. The secondary management flow may be packed and/or fragmented, similarly to the primary management except that no ARQ should be used for the

latter since it is more time critical.

Change the fourth paragraph as follows:

(Note: Different FID can be set for downstream and upstream in order to support different services for downstream and upstream)

The FIDs for these connections shall be assigned according to the specification in 12.2. The same FID value is assigned to both upstream and downstream members of each connection. A 4-bit LSB of FID defines downstream flow ID, while a 4-bit MSB of FID defines upstream flow ID.

Change the fifth paragraph as follows:

The CID, which is a tuple of LCID | SID | FID, can be considered a connection identifier even for nominally connectionless traffic like IP, since it serves as a pointer to destination and context information.

Change the sixth paragraph as follows:

Many higher-layer sessions may operate over the same wireless connection. For example, many users within a company may be communicating with Transmission Control Protocol (TCP)/IP to different destinations, but since they all operate within the same overall service parameters, all of their traffic is pooled for request/grant purposes. A service flow is a unidirectional flow of traffic (BS/MR-BS to CPE, or CPE to BS/ MR-BS, distributed scheduling R-CPE to CPE or CPE to distributed scheduling R-CPE) that defines the mapping of higher-layer application service parameters (e.g., QoS) to a LCID assigned to a particular local cell with a FID assigned to a particular CPE's unicast SID or multicast group (multicast SID).

7.3 General superfame structure

Insert the following paragraph as the first paragraph in section [7.3:](#page-24-0)

The MR-WRAN supports two PHY modes of PHY mode 1 (Clause 9) and PHY mode 2 (Clause 9a).

The WRAN system and the MR-WRAN system on PHY mode 1 shall support the following superframe structure.

The MR-WRAN on PHY mode 2 does not support the following superframe structure.

Change the paragraph as follows:

The IEEE 802.22 WRAN system and the MR-WRAN system on PHY mode 1 includes two operational modes: a normal mode and a self-coexistence mode. In normal mode, one WRAN cell occupies one channel or more channels and operates on all the frames in a superframe; while in self-coexistence mode, multiple WRAN and/or MR-WRAN cells share the same channel and each coexisting WRAN-and/or MR-WRAN cells operates on one or several different frames exclusively.

- **7.4 General frame structure (on PHY Mode 1)**
- *Insert the following paragraph as the first paragraph in section [7.4:](#page-24-1)*

 The WRAN system and the MR-WRAN system on PHY mode 1 described in Clause 9 shall support the following frame structure.

 Insert the new subsection [7.4a](#page-25-0) after section [7.4:](#page-24-1)

7.4a General frame structure (on PHY Mode 2)

The MR-WRAN on PHY mode 2 described in Clause 9a shall support the following frame structure.

The MR-WRAN on PHY mode 2 includes two operational modes: a normal mode and a self-coexistence mode. In normal mode, one MR-WRAN cell occupies one or more channels and operates on all the frames; while in self-coexistence mode, multiple MR-WRAN cells share the same channel and each coexisting WRAN cell operates on one or several different frames exclusively.

The MR-WRAN on PHY mode 2 shall transmit the Frame Control Header (FCH) (7.5.2a, Table A1) at the beginning of every frame on the operating channel in both normal mode and self-coexistence mode. An MR-WRAN run in normal mode by default and transits to self-coexistence mode when the MR-WRAN can detect and decode an FCH or a CBP from an adjacent MR-WRAN cell on its operating channel.

7.4a.1 General frame structure for normal mode

The MR-WRAN frame structure depicted in Figure 12 shall be used and the first frame shall be constituted of the following:

- A PHY frame preamble, see Clause 9a
- A Frame Control header (FCH), see Clause 7.5.2a
- The rest of the first frame including its frame header and data payload

At the beginning of every frame, the MR-BS shall transmit the frame preamble and the FCH on the operating channel using the modulation/coding specified in 9a.2 and Table E1 respectively. In order to associate with an MR-BS, a CPE must receive the FCH to establish communication with the MR-BS. During each MAC frame, the MR-BS shall manage the upstream and downstream operations, which may include ordinary data communication, measurement activities, coexistence procedures, and so on.

7.4a.2 General frame structure for self-coexistence mode

> The MR-WRAN frame structure in self-coexistence mode is shown in [Figure A1](#page-26-1). The self-coexistence mode is for the scenario when multiple MR-BSs with overlapping coverage have to share the same channel. The frequency reuse factor cannot be maintained as one due to their mutual interference. In this case, these MR-BSs shall share the channel on a per frame basis, i.e., each MR-BS is allocated the frames on a non- interference basis. The negotiation process of frame allocation can be found in 7.20.

 In self-coexistence mode, the MR-BS and CPEs in an MR-WRAN cell shall only transmit during the active frames allocated to that MR-WRAN cell. They can only transmit during other frames when a self-coexistence window (SCW) has been scheduled. During the frames not allocated to the present cell, the MR-BS and CPEs may monitor the channel for any transmission from neighboring MR-WRAN cells to improve self-coexistence.

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7.4a.3 Frame format

The MR-WRAN system on PHY mode 2 described in Clause 9a shall support the following frame structure.

The top-down time division duplex (TDD) frame structure employed in the MAC is illustrated in Figure 12.

As illustrated in [Figure B1](#page-27-0), a frame is comprised of two parts: a downstream (DS) subframe and an upstream (US) subframe. A portion of the US subframe may be allocated as a window to facilitate self- coexistence. This SCW may be scheduled by the MR-BS at the end of the US subframe when necessary to allow transmission of opportunistic coexistence beacon protocol bursts. The SCW includes the necessary time buffers to absorb the difference in propagation delay between close-by and distant MR-BSs and CPEs operating on the same channel. The boundary between the DS and US subframes shall be adaptive to adjust to the downstream and upstream relative capacity. The upstream subframe may contain scheduled upstream PHY PDUs, each transmitted from different CPEs for their upstream traffic. It may also include contention intervals scheduled for the following:

- CPE association (initial ranging)
- CPE link synchronization, power control and geolocation (periodic ranging)
- Bandwidth request
- Urgent coexistence situation (UCS) notification
- Quiet period resource adjustment
- The definitions of the fields/messages are given in 7.6 and 7.7.

The PHY PDUs may be transmitted across several subchannels as shown in [Figure B1,](#page-27-0) which depicts how a frame may be transmitted (in time and frequency) by the PHY layer.

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Figure B1—Example of a time/frequency structure of a MAC frame for PHY Mode 2

[Figure B1](#page-27-0) shows an example of the two-dimensional (time/frequency) structure of the MAC frame that shall consist of an integer number of fixed size OFDM slots. Each slot shall consist of 4 OFDM symbols by one subchannel (i.e., 1 OFDM slot for $DS = 4$ symbols \times 1 subchannel) for downstream, while shall consist of 7 OFDM symbols by subchannel (i.e., 1 OFDM slot for US= 7 symbols \times subchannel) for upstream (9a.1.3.1, tile, slot and data region). A subchannel consists of 16 subcarriers. To help understand [Figure B1](#page-27-0), the MAC packets are assumed to be structured in a linear TDM manner (see Figure 12), while the PHY packets are arranged in a two-dimensional time/frequency domain (symbol in the horizontal direction, logical subchannels in the vertical direction). For the FCH, the DS/US-MAP, the DCD, and UCD, as well as for the downstream payload, the MAC information is first laid vertically by subchannels then stepped horizontally in the time direction. This vertical layering allows early scheduling of DS bursts assigned to distant CPEs to compensate for propagation delays and to avoid potential interference at the CPE in the case of overlapping MR-WRAN cells with different DS/US capacity split.

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51 52 53 54 55 56 57 58 59 60 61 The MAC data elements, starting from the FCH and including the first broadcast burst, shall be entered into the portion between the second OFDM symbol and fifth OFDM symbol, which is based on the number of symbols defined in a tile (9a.1.3.1, tile, slot and data region), as shown in [Figure B1](#page-27-0), in the increasing order of logical subchannels until all logical subchannels are occupied. Then, the subsequent data elements, if they have not all been mapped, shall be placed in the same order on the following OFDM symbols. The balance of the last OFDM symbols shall be padded with zeros. The modulation and coding schemes for the padding zeros are defined by the DIUC for the last DS burst in the DS-MAP. Note that the DS-MAP indicates the length of the contiguous DS MAC elements, not their absolute position in the DS subframe.

62 63 64 65 The MAC data elements that are contained in upstream bursts shall be mapped to the US subframe in a different order as shown in [Figure B1](#page-27-0). They are first mapped horizontally, 7 OFDM symbols by 7 OFDM IEEE

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ing CBP packets transmitted by nearby CPEs belonging to other MR-WRAN cells, either on the same channel (N), or on adjacent channels (N \pm 1), or on alternate channels (N \pm 2 and beyond). This capability shall also be available at CPE initialization. In addition, MR-BS frame synchronization is based on the absolute local start time of their frame period to the start of every minute referenced to UTC as specified in 7.23. Hence, multiple co-located or nearby MR-BS cells can efficiently communicate with each other and align their SCW for CBP exchange as well as their quiet periods for sensing incumbents.

Insert the new subsection [7.4b](#page-29-0) after section [7.4a:](#page-25-0)

7.4b General frame structure for a relay network

The MR-WRAN system on the both PHY mode 1 and 2 shall support the following frame structure for relay.

A general frame structure has two different modes for relay: a centralized relay mode and a distributed relay mode. On the centralized relay mode, a centralized scheduling R-CPE provides relay connections for the S-CPEs under the management of the MR-BS. On the distributed relay mode, on the other hand, a distributed scheduling R-CPE configures a local cell within the MR-WRAN cell, and has the similar functionality of MR-BS and manages S-CPEs within the local cell.

7.4b.1 General frame structure for a centralized relay mode

Each of the downstream and upstream subframes for a centralized relay mode may include two zones: access zone (AZ) and centralized relay zone (CRZ) as shown in [Figure C1.](#page-30-0) Each AZ in the downstream and upstream subframes is used for transmission between an MR-BS and CPEs (i.e., centralized scheduling R-CPEs or S-CPEs), while each CRZ in the downstream and upstream subframes is used for transmission between a centralized scheduling R-CPE and S-CPEs.

For a centralized scheduling mode, both of AZs and CRZs in the downstream and upstream subframes are managed by an MR-BS.

7.4b.2 General frame structure for a distributed relay mode

Each of the downstream and upstream subframes for a distributed relay mode may include two zones: access zone (AZ) and distributed relay zone (DRZ) as shown in [Figure D1.](#page-30-1) Each AZ in the downstream and upstream subframes is used for transmission between an MR-BS and CPEs (distributed scheduling R-CPEs or S-CPEs), while each DRZ in the downstream and upstream subframe is used for transmission between a distributed scheduling R-CPE and S-CPEs.

> The both of AZs and DRZs in the downstream and upstream subframes are scheduled by an MR-BS. For a distributed relay mode, the AZs in the downstream and upstream subframes are managed by an MR-BS, while the DRZs in the downstream and upstream subframes are controlled by a distributed scheduling R-CPE, which is capable of configuring and maintaining a local cell within an 802.22b MR-WRAN cell.

- For the IEEE 802.22b MR-WRAN on PHY mode 2, the subchannels of the DRZs in the downstream and upstream subframes can be grouped by 3 segments with the same number of subchannels as shown in [Figure E1](#page-31-2).
- The segmentation can be scheduled by the MR-BS, and each segment is assigned to the different distributed
- scheduling R-CPEs. This segmentation is used to increase network capacity.

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Figure E1—Example of a time/frequency structure of a MAC frame for a distributed relay mode on segmentation on PHY mode 2

7.4b.3 Detail of Zones

7.4b.3.1 Access Zone (AZ)

At the beginning of every frame in AZ, the MR-BS shall transmit the frame preamble and the FCH on the operating channel using the modulation/coding specified in 9a.2 and Table E1 respectively. In order to associate with an MR-BS, a CPE must receive the FCH to establish communication with the MR-BS.

An AZ in the upstream subframe may contain scheduled upstream PHY PDUs, each transmitted from different CPEs for their upstream traffic. It may also include contention intervals scheduled for the following:

- CPE association (initial ranging)
- CPE link synchronization, power control and geolocation (periodic ranging)
- **Bandwidth request**
- Urgent coexistence situation (UCS) notification
- Quiet period resource adjustment

57 58 59 60 61 62 63 64 65 The two-dimensional (time/frequency) structure of the MAC frame shall consist of an integer number of fixed size OFDM slots. For PHY mode 1, each slot shall consist of one OFDM symbol by one subchannel $(i.e., 1$ OFDM slot = 1 symbol \times 1 subchannel) for both downstream and upstream. For PHY mode 2, on the other hand, each slot shall consist of 4 OFDM symbols by one subchannel (i.e., 1 OFDM slot for $DS = 4$) symbols \times 1 subchannel) for downstream, while shall consist of 7 OFDM symbols by subchannel (i.e., 1 OFDM slot for US= 7 symbols \times subchannel) for upstream (9a.1.3.1, tile, slot and data region). For the FCH,

tion is first laid vertically by subchannels then stepped horizontally in the time direction. This vertical layering allows early scheduling of DS bursts assigned to distant CPEs to compensate for propagation delays and to avoid potential interference at the CPE in the case of overlapping MR-WRAN cells with different DS/US capacity split. In an AZ, the MAC data elements, starting from the FCH and including the first broadcast burst, shall be mapped to the DS subframe as the same manner described in [7.4](#page-24-1) for PHY mode 1 and [7.4a.3](#page-26-0) for PHY mode 2. In an AZ, the MAC data elements that are contained in upstream bursts shall be mapped to the US subframe as the same manner described in [7.4](#page-24-1) for PHY mode 1 and [7.4a.3](#page-26-0) for PHY mode 2. **7.4b.3.2 Centralized Relay Zone (CRZ)** During a CRZ in the DS subframe, the centralized scheduling R-CPE transmits the MAC frames, which are transferred from the MR-BS during an AZ in the downstream subframe, to the S-CPE on the scheduled slots determined by the MR-BS. A CRZ in the upstream subframe may contain scheduled upstream PHY PDUs, each transmitted from different S-CPEs for their upstream traffic, which forwards the centralized scheduling R-CPE. It may also include contention intervals scheduled for the following: — CPE relay association (relay initial ranging 7.15.2) — CPE relay power control and geolocation (relay periodic ranging 7.15.2) — Relay bandwidth request — Relay urgent coexistence situation (UCS) notification — Quiet period resource adjustment The two-dimensional (time/frequency) structure of the MAC frame in a CRZ is the same manner as that in an AZ [\(7.4b.3.1\)](#page-31-1). If a CRZ is appeared in the downstream subframe, the CRZ shall be appeared followed by the downstream AZ in the MAC frame. The MAC data bursts in the CRZ shall be entered into the first subchannel within the portion, calculated by CRZ Start Offset and Length in CRZDS-MAP IE (7.7.2.3), in the increasing order of logical subchannels until all logical subchannels are occupied in the portion. Then, the subsequent data elements if they have not all been mapped, shall be placed in the same order on the following OFDM symbols. The balance of the last OFDM symbols within the portion shall be padded with zeros. The modulation and coding schemes for the padding zeros are defined by the DIUC for the last DS burst in CRZDS-MAP IE. If a CRZ is appeared in the upstream subframe, the MAC data elements that are contained in relay upstream bursts shall be mapped to the CRZ in the US subframe in the same manner of US subframe mapping in AZ $(7.4b.3.1)$. The MR-BS may schedule up to four types of contention windows (see 7.13) in the CRZ: the relay initial ranging window is used for initializing the relay association; the relay periodic ranging window is used for regularly adjusting the timing and power at the CPE; the relay BW request window is for CPEs to request relay upstream bandwidth allocation from the MR-BS; the relay UCS notification window is used for CPEs to report an urgent coexistence situation with incumbents. **7.4b.3.3 Distributed Relay Zone (DRZ)** For local cell operations within an 802.22b MR-WRAN, the MR-BS will schedule a DRZ for a distributed scheduling R-CPE, which is capable of managing a local cell. During a DRZ, the distributed scheduling R-

64 65 CPE shall transmit the local frame preamble and the DRZ-FCH (7.5.2b) on the operating channel using the

64 65 *Insert the new subsection [7.5.2a](#page-34-0) after section [7.5.2:](#page-33-1)*

7.5.2a Frame control header for PHY mode 2

The format of the FCH for PHY mode 2 is shown in Table A1. Since FCH decoding is critical, the FCH shall be encoded using either the modulation specified by the PHY mode 2 as described in Table E1. The FCH contains the length of either the DS-MAP or US-MAP that immediately follows the FCH (note that Length = 0 indicates the absence of any burst in the frame). In the case where the DS-MAP is specified, the US-MAP length information shall be contained in the first DS-MAP information element. In the case where the US-MAP length is indicated in the FCH, there shall be no DS burst in the current frame. DCD and UCD messages, if present, are carried by the next DS bursts specified by the DS-MAP. Location and profile of the data bursts are specified in the rest of the DS-MAP and US-MAP management messages. A HCS field occupies the last byte of the FCH.

Table A1—Frame control header format for PHY mode 2

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Insert the new subsection [7.5.2a.1](#page-35-0) as follows:

7.5.2a.1 Extended Frame control header (Ex-FCH)

The Ex-FCH specification is shown in Table B1. The Ex-FCH decoding is the same as FCH. TheEx-FCH provides information about the MR-WRAN cell, in order to protect incumbents, support self-coexistence mechanisms, and support the intra- frame and inter-frame mechanisms for management of quiet periods for sensing.

Table B1—Extended frame control header format

1 2

62 63 64

61
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Table B1—Extended frame control header format

- 60 61
- 62
- 63
- 64 65

Table B1—Extended frame control header format

- 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48 49 50 51 52 53 54 55 56 57 58 59 60
- 61 62 63
- 64 65

P

Table B1—Extended frame control header format

- 59 60
- 61 62
- 63
- 64 65

Table B1—Extended frame control header format

Insert the new subsection [7.5.2b](#page-39-0) as follows:

7.5.2b Distributed Relay Zone (DRZ) Frame Control header (DRZ-FCH)

The DRZ-FCH is used in a DRZ for a distributed relay mode. The format of the DRZ-FCH is shown in Table C1. The DRZ-FCH shall have the same encoding as the FCH in each mode of PHY mode 1 or PHY mode 2. The DRZ-FCH contains the length of either the DS-MAP or US-MAP that immediately follows the DRZ-FCH (note that Length = 0 indicates the absence of any burst in the frame). In the case where the DS-MAP is specified, the US-MAP length information shall be contained in the first DS-MAP information element. In the case where the US-MAP length is indicated in the DRZ-FCH, there shall be no DS burst in the current frame. DCD and UCD messages, if present, are carried by the next DS bursts specified by the DS-MAP. Location and profile of the data bursts are specified in the rest of the DS-MAP and US-MAP management messages. A HCS field occupies the last byte of the DRZ-FCH.

Table C1—DRZ Frame control header format (DRZ-FCH)

Table C1—DRZ Frame control header format (DRZ-FCH)

7.6 MAC PDU formats

7.6.1 MAC headers

7.6.1.1 Generic MAC header

Change the size of Type in Table 3 as follows:

Table 3—Generic MAC header format

Insert new items in Table 4 as follows:

Table 4—Encoding of the Type field

7.6.1.2 MAC subheaders and special payloads

Change the first paragraph as follows:

Five types of subheaders may be present. The per-PDU subheaders (i.e., Bandwidth Request, Fragmentation/ Packing, Grant Management, Extended Bandwidth Request, Channel Aggregation) may be inserted in MAC PDUs immediately following the generic MAC header. If indicated, the Bandwidth Request subheader and Extended Bandwidth Request subheader shall always follow the Generic MAC header. In the upstream, if both the Grant Management subheader and Fragmentation/Packing subheader are indicated, the Grant Management subheader shall come first. If both the Grant Management subheader and Bandwidth Request subheader are indicated, the Grant Management subheader shall come first.

7.6.1.2.1 Bandwidth Request subheader

Insert the new subsection [7.6.1.2.1a](#page-41-0) after section [7.6.1.2.1](#page-41-1):

7.6.1.2.1a Extended Bandwidth Request subheader

Extended Bandwidth Request subheaders are transmitted by the centralized scheduling R-CPE to the MR-BS to request additional bandwidth for a CRZ connection. They shall be sent in a PDU by itself or in a PDU with other subheaders and/or data. (See Table D1).

7.6.1.2.5 Channel aggregation subheader

 The format of channel aggregation subheader is shown in Table E1. This channel aggregation subheader is used to manage the aggregation data sequence and aggregation type during the multi-channel operation. The channel aggregation header with fixed-length size of 3 bytes shall be added to each PDU after the generic MAC header.

7.7 Management messages

Insert new messages in Table 19.

Table 19—Management messages

Table E1—Aggregation subheader format

Table 19—Management messages

7.7.1 Downstream Channel Descriptor (DCD)

Change the paragraph as follows:

The format of a DCD message is shown in Table 20. This message shall be transmitted by the BS/MR-BS or the distributed scheduling R-CPE at a periodic interval (Table 273) to define the characteristics of a downstream physical channel.

Change Table 20 as follows:

Table 20 — DCD message format

Table 20 — DCD message format

7.7.1.1 DCD Channel information elements

Change Table 21 as follows:

Table 21 — DCD channel information elements

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Table 21 — DCD channel information elements

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Change Table 22 as follows:

- 61 62 63
- 64 65

Table 22—Backup and Candidate channel list

7.7.1.2 Downstream Burst Profile

Change the size from 6 bits to 7 bits for DIUC and from 2 bits to 1 bit for reserved in Table 23 :

7.7.2 Downstream MAP (DS-MAP)

Change Table 25 as follows:

Table 25 — DS-MAP message format

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Table 25 — DS-MAP message format

7.7.2.1 DS-MAP IE

Change the size from 9 bits to 13 bits for SID, and from 6 bits to 7 bits for DIUC in Table 26 :

7.7.2.1.1 DIUC allocations

Insert the values from 63 to 126 in Table 27:

Table 27—DIUC values

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7.7.2.1.2 DS-MAP Extended DIUC IE

Change Table 28 as follows:

Table 28 — DS-MAP Extended IE general format

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Table 28 — DS-MAP Extended IE general format

Add Table 28a as follows:

Table 28a — Extended DIUC code assignment

7.7.2.1.2.1 DS-MAP Dummy Extended IE

Change the size from 6 bits to 7 bits for Extended DIUC in Table 29 :

7.7.2.1.2.2 DS Multi-Zone Configuration IE

A CPE shall be able to decode the DS Multi-Zone Configuration IE shown in Table F1. An MR-BS shall transmit this IE for multi-hop relay operations.

Table F1—DS Multi-Zone Configuration IE format

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Table F1—DS Multi-Zone Configuration IE format

7.7.2.2 Access Zone DS-MAP IE (AZDS-MAP IE)

Encodings of Access Zone DS-MAP IE for the downstream from the MR-BS are provided in Table G1.

Table G1—AZDS-MAP IE

7.7.2.3 Centralized Relay Zone DS-MAP IE (CRZDS-MAP IE)

Encodings of Centralized Relay Zone DS-MAP IE for the relay downstream from the centralized scheduling R-CPE to the S-CPE are provided in Table H1.

7.7.2.4 Distributed Relay Zone DS-MAP IE (DRZDS-MAP IE)

Encodings of Distributed Relay Zone DS-MAP IE for the relay downstream from the distributed scheduling R-CPE to the S-CPE are provided in Table I1.

Table I1—DRZDS-MAP IE

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7.7.2.5 DRZDS-MAP GRA IE

The format of the DRZDS-MAP GRA IE is shown in Table J1.

Table J1—DRZDS-MAP GRA information elements

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Table I1—DRZDS-MAP IE

7.7.3 Upstream Channel Descriptor (UCD

The format of a UCD message is shown in Table 30. This message shall be transmitted by the BS/MR-BS or the distributed scheduling R-CPE at a periodic interval (Table 272) to define the characteristics of an upstream physical channel.

Change Table 30 as follows:

Table 30—UCD message format

Table 30—UCD message format

7.7.3.1 UCD Channel IEs

Change Table 31 as follows:

Table 31—UCD Channel IE

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-
-

Table 31—UCD Channel IE

7.7.3.2 Upstream burst profile

Change the size from 6 bits to 7 bits for UIUC and from 2 bits to 1 bit reserved in Table 32

7.7.4 Upstream MAP (US-MAP)

Change Table 34 as follows:

Table 34—US-MAP message format

Table 31—UCD Channel IE

Table 34—US-MAP message format

Table 34—US-MAP message format

7.7.4.1 US-MAP IE

Change the size from 6 bits to 7 bits for UIUC in Table 35

7.7.4.1.1 UIUC allocations

Insert the values from 63 to 126 in Table 36:

Table 36—UIUC values

7.7.4.1.2 CDMA Allocation IE

Change the size from 6 bits to 7 bits for UIUC in Table 37:

7.7.4.1.3 US-MAP EIRP Control IE

Change the size from 6 bits to 7 bits for UIUC in Table 38:

7.7.4.1.4 US-MAP Extended UIUC IE

Change Table 39 as follows:

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Table 39 — US-MAP extended IE general format

Add Table 39a as follows:

Table 39a — Extended UIUC code assignment

7.7.4.1.4.1 US-MAP Dummy Extended IE

7.7.4.1.4.2 US Multi-Zone Configuration IE

A CPE shall be able to decode the US Multi-Zone Configuration IE shown in Table K1. An MR-BS shall transmit this IE for multi-hop relay operations.

Table K1—US Multi-Zone Configuration IE format

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Table K1—US Multi-Zone Configuration IE format

7.7.4.2 Access Zone US-MAP IE (AZUS-MAP IE)

Encodings of Access Zone DS-MAP IE for the upstream to the MR-BS are provided in Table L1.

Table L1—AZUS-MAP IE

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Table L1—AZUS-MAP IE

7.7.4.3 Centralized Relay Zone US-MAP IE (CRZUS-MAP IE)

Encodings of Centralized Relay Zone US-MAP IE for the relay upstream to the centralized scheduling R-CPE from the S-CPE are provided in Table M1.

Table M1—CRZUS-MAP IE

Table L1—AZUS-MAP IE

Table M1—CRZUS-MAP IE

Table M1—CRZUS-MAP IE

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- 62
- 63 64
- 65

7.7.4.4 Distributed Relay Zone US-MAP IE (DRZUS-MAP IE)

Encodings of Distributed Relay Zone US-MAP IE for the relay upstream to the distributed scheduling R-CPE from the S-CPE are provided in Table N1.

Table N1—DRZUS-MAP IE

Table M1—CRZUS-MAP IE

Table N1—DRZUS-MAP IE

Table N1—DRZUS-MAP IE

63 64 65

7.7.4.5 DRZUS-MAP GRA IE

The format of the DRZUS-MAP GRA IE is shown in Table O1

Table O1—DRZUS-MAP GRA information element

Table O1—DRZUS-MAP GRA information element

7.7.7 REG-REQ/RSP

7.7.7.3 REG-REQ/RSP information elements

7.7.7.3.6 Local SID Group

The format of a Local SID IE is shown in Table P1. This IE shall be transmitted by the MR-BS to the distributed scheduling R-CPE at registration.Instead of the MR-BS, the distributed scheduling R-CPE allocates a Local SID to the S-CPE at initialization.

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-
-

Table P1—Local SID Group Information element

7.7.7.3.6.12 Permanent Station ID

Change the value of Table 61 as follows:

Table 61—Permanent Station ID information element

7.7.7.3.4.13 CPE Operational Capability

Change Table 62 as follows:

Table 62—CPE Operational Capability information element

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7.7.8.9 Service Flow encodings

7.7.8.9.19 Per-RS QoS

The format of a Per-RS QoS IE is shown in Table Q1.

Table Q1—Per-RS QoS information elements

Per-RS QoS value is shown in Table R1 as following.

Table R1—Per-RS QoS value

The value of Maximum Latency for the R-CPE specifies the maximum interval between the reception of an MAC PDU at the R-CPE's Air Interface that is receiving the MAC PDU and the Air Interface that is forwarding the MAC PDU.

7.7.11 CPE Basic Capability Request/Response (CBC-REQ/RSP)

7.7.11.1 CBC-REQ

7.7.11.3.2.2.3 Centralized Scheduling R-CPE Demodulator

The format of a Centralized Scheduling R-CPE Demodulator IE is shown inTable S1. This field indicates the different demodulator options supported by a centralized scheduling R-CPE for the downstream reception.

Table S1—Centralized Scheduling R-CPE Demodulator

7.7.11.3.2.2.4 Centralized Scheduling R-CPE Modulator

The format of a Centralized Scheduling R-CPE Demodulator IE is shown in Table T1. This field indicates the different modulator options supported by a centralized scheduling R-CPE for upstream transmission.

Table T1—Centralized Scheduling R-CPE Modulator

7.7.11.3.4 Relay CPE Mode

The format of a Relay CPE Mode IE is shown in Table U1. This IE defines a relay operation mode for the CPEs.

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Table U1—Relay CPE Mode information element

7.7.11.3.5 Multi-channel operation supported

This information element indicates the capability of the CPE whether the multi-channel operation is supported or not supported

Table V1—Multi-channel operation supported information element

7.7.24 Confirmation codes

Following fields are inserted in Table 173 as follows:

Table 173—Confirmation Codes

7.7.25 Local Cell Update

7.7.25.1 Local Cell Update REQ

The format of a Local Cell Update request message is shown in Table W1. This message shall be transmitted by a distributed scheduling R-CPEs to the MR-BS at the change of local cell information.

Table W1—Local Cell Update REQ message format

7.7.25.2 Local Cell Update RSP

The format of a Local Cell Update response message is shown in Table X1. This message shall be transmitted by an MR-BS to a distributed scheduling R-CPEs for the confirmation of local cell update request.

Table X1—Local Cell Update RSP message format

Table X1—Local Cell Update RSP message format

7.7.25.3 Local Cell Update information element

7.7.25.3.1 De-registration

The format of a de-registration IE is shown in Table Y1.

Table Y1—De-registration information element

7.7.26 Container Message

The format of a Container message is shown in Table Z1. A container message is used to convey management messages from the centralized scheduling R-CPE to the BS/MR-BS.

Table Z1—Container message format

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Table Z1—Container message format

7.7.26.1 Container ACK Message

The format of a Container ACK message is shown in Table AA1. A container ACK message is used to acknowledgment for a container message sent to the centralized scheduling R-CPE from the BS/MR-BS.

Table AA1—Container ACK message format

7.7.27 Downstream Transit Test Message

7.7.27.1 Downstream Transmit Test (DTT) Request

The format of a DTT request message is shown in Table AB1.

Table AB1—DTT-REQ message format

7.7.27.1.1 Downstream Transmit Test (DTT) Request information element

The format of a DTT request IE is shown in Table AC1.

Table AC1—DTT-REQ information element

7.7.27.2 Downstream Transmit Test (DTT) Response

The format of a DTT response message is shown in Table AD1.

Table AD1—DTT-RSP message format

7.7.27.2.1 Downstream Transmit Test (DTT) Response information element

The format of a DTT response IE is shown in Table AE1.

Table AE1—DTT-RSP information element

7.7.27.3 Downstream Transmit Test (DTT) Report Message

The format of a DTT report message is shown in Table AF1.

Table AF1—DTT-RPT message format

7.7.27.3.1 Downstream Transmit Test (DTT) Report information element

The format of a DTT report IE is shown in Table AG1.

Table AG1—DTT-RPT information element

7.7.27.4 Downstream Transmit Test (DTT) Confirmation Message

The format of a DTT confirmation message is shown in Table AH1.

Table AH1—DTT-CFM message format

7.7.27.4.1 Downstream Transmit Test (DTT) Confirmation information element

The format of a DTT confirmation IE is shown in Table AI1.

Table AI1—DTT-CFM information element

7.7.28 Relay-SCHE message

The format of a Relay SCHE message is shown in Table AJ1. This message may be used for the coordination of the uplink allocation. It is sent by an MR-BS to an R-CPE or sent by an R-CPE to an S-CPE.

Table AJ1—Relay-SCHE message format

7.7.29 Channel Allocation Manager (CAM-AIF/STP/STP-ACK/SWH/SWH-ACK)

This clause describes the channel allocation manager management messages for the basic multi channel operations such as add new operating channel operation (CAM-AIF), stop operating channel (CAM-STP/ STP-ACK)and switch operating channel (CAM-SWH/SWH-ACK).

7.7.29.1 Add new operating channel (CAM-AIF)

The format of the add new operating channel message is shown in Table AK1. This message is used to configure add new operating channel procedure during the multichannel operation. The aggregation information is needed by the CPE-CAM in order to identify the aggregation information transmitted from the BS-CAM. This message includes the number of maximum aggregation channel allowed and the channel aggregation information for CPE.

7.7.29.2 Stop operating channel (CAM-STP)

The format of the stop operating channel message is shown in Table AL1. This message is used to configure stop operating channel procedure during the multichannel operation. This message is sent by BS-CHU to the CPE-CHU in order to stop the operating channel in CPE-CHU. Transmission of this message may result from various conditions such as protection of incumbent services (BS incumbent sensing report, CPE incumbent sensing report), channel availability in database and BS channel scheduling.

Table AL1—CAM-STP message format

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Table AL1—CAM-STP message format

7.7.29.3 Stop operating channel acknowledgment (CAM-STP-ACK)

The format of the stop operating channel acknowledgment message is shown in Table AM1. This message shall be sent by CPE-CHU to the BS-CHU in response to a received CAM-STP. This message serves to confirm to the BS-CHU the reception of the CAM-STP message by the CPE-CHU.

Table AM1—CAM-STP-ACK message format

7.7.29.4 Switch operating channel (CAM-SWH)

The format of the switch operating channel message is shown in Table AN1. This message is used to configure switch operating channel procedure during the multichannel operation. This message is sent by BS-CHU to the CPE-CHU in order to switch the operating channel in CPE-CHU. Transmission of this message may result from various conditions such as protection of incumbent services (BS incumbent sensing report, CPE incumbent sensing report), channel availability in database and BS channel scheduling.

Table AN1—CAM-SWH message format

Table AN1—CAM-SWH message format

7.7.29.5 Switch operating channel acknowledgment (CAM-SWH-ACK)

The format of the switch operating channel acknowledgment message is shown in Table AO1. This message shall be sent by CPE-CHU to the BS-CHU in response to a received CAM-SWH. This message serves to confirm to the BS-CHU the reception of the CAM-SWH message by the CPE-CHU.

Table AO1—CAM-SWH-ACK message format

7.7.30 Group Resource Allocation

7.7.30.1 Group Resource Allocation Configuration (GRA-CFG)

The format of Group Resource Allocation Configuration message is shown in Table AP1. This message is used to configure the group resource allocation. The BS uses this message to create a new group and indicate identify the devices that is belonging to a group.

 The device bitmap size specifies the maximum number of devices that can be supported by a new group. The SID bitmap is used to indicate the device belonging to the group. The total size of the SID bitmap is the number of devices multiplied by 9 bits station ID. Each group is identified by a unique 12-bit group ID. The group is classified into two types, fixed group and portable or mobile group. The type of group is determined according to the mobility of H-CPE. The location of group is represented by the latitude and longitude of H-CPE.

Table AP1—GRA-CFG message format

7.7.30.2 Group Resource Allocation Update (GRA-UPD)

The format of Group Resource Allocation Update message is shown in Table AQ1. This message is used to update the group resource allocation configuration. The device can be added to or deleted from a group.

Table AQ1—GRA-UPD message fomat

Table AQ1—GRA-UPD message fomat

7.9 ARQ mechanism

7.9.6 ARQ operation

Insert new subclause [7.9.6.4:](#page-93-0)

7.9.6.4 ARQ for a relay network

In MR-WRAN systems, there are two ARQ modes. The first mode is an end-to-end ARQ mode that is performed between an MR-BS and an S-CPE; the second mode is a two-link ARQ mode that is performed both between an MR-BS and an R-CPE and between an R-CPE and an S-CPE. The support of ARQ mode is performed during the network entry.

In the end-to-end ARQ mode, the ARQ operation is same as the operations described in 7.9.6.1, 7.9.6.2 and 7.9.6.3. An R-CPE does not have an additional ARQ functionality.

In two-link ARQ mode, the ARQ operation is divided into two links that are a relay link between MR-BS and R-CPE and an access link between R-CPE and S-CPE. The detailed procedure for two-link ARQ mode is de-scribed in the [7.9.6.4.1](#page-93-1).

7.9.6.4.1 Two-link ARQ mode

For an access link between R-CPE and S-CPE, the ARQ state machine runs between the R-CPE and the S-CPE. For relay link between MR-BS and R-CPE, the ARQ state machine runs between the MR-BS and the R-CPE. The MR-BS schedules retransmission to the R-CPE when ARQ block is corrupted in the relay link. The R-CPE schedules retransmission to the S-CPE when ARQ block is corrupted in the access link.

The ARQ feedback IE described in Table 176 is used by the MR-BS and R-CPE to ACK/NAK to corresponding data transmitted between MR-BS and R-CPE. The ARQ feedback IE is transported either as a packed payload ("piggybacked") within a packed MAC PDU or as a payload of a standalone MAC PDU defined in 7.6.

 In downlink ARQ operation, when MR-BS sends ARQ block to R-CPE, it waits for the ARQ feedback IE from R-CPE. When ARQ block is corrupted in the relay link, the R-CPE sends NAK to MR-BS, and MR-BS schedules the retransmission of the corresponding ARQ block to R-CPE as shown in [Figure F1.](#page-94-0) When MR-BS receives ACK from R-CPE, it waits for the ACK from the S-CPE relayed by R-CPE. R-CPE may modify

 the ARQ feedback IE received from S-CPE to inform only ACK to MR-BS. When MR-BS receives ACK from S-CPE, it clears the buffer corresponding to ARQ block as shown in [Figure F1.](#page-94-0) When ARQ block is corrupted in the access link, R-CPE shall not send NAK to MR-BS and shall schedule the retransmission of ARQ blocks to S-CPE. R-CPE shall discard the ARQ block when ARQ block transmission failed in the access link after a timeout of the ARQ_BLOCK_LIFETIME. MR-BS or R-CPE discards the corresponding ARQ block after the timeout of its ARQ_BLOCK_LIFETIME. MR-BS and RS ARQ_BLOCK_LIFETIME are independently operated in MR-BS and R-CPE respectively.

Figure F1—Example of downlink ARQ for relay

In uplink ARQ operation, when R-CPE receives ARQ block correctly from S-CPE, R-CPE sends ARQ block to MR-BS. When MR-BS receives ARQ block correctly, MR-BS sends ACK to R-CPE and the R-CPE sends ACK to S-CPE. When ARQ block is corrupted in the relay link, the retransmission shall be scheduled from R-CPE to MR-BS. R-CPE discards the corresponding ARQ block after a timeout of ARQ_BLOCK_LIFE-TIME in R-CPE.

7.9.6.4.2 ARQ State machine

 The ARQ state machine operation in R-CPE and receiver in MR-BS is the same as described in 7.9.6.2 and 7.9.6.3. In case of transmitter state machine in MR-BS, an ARQ block may be in one of the following five states—not sent, outstanding for R-ACK, outstanding for S-CPE-ACK, waiting for retransmission, and data discard. Outstanding for R-ACK is the state waiting for receiving acknowledged from R-CPE. When R-ACK received, the state transits to outstanding for S-CPE-ACK. In this state, MR-BS receives S-CPE-NACK or after ARQ_BLOCK LIFE_TIME, the state transits to discard. If MR-BS receives S-CPE-ACK in the state of outstanding for R-ACK or waiting for retransmission, the state transits to done. Other state transition descriptions are the same as transmitter state machine defined in x.x.x. The ARQ Tx block state sequence in MR-BS is shown in [Figure G1.](#page-95-0)

7.11.1a Bandwidth Request for a relay network

In 802.22b systems, the bandwidth request message, mechanism, and capability defined for the CPE and MR-BS shall be applicable for the R-CPE. Capability of incremental BRs is only mandatory if the R-CPE is a distributed scheduling R-CPE.

7.11.1a.1 Bandwidth Request by a distributed scheduling R-CPE

A distributed scheduling R-CPE directly handles the bandwidth requests it receives from its S-CPEs.

A distributed scheduling R-CPE may receive bandwidth requests from its S-CPEs via the MAC signaling header, the grant management subheader or the CDMA bandwidth request code.

To forward upstream traffic to MR-BS, a distributed scheduling R-CPE may request uplink bandwidth via a stand-alone bandwidth request header. A distributed scheduling R-CPE may combine the bandwidth requests that arrive from S-CPEs together by using a Container message (7.7.26) or with the bandwidth needs of queued packets into one bandwidth request header per QoS class.

The distributed scheduling R-CPE may transmit a BW request header soon after it receives a BW request header from one of its S-CPEs (timed to yield an uplink allocation sequential to the arrival of those packets) instead of waiting for the actual packets to arrive in order to reduce delay in relaying traffic (see [Figure H1](#page-96-1)).

Figure H1—Reducing latency in relaying traffic by transmitting BW request header before packets arrive

7.11a.2 Bandwidth Request by a centralized scheduling R-CPE

In centralized scheduling mode, the MR-BS shall determine the bandwidth allocations (i.e., MAPs) for all links in its cell. As a result, centralized scheduling R-CPEs shall receive the MAPs from the MR-BS for the links to/from their CPEs before they can transmit them.

 For the same reason, centralized scheduling R-CPEs shall forward all bandwidth request headers and bandwidth request CDMA ranging code information they receive from CPEs to the MR-BS. The centralized scheduling R-CPEs may combine bandwidth request by using a Container message (7.7.26).

If the centralized scheduling R-CPE has available uplink bandwidth, it shall simply forward the bandwidth

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request information to the MR-BS. Otherwise, the centralized scheduling R-CPEs shall request uplink bandwidth from the MR-BS using CDMA ranging codes.

If the centralized scheduling R-CPE needs bandwidth for a MAC management message to a CPE, the centralized scheduling R-CPE shall either send a CRZ CDMA ranging code dedicated for that purpose or a BR header. In response, the MR-BS shall allocate bandwidth for a management message in the DS-MAP it sends to the centralized scheduling R-CPE for broadcast.

7.11.2 Grants

Insert new subclauses [7.11.3a](#page-97-0) as follows:

7.11.3a Grants for a relay network

Insert new subclauses [7.11.3a.1](#page-97-1) and [7.11.3a.2](#page-98-1) as follows:

7.11.3a.1 Bandwidth grant for relay with a distributed scheduling R-CPE

If the bandwidth request comes from a distributed scheduling R-CPE, the MR-BS shall address the bandwidth grant to the R-CPE's Basic FID. The distributed scheduling R-CPE may schedule a MAC PDU or relay MAC PDU on the bandwidth allocation it receives.

 An MR-BS may send its distributed scheduling R-CPEs uplink scheduling information ahead of time via an Relay-SCHE management message. This message indicates when a given uplink bandwidth allocation will be granted to the distributed scheduling R-CPE (i.e., in how many frames), the size of the allocation, and the intended CID. The actual bandwidth grant is issued to the distributed scheduling R-CPE using a Data Grant IE in an upcoming US-MAP. In the case of periodic bandwidth grants, the scheduling information need only be sent once (see [Figure I1](#page-98-0)).

 When a distributed scheduling R-CPE receives an Relay-SCHE management message with uplink scheduling information from the MR-BS, it shall look up the target CPE of the given FID. Based on this scheduling information and the target CPE of the FID, the distributed scheduling R-CPE can determine the appropriate bandwidth allocations and associated RS UL allocation frame offset on the uplinks it controls.

 Figure I1—Periodic bandwidth grant with R-CPE scheduling information 7.11.3a.2 Bandwidth grant for Relay with a centralized scheduling R-CPE For centralized scheduling, when an MR-BS allocates bandwidth to forward a packet to/from a given station, it shall allocate bandwidth on all links (relay and access) that make up the path to/from that station taking into account the processing delay and link qualities at each R-CPE. **7.11.4 Polling** *Insert new subclause [7.11.4.1](#page-98-2) as follows:* **7.11.4.1 Polling for a relay network** The polling procedure defined in 7.11.3 for the CPE and the MR-BS may be used between the CPE/R-CPE. If an R-CPE is regularly polled, it can transmit a bandwidth request header to the MR-BS as soon as it detects impending uplink traffic in order to reduce delay (see Figure J1). An MR-BS or a distributed scheduling R-CPE may inform a CPE of upcoming polling via an Relay SCHE management message (see Figure K1). S-CPE R-CPE MR-BS Relay SCHE message US-MAP (Data Grant IE) US-MAP (Data Grant IE) Data 1 Data 1 US-MAP (Data Grant IE) US-MAP (Data Grant IE) Data 1 Data 1

 For centralized scheduling, only the MR-BS may establish a polling process with a CPE or centralized scheduling R-CPE in the MR-cell.

7.12 PHY support

7.13Contention resolution

Change the paragraph as follows:

The BS, MR-BS or distributed scheduling R-CPE controls assignments on the upstream channel through the US-MAP messages and determines which symbol periods are subject to collisions. Collisions may occur during Initial Ranging/Relay Initial Ranging/Local Initial Ranging, Periodic Ranging/Relay Periodic Ranging/Local Periodic Ranging, Bandwidth Request/Relay Bandwidth Request/Local Bandwidth Request, UCS notification/Relay UCS notification/Local UCS notification, and the SCW defined by their respective IEs. The potential occurrence of collisions in the Intervals is dependent upon the number of SIDs whose US-MAP IEs are (simultaneously configures to use an Interval for a specific purpose (e.g., Ranging, UCS notification, BW Request). The CPE has to make a decision in order to resolve collision in the upstream direction for Initial Ranging/Relay Initial Ranging/Local Initial Ranging, Periodic Ranging/Relay Periodic Ranging/Local Periodic Ranging, and BW Request/Relay Bandwidth Request/Local Bandwidth Request. Since in the case of UCS notification/Relay UCS notification/Local UCS notification and SCW (CBP packet transmission in the SCW) no explicit feedback is expected to be received from the BS, MR-BS or distributed scheduling R-CPE, collision resolution does not apply.

Change the paragraph as follows:

28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48 49 In the case of Initial Ranging/Relay Initial Ranging/Local Initial Ranging and Periodic Ranging/Relay Periodic Ranging/Local Periodic Ranging, collision resolution is to be done by a CDMA method (see Table 31 and Table 37). In the case of Bandwidth Request/Relay Bandwidth Request/Local Bandwidth Request and UCS notification/Relay UCS notification/Local UCS notification, both those methods, CDMA as well as exponential time backoff, explained later in this subclause, can be used. In the case of collision resolution in the SCW, a special scheduling scheme, described in 7.20.1.2, shall be used. Since a CPE may need to service multiple upstream service flows (each with its own FID), it makes these decisions on a per FID or on a QoS (see 7.17) basis. The method of contention resolution that shall be supported for BW Request/Relay Bandwidth Request/Local Bandwidth Request and UCS notification/Relay UCS notification/Local UCS notification isare based on a truncated binary exponential backoff, with the initial backoff window and the maximum backoff window controlled by the BS, MR-BS or distributed scheduling R-CPE (see Table 30). The values, expressed in units of opportunity (see Table 31) are specified as part of the UCD message and represent a power-of-two value. For example, a value of 4 indicates a window between 0 and 15 opportunities; a value of 10 indicates a window between 0 and 1023 opportunities. When a CPE has information to send and wants to enter the contention resolution process, it sets its internal backoff window equal to the BW Request or UCS Notification Backoff Start defined in the UCD message referenced by the UCD Count in the US-MAP message currently in effect (the map currently in effect is the map whose allocation start time has occurred but which includes IEs that have not occurred).

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51 52 53 54 55 56 57 58 Note that the number of these opportunities per frame depends on the size of the opportunity window in number of subchannels defined by the US-MAP for UIUC 2 or 3 (see Table 35) and the opportunity size for the BW Request/Relay Bandwidth Request/Local Bandwidth Request and UCS notification/Relay UCS notification/Local UCS notification defined in Table 31. These opportunities shall be mapped horizontally in the time domain and fill a subchannel before moving to the next subchannel as is done for the upstream data PDU mapping.

7.13.1 Transmission opportunities

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Change the paragraph as follows:

64 65 A transmission opportunity is defined as an allocation provided in a US-MAP or part thereof intended for a

group of CPEs authorized to transmit initial ranging requests/relay initial ranging requests/local initial ranging requests, periodic ranging requests/relay periodic ranging requests/local periodic ranging requests, bandwidth requests/relay bandwidth requests/local bandwidth requests, or UCS notifications/relay UCS notifications/local UCS notifications. This group may include either all CPEs that have an intention to join the cell or all registered CPEs or a multicast polling group. The number of transmission opportunities associated with a particular IE in a map is dependent on the total size of the allocation as well as the size of an individual transmission.

7.14 Initialization and network association

Insert new subclause [7.14.3](#page-101-0) as follows:

7.14.3 CPE initialization for relay

Figure L1—MR-WRAN scenario where a safe bootstrap operation is required to protect incumbents

 Figure L1 illustrates an MR-WRAN scenario where the need for the definition of an incumbent safe CPE initialization can be easily seen. In this figure, consider that S-CPE 4, which is located outside of a MR-BS's cell but located within a distributed scheduling R-CPE 2's local cell, is powered down whereas the MR-BS is transmitting in the cell and R-CPE 2 being a member of the MR-BS is transmitting in the local cell that are under normal operation. Further, assume that the TV station in Figure L1 is powered up and starts transmitting in the same channel (i.e., channel #N in this example) that is being used by the MR-BS and R-CPE 2 for their transmissions in the cell. S-CPE 4 should be capable of detecting that R-CPE 2 is operating in a

channel that is occupied by an incumbent service. The MR-BS must be capable of determining if S-CPE 4 is located within interference range of the TV station protected contour (i.e., in the keep-out region). If S-CPE 4 is already registered with the network managed by the R-CPE 2, it will alert the R-CPE 2. If S-CPE 4 is not registered with the network, it shall not transmit. See 10.2.5, policies 5 and 6. In the response to the alert from S-CPE 4, the SM at R-CPE 2 performs to detect TV station and shall sends the notification of detecting TV station to the MR-BS. In response to the notification from R-CPE 2, the SM at the MR-BS may or may not decide to switch channel to accommodate the connected CPEs (see 10.2.6.6). The purpose of the sensing and geolocation capabilities of the WRAN system shall be to prevent harmful interference to the primary TV service by providing the necessary information to the MR-BS's SM that generates the list of available channels. The definition of an incumbent safe CPE initialization phase is critical for cognitive radio systems. The SM incorporates algorithms to address this need (see Table 234, policies 5 and 6). First and foremost, the MAC does not presuppose any preassigned channel where a CPE is able to look for

16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 an MR-BS or a distributed scheduling R-CPE given the time-varying and unpredictable nature of channel occupancy. Hence, the first task a CPE must perform in attempting to join a network is to scan the set of channels for MR-BSs or R-CPEs and incumbent services on which the transmissions of the CPE might interfere. Since the MR-BS shall send concentrated OFDM symbols composed of a frame preamble and SCH once every superframe in PHY mode 1, or a frame preamble and an FCH once every frame in PHY mode 2 in its operating channel, and the distributed scheduling R-CPE shall send concentrated OFDM symbols composed of a local frame preamble and a DRZ-FCH in the downstream DRZ subframe within a frame, if available, in its operating channel (see 7.3), the CPE will recognize the existence of an MR-BS or a distributed scheduling R-CPE transmission and, if appropriate, proceed with the CPE initialization procedure with the corresponding MR-BS or distributed scheduling R-CPE. Although a CPE will recognize the existence of an MR-BS, in particular, the CPE may not be initialized with the MR-BS directly since the transmission of the CPE is not able to reach the MR-BS due to the power constraint. In this case, the CPE will make an initial-

31 32 ization by relaying on a centralized scheduling R-CPE.

33 34 35 The procedure carried out by the MR-BS, the centralized scheduling R-CPE, the distributed scheduling R-CPE and the CPE to perform CPE network entry and initialization shall be as follows:

36 a) CPE performs self test.

- 37 38 b) CPE acquires the antenna gain information.
- 39 40 c) CPE senses for and synchronizes to WRAN services. The sensing thread also begins during this step to detect broadcasting incumbents.
- 41 d) CPE presents sensing results to the higher layers.
- 42 43 e) CPE chooses a WRAN service.
- 44 45 46 47 48 f) If CPE is capable of geolocation, CPE acquires valid geolocation data from the satellites. If the data acquisition is unsuccessful, CPE initialization should not continue or may continue to operate as an S-CPE mode. If CPE is not capable of geolocation, CPE initialization should not continue or may continue to operate as an S-CPE mode (FCC Mode I).
- 49 g) CPE acquires the downstream and upstream parameters from the selected WRAN service.
- 50 51 h) CPE directional antenna azimuth adjustment.
- 52 53 i) If channels N and $N\pm1$ pass the sensing and timing requirements, CPE perform initial ranging (see 7.15.2.1).
- 54 55 j) CPE transmits basic capabilities.
- 56 57 58 59 k) If all required basic capabilities are present in the CPE, the AAA authenticates the CPE and key exchange is performed; otherwise, the CPE does not proceed to registration and the MR-BS deregisters the CPE.
- 60 l) Perform Registration (REG-REQ/RSP).
- 61 m) Upon completing registration, MR-BS transmits channel sets to CPE.
- 62 63 n) Establish IP connectivity.
- 64 o) Establish time of day.
- 65 p) Transfer operational parameters.

q) Establish dynamic service flows.

r) CPE reports sensing results and discovered neighboring networks.

Figure M1 summarizes the network entry of the CPE and its initialization procedure. Note that these steps taken by the CPE consist of a set of actions and error verification. In the following subclauses, a more detailed description of these steps and their individual responsibilities are provided.

7.14.3.1 CPE performs self test

On initialization or after signal loss, the CPE shall perform a self test.

7.14.3.2 CPE antenna gain information acquisition

The CPE shall determine if its antenna is integrated or not by querying it using the M-ANTENNA- INTE-GRATED primitive structure described in 10.7.6.1 and 10.7.6.2. The CPE shall acquire the antenna information including the maximum antenna gain information for the channels that can be used in the regulatory domain of interest. This information is stored in a MIB, *wranIfBsCpeAntennaGainTable*. If the antenna is integrated to the CPE TRU, this MIB object shall be pre-populated by the manufacturer of the CPE. If the antenna is not integrated into the CPE TRU, the MIB object shall be populated by querying the AU through the interface defined in 9.12.2. The information at the antenna shall be pre-populated by the antenna manufacturer.

7.14.3.3 CPE senses for and identifies WRAN services and incumbents

The CPE identifies WRAN services from detecting the MR-BS or the distributed scheduling R-CPE. The CPE shall perform spectrum sensing to detect the MR-BS or the distributed scheduling R-CPE, and may perform spectrum sensing to detect and identify legitimate incumbent services that are to be protected on each active WRAN channel in the area and its adjacent channels as described in 10.3.2.

7.14.3.4 Present sensing results to the higher layers

As a result of spectrum sensing, the available MR-BSs or distributed scheduling R-CPEs in the area are presented to the application layer program via connection C2 and MIBs through M-SAP as shown in IEEE 802.22 reference architecture (Figure 7). The application may be running on the CPE or on an attached computer. The data presented includes the operating channel of the MR-BS and RSSL in addition to the WRAN service being advertised.

7.14.3.5 CPE chooses a WRAN service

> A WRAN service is selected at the higher layers of the CPE after preliminary sensing and identification of available MR-BSs or distributed scheduling R-CPEs and the presence of incumbents in the area as the previous subclauses describe. The CPE SSA shall issue an M-WRAN-SERVICE-REPORT primitive to request the higher layers through the NCMS to select a channel from the available WRAN service list that is included in the primitive, as described in 10.7.4.1. The SSA shall receive an M-WRAN-SERVICE-RE-SPONSE primitive with the selected channel from the NCMS, as described in 10.7.4.3. Once the channel is selected, it and its adjacent channels are more rigorously sensed in order to detect the presence of a weak incumbent service that might be masked by the selected WRAN service. This procedure is described in more detail in 10.3.2.

51 **7.14.3.6 CPE performs satellite-based geolocation**

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The CPE shall acquire geolocation data from a satellite-based geolocation receiver when it will operate as a fixed mode or as a distributed scheduling R-CPE (which is a mode II defined in FCC regulation). A CPE shall not progress to the next step of initialization for the fixed mode operation or the distributed scheduling R-CPE operation until the satellite-based geolocation technology successfully establishes lock and acquires valid geolocation data from the satellites. The CPE sends the NMEA string to the MR-BS during registration (see [7.14.3.11](#page-120-0)).

7.14.3.7 Acquire downstream and upstream parameters

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65 There are two methods for acquiring downstream and upstream parameters; acquire downstream and up-

stream parameters from a MR-BS and acquire downstream and upstream parameters from a distributed scheduling R-CPE.

7.14.3.7.1 Obtaining downstream parameters from an MR-BS

The MAC shall search for the SCH for PHY mode 1 (Clause 9) or FCH for PHY mode 2 (Clause 9a) from the MR-BS, which indicates the beginning of the frame in normal mode, and the allocated frame in self-coexistence mode. To improve the joining latency, the CPE shall use energy detection to help ascertain about the presence/absence of a MR-BS in a particular channel. If the energy detected is below the detection threshold, the CPE can safely move to the next channel.

 After having received SCH or FCH in a channel, the CPE shall perform sensing not only in the detected operating channel, but also in all other affected channels. During this sensing, the CPE shall attempt to identify incumbent operation. If incumbents are detected on the operating channel or either first adjacent channel, the MAC shall cause the CPE to cease transmitting application traffic on the channel and, at the first transmit opportunity send a short control message to the MR-BS indicating that it is using a channel occupied by an incumbent. In case the MR-BS receives such notification, it may take numerous actions as described in Figure 96. The aggregate duration of the short control messages shall not exceed the Channel Closing Transmission Time (see Table 276) of transmissions by the WRAN system before remedying the interference condition (changing channels, backing off transmit EIRP, terminating transmissions, etc.).

 Provided no incumbents are found, the CPE may proceed to the next step. Here, the MAC shall search for the DS-MAP MAC management messages. The CPE achieves MAC synchronization once it has received at least one DS-MAP message. A CPE MAC remains in synchronization as long as it continues to successfully receive the FCH, DS-MAP, and DCD messages for its channel(s). If the Lost DS-MAP Interval (Table 273) has elapsed without a valid DS-MAP message or the T1 interval (Table 273) has elapsed without a valid DCD message or Lost FCH counts of FCH are missed, a CPE shall try to re-establish synchronization. The process of acquiring synchronization is illustrated in Figure N1. The process of maintaining synchronization is illustrated in Figure O1.

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Figure O1—Maintaining downstream parameters

7.14.3.7.2 Obtaining downstream parameters from a distributed scheduling R-CPE

As another method to obtain downstream parameters, the MAC may search for a DRZ-FCH (7.5.2b) transmitted from a distributed scheduling R-CPE, which indicates the beginning of the distributed relay zone [\(7.4b.3.3\)](#page-32-0) of downstream.

32 33 34 35 36 37 38 39 40 41 42 43 44 45 After having received a DRZ-FCH in a channel, the CPE shall perform sensing not only in the detected operating channel but also in all other affected channels. During this sensing, the CPE shall attempt to identify incumbent operation. If incumbents are detected on the operating channel or either first adjacent channel, the MAC shall cause the CPE to cease transmitting application traffic on the channel and, at the first transmit opportunity in a distributed relay zone (DRZ) of upstream send a short control message to the distributed scheduling R-CPE indicating that it is using a channel occupied by an incumbent. In case that the distributed scheduling R-CPE receives such notification, it shall send a short control message to the MR-BS. In case the MR-BS receives such notification, it may take numerous actions as described in Figure 96. The aggregate duration of the short control messages shall not exceed the Channel Closing Transmission Time (see Table 276) of transmissions by the WRAN system before remedying the interference condition (changing channels, backing off transmit EIRP, terminating transmissions, etc.).

46 47 48 49 50 51 52 53 54 55 56 57 Provided no incumbents are found, the CPE may proceed to the next step. Here, the MAC shall search for the DS-MAP MAC management messages, which are transmitted from the distributed scheduling R-CPE, in a DRZ of downstream. The CPE achieves MAC synchronization to the distributed scheduling R-CPE once it has received at least one DS-MAP message. A CPE MAC remains in synchronization as long as it continues to successfully receive the DRZ-FCH, DS-MAP, and DCD messages for its channel(s) within a DRZ. If the lost DS-MAP Interval (Table 273) has elapsed without a valid DS-MAP message or the T1 interval (Table 273) has elapsed without a valid DCD message or lost DRZ-FCH counts of DRZ-FCH are missed, a CPE shall try to re-establish synchronization. The process of acquiring synchronization is illustrated in Figure N1. The process of maintaining synchronization is illustrated in Figure P1.

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Figure P1—Maintaining downstream parameters in DRZ

7.14.3.7.3 Obtaining upstream parameters from an MR-BS

After synchronization to the MR-BS, the CPE shall wait for a UCD message from the MR-BS in order to retrieve a set of transmission parameters for a possible upstream channel. These messages are transmitted periodically from the MR-BS for all available upstream channels and are addressed to the MAC broadcast address.

If no upstream channel can be found after a suitable timeout period, then the CPE shall continue scanning to find another downstream channel. The process of obtaining upstream parameters is illustrated in Figure 37.

 The CPE shall determine from the channel description parameters whether it may use the upstream channel. If the channel is not suitable, then the CPE shall continue scanning to find another downstream channel. If the channel is suitable, the CPE shall extract the parameters for this upstream from the UCD. It then shall wait for the next DS-MAP message and extract the time synchronization from this message. Then, the CPE shall wait for a bandwidth allocation map for the selected channel. It may begin transmitting upstream in accordance with the MAC operation and the bandwidth allocation mechanism.

 The CPE shall perform initial ranging at least once. If initial ranging is not successful, the procedure is restarted from scanning to find another downstream channel.

The CPE MAC is considered to have valid upstream parameters as long as it continues to successfully receive the SCH/FCH, US-MAP, and UCD messages. If at least one of these messages is not received within the time intervals specified in Table 273, the CPE shall not use the upstream. This is illustrated in Figure Q1.

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Figure R1—Maintaining upstream parameters in DRZ

7.14.3.8 CPE transmits ranging/CDMA burst

From the result of synchronization as described in [7.14.3.7,](#page-105-0) initial ranging will be performed. There are three methods of CPE transmit initial ranging; initial ranging to a MR-BS, initial ranging to a distributed scheduling R-CPE, and initial ranging to a centralized scheduling R-CPE on relaying.

36 37 38 39 40 41 42 43 The selected channel is analyzed to determine if it passes the restrictions specified in 10.3.2. If the selected channel does not pass these restrictions, the association with the selected MR-BS or distributed scheduling R-CPE is unsuccessful and the selected channel shall be removed from further consideration. Available MR-BSs or distributed scheduling R-CPEs are again presented to the higher layers for selection if there exists any other MR-BSs or distributed scheduling R-CPEs with which to associate.

Next the selected channel and the channels that could be harmfully interfered by operation on this selected channel shall be more finely sensed as to determine if there exists a weak protected incumbent signal that was not detected at an earlier stage in the CPE initialization procedure. This process is described in 10.3.2.

48 49 50 51 52 53 54 55 56 Time in this subclause shall be referenced to two positions in space. One position will be that of the MR-BS or distributed scheduling R-CPE and the other position will be that of the CPE. Many such CPE positions will exist. Ranging is the process of acquiring the correct timing offset and EIRP adjustments such that the CPE's transmissions are aligned at the MR-BS or distributed scheduling R-CPE position. Ranging also adjusts transmit EIRP of the various CPEs such that the OFDMA signal received at the MR-BS or distributed scheduling R-CPE arrives with compatible amplitudes from all the CPEs.

57 58 59 60 61 62 63 64 Although a CPE successfully obtains downstream parameters from a MR-BS, in particular, ranging to the MR-BS as described in [7.14.3.8.1m](#page-112-0)ay be failed due to the CPE transmitting power constraint. However, the CPE is still able to have an uplink transmission to the MR-BS by relaying on a centralized scheduling R-CPE. In this case, the CPE may perform ranging to a centralized scheduling R-CPE for the relaying operations that acquiring the correct timing offset and EIRP adjustments aligned at the centralized scheduling R-CPE.

65 The timing delays through the PHY shall be constant to within 25% of the shortest symbol cyclic prefix as indicated in 9.9.1.

7.14.3.8.1 CDMA initial ranging and automatic adjustments to an MR-BS

First, a CPE shall synchronize to the frame preamble in order to perform initial ranging to MR-BS. At this point, the CPE shall scan the US-MAP message to find an Initial Ranging Interval. The MR-BS may allocate an Initial Ranging Interval consisting of one or more transmission opportunities. The CPE shall extract the number of initial ranging codes (see Table 31, element ID 150) from the UCD MAC management message.

The CPE randomly selects the CDMA code as described in 7.15.2.1a and sends the initial ranging CDMA code on the US allocation dedicated for that purpose. The MR-BS receives the CDMA code. As many CPEs may contend for ranging, the CDMA code received may be the sum of many CPE transmissions. The MR-BS isolates each of these transmissions and computes the ranging adjustments based on the relative time of arrival of each CPE upstream burst, i.e., the timing offset, so that all these bursts arrive at the MR-BS at the beginning of the symbol period within sufficient tolerance.

20 21 22 23 24 25 26 27 28 Ranging adjusts each CPE's timing offset such that each CPE appears to be co-located with the MR-BS. The CPE shall set its initial timing offset to "zero advance" as if it was physically co-located with the MR-BS. When the Initial Ranging transmission opportunity occurs, the CPE shall send a CDMA code. After reception and decoding of this CDMA code, the MR-BS will react by sending a RNG-CMD MAC message in a following frame with the same CDMA code and indicate the timing advance that the CPE should use for its upstream transmissions (see Table 44) so that the beginning of its bursts is aligned with the center of the cyclic prefix within the tolerance indicated in 9.9.1.

When the Initial Ranging transmission opportunity occurs, the CPE shall send a CDMA code. Thus, the CPE sends the message as if it were co-located with the MR-BS.

The CPE shall calculate the transmit EIRP per subcarrier for initial ranging, EIRPIR CPE, from the following equation:

37 38 EIRPIR_CPE = EIRPMR-BS + RSSIR_MR-BS_nom – (RSSIR_CPE – GRX_CPE) + $10 \times log(NIR_{sub}/N_{sub})$

where

39

where

45 46 47 48 49 50 sage to find a DRZ Initial Ranging Interval within a local cell managed by a distributed scheduling R-CPE. The distributed scheduling R-CPE may allocate a DRZ Initial Ranging Interval consisting of one or more transmission opportunities in a DRZ for upstream. The CPE shall extract the number of DRZ initial ranging codes (see Table 31, element ID 157) from the UCD MAC management message.

51 52 53 54 55 56 57 58 59 60 The CPE randomly selects the CDMA code as described in 7.15.2.1a and sends the DRZ initial ranging CDMA code on the DRZ of US allocation dedicated for that purpose. The distributed scheduling R-CPE receives the CDMA code. As many CPEs may contend for ranging, the CDMA code received may be the sum of many CPE transmissions. The distributed scheduling R-CPE isolates each of these transmissions and computes the ranging adjustments based on the relative time of arrival of each CPE upstream burst, i.e., the timing offset, so that all these bursts arrive at the distributed scheduling R-CPE at the beginning of the symbol period within sufficient tolerance.

61 62 63 64 65 Ranging adjusts each CPE's timing offset such that each CPE appears to be co-located with the distributed scheduling R-CPE. The CPE shall set its initial timing offset to "zero advance" as if it was physically co-located with the distributed scheduling R-CPE. When the DRZ Initial Ranging transmission opportunity occurs, the CPE shall send a CDMA code. After reception and decoding of this CDMA code, the distributed schedIEEE

If the status of the RNG-CMD message is "continue," the CPE shall wait for a DRZ individual Initial Ranging Interval assigned to its Basic FID. Using this interval, the CPE shall transmit another RNG-REQ message

using the Basic FID along with any power level and timing offset corrections. The distributed scheduling R-CPE shall return another RNG-CMD message to the CPE with any additional fine-tuning required. The ranging request/response steps shall be repeated until the response contains a

"Ranging Successful" notification or the R-CPE aborts ranging. Once successfully ranged (timing, frequency and EIRP are within tolerance at the R-CPE), the CPE shall join normal data traffic in the upstream. In particular, the retry counts and timer values for the ranging process are defined in Table 273.

On receiving a RNG-CMD instruction to move to a new channel during initial ranging, the CPE shall obtain a new SID via initial ranging and registration.

It is possible that the RNG-CMD may be lost after transmission by the distributed scheduling R-CPE. The CPE shall recover by timing out and reissuing its Initial RNG-REQ. Since the CPE is uniquely identified by the source MAC address in the Ranging Request, the distributed scheduling R-CPE may immediately reuse the SID previously assigned. If the distributed scheduling R-CPE assigns a new SID, it shall immediately age out the old SID and associated CPE.

7.14.3.8.3 CDMA initial ranging and automatic adjustments by relaying on centralized scheduling R-CPE

27 28 29 30 31 32 33 34 35 36 37 Although a CPE successfully obtains downstream parameters from a MR-BS, CDMA initial ranging to the MR-BS as described in [7.14.3.8.1](#page-112-0) may be failed due to the CPE transmitting power constraint. However, a CPE is still able to have an uplink to MR-BS by relaying on a centralized scheduling R-CPE. A CPE shall synchronize to the frame preamble in order to perform initial ranging to a MR-BS. At this point, the CPE shall scan the US-MAP message to find an Initial Ranging Interval and CRZ Initial Ranging Interval if available. The MR-BS may allocate a CRZ Initial Ranging Interval consisting of one or more transmission opportunities within a CRZ of US subframe. The CPE shall extract the number of initial ranging codes and may extract the number of CRZ initial ranging codes (see Table 31, element ID 155) from the UCD MAC management message.

38

39 40 41 42 43 44 45 46 The CPE randomly selects the CDMA code as described in 7.15.2.1a and sends the initial ranging CDMA code to the MR-BS on the Initial Ranging Interval, and sends the CRZ initial ranging CDMA code to the centralized scheduling R-CPE on the CRZ Initial Ranging Interval as well in US allocation dedicated for that purpose. The initial ranging between the CPE and the MR-BS shall be following as described in [7.14.3.8.1](#page-112-0). The following section describes the case that the CRZ initial ranging between the CPE and the centralized scheduling R-CPE.

47 48 49 50 51 52 53 54 55 The centralized scheduling R-CPE may receive the CRZ Initial Ranging CDMA code within the CRZ Initial Ranging Interval in a CRZ of US subframe. As many CPEs may contend for ranging, the CDMA code received may be the sum of many CPE transmissions. The centralized scheduling R-CPE isolates each of these transmissions and computes the ranging adjustments based on the relative time of arrival of each CPE upstream burst, i.e., the timing offset, so that all these bursts arrive at the centralized scheduling R-CPE at the beginning of the symbol period within sufficient tolerance.

56 57 58 59 60 61 62 63 64 65 Ranging adjusts each CPE's timing offset such that each CPE appears to be co-located with the centralized scheduling R-CPE. The CPE shall set its initial timing offset to "zero advance" as if it was physically co-located with the centralized scheduling R-CPE. When the CRZ Initial Ranging transmission opportunity occurs, the CPE may send a CRZ CDMA code. After reception and decoding of this CDMA code, the centralized scheduling R-CPE will react by sending a RNG-CMD MAC message in a following frame with the same CDMA code and indicate the timing advance that the CPE should use for its upstream transmissions (see Table44) so that the beginning of its bursts is aligned with the center of the cyclic prefix within the tolerance indicated in 9.9.1. For the transmission of RNG-CMD to the CPE, a centralized scheduling R-CPE IEEE

Moreover, a CPE can successfully perform CDMA initial ranging to the several devices including a MR-BS and centralized scheduling R-CPEs. In this case, the CPE shall select one of those.

7.14.3.8.4 Ranging parameter adjustment

Adjustment of local parameters (e.g., transmit EIRP) in a CPE as a result of the receipt or non-receipt of a RNG-CMD message is considered to be implementation-dependent with the following restrictions:

- a) All parameters shall be within the approved range at all times.
- b) EIRP adjustment shall start from the initial value selected with the algorithm described in [7.14.3.8.1](#page-112-0), [7.14.3.7.2,](#page-108-0) or [7.14.3.7.3](#page-109-0) unless a valid EIRP setting is available from non-volatile storage, in which case this value may be used a the starting point.
- c) EIRP adjustment shall be capable of being reduced or increased by the specified amount in response to the RNG-CMD messages.
- d) If, during initialization, EIRP is increased to the maximum value as determined in [7.14.3.8.1](#page-112-0), [7.14.3.7.2](#page-108-0), or [7.14.3.7.3](#page-109-0) without a response from the MR-BS, it shall go back to the minimum EIRP and ramp up to its maximum EIRP four (4) times before aborting the ranging process with this base station.

On receiving a RNG-CMD message, the CPE shall not transmit until the RF signal has been adjusted in accordance with the RNG-CMD and has stabilized.

7.14.3.9 CPE transmit basic capabilities

7.14.3.9.1 CPE transmit basic capabilities to an MR-BS

Immediately following the completion of initial ranging to the MR-BS, the CPE informs the MR-BS of its basic capabilities by transmitting a CBC-REQ message (see Table 105) with its capabilities set to "on" (see Figure 39). Note that T18 is a timer used to wait for CBC-RSP timeout and the default value is indicated in Table 272.

37 38

39 40 41 42 43 44 45 46 47 The MR-BS responds with a CBC-RSP message (see Table 106) with the intersection of the CPE's and MR-BS's capabilities set to "on" (see Figure 40 and Figure 41, respectively). The timer T9 refers to the time allowed between the MR-BS sending a RNG-CMD to a CPE, and receiving a CBC-REQ from that same CPE, and the minimum value is specified in Table 272. Note that the CPE capability information is presented in 7.7.7.3.4. When T9 expires, the SID assigned during ranging shall be aged out and the CPE shall have to attempt ranging process over again while not exceeding the maximum number of CDMA ranging retries indicated in Table 273.

7.14.3.9.2 CPE transmit basic capabilities to distributed scheduling R-CPE

51 52 53 54 55 Immediately following the completion of DRZ initial ranging, the CPE informs the distraibuted scheduling R-CPE of its basic capabilities by transmitting a CBC-REQ message (see Table 105) with its capabilities set to "on" (see Figure 39). Note that T18 is a timer used to wait for CBC-RSP timeout and the default value is indicated in Table 272.

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48 49 50

57 58 59 60 61 62 63 64 65 The distributed scheduling R-CPE responds with a CBC-RSP message (see Table 106) with the intersection of the CPE's and distributed scheduling R-CPE's capabilities set to "on" (see Figure 40 and Figure S1, respectively). The timer T9 refers to the time allowed between the distributed scheduling R-CPE sending a RNG-CMD to a CPE, and receiving a CBC-REQ from that same CPE, and the minimum value is specified in Table 272. Note that the CPE capability information is presented in 7.7.7.3.4. When T9 expires, the SID assigned during ranging shall be aged out and the CPE shall have to attempt ranging process over again while not exceeding the maximum number of CDMA ranging retries indicated in Table 273.

- have to attempt ranging process over again while not exceeding the maximum number of CDMA ranging re-
	- tries indicated in Table 273.

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7.14.3.10 CPE authentication and key exchange

7.14.3.11 Registration

7.14.3.11.1 Registration to MR-BS

Registration is the process by which the CPE verifies its configuration with the MR-BS. If the CPE supports a configuration that is set by the MR-BS, it is allowed entry into the network and thus becomes manageable. To register with a MR-BS, the CPE shall send a REG-REQ message to the MR-BS. The REG-REQ message shall include a CPE NMEA Location string IE except for Mode I CPE.

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During registration, the CPE's NMEA Location String and various operational parameters are configured (see 7.7.7.3). The CPE sends its location data string (see 7.6.1.3.1.6) upon initial registration and re-registration. When the IP Address Allocation Information Element (see 7.7.7.3.4.11) is present in the REG-REQ message, the MR-BS shall include this IP address allocation parameter in the REG-RSP message to command the CPE to use the indicated version of IP on the secondary management connection. The MR-BS shall command the use of exactly one of the IP versions supported by the CPE.

23 24 25 26 The MR-BS shall determine the location of the antenna of each associated CPE with the accuracy as specified in Table A.9 for the specific regulatory domain. The MR-BS's SM shall receive the generated NMEA string and validate its contents.

The MR-BS's SM shall provide the geolocation data to the database service. The MR-BS shall refuse to serve the CPE if

- The geographic location of the CPE except for Mode I CPE has not been successfully determined as indicated by a failed validation of the data in the NMEA string. Validation shall fail if
- a) the NMEA string contains data that is outside the allowable range of values or;
- b) the distance between the initializing CPE and the MR-BS or other associated CPEs is outside the allowable range of values.
- The database service has indicated that the CPE except for Mode I CPE cannot operate on the channel on which the WRAN network intends to operate.

In the first case, validation of the NMEA string fails and CPE initialization fails, in the second case, the CPE initialization fails on the current channel and shall proceed to the next channel on its available WRAN services list.

The MR-BS shall respond with a REG-RSP message. The REG-RSP message shall include the Permanent Station ID (see Table 61), if CPE Privacy (see 8.7) is enabled. Figure 42 shows the procedure that shall be followed by the CPE to initiate registration.

50 51 52 Once the CPE has sent a REG-REQ to the MR-BS, it shall wait for a REG-RSP to authorize it to forward traffic to the network. Figure 43 shows the waiting procedure that shall be followed by the CPE.

53 54 55 56 57 From encoding CPE operation capabilities in the REG-RSP (7.7.7.3.4.13), the CPE will operate as one of operating modes: a fixed subscriber CPE, a portable subscriber CPE (Mode I), a centralized scheduling R-CPE, or a distributed scheduling R-CPE (fixed or portable Mode II).

58 59 60 61 62 63 The MR-BS shall perform the operations shown in Figure 44. Note that the Timer T13 represents the time allowed for a CPE, following receipt of a REG-RSP message, to send a TFTP-CPLT message to the MR-BS, and its minimum time is specified in Table 272. In addition, the Timer T28 is the time allowed for the MR-BS to complete the transmission of channel sets; its default value is specified in Table 272.

after the TFTP- CPLT/RSP (see 7.7.19). When the MR-BS and CPE complete the TFTP-CPLT/RSP exchange, timer T30 is scheduled for the value set in CPE Registration Timer (7.7.7.3.5) IE. When T30 expires the MR-BS and CPE shall delete all information pertaining to their associations (e.g., SIDs, registered capabilities, active service-flow parameters, remaining security context), regardless of whether or not the CPE

Prior to expiration of T30, the MR-BS may attempt to verify connectivity to a CPE via periodic ranging.

is currently being served by the MR-BS.

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a) Send a DREG-CMD to CPE with Action Code = $0x05$ (see Table 115) to force CPE to reinitialize on the current operating channel. This is done if the CPE's movement is beyond the movement threshold of ± 25 m (see policy 8 in Table 234), but the CPE's movement does not result in a new backup/candidate channel list upon query of the database service.

- b) Send a DREG-CMD to the CPE with Action Code = $0x01$ and subsequently another DREG-CMD with Action Code = $0x03$ (see Table 115) to temporarily disable the CPE's transmission. This is done, to temporarily disable the CPE's transmission when a CPE's movement is within the movement threshold of ± 25 m (see Policy 8 in Table 234), but the CPE's movement does not results in a new backup/candidate channel list upon query of the database service. This avoids having to reinitialize the CPE.
	- c) For case a), T30 shall be cleared when the CPE is shutdown. For case b), the T30 shall be reset upon completion of re-registration. For case c), the T30 shall be reset upon sending the DREG-CMD to re-enable CPE.

If the SM (upon interrogating the SSA) detected that the CPE has moved, the distributed scheduling R-CPE shall request de-registration by sending a DREG-CMD message to the CPE set with the appropriate Action Code as mentioned above.

After the distributed scheduling R-CPE de-registers the CPE, the distributed scheduling R-CPE shall send Local Cell Update message (7.7.25) to the MR-BS as shown in Figure Y1. When the MR-BS receives Local Cell Update request message from the distributed scheduling R-CPE, the MR-BS shall update registration information of CPEs indicated in the message (see Figure AA1), and send Local Cell Update response to the distributed scheduling R-CPE as shown in Figure Z1.

Figure V1—CPE registration in a local cell

1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48 49 50 51 52 53 54 55 56 57 58 59 60 61 62 63 64 Once the CPE has sent a REG-REQ to the MR-BS, it shall wait for a REG-RSP to authorize it to forward traffic to the network. Figure AC1 shows the waiting procedure that shall be followed by the CPE. The MR-BS shall perform the operations shown in Figure 44. Note that the Timer T13 represents the time allowed for a CPE, following receipt of a REG-RSP message, to send a TFTP-CPLT message to the MR-BS, and its minimum time is specified in Table 272. In addition, the Timer T28 is the time allowed for the MR-BS to complete the transmission of channel sets; its default value is specified in Table 272. IEEE 802.22b CPEs are managed devices. Network entry is not considered complete until after the TFTP-CPLT/RSP (see 7.7.19). When the MR-BS and CPE complete the TFTP-CPLT/RSP exchange, timer T30 is scheduled for the value set in CPE Registration Timer (7.7.7.3.5) IE. When T30 expires the MR-BS and CPE shall delete all information pertaining to their associations (e.g., SIDs, registered capabilities, active serviceflow parameters, remaining security context), regardless of whether or not the CPE is currently being served by the MR-BS. Prior to expiration of T30, the MR-BS may attempt to verify connectivity to a CPE via periodic ranging. This can be facilitated by the MR-BS sending an unsolicited RNG-CMD message with Ranging Status field set to "Re-range & Re-register" (see Table 44). Upon receiving said RNG-CMD, the CPE shall attempt to re-range with the centralized scheduling R-CPE, as well as send a REG-REQ to the centralized scheduling R-CPE. The centralized scheduling R-CPE sends a Container message containing the received REG-REQ message to the MR-BS. Upon sending this REG-REQ to the MR-BS, the CPE should use the signaling in 9.12.2 to repopulate the MIBs used to configure these IEs and update the configuration of these IEs by reading the information. If the CPE finds out that this information has changed, it shall re-initialize itself. If the MR-BS does not receive either the RNG-REQ or the REG-REQ (with the location information) from the CPE in the allocated opportunity, the MR-BS shall wait until T30 expires before de-registering the CPE. If the CPE is currently being served by the MR-BS, the MR-BS can force the CPE to delete the pertinent information before expiration of T30 by the following: a) Send a DREG-CMD to CPE with Action Code = $0x04$ (see Table 115) to shutdown the CPE. This is done if the MR-BS detects that the CPE has moved outside the current coverage area of the MR-BS and is not able to service it. b) Send a DREG-CMD to CPE with Action Code = $0x05$ (see Table 115) to force CPE to reinitialize on the current operating channel. This is done if the CPE's movement is beyond the movement threshold of ± 25 m (see policy 8 in Table 234), but the CPE's movement does not result in a new backup/candidate channel list upon query of the database service. c) Send a DREG-CMD to the CPE with Action Code = $0x01$ and subsequently another DREG-CMD with Action Code = $0x03$ (see Table 115) to temporarily disable the CPE's transmission. This is done, to temporarily disable the CPE's transmission when a CPE's movement is within the movement threshold of ± 25 m (see Policy 8 in Table 234), but the CPE's movement does not results in a new backup/candidate channel list upon query of the database service. This avoids having to reinitialize the CPE. For case a), T30 shall be cleared when the CPE is shutdown. For case b), the T30 shall be reset upon completion of re-registration. For case c), the T30 shall be reset upon sending the DREG-CMD to re-enable CPE. If the SM (upon interrogating the SSA) detected that the CPE has moved, the MR-BS shall request de- registration by sending a DREG-CMD message to the CPE set with the appropriate Action Code as mentioned

65 above.

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7.14.3.12 MR-BS transmits channel sets to CPE

The MR-BS shall send the channel sets to the new CPE. The channel sets are described in 10.2.3. The channel sets that are sent to the initializing CPE are the backup channels and the candidate channels. The channel sets are sent in a DCD message, as described in 7.7.1 and in Table 24 to Table 26. The MR-BS shall send DCD channel information elements 11 and 12. Table 26 describes information element 12 as the backup and candidate channel list. It is a prioritized list of the channels with the backup channel set higher in priority than the candidate channel set. The two sets are identified by sending information element 11, which provides the number of the higher prioritized backup channel set. Each channel in DCD information element 12 is characterized by both the channel number.

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The distributed scheduling R-CPE shall send the channel sets to the new CPE, which is registered with the distributed scheduling R-CPE. The channel sets are described in 10.2.3. The channel sets that are sent to the initializing CPE are the backup channels and the candidate channels. The channel sets are sent in a DCD message in a DRZ, as described in 7.7.1 and in Table 24 to Table 26. The distributed scheduling R-CPE shall send DCD channel information elements 11 and 12. Table 26 describes information element 12 as the backup and candidate channel list. It is a prioritized list of the channels with the backup channel set higher in priority than the candidate channel set. The two sets are identified by sending information element 11, which provides the number of the higher prioritized backup channel set. Each channel in DCD information element 12 is characterized by both the channel number.

7.14.3.13 Establish IP connectivity

7.14.3.14 Establish time of day

7.14.3.15 Transfer operational parameters

The CPE shall download the CPE's configuration file using TFTP on its own secondary management connection as shown in Figure 47. The CPE shall use an adaptive timeout for TFTP based on binary exponential backoff (IETF RFC 1123 [B19], IETF RFC 2349 [B21]).

When the configuration file download has completed successfully, the CPE shall notify the MR-BS directly or through the R-CPE by transmitting the TFTP-CPLT message on the CPE's primary management connection. Transmissions shall continue successfully until a TFTP-RSP message is received with response "OK" from the MR-BS (see Figure 48 and Figure 49) or the CPE terminates retransmission due to retry exhaustion.

Upon sending a REG-RSP, the MR-BS shall wait for a TFTP-CPLT. If the timer T13 (defined in Table 272) expires, the MR-BS shall restart the registration process (REG-REQ/RSP) with the CPE (see Figure 48). Note that the Timer T26 refers to the time waited for TFTP-RSP. If T26 expires, then TFTP-CPLT is attempted until the maximum number of retries is exhausted. Upon the exhaustion, the CPE shall be deregistered (i.e., forced to reinitialize MAC) by sending a DREG-REQ with Action Code set to 0x05 to force itself to reattempt system access or 0x04 to shut itself down (see Figure 49)

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7.14.3.16 Establish dynamic service flows

7.14.3.17 Neighboring network discovery

61 62 63 64 65 After a CPE has registered with a WRAN MR-BS, it shall perform neighboring network discovery in order to identify other nearby WRANs and enable efficient self-coexistence, if the CPE has not already done so. The neighboring network discovery involves listening to the medium for CBP packets or MR-BS transmitted by other WRAN MR-BSs. This network discovery mechanism is described in 7.20.1.3.

7.15 Ranging

Insert the following paragraphs after the first paragraph:

An MR-WRAN system provides a further ranging, which will be peformed between CPEs and the distributed scheduling R-CPE as well as between CPEs and the centralized scheduling R-CPE for relaying.

The MR-WRAN ranging can be categorized as the following ranging operations

- a) between CPEs and MR-BS (ranging),
- b) between CPEs and MR-BS from relaying on the centralized scheduling R-CPE (relay ranging) and
- c) between CPEs and the distributed scheduling R-CPE (local ranging).

7.15.1 Downstream management

Move the paragraphs of [7.15.1](#page-130-0) into [7.15.1.1](#page-130-1)

7.15.1.1 Downstream management (MR-BS and CPE)

Insert the new subsection [7.15.1.2](#page-130-2) as follows:

7.15.1.2 Local downstream management (distributed scheduling R-CPE and S-CPE)

To maintain efficient local cell operations between the distributed scheduling R-CPE and S-CPEs, the downstream burst profile in a distributed relay zone (DRZ) is determined by the distributed scheduling R-CPE according to the quality of the signal that is received by each S-CPE. To reduce the volume of upstream traffic in a DRZ, the S-CPE monitors the CINR and compares the average value against the allowed range of operation. As shown in Figure 50, threshold levels bound this region. These thresholds parameters are specified in the DCD message transmitted by the distributed scheduling R-CPE, and shall be used by S-CPEs to determine their optimal burst profile. If the received CINR falls outside of the allowed operating region as determined by the threshold parameters, the S-CPE requests a change to a new burst profile using one of the following two methods:

- a) If the S-CPE has been granted upstream bandwidth in a DRZ (a data grant allocation to the S-CPE's Basic FID), the S-CPE shall send a RNG-REQ message in that allocation. The distributed scheduling R-CPE responds with a RNG-CMD message.
- b) If a grant is not available and the S-CPE requires a more robust burst profile on the downstream, the S-CPE shall send a RNG-REQ message in a DRZ Initial Ranging interval.

In either of these methods, the message is sent using the S-CPE's Basic FID. The coordination of message transmission and reception relative to actual change of modulation is different depending upon whether an S-CPE is transitioning to a more or less robust burst profile. Figure AD1 shows the case where an S-CPE is transitioning to a more robust profile, while Figure AE1 illustrates the transition to a less robust profile.

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Distributed Scheduling S-CPE R-CPE -DS Data at DIUC n in a DRZ-CINR too low for $D{\rm I}{\rm U}{\rm C}$ i RNG-REQ change to DIUC k Yes **Continue** Send DS monitoring Data at DS data DIUC k through DIUC_n No -DS Data at DIUC k in a DRZ-RNG-CMD ► **Monitoring** DS daa through DIUC k -DS Data at DIUC k in a DRZ-**Figure AD1—Change to a more robust profile in a local cell** Distributed Scheduling S-CPE R-CPE DS Data at DIUC n in a DRZ

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Insert the new subsection [7.15.1.3](#page-132-0) as follows:

7.15.1.3 Relay downstream management (MR-BS and S-CPE via centralized scheduling R-CPE)

Direct downstream from the MR-BS to the S-CPE may transit to relay downstream from the MR-BS to the S-CPE through the centralized scheduling R-CPE as shown in Figure AF1 when the relay downstream has a higher gain rather than the downstream, and vice versa.

Figure AF1—Transit between downstream and relay downstream

The transit from downstream to relay downstream may be performed from the request of each S-CPE. Before an S-CPE transits downstream to relay downstream, the S-CPE shall confirm the relay downstream burst profile by the following a relay downstream test procedure (see Figure AG1).

- a) The S-CPE shall detect a centralized scheduling R-CPE for relay by a CRZ initial ranging procedure.
- b) If CRZ inital ranging is successfully finished, the S-CPE requests the MR-BS to start a relay downstream test by sending a Downstream Transit Test Request (DTT-REQ, 7.7.27.1), which includes a selected centralized scheduling R-CPE's SID.
	- c) The MR-BS sends a Downstream Transit Test Response (DTT-RSP, 7.7.27.2), which indicates the start frame of a bandwidth allocation for a relay downstream test, to the S-CPE.
- d) During the allocated bandwidth, the MR-BS transmits test frames to the S-CPE by relaying on the centralized scheduling R-CPE.
- e) The S-CPE calculates relay downstream burst profile, and report the calculation result (DST-RPT, 7.7.27.3), which includes a relay downstream bust profile, to the MR-BS.
- f) Based on the relay downstream burst profile, the MR-BS decides to transit from downstream to relay downstream, and a Downstream Transmit Confirmation (DST-CFM, 7.7.27.4) is sent to the S-CPE.

Before an S-CPE transit from relay downstream to downstream, on the other hand, the S-CPE shall confirm the downstream burst profile.

- a) The S-CPE shall confirm downstream burst profile from monitoring signals such as frame preamble, FCH, DS-MAP transmitted by the MR-BS.
- b) The S-CPE reports the downstream burst profile to the MR-BS by using DST-RPT (7.7.27.3).
- c) Based on the relay downstream burst profile, the MR-BS decides to transit from relay downstream to downstream, and a DST-CFM (7.7.27.4) is sent to the S-CPE.

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— the centralized scheduling R-CPE shall send a Container message including the RNG-REQ message received from the S-CPE and the RNG-REG message by oneself to the MR-BS if the centralized scheduling R-CPE requires to change downstream burst profile —If a grant is not available for the centralized scheduling R-CPE, —the centralized scheduling R-CPE shall send the RNG-REQ message received from the S-CPE in a CRZ Initial Ranging interval to the MR-BS if the centralized scheduling R-CPE has no change of downstream burst profile or, —the centralized scheduling R-CPE shall send a Container message including the RNG-REQ message received from the S-CPE and the RNG-REG message by oneself in an Initial Ranging interval to the MR-BS if the centralized scheduling R-CPE requires to change downstream burst profile. — The MR-BS responds with a RNG-CMD message and broadcasts DCD with relay downstream burst profile.

7.15.2 Upstream management

Change the paragraph as follows:

43 44 45 Upstream ranging management consists of two procedures: initial ranging and periodic ranging. Initial ranging (see 7.14) allows a CPE joining the network to acquire correct transmission parameters, such as time offset and Tx EIRP level, so that the CPE can communicate with the BS/MR-BS or the distributed scheduling R-CPE. Initial Ranging is categorized as initial ranging between CPEs and MR-BS, relay initial ranging between CPEs and MR-BS from relaying on the centralized scheduling R-CPE, and local initial ranging between CPEs and the distributed scheduling R-CPE. The WRAN PHY specifies a ranging subchannel and a set of special pseudo-noise ranging codes. Initial ranging is performed by using initial ranging codes at initial ranging subchannel in an AZ, relay initial ranging is performed by using CRZ inital ranging codes at relay initial ranging subchannel in a CRZ, and local initial ranging is performed by DRZ initial ranging codes at local initial ranging subchannel in a DRZ. Subsets of codes shall be allocated in the UCD channel encoding for initial ranging, periodic ranging requests, and BRs so that the BS/MR-BS can determine the purpose of the received code by the subset to which the code belongs. CPEs that wish to perform one of the aforementioned operations shall select, with equal probability, one of the codes of the appropriate subset, modulate it onto the ranging subchannel, and subsequently transmit in the ranging slot selected with equal probability from the available ranging slots on the upstream subframe. A CPE shall select one Ranging Slot from all available ranging slots in the upstream frame using a uniform random process. Details on the modulation and ranging codes are specified in 9.9.2. Following initial ranging, periodic ranging allows the CPE to adjust transmission parameters so that it can maintain upstream communications with the BS/MR-BS.

The following subclauses summarize the general algorithm for initial ranging and periodic ranging.

Insert new subclause [7.15.2.1a](#page-134-0) as follows:

7.15.2.1a CDMA initial ranging and automatic adjustments (MR-BS and CPE)

A CPE that wishes to perform initial ranging with CDMA code in an AZ shall take the following steps:

- a) The CPE, after acquiring downlink synchronization and uplink transmission parameters from the MR-BS in an AZ, shall select one Ranging Slot using the random backoff. The random backoff shall use a binary truncated exponent algorithm. After selecting the Ranging Slot, the CPE shall choose a Ranging Code (from the Initial Ranging domain) using a uniform random process. The selected Ranging Code is sent to the BS/MR-BS (as a CDMA code) in the selected Ranging Slot.
- 62 63 64 65 b) The BS/MR-BS cannot tell which CPE sent the CDMA ranging request; therefore, upon successfully receiving a CDMA ranging code, the BS/MR-BS broadcasts a ranging response message (RNG-CMD) that advertises the received ranging code as well as the ranging slot (OFDMA sym-

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bol number, etc.) where the CDMA ranging code has been identified. This information is used by the CPE that sent the CDMA ranging code to identify the ranging response message that corresponds to its ranging request. The ranging response message contains all the needed adjustments

- (e.g., time, EIRP, and possibly frequency corrections) and a status notification. c) Upon receiving a RNG-CMD message with the "Continue" status, the CPE shall continue the ranging process as done on the first entry (using random selection rather than random backoff) with ranging codes randomly chosen from the initial ranging domain sent on the ranging slots. d) When the BS/MR-BS receives an initial-ranging CDMA code that requires no corrections, the BS/ MR-BS shall provide BW allocation for the CPE using the CDMA_Allocation_IE to send an RNG-REQ message. Sending the RNG-CMD message with status "Success" is optional. e) The initial ranging process is over after receiving RNG-CMD message, which includes a valid SID (following a RNG-REQ transmission on a CDMA Allocation IE). If this RNG-CMD message includes a "continue" indication, the ranging process should be continued using the ranging mechanism. f) The timeout required for the CPE to wait for RNG-CMD, following or not following a CDMA Allocation IE, is defined by the timer T3. *Insert new subclause [7.15.2.1b](#page-135-0) as follows:* **7.15.2.1b CDMA local initial ranging and automatic adjustments (distributed scheduling R-CPE and S-CPE)** A CPE is acquiring local downlink synchronization and local uplink transmission parameters from distributed scheduling R-CPE only. A CPE that wishes to perform local initial ranging with CDMA code in a DRZ shall take the following steps: a) The CPE, after acquiring downlink synchronization and uplink transmission parameters from the distributed scheduling R-CPE, shall select one Ranging Slot in a DRZ (DRZ Ranging Slot) using
	- the random backoff. The random backoff shall use a binary truncated exponent algorithm. After selecting the DRZ Ranging Slot, the CPE shall choose a DRZ Ranging Code (from the DRZ Initial Ranging domain) using a uniform random process. The selected DRZ Ranging Code is sent to the distributed scheduling R-CPE (as a CDMA code) in the selected DRZ Ranging Slot.
- b) The distributed scheduling R-CPE cannot tell which CPE sent the CDMA ranging request; therefore, upon successfully receiving a DRZ ranging code, the distributed scheduling R-CPE broadcasts a RNG-CMD message that advertises the received DRZ ranging code as well as the DRZ ranging slot (OFDMA symbol number, etc.) where the DRZ ranging code has been identified. This information is used by the CPE that sent the DRZ ranging code to identify the RNG-CMD message that corresponds to its ranging request. The RNG-CMD message contains all the needed adjustments (e.g., time, EIRP, and possibly frequency corrections) and a status notification.
- c) Upon receiving a RNG-CMD message with the "Continue" status, the CPE shall continue the ranging process as done on the first entry (using random selection rather than random backoff) with ranging codes randomly chosen from the DRZ initial ranging domain sent on the DRZ Ranging Slots.
- d) When the distributed scheduling R-CPE receives an initial-ranging CDMA code that requires no corrections, the distributed scheduling R-CPE shall provide BW allocation in a DRZ for the CPE using the CDMA Allocation IE to send an RNG-REQ message. Sending the RNG-CMD message with status "Success" is optional.
- 62 63 64 65 e) The DRZ initial ranging process is over after receiving RNG-CMD message, which includes a valid SID (following a RNG-REQ transmission on a CDMA Allocation IE). The distributed scheduling R-CPE shall choose one SID into a Local SID Group for the CPE's SID. If this RNG-CMD

7.15.2.2 CDMA Periodic ranging and automatic adjustments

Insert new subclause [7.15.2.2a](#page-137-0) as follows:

7.15.2.2aCDMA periodic ranging and automatic adjustments (MR-BS and CPE)

The following summarizes the general algorithm for CDMA periodic ranging between the BS/MR-BS and the CPE:

- a) The CPE shall choose randomly a Ranging Slot (with random selection with equal probability from available Ranging Slots in a single frame) at the time in an AZ to perform the ranging, and then it chooses randomly a Periodic Ranging Code and sends it to the BS/MR-BS (as a CDMA code).
- b) If the CPE does not receive a response, the CPE may send a new CDMA code at the next appropriate ranging transmission opportunity at one step higher EIRP level.
- c) The BS/MR-BS cannot tell which CPE sent the CDMA ranging request; therefore, upon successfully receiving a CDMA periodic ranging code, the BS broadcasts a ranging response (RNG-CMD) message that advertises the received periodic ranging code as well as the ranging slot (OFDMA symbol number, etc.) where the CDMA periodic ranging code has been identified. This information is used by the CPE that sent the CDMA periodic ranging code to identify the ranging response message that corresponds to its ranging request. The ranging response message contains all the needed adjustments (e.g., time, EIRP, and possibly frequency corrections) and a status notification.
- d) Upon receiving a RNG-CMD message with the "Continue" status, the CPE shall continue the ranging process with further periodic ranging codes randomly chosen. Upon receiving an RNG-CMD message with success status, the CPE shall restart timer T4 with the appropriate value depending whether the CPE is fixed or portable (see Table 273).
- e) The BS/MR-BS may send an unsolicited RNG-CMD as a response to a CDMA-based bandwidth-request or any other data transmission from the CPE.
	- f) Upon timeout of the CPE internal T4 timer, the CPE shall perform Periodic Ranging according to the procedure above.
	- g) When the CPE receives an unsolicited RNG-CMD message, it shall reset the periodic ranging timer and adjust the parameters (timing, EIRP, etc.) as notified in the RNG-CMD message.

Insert new subclause [7.15.2.2b](#page-137-1) as follows:

7.15.2.2b CDMA periodic ranging and automatic adjustments (distributed scheduling R-CPE and CPE)

The following summarizes the general algorithm for CDMA periodic ranging between the distributed scheduling R-CPE and the CPE in a local cell:

- a) a)The CPE shall choose randomly a Ranging Slot (with random selection with equal probability from available Ranging Slots in a single frame) at the time in a DRZ to perform the ranging, and then it chooses randomly a DRZ Periodic Ranging Code and sends it to the distributed scheduling R-CPE (as a CDMA code).
	- b) If the CPE does not receive a response, the CPE may send a new CDMA code at the next appropriate ranging transmission opportunity at one step higher EIRP level.
- 58 59 60 61 62 63 64 65 c) The distributed scheduling R-CPE cannot tell which CPE sent the CDMA ranging request; therefore, upon successfully receiving a CDMA periodic ranging code, the distributed scheduling R-CPE broadcasts a ranging response (RNG-CMD) message that advertises the received DRZ periodic ranging code as well as the DRZ ranging slot (OFDMA symbol number, etc.) where the CDMA periodic ranging code has been identified. This information is used by the CPE that sent the CDMA periodic ranging code to identify the ranging response message that corresponds to its ranging

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possibly frequency corrections) and a status notification.

whether the CPE is fixed or portable (see Table 273).

the procedure above.

Insert new subclause [7.15.2.2c](#page-138-0) as follows:

request. The ranging response message contains all the needed adjustments (e.g., time, EIRP, and

d) Upon receiving a RNG-CMD message with the "Continue" status, the CPE shall continue the ranging process with further periodic ranging codes randomly chosen. Upon receiving an RNG-CMD message with success status, the CPE shall restart timer T4 with the appropriate value depending

e) The distributed scheduling R-CPE may send an unsolicited RNG-CMD as a response to a

f) Upon timeout of the CPE internal T4 timer, the CPE shall perform Periodic Ranging according to

g) When the CPE receives an unsolicited RNG-CMD message, it shall reset the periodic ranging timer and adjust the parameters (timing, EIRP, etc.) as notified in the RNG-CMD message.

CDMA-based bandwidth-request or any other data transmission from the CPE.

- 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48 **7.15.2.2c CDMA periodic ranging and automatic adjustments (centralized scheduling R-CPE and CPE)** The following summarizes the general algorithm for CDMA periodic ranging between the centralized scheduling R-CPE and the CPE: a) The CPE shall choose randomly a Ranging Slot (with random selection with equal probability from available Ranging Slots in a single frame) at the time in a CRZ to perform the ranging, and then it chooses randomly a CRZ Periodic Ranging Code and sends it to the centralized scheduling R-CPE (as a CDMA code). b) If the CPE does not receive a response, the CPE may send a new CDMA code at the next appropriate ranging transmission opportunity at one step higher EIRP level. c) The centralized scheduling R-CPE cannot tell which CPE sent the CDMA ranging request; therefore, upon successfully receiving a CDMA periodic ranging code, the centralized scheduling R-CPE broadcasts a ranging response (RNG-CMD) message that advertises the received CRZ periodic ranging code as well as the CRZ ranging slot (OFDMA symbol number, etc.) where the CDMA periodic ranging code has been identified. This information is used by the CPE that sent the CDMA periodic ranging code to identify the ranging response message that corresponds to its ranging request. The ranging response message contains all the needed adjustments (e.g., time, EIRP, and possibly frequency corrections) and a status notification. For the transmission of RNG-CMD to the CPE, a centralized scheduling R-CPE shall request bandwidth to a BS/MR-BS by using an Extended Bandwidth Request Subheader (7.6.1.2.1a).
	- d) Upon receiving a RNG-CMD message with the "Continue" status, the CPE shall continue the ranging process with further periodic ranging codes randomly chosen. Upon receiving an RNG-CMD message with success status, the CPE shall restart timer T4 with the appropriate value depending whether the CPE is fixed or portable (see Table 273).
		- e) The centralized scheduling R-CPE may send an unsolicited RNG-CMD as a response to a CDMA-based bandwidth-request or any other data transmission from the CPE.
		- f) Upon timeout of the CPE internal T4 timer, the CPE shall perform Periodic Ranging according to the procedure above.
		- g) When the CPE receives an unsolicited RNG-CMD message, it shall reset the periodic ranging timer and adjust the parameters (timing, EIRP, etc.) as notified in the RNG-CMD message.
	- **7.16 Channel descriptor management**
	- 64 65 *Change the paragraph as follows:*

1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 As previously presented, channel descriptor messages (i.e., DCD and UCD) are broadcast by the BS/MR-BS to all associated CPEs at periodic intervals as well as broadcast by the distributed scheduling R-CPE to the associated CPEs in its local cell at periodic interval. Among other things, these channel descriptors define burst profiles, which are used by US-MAP and DS-MAP messages for allocating upstream and downstream transmissions, respectively. Once broadcast by the BS/MR-BS or the distributed scheduling R-CPE and received by its associated CPEs, a given channel descriptor shall remain valid until a new channel descriptor message with a different value for the Configuration Change Count field, is again broadcast by the BS/MR-BS or or the distributed scheduling R-CPE, respectively. When this happens, this new channel descriptor shall overwrite all the information of the previous descriptor. When the distributed scheduling R-CPE receives a new downstream channel descriptor for channel switching from the BS/MR-BS, the distributed scheduling R-CPE shall immediately broadcast the new downstream channel descriptor with the same information of channel switching (i.e., channel action, action mode, and action frame number) to the associated CPEs in the local cell in order to the operating channel in the local cell be changed to the same channel of the BS/MR-BS's cell at the same time.

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19 20 21 22 23 24 25 26 27 28 29 30 Once channel descriptors are known to all CPEs in an IEEE 802.22b BS/MR-BS's cell, the BS/MR-BS shall set the UCD/DCD Count value in an AZ, contained in US-MAP and DS-MAP messages, equal to the Configuration Change Count of the desired channel descriptor. Once channel descriptors are known to all CPEs in the distributed scheduling R-CPE's local cell, the distributed scheduling R-CPE shall set the UCD/DCD Count value in a DRZ, contained in US-MAP and DS-MAP messages, equal to the Configuration Change Count of the desired channel descriptor. This way, a BS/MR-BS and a distributed scheduling R-CPE can easily indicate to its associated CPEs which burst profile is to be used for a given allocation, and hence provide high flexibility to the BS/MR-BS or the distributed scheduling R-CPE in controlling which burst profile to use at any given time by simply changing the UCD/DCD Count value.

Finally, note that the Configuration Change Count shall be incremented by 1 modulo 256 for every new migration of channel descriptor. After issuing a DS-MAP or US-MAP message with the Configuration Change Count equal to that of the new generation, the old channel descriptor ceases to exist and the BS/MR-BS and the distributed scheduling R-CPE shall not refer to it anymore. When migrating from one generation to the next, the BS/MR-BS and the distributed scheduling R-CPE shall schedule the transmissions of the UCD and DCD messages in such a way that each CPE has the possibility to successfully hear it at least once.

7.18 QoS

7.18.9.3 Dynamic Service Addition

7.18.9.3.1 CPE-initiated DSA

Insert the new subsection [7.18.9.3.1.1](#page-139-0) as follows:

7.18.9.3.1.1 MR-BS and R-CPE behaviour during CPE-initiated DSA

When a DSA-REQ message is sent from a CPE, the centralized scheduling R-CPE and the MR-BS may deal with the message in the following way:

- The centralized scheduling R-CPE may add the acceptable QoS parameter set to the DSA-REQ if it cannot support the requested QoS parameter set. It then sends the DSA-REQ to the MR-BS using the primary management CID of the CPE.
- 61 62 63 64 65 — The centralized scheduling R-CPE may include Per-RS QoS TLV in the DSA-REQ to the MR-BS. The Per-RS QoS TLV in this case represents the maximum latency at the centralized scheduling R-CPE to relay the requested QoS parameter set. If the MR-BS receives Per-RS QoS TLV, the MR-BS shall consider the value in Per-RS QoS TLV and ones in the requested QoS parameter set.

6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48 49 50 51 52 53 54 55 56 57 58 59 60 61 62 63 64 65 control algorithm is out of scope of this standard. — If the service flow parameters are changed, the MR-BS shall send a DSC-REQ to the centralized scheduling R-CPE before sending DSA-RSP to the SS. **7.18.9.3.2 BS-initiated DSA** *Insert the new subsection [7.18.9.3.2.1](#page-140-0) as follows:* **7.18.9.3.2.1 MR-BS and R-CPE behaviour during MR-BS-initiated DSA** When an MR-BS initiates a DSA-REQ message to a CPE via a centralized scheduling R-CPE, the centralized scheduling R-CPE and the MR-BS may deal with the message in the following way. If the service flow parameters are changed, the MR-BS shall send a DSC-REQ to the centralized scheduling R-CPE before sending the DSA-REQ to the CPE in the same manner as defined above. — The MR-BS may include Per-RS QoS TLV in the DSA-REQ to centralized scheduling R-CPE. If the centralized scheduling R-CPE receives Per-RS QoS TLV, the centralized scheduling R-CPE shall use values in Per-RS QoS TLV instead of the ones in the service flow parameters. — When the centralized scheduling R-CPE can support the requested QoS parameter set, it sends the DSA-REQ to the CPE using the primary management CID of the CPE. — When the centralized scheduling R-CPE cannot support the requested QoS parameter set in the DSA-REQ, it sends DSA-RSP with CC set to reject-RS-not-supported-parameter-value to the MR-BS indicating that it can support the requested QoS parameter set. The DSA-RSP may contain the acceptable QoS parameter set the centralized scheduling R-CPE can support. — The centralized scheduling R-CPE may get the updated SF parameters and confirmation code from DSA-RSP and DSA-ACK sent from the CPE and the MR-BS, respectively. **7.18.9.4 Dynamic Service Change 7.18.9.4.1 CPE-initiated DSC** Insert the new subsection [7.18.9.4.1.1](#page-140-1) as follows: **7.18.9.4.1.1 MR-BS and centralized scheduling R-CPE behaviour during CPE-initiated DSC** When a DSC-REQ message is sent from a CPE, a centralized scheduling R-CPE and the MR-BS may deal with the message in the following way: — The centralized scheduling R-CPE may add the acceptable QoS parameter set to the DSC-REQ if it cannot support the requested QoS parameter set. It then sends the DSC-REQ to the MR-BS using the primary management CID of the CPE. — The centralized scheduling R-CPE may include Per-RS QoS TLV in the DSC-REQ to the MR-BS. The Per-RS QoS TLV in this case represents the maximum latency at the centralized scheduling R-CPE to relay the requested QoS parameter set. If the MR-BS receives Per-RS QoS TLV, the MR-BS shall consider the value in Per-RS QoS TLV and ones in the requested QoS parameter set. — The centralized scheduling R-CPE may get the updated SF parameters and confirmation code from DSC-RSP and DSC-ACK sent from the MR-BS and the CPE, respectively.

— The centralized scheduling R-CPE may get the updated SF parameters and confirmation code from

— Upon receiving the DSA-REQ from the CPE via the centralized scheduling R-CPE, the MR-BS sends back a response to the CPE in the same way defined for non-relay systems. The admission

DSA-RSP and DSA-ACK sent from the MR-BS and the CPE, respectively.

- Copyright © 20XX IEEE. All rights reserved. This is an unapproved IEEE Standards draft, subject to change. scheduling R-CPE before sending the DSC-REQ to the CPE. DSC-REQ to the CPE using the primary management CID of the CPE. acceptable QoS parameter set the centralized scheduling R-CPE can support. DSC-RSP and DSC-ACK sent from the CPE and the MR-BS, respectively. **7.18.9.5 Dynamic Service Deletion 7.18.9.5.1 CPE-initiated DSD** *Insert the new subsection [7.18.9.5.1.1](#page-141-1) as follows:* **DSD** DSD-RSP, it deletes the service flow information and relays it to the CPE. **7.18.9.5.2 BS-initiated DSD** *Insert the new subsection [7.18.9.5.2.1](#page-141-2) as follows:* **ated DSD**
- **ated DSC** When an MR-BS initiates a DSC-REQ message to a CPE via a centralized scheduling R-CPE, the centralized

7.18.9.4.2.1 MR-BS and centralized scheduling R-CPE behaviour during MR-BS-initi-

- scheduling and the MR-BS may deal with the message in the following way:
- If the service flow parameters are changed, the MR-BS shall send a DSC-REQ to the centralized
- The MR-BS may include Per-RS QoS TLV in DSC-REQ to centralized scheduling R-CPE. If the centralized scheduling R-CPE receives Per-RS QoS TLV, the centralized scheduling R-CPE shall use values in Per-RS QoS TLV instead of the ones in the service flow parameters.
	- When the centralized scheduling R-CPE can support the requested QoS parameter set, it sends the
- When the centralized scheduling R-CPE cannot support the requested QoS parameter set in the DSC-REQ, it sends DSC-RSP with CC set to reject-RS-not-supported-parameter-value to the MR-BS indicating that it cannot support the requested QoS parameter set. The DSC-RSP may contain the
- The centralized scheduling R-CPE may get the updated SF parameters and confirmation code from

7.18.9.4.2 BS-initiated DSC

Insert the new subsection [7.18.9.4.2.1](#page-141-0) as follows:

7.18.9.5.1.1 MR-BS and centralized scheduling R-CPE behaviour during CPE-initiated

When a DSD-REQ message is sent from a CPE, the centralized scheduling R-CPE relays it to the MR-BS using the primary management CID of the CPE. After processing the DSD-REQ, the MR-BS replies with a DSD-RSP using the CPE primary management CID. When the centralized scheduling R-CPE receives the

7.18.9.5.2.1 MR-BS and centralized scheduling R-CPE behaviour during MR-BS-initi-

 When an MR-BS initiates a DSD-REQ message to a CPE via a centralized scheduling R-CPE using the primary management CID of the CPE, the centralized scheduling R-CPE relays it to the CPE using the primary

— Upon receiving the DSC-REQ from the CPE via the centralized scheduling R-CPE, the MR-BS sends back a response to the CPE in the same way defined for non-relay systems. The admission

— If the service flow parameters are changed, the MR-BS shall send a DSC-REQ to the centralized

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control algorithm is out of scope of this standard.

scheduling R-CPE before sending DSC-RSP to the CPE.

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management CID of the CPE. When the centralized scheduling R-CPE receives a DSD-RSP sent from the CPE, it deletes the service flow information and relays it to the MR-BS.

7.19 Incumbent protection

Insert the following paragraph after the second paragraph of [7.19](#page-142-0):

An IEEE 802.22b system shall support incumbent protection on relay connection between MR-BS and CPEs. The incumbent protection procedures for the case that the direct connection exists between MR-BS and CPEs shall follow the operations described from 7.19.1 to 7.19. 6. The measurement management and notification procedures of incumbent protection for a relay network are shown in [7.19.2.1](#page-142-1) and [7.19.4.2,](#page-143-1) respectively.

7.19.2.1 Measurements management for a relay network

Measurement management is to perform a wide range of measurement activities, either related to incumbent detection or to self-coexistence.

In an IEEE 802.22b network, measurement requests can be performed from the MR-BS.

When a centralized scheduling R-CPE receives BLM-REQ from the MR-BS, it shall send it to the destination CPE. The CPE shall report back to the MR-BS on relaying the centralized scheduling R-CPE with a BLM-REP message that contains measurement results. Then, the MR-BS sends the corresponding acknowledgment (BLM-ACK) on the next downstream opportunity following the reception of the measurement report (see [Figure AH1](#page-143-0)).

 When a distributed scheduling R-CPE receives BLM-REQ from the MR-BS, it shall perform measurement within the local cell by sending BLM-REQ to the CPE. The CPE shall report back to the MR-BS on relaying the distributed scheduling R-CPE with the BLM-REP message that contains measurement results. Then, the BS/MR-BS sends the corresponding acknowledgment (BLM-ACK) on the next downstream opportunity following the reception of the measurement report (see [Figure AH1](#page-143-0)).

Figure AH1—Measurement message flow between MR-BS and CPE through R-CPE

7.19.4.2 Measurement report and notification for a relay network

The CPE may have an upstream bandwidth allocation in a CRZ to send the UCS notification to the centralized scheduling R-CPE, or may have an upstream bandwidth allocation in a DRZ to send UCS notification to the distributed scheduling R-CPE. Those R-CPEs shall relay UCS notification transmitted by the CPE to the MR-BS in an AZ by using one of UCS notifications that are upstream bandwidth allocation, opportunistic UCS notification, and CDMA based UCS notification.

The CPE may use an opportunistic UCS notification interval in a CRZ to send the UCS notification to the centralized scheduling R-CPE, or may use an opportunistic UCS notification interval in a DRZ to send UCS notification to the distributed scheduling R-CPE. Those R-CPEs shall relay UCS notification transmitted by the CPE to the MR-BS in an AZ by using one of UCS notifications that are upstream bandwidth allocation, opportunistic UCS notification, and CDMA based UCS notification.

23 24 25 26 27 28 29 30 31 32 33 34 Upon reception of UCS notification codes from CPEs, a centralized scheduling R-CPE shall relay the UCS notification codes to the MR-BS. The MR-BS does not respond with an allocation on the CPE's SID and Basic FID since it is not yet known at this time. Instead, it broadcasts a CDMA_Allocation_IE, which specifies the code and allocation in a CRZ that was used by the CPE. This allows the CPE to determine whether it has been given an allocation by matching the CDMA code that the used for the CDMA UCS notification message and the code broadcast by the BS. The CPE shall use the allocation to transmit a MAC PDU to the centralized scheduling R-CPE with the UCS field in the MAC header properly set. The centralized scheduling R-CPE shall notify the UCS notification to the MR-BS by using any possible ways of UCS notification (7.19.4.1.2.1, 7.19.4.1.2.2).

36 37 38 39 40 41 42 43 44 45 46 Upon reception of UCS notification codes, a distributed scheduling R-CPE does not respond with an allocation on the CPE's SID and Basic FID since it is not yet known at that time. Instead, it broadcasts a CDMA_Allocation_IE, which specifies the code that was used by the CPE. This allows the CPE to determine whether it has been given an allocation by matching the CDMA code that the used for the CDMA UCS notification message and the code broadcast by the distributed scheduling R-CPE. The CPE shall use the allocation to transmit a MAC PDU with the UCS field in the MAC header properly set. The distributed scheduling R-CPE shall notify the UCS notification to the MR-BS by using any possible ways of UCS notification (7.19.4.1.2.1, 7.19.4.1.2.2).

7.20 Self-coexistence

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Change the last paragraph as follows:

54 55 56 57 58 59 60 61 62 63 64 65 The Coexistence Beacon protocol (CBP) is the transport mechanism for the coexistence elements supported in this standard and CBP packets can be transmitted over-the-air or through the backhaul. The BSs and CPEs shall be capable of transmitting and receiving CBP packets over-the-air as specified in 9.5. In order to implement eventual coexistence mechanism over the backhaul, the CBP information from IEEE 802.22 base stations shall be encapsulated in IP packets for transport over the backhaul. A WRAN runs in normal mode by default and transits to self-coexistence mode when the WRAN can detect and decode an SCH or a CBP burst from an adjacent WRAN cell on PHY Mode 1. A WRAN runs in normal mode by default and transits to self-coexistence mode when the WRAN can detect and decode an Extended Frame Control Header or a CBP burst from an adjacent WRAN cell on PHY Mode 2.
7.20.1 Coexistence Beacon Protocol (CBP)

7.20.1.1 CBP packet structure (PHY Mode 1)

Change the first sentence of the first paragraph as follows:

The structure of a CBP packet (i.e., CBP PHY PDU) for PHY Mode 1 is shown in Figure 100.

Insert new subclause [7.20.1.1a](#page-144-0) as follows:

7.20.1.1a CBP packet structure (PHY Mode 2)

The structure of a CBP packet (i.e., CBP PHY PDU) for PHY Mode 2 is shown in [Figure AI1.](#page-144-1) The burst starts with a CBP preamble that shall be common across all 802.22b networks (see 9.4.1.1), and that shall be different from the frame preamble. After the CBP preamble, the CBP MAC PDU as described in Table 8 shall be transmitted. The CBP MAC PDU shall be two OFDM symbols long.

Figure AI1—Structure of a CBP packet

By including the Extended Frame Control Header (which contains information about the 802.22b cell) as part of the beacon MAC header, the transmitting CPE or MR-BS conveys necessary information to allow neighboring network discovery and coordination of quiet periods and SCWs. Including the Extended Frame Control Header is a way to advertise the schedule of QPs and SCWs to CPEs in other neighboring cells.

56 57 58 The Extended Frame Control Header information is needed in situations where WRANs are operating in different channels as well as when they are operating co-channel or adjacent channels. In the first case, the Extended Frame Control Header information obtained through detecting and demodulation the Extended Frame Control Header or through reception of the CBPs allows other WRANs to discover the schedule of QPs, which can be used for out-of-band sensing. In case WRANs are operating co-channel or on adjacent channels, the Extended Frame Control Header, received through the CBPs, will signal the schedule of QPs and SCWs in addition to containing other IEs that can be used to signal frame allocations, when needed.

59 60 61 For communication using CBP over the backhaul, the CBP MAC PDU (see Figure 100) shall be encapsulated into an IP packet.

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64 65 The MR-BS controls access to the medium within the SCW. The MR-BS shall decide which CPEs transmit CBP packets in each scheduled active UIUC=0.

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7.20.2 CBP-based inter-BS communication

7.20.3 Mechanism for inter-BS self-coexistence

Insert new subclause [7.20.4](#page-145-0) as follows:

7.20.4 Self-coexistence for a relay network

Self-coexistence in 802.22b networks shall follow the mechanisms described in [7.20.1,](#page-144-2) [7.20.2,](#page-145-1) and [7.20.3](#page-145-2), which will be performed by the negotiation of the MR-BS and the neighboring MR-BSs.

For self-coexistence in 802.22b networks, the SCW shall be synchronized at all CPEs within a 802.22b network. For synchronizing SCW, an MR-BS shall transmit SCH in PHY Mode 1 or Extended Frame Control Header in PHY Mode 2. When CPEs receives SCH or Extended Frame Control Header from the MR-BS, they synchronize the SCW within a 802.22b network. When a distributed scheduling R-CPE receives the SCW schedule information from the MR-BS, it shall arrange the SCW schedule within a local cell by sending the same information of SCH or Extended Frame Control Header received from the MR-BS to the CPEs in a local cell.

7.20.4.1 Mechanism for inter-MR-BS self-coexistence on a relay network

The self-coexistence operations among IEEE 802.22b WRAN cells shall follow the top-level procedure illustrated in Figure 101 and described as follows:

- 1) The MR-BS of an IEEE 802.22b WRAN cell is powered on.
- 2) The MR-BS performs network discovery, which includes discovering
- TV channel occupancies of the neighboring IEEE 802.22b WRAN cells
- Self-coexistence window (SCW) reservations of the neighboring IEEE 802.22b WRAN cells
- Frame reservation patterns of the neighboring IEEE 802.22b WRAN cells on specific channels (this information can be obtained from the received CBP packets)
- 3) The MR-BS performs channel acquisition based on the Spectrum Etiquette algorithm (as described in 7.20.3.1).
- 4) If the MR-BS successfully acquires a channel, it goes to the normal mode of data service operations on the acquired channel [as described in step 5) below]. If the MR-BS fails to acquire any empty channel, it selects a channel occupied by one or more other WRAN cells and identifies whether the potential interference comes directly from the other MR-BSs or from the CPEs belonging to the other WRAN cells, or both. If it comes only from the other MR-BSs, the new MR-BS initiates the DS/US Split adjustment mechanism [i.e., skips step 5) and goes to step 6)]. If the potential interference comes from the CPEs, it performs the Inter-WRAN On-demand Frame Contention operations on the selected channel by accessing a contention-based SCW (see 7.20.1.2) [i.e., skips step 5) and step 6) and goes to step 7)]. Note that since the new MR-BS arriving on the channel does not have a frame for itself yet, it cannot involve its CPEs in this initial contention process. Only CBP bursts transmitted directly from the new MR-BS will be able to support the frame contention process in this initial phase. As a result, the process may go initially to step 6) but then move to step 7) when the CPEs belonging to the new WRAN cell start to operate and report potential interference through their CBP bursts.
- 57 58 59 60 61 62 63 64 65 5) The MR-BS enters the normal mode of data service operations (see 7.3). During the normal service operations, the MR-BS may receive external demands (received from other WRAN cells) for sharing its occupied data frames on the operating channel. When this occurs and when the MR-BS cannot find another empty channel for its operation through the Spectrum Etiquette algorithm, the MR-BS performs the Inter-WRAN On-demand Frame Contention operations on its operating channel [as described in step 6)]. If an empty channel is found, then the MR-BS moves its cell to this new channel and enters the normal mode of data service operations (see 7.3).

- 6) The MR-BS performs the DS/US Split adjustment mechanism using the relevant parameter exchange carried by the SCH or Extended Frame Control Header (see Table B1) and/or by the CBP burst received directly from the other MR-BSs. Once it has acquired information on the Current DS/US Split, Claimed DS/US Split and the DS/US Change Offset, it applies the same basic algorithm as used for Quiet Period Scheduling described in Table 184 and transmits its updated parameters to the other MR-BSs so that they do the same and converge towards a common DS/US Split, which will vary depending on the compound traffic requirements for the MR-BSs involved. The adjustment of the DS/US Split through this distributed negotiation process, based on the fact that all MR-BSs have their frames aligned (see 9.10), will allow the concurrent use of the same frames by these MR-BSs while avoiding interference caused by a MR-BS that would be still transmitting while the other MR-BSs have started their upstream subframe and try to receive signals from their CPEs. Note that this will cover the cases where MR-BSs would interfere with each other even though there is no CPE being interfered (i.e., no CPE in the overlap area). There may also be cases where CPEs will receive interference from various MR-BSs while these MR-BSs do not interfere with each other as a result of clever MR-BS antenna installation that will block the signal path between the MR-BSs. The normal case will however be when both MR-BSs and CPEs are interfered with. For these two latter cases, step 7) will be needed to distribute the frames to the various MR-BSs and, since there would not be concurrent use of these frames, there is then no longer a need to synchronize the DS/US split in these cases.
	- 7) The MR-BS performs the On-demand Frame Contention operations with a neighboring WRAN cell on the selected channel, and then goes to the self-coexistence mode of data services operations (as described in step 8). A neighboring WRAN cell can contend for some of the frames used by the current MR-BS as long as it occupies a number of frames that is larger that the minimum stated in variable Frame Contention Min (see Table 274). The required message flow and the On-Demand Frame Contention Protocol are described in 7.20.3.2.
	- 8) The MR-BS enters the self-coexistence mode of data services operations (see 7.3). During the selfcoexistence mode of data service operations, the MR-BS may receive either internal demands (received from the inside of the MR-BS's own cell) for additional spectrum resources, or external demands (received from other WRAN cells) for sharing its occupied frames on the operating channel. When either of these events occurs, the MR-BS re-initiates the spectrum acquisition process starting from step 3) (Spectrum Etiquette for channel acquisition).

7.20.4.2 CBP-based Neighboring Network Discovery

During network entry and initialization and before any data transmission takes place, the MR-BS and CPE shall perform a network discovery procedure by scanning the wireless medium for CBP packets, SCH, FCH , or DRZ-FCH. This discovery procedure is part of the MR-BS and CPE initialization procedures described in 7.14.

48 49 50 51 52 53 54 55 56 57 During normal operation, the MR-BS and CPEs can discover other nearby IEEE 802.22b cells by listening to the medium on the look out for CBP packets from other cells and, possibly, SCH, FCH or DRZ-FCH on different channels. This can be accomplished through the scheduling of the Coexistence UIUC = 1 for passive mode SCW. If a CBP packet, SCH, or FCH is received by the CPE, which is managed by the MR-BS, it shall package that information and transport it to its MR-BS (see Table 172). If a CBP packet or DRZ-FCH is received by the CPE, which is managed by the distributed scheduling R-CPE, it shall package that information and transport it to its distributed scheduling R-CPE.

7.20.4.2.1 Discovery with SCW

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61 62 63 64 65 The MR- BS can discover other WRAN cells by scheduling SCWs in passive mode, during which, it may request one or more of its CPEs to listen to the current operating channel to look for CBP packets from other WRANs or to listen to other channels for CBP packets, SCH, FCH or DRZ-FCH transmissions from other MR-BSs or CPEs associated with other MR-BSs.

7.21 Quiet periods and sensing

7.21.1 Two-stage sensing mechanism and quiet period management

7.21.2 Synchronization of overlapping quiet periods

Change the paragraph as follows:

Hence, BSs shall synchronize their quiet periods with other nearby BSs/MR-BSs. This is done using the fields available in the SCH (see Table 1) or Extended Frame Control Header (see Table B1) that are used to schedule quiet periods for intra-frame (see 7.21.1.1) and inter-frame sensing (see 7.21.1.2), and which are also carried in CBP packets (see 7.6.1.3.1). The BS/MR-BS shall be responsible for setting these fields whenever transmitting a SCH or an Extended Frame Control Header. These QP scheduling fields are sent in the following three sets of parameters in a self-coexistence situation:

7.21.2.1 Intra-frame quiet period synchronization

Change the paragraph as follows:

24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 The "current" set of intra-frame quiet period parameters is used by the BS/MR-BS to indicate to its CPEs the quiet periods that are currently scheduled. Before becoming "current," this set of QP scheduling parameters has to be confirmed by all coexisting WRAN cells through the CBP mechanism following a negotiation among these WRAN cells. The "claimed" set of intra-frame quiet period parameters is used by each BS/MR-BS to announce its new scheduling requirement for quiet periods considering the performance of the sensing techniques used by its CPEs, i.e., the sensing time needed to meet the required sensing threshold. This "claimed" set is broadcast by the SCH or the Extended Frame Control Header and retransmitted to the other coexisting WRAN cells by the CBP mechanism so that negotiation can take place to arrive at a common quiet period schedule that meets the maximum QP requirement while minimizing the overhead by reducing the non-concurrent quiet periods as much as possible. This "claimed" quiet period schedule, once it has become common to all coexisting WRAN cells can then be scheduled to become the "current" quiet period parameter set after sufficient time is given for the negotiation to cover for inter-cell propagation.

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40 41 42 43 44 45 46 47 48 49 50 51 52 Each BS/MR-BS sends its claim to other coexisting BSs/MR-BSs through the SCH or the Extended Frame Control Header, which is then carried by the CBP mechanism. Each BS/MR-BS that receives a new "claim" shall compare it to its own claim and either replace the incoming claim by its larger claim for the QP repetition rate (i.e., number of 1's in the bitmap/cycle length) and/or QP duration or keep it as is if its own claim is smaller. If its own claim is larger and the updating results in a new claim that is larger than the "current" QP repetition rate and/or duration, the BS shall reset the Claimed Intra-frame Quiet Period Offset to the minimum number of frames required to make sure that all coexisting BSs have received the claim (e.g., 2 hops, that is 2 superframes or frames) before sending it in the SCH and relaying it through the CBP mechanism. If the new claim is smaller than the "current" scheduling, the Claimed QP Offset parameter is repeater unchanged and the incoming scheduling parameters are also repeated unchanged.

7.21.2.2 Inter-frame Quiet Period Synchronization

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Change the paragraph as follows:

58 59 60 61 62 63 64 65 The BS/MR-BS that receives information about other collocated IEEE 802.22 cells (either directly or reported through CPEs) shall synchronize with all quiet periods scheduled by the other cells for the inter-frame QP schedule. To synchronize inter-frame sensing quiet periods, the BS uses the information contained in the SCH or the Extended Frame Control Header, but in addition to that, the BS shall apply a random mechanism to decide whether to change its quiet period schedule. This mechanism will considerably mitigate the ping-pong effect and it is based on the following rule:

 For example, consider that BS 1 received information on the SCH or the Extended Frame Control Header transmitted by a collocated BS 2. In this case, BS 1 shall modify its inter-frame quiet period schedule in order to synchronize with that of BS 2 if the Inter-frame Quiet Period Offset of BS1 is larger than that of BS2. If this rule is validated, BS 1 can proceed with the synchronization of its quiet period with that of BS 2. To this end, BS 1 shall schedule the change in its quiet period to take place N frames away, where $N = \text{rand}(0, \mathbf{R})$ QThresh) and rand(a, b) is a function that returns an integer number t, where $a \le t < b$, and QThresh is defined in units of superframe. If up until N superframes later BS 1 does not receive any more information regarding the next quiet period of BS 2, it shall proceed with its quiet period change to achieve synchronization. This is done by modifying the values of the Inter-frame Quiet Period Offset and Duration in the SCH when initiating the new superframe, or by transmitting an updated CHQ-REQ command.

7.21.3 CPE report

Insert new subclauses after [7.21.3:](#page-148-1)

7.21.4 Quiet periods and sensing for a relay network

7.21.4.1 Quiet period synchronization for a MR-BS's cell

For Quiet period synchronization for an MR-BS's cell containing S-CPEs and R-CPEs as shown in [Figure AJ1,](#page-148-0) the MR-BS can schedule the quiet periods either in the explicit mode, which is done through the use of CHQ-REQ MAC message as described in 7.7.17.3, or in the implicit mode using the sensing related fields in the SCH on PHY Mode 1, or the Extended Frame Control Header on PHY Mode 2.

Quiet period allocation shall follow the same mechanisms described in [7.21.1](#page-147-0).

 uling information transmitted from an MR-BS to the S-CPE within a local cell. In the implicit quiet period scheduling, when a distributed scheduling R-CPE receives a SCH or an Extended Frame Control Header from the MR-BS, the distributed scheduling R-CPE shall send the SCH or the Extended Frame Control Header followed by DRZ-FCH to synchronize quiet period in a local cell.

 In the explicit quiet period scheduling, the MR-BS uses the CHQ-REQ MAC message described in 7.7.17.3 to advertise the intra-frame sensing schedule and all the relevant parameters for sensing. When the distributed scheduling R-CPE receives CHQ-REQ MAC message from the MR-BS, it shall send CHQ-REQ MAC message to the CPEs within a local cell. This explicit mode should not be used in a self-coexistence operation since the quiet period scheduling information may not be made available to the other WRAN systems operating in the area. Only the implicit mode should be used in a self-coexistence situation.

Quiet period allocation shall follow the same mechanisms described in [7.21.1](#page-147-0).

Figure AK1—Quiet period synchronization for a local network

7.22 Channel management

7.22.2 Scheduling of channel switching time

Insert new subclauses after [7.22.2:](#page-149-1)

7.22.3 Channel management on a relay network

Two modes of channel management supported by WRAN, which are an embedded mode and an explicit mode, are also supported in MR-WRAN.

In the embedded mode in MR-WRAN, the MR-BS shall transmit all IEs related to channel management to all CPEs in the cell. A distributed scheduling R-CPE shall transmit all channel management IEs received from the MR-BS to the CPEs managed by the distributed scheduling R-CPE.

 In the explicit mode in MR-WRAN, the channel management messages could be sent by the MR-BS to the specific CPEs directly or relayed on the R-CPE such as a centralized scheduling R-CPE or a distributed scheduling R-CPE. When a R-CPE receives a channel management message not targeted to the R-CPE, the R-CPE shall relay the channel management message to the target CPE. In MR-WRAN, Figure AL1 depicts the message flow between MR-BS and CPE relayed on R-CPE when the 'Confirmation Need' field is set.

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In order to maintain the channel sets, an MR-BS maintains the following available channel sets: Operating, Backup, Candidate, Protected, Occupied, and Unclassified. Each S-CPE and centralized scheduling R-CPE within the MR-BS's cell maintains only the first three channel sets: Operating, Backup and Candidate. While, each distributed scheduling R-CPE maintains the same channel sets as the MR-BS's channel set. These individual sets have different update steps. For example, on the CPE side managed by the MR-BS, the Operating set is confirmed by every received SCH or FCH and the Backup and Candidate sets are updated

after receiving the DCD. While, on the CPE side managed by the distributed scheduling R-CPE, the Operating set is confirmed by every received DRZ-FCH and the Backup and Candidate sets are updated after receiving the DCD in DRZ. After synchronization, the MR-BS should send an IPC-UPD message to the CPE to update the set of channels prohibited from incumbent operation for the newly connected CPE to allow skipping these channels to speed up the sensing process. These relations are summarized in Table AR1 and Table AS1 In the case of the MR-BS, channel sets are updated after each quiet period either at a periodic interval or aperiodic intervals. The MR-BS shall send all channel sets to the distributed scheduling R-CPE.

Table AR1—Update channel set information in CPE

Figure AL1—Message flow between MR-BS and CPE relayed on R-CPE when confirmation is required

7.22.3.1 Initialization and Channel Sets Updating

In this subclause, procedures of channel list initialization and updating on relay are addressed.

CHS-REQ $(n3 - N2)²$ (Confirmation Needed = 1) CHS-REQ
(Confirmation Needed = 1) $CHS-RSp$ $CHS-RSp$ Channel Switch (The CPE changes its operating parameters)

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 CPE R-CPE $\left($ BS

Table AR1—Update channel set information in CPE

Table AS1—Update channel set information in CPE for DRZ

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37 38 39 40 41 42 43 44 45 46 47 48 49 50 When a CPE turns on, it scans the channels to identify the available WRAN operations and proceeds with the selection of one of these services (see 10.3.2). Such selection identifies the operating channel. As part of the CPE initialization, the list of backup and candidate channels is sent in the DCD message by the MR-BS or the distributed scheduling R-CPE. This procedure is closely related with obtaining downlink parameters procedure (see 7.14.2). After association of a new CPE, the MR-BS or the distributed scheduling R-CPE shall send the IPC-UPD message to indicate the list of channels prohibited from incumbent operation to the CPE so that it can skip incumbent sensing on these channels. Channel sets in the CPE are updated after periodically receiving the DCD message. In the case of the MR-BS, if channel sets are changed as a result of BLM-REP messages, the MR-BS sends the backup and candidate channel list in its DCD message. When the distributed scheduling R-CPE receives the updated channel list from the MR-BS, the distributed scheduling R-CPE sends the updated backup and candidate channl list in its DCD message in DRZ to the CPE.

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7.22.3.2 Scheduling of channel switching time

When the MR-BS decides to switch channels during normal operation, it shall execute the following procedure to determine when to schedule the channel switching operation.

58 59 60 61 62 63 64 65 The MR-BS selects the first backup channel from its backup/candidate channel list, it shall select a waiting time T46 to make sure that all its CPEs are prepared for the channel switch. The value of T46 is a configuration parameter that could be set by the management interface. The first requirement is that the value of T46 shall be smaller or equal to the maximum allowed channel moving time and the second requirement is that is long enough for the CPEs to recover from an incumbent detection.

Then, the MRBS schedules the channel switch using the channel management procedure described in 7.19.5.

— When the distributed scheduling R-CPE receives channel switch requirement from the MR-BS, the distributed scheduling R-CPE shall make sure that all its CPEs in a local cell are prepared for the channel switch within the available switching time (Switch Count 7.7.17.1), which will be transmitted by the MR-BS.

7.23 Synchronization of the IEEE 802.22 base stations and **IEEE 802.22b base stations**

Change the first paragraph of [7.23](#page-152-0):

The BSs and MR-BSs on PHY Mode 1 shall synchronize the absolute local start time of their superframe period, to the start of every minute referenced to UTC to a tolerance of less than or equal to ± 2 μs. The MR-BS on PHY Mode 2 shall synchronize the absolute local start time of their frame period, to the start of every minute referenced to UTC to a tolerance of less than or equal to ± 2 μs.

Insert new clause after [7.23](#page-152-0):

7.24Multi-channel operation

This clause describes the multi-channel operation supported by the IEEE Std. 802.22b, which is required to support enhanced broadband services and monitoring applications that require high data throughput. In the IEEE Std. 802.22-2011, single channel operation is supported as shown in [Figure AM1](#page-152-1) with maximum date rate of 22.69 Mbps. In [Figure AM1,](#page-152-1) each CPE (CPE 1~CPE 5) is using the operating channel (f1) to communicate within the service area of BS where the operating channel (f1) is assigned by the spectrum manager using the available channel list. In the IEEE Std. 802.22-2011, even though there may be several available channels exist in the list, due to the constraint of the single channel operation of IEEE Std. 802.22- 2011, those available channels cannot be utilized effectively since multi-channel operation is not supported.

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 The IEEE Std. 802.22b supports aggregate data rates greater than the maximum data rate supported by the IEEE Std. 802.22-2011 in order to extend its regional area broadband services to a broader range of applications such as real-time and near real-time monitoring, emergency broadband services, remote medical services, etc. which requires higher data rates. Therefore, multi-channel operation shall be considered as a means to achieve throughput greater than the maximum throughput supported by the IEEE Std. 802.22-2011.

The examples of multi-channel operation deployment configuration are shown in [Figure AN1](#page-153-0) and [Figure AO1](#page-154-0) respectively. In [Figure AN1,](#page-153-0) it is assumed that there are 2 available operating channels within the service area of the BS. In this example, multi-channel operation on BS is illustrated where only the BS is capable of receiving and transmitting two or more operating channels and responsible to assign the operating channel to the associated CPEs within it's service area. By performing the multi-channel operation on BS, the BS can utilize the available operating channels by distributing the operating channels among the associated CPEs. The multi-channel operation on BS can improve the individual CPE's throughput by decreasing the total number of associated CPEs per operating channel. In [Figure AN1](#page-153-0), CPE 1 and CPE 2 are assigned to the operating channel (f1) to communicate with the BS while CPE 3, CPE 4 and CPE 5 are assigned to the operating channel (f2) to communicate with the BS. In this example, the total number of associated CPEs assigned per operating channel can be reduce to more than 40% compare to the single channel operation situation in [Figure AM1](#page-152-1)

Figure AN1—Example of multi-channel operation deployment configuration (Multi-channel operation on BS)

 In [Figure AO1,](#page-154-0) it is assumed that there are 5 available operating channels within the service area of the BS. In this example, multi-channel operation on BS and CPEs is illustrated where both BS and associated CPEs are capable of receiving and transmitting two or more operating channels. BS is responsible to assign the operating channel to the associated CPEs within the service area for the utilization of available operating channels. In [Figure AO1](#page-154-0), CPE 1 is assigned to the operating channels (f1, f2, f3) to communicate with the BS while CPE 2 is assigned to the operating channels (f4, f5) to communicate with the BS. In this example, the BS can improve the individual CPE's throughput by increasing the number of operating channels assigned to the associated CPEs.

Figure AO1—Example of multi-channel operation deployment configuration (Multi-channel operation on BS and CPE)

7.24.1 Channel allocation manager

The channel allocation manager (CAM) shown in [Figure](#page-154-1) AP1 is responsible for the basic multi-channel operations such as add new operating channel operation which is described in [7.24.1.1](#page-155-0), stop operating channel which is described in [7.24.1.3](#page-163-0) and switch operating channel which is described in [7.24.1.4](#page-166-0).

Figure AP1—Channel allocation manager

A channel allocation manager is needed on the IEEE 802.22b devices (BS and CPEs) to perform multi-channel operations which are described in [7.24.1.1,](#page-155-0) [7.24.1.3](#page-163-0) and [7.24.1.4](#page-166-0).

In [7.24.1.1](#page-155-0), detailed operation flow of add new operating channel is discussed. The add new operating channel function is responsible for allocating new operating channel to each available channel transceiver unit (CHU) of the IEEE 802.22b devices.

 In [7.24.1.3](#page-163-0), detailed operation flow of stop operating channel is discussed. The stop operating channel function is responsible for stopping the operating channel of the specific CHU of the IEEE 802.22b devices.

 In [7.24.1.4,](#page-166-0) detailed operation flow of switch operating channel is discussed. The switch operating channel IEEE

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function is responsible for switching the operating channel of the specific CHU of the IEEE 802.22b devices.

A channel transceiver unit (CHU) is defined as a transceiver unit for a specific channel operation which is

7.24.1.1 Add new operating channel operation When the BS is ready to operate under the multi-channel operation, the following procedure of adding new operating channel is performed on both BS and CPE which have the capability of receiving and transmitting two or more operating channels. The add new operating channel operation procedure shall consist of the following steps: 1) BS-CAM selects a specific BS-CHU. 2) BS-CAM commences operation request. 3) BS-CHU commences operation acknowledgment. 4) BS-CAM sends management information notification to BS-CHU. 5) BS-CHU memorizes management information. 6) BS-CHU performs frequency setting. 7) BS-CHU performs synchronization. 8) BS-CHU sends operation preparation completed notification to BS-CAM. 9) BS-CHU broadcasts SCH. 10) BS-CAM checks unused BS-CHU. 11) CPE-CAM selects a specific CPE-CHU. 12) CPE-CAM sends BS search command (All / specific channel) to the specific CPE-CHU. 13) CPE-CHU performs BS search. 14) CPE-CHU sends BS detected notification to CPE-CAM. 15) CPE-CAM determines other operating CPE-CHU. 16) CPE-CAM performs BSID matching. 17) CPE-CAM sends BSID mismatch notification to CPE-CHU. 18) CPE-CAM sends proceed notification to CPE-CHU. 19) CPE-CHU performs synchronization. 20) CPE-CHU sends synchronization completed notification to CPE-CAM. 21) CPE-CAM checks unused CPE-CHU. 22) CPE-CAM sends registration request to CPE management unit.

consists of a MAC and a PHY.

- 23) CPE management unit sends registration completed notification to CPE-CAM.
- The add new operating channel operation flow is shown in [Figure AQ1](#page-156-0).

Figure AQ1—Operation flow for adding new operating channel

7.24.1.1.1 BS-CAM selects a specific BS-CHU

The BS channel allocation manager (BS-CAM) shall select specific BS channel transceiver unit (BS-CHU) which is the target of add new operating channel operation. The BS-CAM shall select the BS-CHU which is in the state of unused or unassigned currently and the hardware is corresponds to the new operating channel's frequency. The operating channel selection procedure may be included in this step.

7.24.1.1.2 BS-CAM commences operation request

The BS-CAM shall send a commence operation request to the selected BS-CHU. The commence operation request may include the various parameters in connection with the PHY such as channel center frequency and its offset, etc., and some part of MIB information such as software version information, etc.

7.24.1.1.3 BS-CHU commences operation acknowledgment

The BS-CHU shall send a commence operation acknowledgment to the BS-CAM. The commence operation acknowledgment may include the specific BS-CHU MIB information that is needed for BS-CAM such as device ID or serial number of the BS-CHU, etc. The BS-CHU shall responds with an error when the commence operation request is rejected due to the reasons such as mismatch of the software version, etc.

- **7.24.1.1.4 BS-CAM sends management information notification to BS-CHU**
- The BS-CAM shall send a management information notification to the BS-CHU. The management information notification may mainly include the MIB information necessary for BS-CHU which is maintained by BS-

CAM such as the ID to identify the connection between BS and CPE (carrier index which is associated with the physical or logical channel), etc. If the BS-CHU has a part of MAC layer function then the information on MIB which is used by MAC layer such as Station ID, MAC Address of BS, etc. shall be included.

7.24.1.1.5 BS-CHU memorizes management information

The BS-CHU shall memorize the management information notified by the BS-CAM after the management information notification. Some part of the memorized information (MIB information) shall be immediately reflected on the BS-CHU or reflected as the initial value of the transition state.

7.24.1.1.6 BS-CHU performs frequency setting

The BS-CHU shall perform the frequency setting procedure. The channel center frequency and its offset that was received in the commence operation request or management information notification shall be reflected in the local oscillator of BS-CHU.

7.24.1.1.7 BS-CHU performs synchronization

The BS-CHU shall perform the BS-CHU synchronization procedure. This procedure is intended for network synchronization to synchronize the superframe, frame and TDD timing of a number of BS in a wireless communication system. Basically, this procedure shall synchronize the superframe to the start of each minute of the UTC time obtained from the GPS, etc. As a result, all the operating BS-CHU shall be synchronized with each other.

7.24.1.1.8 BS-CHU sends operation preparation completed notification to BS-CAM

The BS-CHU shall send operation preparation completed notification to the BS-CAM. The BS-CHU shall send a response indicating an error when it fails on the mid-way of completing the operation preparation procedure.

7.24.1.1.9 BS-CHU broadcasts SCH

The BS-CHU shall periodically broadcast a radio frame which included the SCH information.

7.24.1.1.10 BS-CAM checks unused BS-CHU

The BS-CAM shall check whether there is any unused BS-CHU. If the unused BS-CHU exists, then the BS-CAM shall proceed to the select specific BS-CHU procedure.

7.24.1.1.11 CPE-CAM selects a specific CPE-CHU

The CPE channel allocation manager (CPE-CAM) shall select specific CPE channel transceiver unit (CPE-CHU) which is target of add new operating channel operation. The CPE-CAM shall select the CPE-CHU which is in the state of unused or unassigned. In many cases, this procedure is triggered by the BS lost condition occurs in CPE where the CPE-CHU is selected.

7.24.1.1.12 CPE-CAM sends BS search command (All / specific channel) to the specific CPE-CHU

 The CPE-CAM shall send a BS search command (All / specific channel) to the selected CPE-CHU. The BS search command (All / specific channel) shall be performed by searching all the frequency channels that are corresponded by the selected CPE-CHU or by searching one or more specific frequency channels. The specific channel information shall be indicated by using the extended DCD message, newly defined management message, etc. to specify the BS operating channels that are not connected by any CPE or shall be estimated

based on the backup channel information. To prevent overlapping with the other CPE-CHU channel, the channel which other CPE-CHU has already used shall not be searched. Moreover, the channel which other BS has already used that is identified by previous BS search command, etc. shall not be searched.

7.24.1.1.13 CPE-CHU performs BS search

The CPE-CHU shall perform the BS search command by attempting to detect the radio signal (preamble and SCH) from BS at the target frequency of BS search command.

7.24.1.1.14 CPE-CHU sends BS detected notification to CPE-CAM

The CPE-CHU shall send a BS detected notification to the CPE-CAM when it is able to detect the signal strength greater than or equal to a predetermined value that is defined in the BS search procedure. The BS detected notification shall include the BSID which is obtained by decoding the SCH information.

7.24.1.1.15 CPE-CAM determines other operating CPE-CHU

The CPE-CAM shall determine whether there is any other operating CPE-CHU (connection status with BS). If there is no other operating CPE-CHU at that time, then it does not correspond to add new operating channel procedure (multi-channel operation). The CPE-CHU shall proceed to the synchronization process similarly to the conventional IEEE Std. 802.22-2011.

7.24.1.1.16 CPE-CAM performs BSID matching

If there is other operating CPE-CHU detected at that time, the CPE-CAM shall determine the BSID of other operating CPE-CHU match with the BSID obtained by the CPE-CHU during BS detected notification.

7.24.1.1.17 CPE-CAM sends BSID mismatch notification to CPE-CHU

If the BSID mismatch occurred, then the BS-CAM shall send a BSID mismatch notification to the CPE-CHU and the CPE-CHU shall resume its BS search process with the rest of the targeted frequency or the BS-CAM shall send a specific target frequency of BS search command to the CPE-CHU.

7.24.1.1.18 CPE-CAM sends proceed notification to CPE-CHU

If the BSID match is confirmed, then the CPE-CAM shall send a proceed notification to the CPE-CHU to continue with the synchronization procedure.

7.24.1.1.19 CPE-CHU performs synchronization

> The CPE-CHU shall continue with the synchronization procedure with the frequency which is detected in SCH. In addition to the original synchronization procedure such as detecting and decoding the FCH, DS-MAP, etc. to obtain the parameters of the DS, this procedure shall included the reception of UCD message process to obtain the parameters of the US, the ranging process to adjust the TDD timing, etc.

7.24.1.1.20 CPE-CHU sends synchronization completed notification to CPE-CAM

As a response to the proceed notification procedure, the CPE-CHU shall send a synchronization completed notification to the CPE-CAM. By referring to these notifications, the CPE-CAM can recognize the multichannel operation when two or more CPE-CHUs are connected with the BS.

7.24.1.1.21 CPE-CAM checks unused CPE-CHU

The CPE-CAM shall check whether there is any unused CPE-CHU. If the unused CPE-CHU exists, then the

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CPE-CAM shall proceed to the select specific CPE-CHU procedure.

7.24.1.1.22 CPE-CAM sends registration request to CPE management unit

The CPE-CAM shall send a registration request to the BS for CPE registration after completed the multichannel operation capability. The registration request shall contain the information (carrier index, etc.) which can uniquely identify each channel used in the multi-channel operation. Some management messages may be exchanged only between the BS-CHU and CPE-CHU if necessary.

7.24.1.1.23 CPE management unit sends registration completed notification to CPE-CAM

The CPE management unit shall send a registration completed notification to the CPE-CAM.

7.24.1.2 Add new operating channel operation by using BS search command (specific channel)

As described in [7.24.1.1.12,](#page-157-0) the BS search command can be conducted in 2 modes (All / specific channel). In this sub clause, the detailed operation flow for add new operating channel operation by using BS search command in specific channel mode is shown here. In this operation flow, the BS-CHU and CPE-CHU shall have at least one operating channel to enable the exchange of management message between BS and CPE.

The operation flow for add new operating channel operation by using BS search command in specific channel mode shall consist of the following steps:

- 1) BS-CAM sends a aggregation information to BS-CHU1.
- 2) BS-CHU1 forwards a aggregation information to CPE-CHU1.
- 3) CPE-CHU1 forwards aggregation information to CPE-CAM.
- 4) BS-CAM selects a specific BS-CHU.
- 5) BS-CAM commences operation request.
- 6) BS-CHU2 commences operation acknowledgment.
- 7) BS-CAM sends management information notification to BS-CHU2.
- 8) BS-CHU2 memorizes management information.
- 9) BS-CHU2 performs frequency setting.
- 10) BS-CHU2 performs synchronization.
- 11) BS-CHU2 sends operation preparation completed notification to BS-CAM.
- 12) BS-CHU2 broadcasts SCH.
- 13) BS-CAM checks unused BS-CHU.
- 14) CPE-CAM selects a specific CPE-CHU.
- 15) CPE-CAM sends BS search command (All / specific channel) to the specific CPE-CHU2.
- 16) CPE-CHU2 performs BS search.
- 17) CPE-CHU2 sends BS detected notification to CPE-CAM.
- 18) CPE-CAM determines other operating CPE-CHU.
- 57 19) CPE-CAM performs BSID matching.
- 58 59 20) CPE-CAM sends BSID mismatch notification to CPE-CHU2.
- 60 21) CPE-CAM sends proceed notification to CPE-CHU2.
- 61 62 22) CPE-CHU2 performs synchronization.
- 63 64 23) CPE-CHU2 sends synchronization completed notification to CPE-CAM.
- 65 24) CPE-CAM checks unused CPE-CHU.

25) CPE-CAM sends registration request to CPE management unit.

26) CPE management unit sends registration completed notification to CPE-CAM.

The add new operating channel operation by using BS search command (specific channel) operation flow is shown in [Figure AR1](#page-160-0).

7.24.1.2.3 CPE-CHU1 forwards aggregation information to CPE-CAM

The CPE-CHU1 shall forward the aggregation information to the CPE-CAM after receiving the information from BS-CHU1. The aggregation information shall be designed as a newly defined management message from BS-CAM. The detailed of the management message CAM-AIF is described in 7.7.29.1. The BS-CHU1 and CPE-CHU1 do not need to understand the content of the message when performing the forwarding process.

7.24.1.2.4 BS-CAM selects a specific BS-CHU

The BS-CAM shall select specific BS-CHU which is the target of add new operating channel operation. The BS-CAM shall select the BS-CHU which is in the state of unused or unassigned currently and the hardware is corresponds to the new operating channel's frequency. The operating channel selection procedure may be included in this step.

7.24.1.2.5 BS-CAM commences operation request

The BS-CAM shall send a commence operation request to the selected BS-CHU. The commence operation request may include the various parameters in connection with the PHY such as channel center frequency and its offset, etc., and some part of MIB information such as software version information, etc.

7.24.1.2.6 BS-CHU2 commences operation acknowledgment

The BS-CHU shall send a commence operation acknowledgment to the BS-CAM. The commence operation acknowledgment may include the specific BS-CHU MIB information that is needed for BS-CAM such as device ID or serial number of the BS-CHU, etc. The BS-CHU shall responds with an error when the commence operation request is rejected due to the reasons such as mismatch of the software version, etc.

7.24.1.2.7 BS-CAM sends management information notification to BS-CHU2

The BS-CAM shall send a management information notification to the BS-CHU. The management information notification may mainly include the MIB information necessary for BS-CHU which is maintained by BS-CAM such as the ID to identify the connection between BS and CPE (carrier index which is associated with the physical or logical channel), etc. If the BS-CHU has a part of MAC layer function then the information on MIB which is used by MAC layer such as Station ID, MAC Address of BS, etc. shall be included.

7.24.1.2.8 BS-CHU2 memorizes management information

The BS-CHU shall memorize the management information notified by the BS-CAM after the management information notification. Some part of the memorized information (MIB information) shall be immediately reflected on the BS-CHU or reflected as the initial value of the transition state.

- **7.24.1.2.9 BS-CHU2 performs frequency setting**
- The BS-CHU shall perform the frequency setting procedure. The channel center frequency and its offset that was received in the commence operation request or management information notification shall be reflected in the local oscillator of BS-CHU.
- **7.24.1.2.10 BS-CHU2 performs synchronization**

 The BS-CHU shall perform the BS-CHU synchronization procedure. This procedure is intended for network synchronization to synchronize the superframe, frame and TDD timing of a number of BS in a wireless communication system. Basically, this procedure shall synchronize the superframe to the start of each minute of the UTC time obtained from the GPS, etc. As a result, all the operating BS-CHU shall be synchronized with

each other.

7.24.1.2.11 BS-CHU2 sends operation preparation completed notification to BS-CAM

The BS-CHU shall send operation preparation completed notification to the BS-CAM. The BS-CHU shall send a response indicating an error when it fails on the mid-way of completing the operation preparation procedure.

7.24.1.2.12 BS-CHU2 broadcasts SCH

The BS-CHU shall periodically broadcast a radio frame which included the SCH information.

7.24.1.2.13 BS-CAM checks unused BS-CHU

The BS-CAM shall check whether there is any unused BS-CHU. If the unused BS-CHU exists, then the BS-CAM shall proceed to the select specific BS-CHU procedure.

7.24.1.2.14 CPE-CAM selects a specific CPE-CHU

The CPE-CAM shall select specific CPE-CHU which is target of add new operating channel operation. The CPE-CAM shall select the CPE-CHU which is in the state of unused or unassigned. In many cases, this procedure is triggered by the BS lost condition occurs in CPE where the CPE-CHU is selected.

7.24.1.2.15 CPE-CAM sends BS search command (All / specific channel) to the specific CPE-CHU2

The CPE-CAM shall send a BS search command (specific channel) to the selected CPE-CHU. The BS search command (specific channel) shall be performed by searching one or more specific frequency channels. The specific channel information shall be indicated by using the extended DCD message, newly defined management message, etc. to specify the BS operating channels that are not connected by any CPE or shall be estimated based on the backup channel information. To prevent overlapping with the other CPE-CHU channel, the channel which other CPE-CHU has already used shall not be searched. Moreover, the channel which other BS has already used that is identified by previous BS search command, etc. shall not be searched.

7.24.1.2.16 CPE-CHU2 performs BS search

The CPE-CHU shall perform the BS search command by attempting to detect the radio signal (preamble and SCH) from BS at the target frequency of BS search command.

7.24.1.2.17 CPE-CHU2 sends BS detected notification to CPE-CAM

The CPE-CHU shall send a BS detected notification to the CPE-CAM when it is able to detect the signal strength greater than or equal to a predetermined value that is defined in the BS search procedure. The BS detected notification shall include the BSID which is obtained by decoding the SCH information.

7.24.1.2.18 CPE-CAM determines other operating CPE-CHU

 The CPE-CAM shall determine whether there is any other operating CPE-CHU (connection status with BS). If there is no other operating CPE-CHU at that time, then it does not correspond to add new operating channel procedure (multi-channel operation). The CPE-CHU shall proceed to the synchronization process similarly to the conventional IEEE Std. 802.22-2011.

7.24.1.2.19 CPE-CAM performs BSID matching

If there is other operating CPE-CHU detected at that time, the CPE-CAM shall determine the BSID of other operating CPE-CHU match with the BSID obtained by the CPE-CHU during BS detected notification.

7.24.1.2.20 CPE-CAM sends BSID mismatch notification to CPE-CHU2

If the BSID mismatch occurred, then the BS-CAM shall send a BSID mismatch notification to the CPE-CHU and the CPE-CHU shall resume its BS search process with the rest of the targeted frequency or the BS-CAM shall send a specific target frequency of BS search command to the CPE-CHU.

7.24.1.2.21 CPE-CAM sends proceed notification to CPE-CHU2

If the BSID match is confirmed, then the CPE-CAM shall send a proceed notification to the CPE-CHU to continue with the synchronization procedure.

7.24.1.2.22 CPE-CHU2 performs synchronization

The CPE-CHU shall continue with the synchronization procedure with the frequency which is detected in SCH. In addition to the original synchronization procedure such as detecting and decoding the FCH, DS-MAP, etc. to obtain the parameters of the DS, this procedure shall included the reception of UCD message process to obtain the parameters of the US, the ranging process to adjust the TDD timing, etc.

7.24.1.2.23 CPE-CHU2 sends synchronization completed notification to CPE-CAM

As a response to the proceed notification procedure, the CPE-CHU shall send a synchronization completed notification to the CPE-CAM. By referring to these notifications, the CPE-CAM can recognize the multichannel operation when two or more CPE-CHUs are connected with the BS.

7.24.1.2.24 CPE-CAM checks unused CPE-CHU

The CPE-CAM shall check whether there is any unused CPE-CHU. If the unused CPE-CHU exists, then the CPE-CAM shall proceed to the select specific CPE-CHU procedure.

7.24.1.2.25 CPE-CAM sends registration request to CPE management unit

The CPE-CAM shall send a registration request to the BS for CPE registration after completed the multichannel operation capability. The registration request shall contain the information (carrier index, etc.) which can uniquely identify each channel used in the multi-channel operation. Some management messages may be exchanged only between the BS-CHU and CPE-CHU if necessary.

7.24.1.2.26 CPE management unit sends registration completed notification to CPE-CAM.

The CPE management unit shall send a registration completed notification to the CPE-CAM.

7.24.1.3 Stop operating channel operation

When the BS is operating under the multi-channel operation, the following procedure of stop operating channel is performed on both BS and CPE to stop the operating channel which is request by the BS.

The stop operating channel operation procedure shall consist of the following steps:

- 1) BS-CAM sends stop operation request to BS-CHU.
- 2) BS-CHU starts stop operation timer.

3) BS-CHU sends stop operation request acknowledgment to BS-CAM

- 10) CPE-CHU sends stop operation completed notification to CPE-CAM.
- 11) BS-CHU checks stop operation timer expired and stops operation.
- 12) BS-CHU sends stop operation completed notification to CPE management unit.

The stop operating channel operation flow is shown in [Figure AS1.](#page-164-0)

Figure AS1—Operation flow for stopping operating channel

7.24.1.3.1 BS-CAM sends stop operation request to BS-CHU

The BS-CAM shall send the stop operation request to the BS-CHU which is the target of stop operating channel operation.

7.24.1.3.2 BS-CHU starts stop operation timer

 The BS-CHU shall start the stop operation timer after receiving the stop operation request from BS-CAM. The start of the stop operation timer shall determine the frame number where the operation is scheduled to stop.

7.24.1.3.3 BS-CHU sends stop operation request acknowledgment to BS-CAM

The BS-CHU shall send the stop operation request acknowledgement to the BS-CAM.

7.24.1.3.4 BS-CHU sends stop operation request to CPE-CHU

The BS-CHU shall send the stop operation request to the CPE-CHU by using the downstream transmission. The stop operation request can be send as a new defined management message. The detailed of the management message CAM-STP is described in 7.7.29.2.

7.24.1.3.5 CPE-CHU starts stop operation timer

Based on the information which specifies the target of the stop operation channel that can be obtained after receiving the stop operation request from the BS-CHU, the CPE-CHU shall confirm the target channel of the request. If the request is addressed to the CPE-CHU, then the CPE-CHU shall start the stop operation timer.

7.24.1.3.6 CPE-CHU sends stop operation notification to CPE-CAM

The CPE-CHU shall send the stop operation notification to the CPE-CAM.

7.24.1.3.7 CPE-CAM sends stop operation approval/command to CPE-CHU

The CPE-CAM shall send the stop operation approval/command to the CPE-CHU after the CPE-CAM is notified that the channel operation of the CPE-CHU will be stopped.

7.24.1.3.8 CPE-CHU sends stop operation request acknowledgment to BS-CHU

The CPE-CHU shall send the stop operation request acknowledgement to the BS-CHU after receiving the stop operation approval/command from the CPE-CAM. The stop operation acknowledgement can be send as a new defined management message through the upstream transmission. The detailed of the management message CAM-STP is described in 7.7.29.2.

7.24.1.3.9 CPE-CHU checks stop operation timer expired and stops operation

The CPE-CHU shall stop the operation when the stop operation timer is expired which means that it has reached the frame number that is set during the set stop operation timer procedure. The CPE-CHU shall stop all transmission and reception after the stop operation procedure is performed.

7.24.1.3.10 CPE-CHU sends stop operation completed notification to CPE-CAM

The CPE-CHU shall send the stop operation completed notification to the CPE-CAM after completed the stop operation procedure.

7.24.1.3.11 BS-CHU checks stop operation timer expired and stops operation

The BS-CHU shall stop the operation when the stop operation timer is expired and stop all the transmission and reception after the stop operation procedure is performed.

7.24.1.3.12 BS-CHU sends stop operation completed notification to CPE management unit.

 The BS-CHU shall send the stop operation completed notification to the BS-CAM and CPE management unit after completed the stop operation procedure. The BS-CHU and CPE-CHU that has stopped their operation will be the target CHU for the add new operating channel procedure.

13) BS-CHU sends DS-MAP/DCD/US-MAP/UCD to CPE-CHU.

- 14) CPE-CHU sends channel switch completed notification to CPE-CAM.
- 15) CPE-CHU sends channel switch completed notification to CPE management unit.

The switch operating channel operation flow is shown in [Figure AT1](#page-166-1).

7.24.1.4.1 BS-CAM sends channel switch request to BS-CHU

The BS-CAM shall send the channel switch request to the BS-CHU which is the target of switch operating channel operation. The BS-CHU shall correspond to the requested switch operating channel's frequency.

7.24.1.4.2 BS-CHU starts channel switch timer

The BS-CHU shall start the channel switch timer after receiving the channel switch request from BS-CAM. The start of the channel switch timer shall determine the frame number where the new operating channel is scheduled to switch.

7.24.1.4.3 BS-CHU sends channel switch request acknowledgment to BS-CAM

The BS-CHU shall send the channel switch request acknowledgement to the BS-CAM.

7.24.1.4.4 BS-CHU sends channel switch request to CPE-CHU

The BS-CHU shall send the channel switch request to the CPE-CHU by using the downstream transmission. The channel switch request can be send as a new defined management message. The detailed of the management message CAM-SWH is described in 7.7.29.4. The management message shall be broadcasted to all the CPE and the CPE shall be able to receive and interpret the content of the management message.

7.24.1.4.5 CPE-CHU starts channel switch timer

The CPE-CHU shall start the channel switch timer after receiving the channel switch request from the BS-CHU.

7.24.1.4.6 CPE-CHU sends channel switch notification to CPE-CAM

The CPE-CHU shall send the channel switch notification to the CPE-CAM.

7.24.1.4.7 CPE-CAM sends channel switch approval/command to CPE-CHU

The CPE-CAM shall send the channel switch approval/command to the CPE-CHU after the CPE-CAM is notified that the operating channel of the CPE-CHU will be switched.

7.24.1.4.8 CPE-CHU sends channel switch request acknowledgment to BS-CHU

The CPE-CHU shall send the channel switch request acknowledgement to the BS-CHU after receiving the channel switch approval/command from the CPE-CAM. The channel switch request acknowledgement can be send as a new defined management message through the upstream transmission. The detailed of the management message CAM-SWH is described in 7.7.29.4.

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- **7.24.1.4.9 BS-CHU checks channel switch timer expired and performs channel switch**
- The BS-CHU shall switch to a new operating channel when the channel switch timer is expired which means that it has reached the frame number that is set during the start channel switch timer procedure. The BS-
- CHU shall modify the operating parameters within the RTG period and shall change the frequency of the
- local oscillator in order to switch to a new operating channel. Since channel switch is performed due to the
- necessity of termination of operation on current channel in most of the cases, a channel switch is enforced
- even if the channel switch acknowledgement is not receive from neither one of the CPEs.

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7.24.1.4.10 CPE-CHU checks channel switch timer expired and performs channel switch

The CPE-CHU shall switch to a new operating channel when the channel switch timer is expired.

7.24.1.4.11 BS-CHU sends channel switch completed notification to BS-CAM

The BS-CHU shall send the channel switch completed notification to the BS-CAM after completed the channel switch procedure. This shall indicate that the channel switch procedure at the physical layer of BS-CHU is completed (such as the frequency of the local oscillator of BS-CHU is locked to the new channel, etc.).

7.24.1.4.12 BS-CHU broadcasts SCH

The BS-CHU shall broadcast a radio frame which included the SCH information.

7.24.1.4.13 BS-CHU sends DS-MAP/DCD/US-MAP/UCD to CPE-CHU

The BS-CHU shall send the DS-MAP/DCD/US-MAP/UCD information to CPE-CHU for synchronization procedure.

7.24.1.4.14 CPE-CHU sends channel switch completed notification to CPE-CAM

The CPE-CHU shall send the channel switch completed notifiction to CPE-CAM when the frame containing SCH, etc. is received correctly. The channel switch completion notification shall indicate that the channel switch has been completed at the MAC layer.

7.24.1.4.15 CPE-CHU sends channel switch completed notification to CPE management unit

The CPE-CHU shall send the channel switch completed notification to the CPE management unit. The channel switch completed notification can be send as a new defined management message through the upstream transmission. The detailed of the management message CAM-SWH is described in 7.7.29.4. Upon receiving the management message, the CPE management unit in BS shall update the latest information of the CPEs.

7.24.2 Multi-channel operation at BS

45 46 47 48 49 50 51 52 This clause explain the operation flow of the BS's channel allocation manager (BS-CAM) for commencing the multi-channel operation. The operation flow of commencing multi-channel operation at BS is shown in [Figure AU1](#page-169-0). In order to perform the multi-channel allocation which is neccesary for multi-channel operation, three basic functions which are add new operating channel, stop operating channel and switch operating channel are newly defined. The detailed explanation of each function and it's operation flow are described in [7.24.1.1](#page-155-0), [7.24.1.3](#page-163-0) and [7.24.1.4.](#page-166-0)

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54 55 56 57 58 59 60 61 62 63 64 65 In commencing multi-channel operation at BS, the BS-CAM shall play the key role to decide the operating channel and determine the implementation of either one of the 3 basic functions as shown in [Figure AU1.](#page-169-0) The triggers for the BS-CAM to decide the operating channel are database access, BS sensing report, CPE sensing report and BS channel scheduling. The database access trigger shall referring to the database access result which concluded that there are changes in the available operating channels after accessing the whitespace database by the database access control in BS. The BS sensing report and CPE sensing report shall refer to the sensing report which concluded that there are changes in the available operating channels after performing the sensing process. These are triggers that caused by the changes in the available operating channels. The BS channel scheduling is the case where a particular operating channel is available under specific time scheduling by the BS.

Figure AU1—Commence multi-channel operation at BS

7.24.3 Multi-channel operation at CPE

 This clause explain the operation flow of the CPE's channel allocation manager (CPE-CAM) for commencing the multi-channel operation. The operation flow of commencing multi-channel operation at CPE is shown in [Figure AV1.](#page-170-0) In order to perform the multi-channel allocation which is neccesary for multichannel operation, the CPE-CAM also possess three basic functions which are add new operating channel, stop operating channel and switch operating channel. The detailed explanation of each function and it's operation flow are described in [7.24.1.1](#page-155-0), [7.24.1.3](#page-163-0) and [7.24.1.4.](#page-166-0)

 In commencing multi-channel operation at CPE, most of the triggers of the CPE-CAM operation are resulted from the BS control messages. The triggers for the CPE-CAM to commence the multi-channel operation are BS control message, CPE incumbent sensing report, CPE channel scheduling and BS lost message.The BS control message including the switch operating channel and stop operating channel control messages. When the CPE-CAM received the switch operating channel control message from the BS, it shall proceed to the switch operating channel procedure and switch to the operating channel as stated in the switch operating channel control message. When the CPE-CAM received the stop operating channel control message from the BS, it shall proceed to the stop operating channel procedure and stop the operating channel as stated in the stop operating channel control message. Furthermore, when the CPE incumbent sensing report showed the detection of incumbent or the CPE channel scheduling is scheduled to stop the operating channel, it shall proceed to the stop operating channel procedure as well. The BS lost message which indicates the lost connection between a CPE-CHU and a BS or the CPE channel scheduling for adding a new operating channel shall proceed to the add new operating channel procedure.

Figure AV1—Commence multi-channel operation at CPE

Insert new clause after [7.25](#page-170-1):

7.25 Group Resource Allocation

A large number of CPEs (at least 2048 CPEs) may be connected to the BS. Among them, some CPEs have similar traffic pattern, such as, payload size, traffic period, and data rate (PHY mode), etc. It is a burden of MAP overhead to allocate the resources to all CPEs individually. The Group Resource Allocation (GRA) is very efficient for a group of CPEs communicating using a same PHY mode and with a fixed payload size. The MAP overhead is significantly reduced by allocating the resources to the Group using bitmap format.

The group is composed of one H-CPE and many L-CPEs. Within the group, H-CPE is a controller of a group consisting of many L-CPEs. The H-CPE capabilities include access to the database services, identification of the group, network entry with BS, etc. All the L-CPEs within the group are synchronized to the H-CPE.

There are two types of group: fixed group and mobile (or portable) group. The type of group is determined according to the mobility of H-CPE. The H-CPE within fixed group is fixed on the building, house, tower, etc. The H-CPE within mobile (or portable) group is mobile (or portable) on the vehicles, etc.

 The BS configures the group resource allocation by using the Group Resource Allocation Configuration (GRA-CFG) message, as shown in Table AK1. The BS creates a new group, identifies the devices that are belonging to the group, and allocates the resources on a group basis. The GRA-CFG message includes the characteristics of group, such as Device Bitmap Size, Bitmap of Station ID, Group ID, Group Type, and Group Location. The group resource allocation configuration can be updated using the Group Resource Allocation Update (GRA-UPD) message, as shown in Table AL1. The BS uses GRA-UPD message to add a device to a group or delete a device from a group. The DS/US-MAP message defines the access to the downstream/upstream resources, as shown in Table 25 and Table 34, respectively. The format of a DS/US-MAP IEs is defined for the Individual Resource Allocation (IRA), as shown in Table 26 and Table 35,

respectively. And the format of a DS/US-MAP GRA IEs is defined for the Group Resource Allocation (GRA), as shown in Table J1 and Table J1, respectively.

The backup and candidate channels can also be updated on a group basis using Backup and Candidate Channel List IE, as shown in Table 22. When Group Flag is set to 1, the backup and candidate channels are used locally within a group. Otherwise, when Group Flag is set to 0, the backup and candidate channels are used globally within a cell. The backup and candidate channels are selected using the mobility and the location of H-CPE. Same channel is selected as the backup (or candidate) channel between the fixed groups. But if the groups could overlap, the backup (or candidate) channel shall be different to avoid interference among groups. On the other hand, different channels are selected as the backup (or candidate) channel between the fixed and the mobile group or between the mobile groups. But if the groups could not overlap, the backup (or candidate) channel could be same for frequency reuse. The backup and candidate channel list of each group shall be updated according to the periodic monitoring which checks whether the groups could overlap each other or new group appears. Therefore, when mobile group moves into other group, or when new group or incumbent user appears within a cell, the BS and CPEs can reduce the signaling overhead and can prevent QoS degradation by avoiding frequent channel switching.

Figure AW1—Example of backup channel selection

 [Figure AW1](#page-171-0) shows an example of how the backup channel is selected. There are three fixed groups and single mobile group. The H-CPE of fixed groups is installed at the fixed object, such as farmhouse, building, tower, etc. The H-CPE of mobile group is installed at the mobile or portable object, such as car, train, ship, etc. In a relationship between the group 1 and the group 2, there are two fixed groups which is overlapping each other, thus the BS may allocate different backup channels, for example, backup channel #2 and backup channel #3, to the group 1 and the group 2, respectively. In a relationship between the group 1 and the group 3, there are two fixed groups which is not overlapping each other, thus the BS may allocate same backup channel, for example, backup channel #2, to both the group 1 and the group 3. In a relationship between the group 3 and the group 4, there are fixed and mobile groups which is overlapping each other, thus the BS may allocate different backup channels, for example, backup channel #2 and backup channel #3, to the group 3

1 and the group 4, respectively. In a relationship between the group 2 and the group 4, there are fixed and 2 mobile groups which is not overlapping each other, thus the BS may allocate same backup channel, for 3 example, backup channel #3, to both the group 2 and the group 4. 4 5 6 7 Start 8 9 10 Are there any Tre there any backur 11 \overline{N} idle backup channels Ves channels which are which are not being 12 being allocated to allocated to other mobile groups? 13 groups? (5) Allocate some of 14 -
No Yes backup channels which 1 Allocate the idle backup 15 are being allocated to channels to target group $_{\rm BS}$ 16 Are there any backur 17 \overline{N} \overline{N} channels which are Do they overlap each 18 being allocated to other? 19 fixed groups? 20 Yes Yes 3 Allocate some of 21 backup channels which 22 are being allocated to 4) Allocate some of mobile groups 23 backup channels which No Do they overlap each 24 are being allocated to other? fixed and/or mobile 25 groups 26 2 Allocate some of Yes 27 backup channels which are being allocated to 28 fixed groups 29 30 End 31 32 33 **Figure AX1—Example of backup channel decision** 34 35 [Figure AX1](#page-172-0) shows an example of how the backup channel is decided. When there are any idle backup

36 37 38 39 40 41 42 43 44 45 46 47 48 49 50 51 52 53 54 55 56 57 58 59 channels which are not being allocated to other groups, the BS allocates the idle backup channels to the target group (1). When there are no idle backup channels to be allocated, the BS may first check if there exist any backup channels allocated to a fixed group. When there are any backup channels which are being allocated to fixed groups, and target group and fixed group do not overlap, the BS allocates the backup channels allocated to the fixed group, to the target group (2). A presence of a backup channel allocated to the fixed group may be first checked since a burden of changing the backup channels may exist when a state of a backup channel being currently allocated to a mobile group is changed to an unavailable backup channel, due to mobility of the mobile group, although it is determined that the allocated backup channel is available. When there are no backup channels which are being allocated to fixed groups, or when there are any backup channels which are being allocated to fixed groups but the target group and the fixed group overlap, the BS may check if there exist any backup channels allocated to a mobile group. When there are backup channels which are being allocated to mobile groups, and the target group and the mobile group do not overlap, the BS allocates the backup channels allocated to the mobile group (3). Although there are backup channels which are being allocated to the mobile group, but the mobile group and the target group are also overlap, the BS allocates the backup channels allocated to the fixed group or the mobile group (4). When there are also no backup channels which are being allocated to mobile groups, the BS allocates the backup channels allocated to the BS, to the target group (5). When at least two overlapping groups share the backup channels or when the BS and some groups share the backup channels, the BS may use a mechanism for proper resources sharing between the overlapping groups or the BS and some groups after channel switching.

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8. Security mechanism in IEEE 802.22

9. PHY (Mode 1)

Change Table 198 as indicated.

Table AT1—System parameters

9.2 Data Rates

Change Table 202 as indicated.

Table AU1—PHY Modes and their related modulations, coding rates and data rates for T_{CP} = $T_{\text{FFT}}/16$

9.7 Channel coding

9.7.2.1.2 Puncturing

Change Table 208 as indicated

9.7.2.1.3 OFDM slot concatenation

Change Table 209 as indicated.

Table 209—Concatenation index for different modulations and coding

Modulation and Rate	j
16-QAM 5/6	3
64-QAM 1/2	$\overline{4}$
64-QAM 2/3	3
64-QAM 3/4	$\overline{2}$
64-QAM 5/6	\overline{c}
256-QAM 1/2	$\overline{3}$
256-OAM 2/3	$\overline{2}$
256-QAM 3/4	$\overline{2}$
256-QAM 5/6	1
256-OAM 7/8	1

Table 209—Concatenation index for different modulations and coding

Change Table 211 as indicated.

Table 211—Useful data payload in bytes for an FEC block

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Table 211—Useful data payload in bytes for an FEC block

9.8.1.1 Conventional QPSK and QAM

The output of the bit interleaver is entered serially to the constellation mapper. The input data to the mapper is first divided into groups of number of coded bits per carrier, i.e., N_{CBPC} bits and then converted into complex numbers representing QPSK, 16-QAM, 64-QAM, or 256-QAM constellation points. The mapping for QPSK, 16-QAM, 64-QAM, and 256-QAM is performed according to Gray-coding constellation mapping, as shown in-Figure 150, Figure 151, and [Figure AY1,](#page-178-0) respectively where b_0 represents the most significant modulation bit for all constellations.

Figure AY1—Gray Mapping for 256-QAM

Change Table 226 and Table 227 as indicated.

Table 227—Number of coded bits per OFDM slot (N_{CBPS}) and corresponding number of **data bits for different modulation constellation and coding rate combinations**

9.8.1.2 QAM with multidimensional trellis coded modulation

The output of the multidimensional trellis encoder is entered to the constellation mapper. The input data to the mapper has a group of number of coded bits per two carriers, i.e., N_{CBPC} bits and then converted into complex numbers representing 48-QAM, or 192-QAM constellation points. The mapping for 48-QAM and 192-QAM are performed according to constellation mapping, as shown in Figure YYY and ZZZ, respectively.

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9.9 Control mechanisms

9.9.4.2 Transmit Power Control mechanism

9.14 Receiver Requirements

9.14.1 Receiver minimum sensitivity

Required Signal-to-Noise Ratio = the Reference Normalized SNR as shown in [Figure 228](#page-182-0) for a BER performance of $2x10^{-4}$ where the values include 1.1 dB, 1.3 dB, 1.5 dB, and 1.7 dB decoder implementation margins for QPSK, 16-QAM, 64-QAM, and 256-QAM modulations respectively;

Table 228—Normalized CNR per modulation for BER= 2*10-4

9a. PHY (Mode 2)

This clause specifies the basic technologies for the standardization of the physical (PHY) layer for WRAN systems. The specification is for a system that uses vacant channels to provide wireless communication.

The system reference frequency is the center frequency of the channel in which the transmitter and the receiver equipment operates. Annex A lists the frequencies corresponding to the channels used for WRAN operation in various regulatory domains.

 The PHY specification is based on an orthogonal frequency division multiple access (OFDMA) scheme where information to (downstream) or from (upstream) multiple CPEs are modulated on orthogonal subcarriers using Inverse Fourier Transforms. The main system parameters are provided in Table AV1.

 The following subclauses provide details on the various aspects of the PHY specifications.

9a.1 Symbol description

9a.1.1 OFDM symbol mathematical representation

The RF signal transmitted during any OFDM symbol duration can be represented mathematically as follows:

$$
s(t) = \text{Re}\left\{e^{j2\pi f_c t} \sum_{\substack{k=-N_T/2\\k \neq 0}}^{N_T/2} c_k e^{j2\pi k \Delta f (t - T_{CP})}\right\}
$$

- *t* is the time elapsed since the beginning of the current symbol, with $0 \le t \le T$ *T* is the symbol duration, including cyclic prefix duration *Re(.)* real part of the signal *f* is the carrier frequency
- *c* is a complex number; the data to be transmitted on the subcarrier whose frequency offset index is *k*, during the current symbol. It specifies a point in a QAM constellation. Δ*f* is the subcarrier frequency spacing *T* is the time duration of cyclic prefix
- *N* is the number of used subcarriers (not including DC subcarrier)

9a.1.1.1 Time domain description

The time-domain signal is generated by taking the inverse Fourier transform of the length NFFT vector. The vector is formed by taking the constellation mapper output and inserting pilot and guard tones. At the receiver, the time domain signal is transformed to the frequency domain representation by using a Fourier transform.

Let T_{FFT} represent the time duration of the IFFT output signal. The OFDM symbol is formed by inserting a cyclic prefix of time duration T_{CP} (shown in Figure BB1), resulting in a symbol duration of $T_{SYM} = T_{FFT}$ $+T_{CP}$.

Figure BB1—OFDM symbol format

The specific values for T_{FFT} , T_{CP} and T_{SYM} are given in [9a.1.2.](#page-184-0) The BS determines these parameters and conveys the T_{CP} to T_{FFT} ratio to the CPEs using the FCH.

The time at which the FFT window starts within the symbol period for reception at the CPE is determined by the local synchronization strategy to minimize inter-symbol interference due to pre- and post-echoes and any synchronization error, and is implementation dependent.

9a.1.1.2 Frequency domain description

In the frequency domain, an OFDM symbol is defined in terms of its subcarriers. The subcarriers are classified as: 1) data subcarriers, 2) pilot subcarriers, 3) guard and null (including DC) subcarriers. The classification is based on the functionality of the subcarriers. The DS and US may have different allocations of subcarriers. The total number of subcarriers is determined by the FFT/IFFT size. The pilot subcarriers are distributed across the bandwidth. The exact location of the pilot and data subcarriers and the symbol's subchannel allocation is determined by the particular configuration used. All the remaining guard/null subcarriers carry no energy and are located at the center frequency of the channel (DC subcarrier) and at both edges of the channel (guard subcarriers).

9a.1.2 Symbol parameters

9a.1.2.1 Subcarrier spacing

 The BS and CPEs shall use the 1024 FFT mode with the subcarriers spacing specified in Table AW1. The subcarrier spacing, ΔF, is dependent on the bandwidth of the channel (6 MHz, 7 MHz, or 8 MHz). Table AW1 shows the subcarrier spacing and the corresponding $FFT/IFFT$ period (T_{FFT}) values for the different channel bandwidth options.

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9a.1.2.2 Symbol duration for different cyclic prefix modes

The cyclic prefix duration T_{CP} could be one of the following derived values: $T_{FFT}/32$, $T_{FFT}/16$, $T_{FFT}/8$, and $T_{FFT}/4$. The OFDM symbol duration for different values of cyclic prefix is given in Table AX1.

Table AX1—Symbol duration for different cyclic prefixes and bandwidth options

9a.1.2.3 Transmission parameters

Table AY1 shows the different parameters and their values for the three bandwidths.

Table AY1—OFDM parameters for the three channel bandwidths

9a.1.3 OFDMA basic terms definition

9a.1.3.1 Tile, slot and data region

In DS, a tile consists of 4 successive active subcarriers and 4 OFDM symbols as shown in Figure BC1. In US, a tile consists of 4 successive active subcarriers and 7 OFDM symbols as shown in Figure BD1.

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A slot is the minimum possible data allocation unit. A slot requires both a time and subchannel dimension. In DS, a slot consists of 16 subcarriers and 4 OFDM symbols (or 4 DS tiles) as shown in Figure BE1. In US, a tile consists of 8 subcarriers and 7 OFDM symbols (or 2 US tiles) as shown in Figure BF1

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Step 2—Map slots within the UL allocation.

- h) Map the slots so that the lowest numbered slot occupies the lowest numbered subchannel in the lowest numbered OFDMA symbol.
- i) Continue the mapping so that the subchannel index is increased. When the last subchannel is reached, continue the mapping from the lowest numbered subchannel in the next OFDMA symbol that belongs to the UL allocation. The resulting order is shown by the arrows in Figure BJ1.

Figure BJ1 illustrates the order in which OFDMA slots are mapped to subchannels and OFDMA symbols in US.

The subchannels referred to in this subclause are logical subchannels,

Figure BJ1—Example of mapping slots to subchannels and symbols in the US

9a.2 Data rates

Table AZ1 defines the different PHY modulation and encoding modes with their associated parameters along with an example of the resulting gross data rates in the case of the 6 MHz channel bandwidth.

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Table AZ1—PHY Modes and their related modulations, coding rates and data rates for $T_{CP} = T_{FFT}/16$

NOTE 1: Mode 1 is only used for CDMA opportunistic bursts.

NOTE 2: Mode 2 is only used for FCH and DRZ-FCH transmission.

NOTE 3: Spectral efficiency informative values are calculated assuming continuous stream for the given modulation and FEC modes (i.e., assuming no TTG, RTG or frame headers).

NOTE 4: These modes are for control signal transmissions and there is no need to specify data rate or spectral efficiency.

9a.3 Functional block diagram applicable to the PHY layer

 The functional block diagram of the transmitter and receiver for the PHY layer is shown in Figure BK1. This subclause describes the general processing of the WRAN baseband signal. The binary data intended for transmission is supplied to the PHY layer from the MAC layer. This input is sent to a channel coding processor which includes a data scrambler, encoder, puncturer (a bit interleaver specified in [9a.6.4](#page-211-0). The interleaved data is mapped to data constellations as described in [9a.8](#page-214-0) according to the modulation schemes specified as shown in Table AZ1. The subcarrier allocator assigns the data constellations to the corresponding subchannels according to the subcarrier allocation methods described in [9a.6.2](#page-204-0) and [9a.6.3](#page-206-0).

 A frame has its first OFDM symbol occupied by the frame preamble in [9a.4.1.1.](#page-194-0) The pilot subcarriers are IEEE

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 transmitted at fixed positions in the frequency domain within each OFDM data symbol as specified in [9a.6.1](#page-203-0). Preambles and pilots can support the synchronization, channel estimation and tracking process. In the frequency-domain, an OFDM symbol contains the data, pilot, and null subcarriers, as defined in Table AY1. The resultant stream of constellations is subsequently input to an inverse Discrete Fourier Transform after a serial-to-parallel conversion. The inverse Fast Fourier Transform (IFFT) is the expected means of performing the inverse Discrete Fourier Transform. In order to prevent inter-symbol interference (ISI) eventually caused by the channel delay spread, the OFDM symbol is extended by a cyclic prefix that contains the same waveform as the corresponding ending part of the symbol. Finally, the OFDM signal is transferred to the RF transmission modules via a digital-to-analog converter.

The OFDM receiver roughly implements the same operations as performed by the transmitter but in reverse order. In addition to the data processing, synchronization and channel estimation must be performed at the receiver.

The CBP packet can also be generated through the same process as that used for the data transmission. The CBP packet subcarrier allocation, preamble and pilot patterns are described in [9a.5.](#page-203-1)

Figure BK1—Transmitter and receiver block diagram for the OFDMA PHY

9a.4 Frame structure

The basic frame structure is shown in Figure 12. See [Figure 7.4a](#page-25-0) for a full description of the frame structure.

Each frame contains a preamble, header, and data bursts.

For both normal and self-coexistence operational modes, the first symbol shall be the frame preamble. The second to fifth symbols shall contain the FCH, and DS-MAP, US-MAP, when needed, DCD and UCD, and data bursts if there is some room left. The FCH specifies the length of the first MAP that will immediately follow the FCH.

 In each frame, a TTG shall be inserted between the downstream and upstream bursts to allow the CPE to switch between the receive mode and transmit mode and to absorb the signal propagation time. A RTG shall be inserted at the end of each frame to allow the BS to switch between its receiving mode and transmit mode

(see [Figure B1\)](#page-27-0).

The values indicated in Table BA1 for the TTG and RTG shall be used for the specified cyclic prefixes and channel bandwidth options.

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Table BA1—WRAN frame parameters

NOTE 1—Indicates the DS/US payload symbols and symbols for FCH, DS/US MAP and DCD/UCD. Here, one frame preamble symbol is assumed. Different values may apply when the frame carries more header symbols.

NOTE 2—Example of TTG set to absorb the propagation delay

NOTE 3—Portion of symbol left over to arrive at the 10 ms frame period.

9a.4.1 Preamble

9a.4.1.1 Frame preamble

The first symbol of the DS transmission is the preamble. Three different preamble carriersets are defined, differing in the allocation of subcarriers. Those subcarriers are modulated using a boosted BPSK modulation with a specific pseudo-noise (PN) code.

The preamble carrier-sets are defined using Equation (1).

 $PreambleCarrierSet_n = n + 3k$ (1)

where

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PreambleCarrierSet_n specifies all subcarriers allocated to the specific preamble

n is the designating number of the preamble carrier-set indexed 0, 1, and 2

 k is a running index. $0...283$

63 64 Each segment uses a preamble composed of a single carrier-set in the following manner:

— Segment 0 uses preamble carrier-set 0 (*n* =0).

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Table BB1—Preamble modulation series per segment and Cell ID

9a.4.1.2 CBP preamble

The CBP preamble shall have a duration of 1 OFDM symbol. The PN series modulating the CBP preamble carrier-set is defined in Table H1. The series modulated depends on the segment used and CBP ID parameter. The defined series shall be mapped onto the CBP preamble subcarriers in ascending order. Table H1 includes the PN sequence in a hexadecimal format. The value of the PN is obtained by the same manner as described in [9a.4.1.1](#page-194-0).

Table BC1—CBP Preamble modulation series per segment and Cell ID

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9a.4.2 Control header and MAP definitions

9a.4.2.2 DS-MAP, US-MAP, DCD, and UCD

9a.4.2.1 Frame control header (FCH)

The frame control header is transmitted as part of the downstream PDU in the DS subframe. The length of the FCH shall be 3 bytes and contain information as specified in Table 7.5.2a (to be described in MAC section). The FCH shall be sent in the first subchannel of the symbol immediately following the frame preamble symbol. The FCH shall be encoded using QPSK rate 1/2 with four repetitions using the binary convolutional channel coding . The FCH contains the downstream frame prefix as described in 7.5.2a (to be determined in MAC section), and specifies the length of the DS-MAP message that immediately follows the downstream frame prefix and the repetition coding used for the DS-MAP message.

 The length of the DS-MAP PDU is variable and is defined in the FCH [\(9a.4.2.1](#page-202-0)). This PDU shall be encoded using the binary convolutional channel coding specified in [9a.7.2.1](#page-212-1) and transmitted using the PHY mode 3 listed in Table AZ1 in the logical subchannel immediately following the FCH. The length of the US-MAP, DCD and UCD, when present, shall be specified at the beginning of the DS-MAP in that order. The number of subchannels required to transmit these fields shall be determined by their respective lengths in number of OFDM slots. These fields shall be transmitted using PHY mode 4. If this number exceeds the number of subchannels, the transmission of these PDUs will continue in the next slot starting with the first logical subchannel. The unused subchannels in the last slot of the frame header shall be used for DS transmissions.

The format of the CBP packet is shown in Table BM1. The CBP packet consists of a preamble portion and a data portion. The CBP preamble is one OFDM symbol in duration and is generated as described in [9a.4.1.2](#page-201-0). The format of the CBP data portion is the same as the data portion of the normal zone.

Figure BM1—CBP packet format

9a.6 OFDM subcarrier allocation

Sampling frequencies are $F_s = 5.6$ MHz, 6.53 MHz, and 7.47 MHz for the channel bandwidth of 6 MHz, 7 MHz, and 8 MHz, respectively. Subtracting the guard subcarriers from N_{FFT} (=1024), one obtains the set of used subcarriers which consists of both pilot subcarriers and data subcarriers. In the DS, the pilot subcarriers are allocated first; then data subcarriers are divided into subchannels. In the US, the set of used subcarriers is first partitioned into subchannels, and then the pilot subcarriers are allocated from within each subchannel.

9a.6.1 Pilot pattern

9a.6.1.1 Downstream (DS)

A slot (or a subchannel) in the DS is composed of four (4) OFDMA symbols and 16 subcarriers as shown in Figure BE1 Within each slot, there are 48 data subcarriers and 16 fixed-position pilots. The subchannel is constructed from four (4) DS tiles. Each tile has four successive active subcarriers, and its configuration is illustrated in Figure BN1

9a.6.1.2 Upstream (US)

A slot (or a subchannel) in the US is composed of seven (7) OFDMA symbols and 8 subcarriers as shown in Figure BF1. Within each slot, there are forty eight (48) data subcarriers and eight (8) fixed-position pilots. The subchannel is constructed from two US tiles. Each tile has four successive active subcarriers, and its configuration is illustrated in Figure BO1.

Figure BO1—Pilot pattern for US

9a.6.2 Downstream subcarrier allocation

9a.6.2.1 Symbol structure for subchannel in the downstream

The symbol structure is constructed using pilot, data, and null subcarriers. The symbol is first divided into basic tiles and null carriers are allocated. Pilot and data subcarriers are allocated within each tile. Table BD1 summarizes the parameters of the symbol structure in the downstream (DS).

Table BD1—Symbol structure parameters in the downstream (DS)

Table BD1—Symbol structure parameters in the downstream (DS)

9a.6.2.2 Subcarrier allocation and data mapping onto subcarriers

The carrier allocation to subchannels is performed using the following procedure:

- a) Subcarriers shall be divided into the number of tiles (*N_{tiles}*) containing 4 adjacent subcarriers each (starting from carrier 0). The number of tiles (N_{tiles}) in the downstream is 208.
- b) Logical tiles are mapped to physical tiles in the FFT using Equation (3).

$$
\underline{Files(s, n)} = N_{subchannels} \cdot n + (P_{t}[(s+n) \mod N_{subchannels}]+ DS_{premBase} \mod N_{subchannels}
$$
(3)

where

- *Tilessn* is the physical tile index in the FFT with tiles being ordered consecutively from the most negative to the most positive used subcarrier (0 is the starting tile index)
- $-$ *n* is the tile index $0,1,2,3$ in a subchannel
- *Nsubchannels* is the number of subchannels: 52
- *s* is the index number of a subchannel: 0…*Nsubchannels*–1
- 59 60 61 — P_t is the sequence for the downstream tile permutation shown below DS_PermBase is an integer ranging from 0 to 31, which is set to preamble Cell ID in the first zone
	- —*Pt* = {6, 48, 37, 21, 31, 40, 42, 32, 47, 30, 33, 18, 10, 15, 50, 51, 46, 23, 45, 16, 39, 35, 7, 25, 11, 22, 38, 28, 19, 17, 3, 27, 12, 29, 26, 5, 41, 49, 44, 9, 8, 1, 13, 36, 14, 43, 2, 20, 24, 4,34, 0}
	- DS PermBase is an integer ranging from 0 to 31, which is set to preamble Cell ID in the first zone.

 —Example of the logical tile mapping to the physical tile is provided below to clar- ify the operation of Equation 9.X.6.3.2-1. In this example, tiles used for subchannel $s = 2$ in DS_PermBase = 1 are computed. •Apply the permutation due to the selection of the subchannel $(s = 2)$, rotate times: {37,} 21, 31, 40, 42, 32, 47, 30, 33, 18, 10, 15, 50, 51, 46, 23, 45, 16, 39, 35, 7, 25, 11, 22, 38, 28, 19, 17, 3, 27, 12, 29, 26, 5, 41, 49, 44, 9, 8, 1, 13, 36, 14, 43, 2, 20, 24, 4,34, 0, 6, 48 }. •Take the first 4 numbers, and add the DS_PermBase (perform modulo operation if needed): {38, 22, 32, 41}. •Finally, add the appropriate shift: {38, 74, 136, 197}. c) After allocating the pilot subcarriers within each tile, indexing of the data subcarriers within each slot is performed starting from the first symbol at the lowest indexed subcarrier of the lowest indexed tile, continuing in an ascending manner through the subcarriers in the same symbol, then going to the next symbol at the lowest indexed data subcarrier, and so on. Data subcarriers shall be indexed from 0 to 47. The indexing of the data subcarriers (48 data subcarriers) in one subchannel in DS is shown in Figure BP1 subchannel **OFDM** symbol $\bigcap (42) (43) \bigcap (44) (45)$ $(40)(41)$ **Figure BP1—DS data subcarrier index in one subchannel** d) The mapping of data onto the subcarriers shall follow Equation (4). This equation calculates the sub- carrier index to which the data constellation point is to be mapped. $\frac{\text{Subcarrier}(n, s) = (n + 13 \cdot s) \text{ mod } N_{\text{subcarriers}}}{(4)}$ where $Subcarrier(n, s)$ is the permutated subcarrier index corresponding to data subcarrier. n is a running index $0...47$, indicating the data constellation point — *s* is the subchannel number 0…51 — *Nsubcarriers* is the number of data subcarriers per slot: 48 **9a.6.3 Upstream Subcarrier allocation 9a.6.3.1 Symbol structure for subchannel in the upstream** The symbol structure is constructed using pilot, data, and null subcarriers. The symbol is first divided into basic tiles and null carriers are allocated. Pilot and data subcarriers are allocated within each tile. Table BE1 summarizes the parameters of the symbol structure in the upstream (US).

Table BE1—Symbol structure parameters in the upstream (US)

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9a.6.3.2 Subcarrier allocation and data mapping onto subcarriers

The carrier allocation to subchannels is performed using the following procedure:

 a) The usable subcarriers in the allocated frequency band shall be divided into *N_{tiles}* physical tiles with parameters specified by Table BE1. The number of tiles (N_{tiles}) in the upstream is 210. b) Logical tiles are mapped to physical tiles in the FFT using Equation (5). $Tiles(s, n) = N_{subchannels} \cdot n + (P_t[(s+n) \mod N_{subchannels}]\cdot \text{US}_P$ ermBase) mod $N_{subchannels}$ (5) where — *Tilessn* is the physical tile index in the FFT with tiles being ordered consecutively from the most negative to the most positive used subcarrier (0 is the starting tile index) n is the tile index $0,1$ in a subchannel — *Nsubchannels* is the number of subchannels: 105 — *s* is the index number of a subchannel: $0...N_{subchannels}$ ⁻¹ $-\frac{P_t}{q}$ is the sequence for the upstream tile permutation shown below —*Pt* = {33, 52, 35, 67, 94, 13, 80, 6, 34, 45, 43, 68, 84, 66, 7, 37, 71, 89, 55, 101, 27, 60, 51, 14, 21, 17, 93, 72, 95, 73, 81, 24, 103, 86, 39, 29, 56, 62, 70, 64, 23, 22, 54, 15, 90, 76, 100, 33, 36, 18, 9, 91, 19, 26, 12, 92, 48, 25, 87, 74, 5, 31, 85, 40, 104, 2, 102, 69, 57, 50, 1, 44, 0, 20, 88, 79, 16, 28, 46, 42, 41, 59, 96, 97, 99, 82, 30, 49, 65, 77, 63, 11, 8, 75, 98, 38, 32, 83, 4, 47, 58, 61, 78, 10, 53} US PermBase is an integer value which is assigned by a management entity —Example of the logical tile mapping to the physical tile is provided below to clarify the operation of Equation 9.X.6.3.2-1. In this example, tiles used for subchannel $s = 3$ in US PermBase $= 2$ are computed. •Apply the permutation due to the selection of the subchannel $(s = 3)$, rotate three times: {67, 94, 13, 80, 6, 34, 45, 43, 68, 84, 66, 7, 37, 71, 89, 55, 101, 27, 60, 51, 14, 21, 17, 93, 72, 95, 73, 81, 24, 103, 86, 39, 29, 56, 62, 70, 64, 23, 22, 54, 15, 90, 76, 100, 33, 36, 18, 9, 91, 19, 26, 12, 92, 48, 25, 87, 74, 5, 31, 85, 40, 104, 2, 102, 69, 57, 50, 1, 44, 0, 20, 88, 79, 16, 28, 46, 42, 41, 59, 96, 97, 99, 82, 30, 49, 65, 77, 63, 11, 8, 75, 98, 38, 32, 83, 4, 47, 58, 61, 78,10, 53, 33, 52, 35}. •Take the first 2 numbers, and add the US_PermBase (perform modulo operation if needed): $\{69, 96\}$. •Finally, add the appropriate shift: {69, 201}. c) After allocating the pilot subcarriers within each tile, indexing of the data subcarriers within each slot is performed starting from the first symbol at the lowest indexed subcarrier of the lowest indexed tile, continuing in an ascending manner through the subcarriers in the same symbol, then going to the next symbol at the lowest indexed data subcarrier, and so on. Data subcarriers shall be indexed from 0 to 47. The indexing of the data subcarrier (48 data subcarriers) in one subchannel in US is shown in Figure BQ1.

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1 2 3 48 data sequence for subchannel 1 4 5 1718192021222324252627 6 7 8 subchannel 9 10 OFDM symbol symbol0 11 \circ $\mathbf 1$ $2 \nightharpoonup$ $\overline{\mathbf{3}}$ 12 symbol1 $\mathbf{4}$ $\overline{5}$ $\left[9\right]$ (10) (11) 6 $\bf 8$ 13 14 symbol2 $\left(13\right)$ (14) (15) (17) (18) (19) (12 (16) 15 16 symbol3 (20 (21) (22) (23) (24) (25) (26) (27) 17 (30) (31) symbol4 (28) (29) (32) (33) (34) 35 18 19 (37) (38) (39) (40) (41) symbol5 (36) (42) $\left[43\right]$ 20 21 $\left(44\right)$ (45) (46) (47) symbol6 22 23 24 for subchannel 1 ($s = 1$), the first data constellation point ($n = 0$) 25 is mapped onto Subcarrier($0,1$) = 13 26 27 28 29 **Figure BR1—Example of data mapping onto subcarrier (***s***=1,** *n***=0)** 30 31 32 Similarly, for subchannel 3, the ninth data constellation point $(n = 8)$ is mapped onto *Subcarrier* (8, 33 3) =47. According to step a), this is the last indexed subcarrier of the seventh symbol within the slot. 34 35 36 37 38 48 data sequence for subchannel 3 39 40 41 42 43 subchannel 44 45 OFDM symbol symbol0 46 $\mathbf{0}$ $\mathbf 1$ $\mathbf{2}^{\prime}$ $\left(3\right)$ 47 symbol1 $\begin{bmatrix} 7 \end{bmatrix}$ ໌8 48 $\overline{4}$ $\overline{5}$ $\left[6\right)$ ່ງ່ (10) (11) 49 symbol2 $\left(14\right)$ (18) (12) (13) (15) (16) (17) (19) 50 51 (24) (25) (26) $\left(27\right)$ symbol3 (20) (21) (22) (23) 52 53 (28 (31) (32) (34 $\left[35\right]$ symbol4 (29 (30) (\$3 54 (38) (39) (40) (41) symbol5 55 (36) (37) (42 $\left[43\right]$ 56 $\left(44\right)$ (46) (45) (47) symbol6 57 58 59 for subchannel 3 ($s = 3$), the ninth data constellation point ($n = 8$) 60 is mapped onto Subcarrier(3,8) = 47 61 62 63 64 **Figure BS1—Example of data mapping onto subcarrier (***s***=3,** *n***=8)**65

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9a.6.3.3 Data subchannel rotation scheme

In the upstream, a rotation scheme shall be applied per OFDMA slot duration. On each slot duration, the rotation scheme shall be applied to all US subchannels that belong to the normal data burst. The rotation scheme is defined by applying the following rules:

- a) Per OFDMA slot duration, pick the subchannels that are used for the normal data burst. Renumber these subchannels contiguously so that the lowest numbered physical subchannel is renumbered with 0. The total number of subchannels picked shall be designated N_{subchn} .
- b) The mapping function defined by rule a) shall define a function, *f*, so that temp1 subchannel_number = f (old_subchannel_number).
- c) Mark the first US OFDMA slot duration with the slot index $S_{\text{idx}} = 0$. Increase S_{idx} by 1 in every slot duration so that subsequent slots are numbered 1, 2, 3..., etc.
- d) Apply the following formula:
- $\frac{\text{temp2}}{\text{subchannel}}$ mumber = (temp1_subchannel_number + 13× S_{idx}) mod N_{subchn}
- e) To get the new subchannel number, apply the following formula:
- new subchannel number = f^{-1} (temp2 subchannel number), where f^{-1} (.) is the inverse mapping of the mapping defined in rule b).
- f) For subchannels that are used for control burst (for the UIUC value less than 14), new_subchan $nel number = old subchannel number.$
- g) The new subchannel number shall replace the old subchannel number in each allocation defined by [9a.1.3.2](#page-189-0) data mapping where the new_subchannel_number is the output of the rotation scheme and the old subchannel number is the input of the rotation scheme.

9a.6.4 Bit interleaving

All encoded data bits shall be interleaved by a block interleaver with a block size corresponding to the number of coded bits per the encoded block size N_{cbps} (Possible values of N_{cbps} for each MCS are spedified later.) The interleaver is defined by a two-step permutation. The first ensures that adjacent coded bits are mapped onto nonadjacent subcarriers. The second permutation insures that adjacent coded bits are mapped alternately onto less or more significant bits of the constellation, thus avoiding long runs of lowly reliable bits.

Let *N_{cpc}* be the number of coded bits per subcarrier, i.e., 2, 4, or 6 for QPSK, 16-QAM, or 64-QAM, respectively. Let $s = N_{\text{cpc}}/2$. Within a block of N_{cbps} bits at transmission, let *k* be the index of the coded bit before the first permutation, m_k be the index of that coded bit after the first and before the second permutation and let j_k be the index after the second permutation, just prior to modulation mapping, and *d* be the modulo used for the permutation.

The first permutation is defined byEquation (7):

$$
m_k = (N_{\text{cbps}}/d) \cdot k_{\text{mod}(d)} + \text{floor}(k/d) \ k = 0, 1, \ \dots, N_{\text{cbps}} - 1d = 16 \tag{7}
$$

The second permutation is defined by Equation (8).

 $j_k = s \cdot \text{floor}(m_k/s) + (m_k + N_{\text{cbps}} - \text{floor}(d \cdot m_k/N_{\text{cbps}}))_{mod(s)} \&= 0, 1, ..., N_{\text{cbps}} - 1 \, d = 16$ (8)

62 63 64 65 The de-interleaver, which performs the inverse operation, is also defined by two permutations. Within a received block of N_{cbps} bits, let *j* be the index of a received bit before the first permutation; m_j be the index of that bit after the first and before the second permutation; and let k_j be the index of that bit after the second permutation, just prior to delivering the block to the decoder.

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$$
\underline{m_i} = s \cdot floor(j/s) + (j + floor(d \cdot j/N_{\text{cbps}}))_{mod(s)} \underline{j} = 0, 1, ..., N_{\text{cbps}} - 1 \underline{d} = 16 \tag{9}
$$

The second permutation is defined by Equation (10).

 $k_j = d \cdot m_j - (N_{\text{cbps}} - 1) \cdot f (N_{\text{cbps}} - d \cdot m_j / N_{\text{cbps}}) j = 0, 1, ..., N_{\text{cbps}} - 1 d = 16$ (10)

The first permutation in the de-interleaver is the inverse of the second permutation in the interleaver, and conversely.

9a.7 Channel coding

9a.7.2 Forward Error Correction (FEC)

9a.7.2.1 Binary Convolutional code (BCC) mode (mandatory)

9a.7.2.1.3 OFDM slot concatenation

The encoding block size shall depend on the number of OFDMslots allocated and the modulation specified for the current transmission. Concatenation of a number of OFDM slots shall be performed in order to allow for transmission of larger blocks of coding where it is possible, with the limitation of not exceeding the largest block size for the corresponding modulation and coding. Table BF1 specifies the concatenation index for different modulations and coding.

For any modulation and coding, the following parameters are defined:

- *j* : index dependent on the modulation level and FEC rate
- *n* : number of allocated OFDM slots
- k : floor (n / j)
- $m : n \mod j$

Table BG1 shows the rules used for OFDM slot concatenation.

Table BF1—Concatenation index for different modulations and coding

Table BF1—Concatenation index for different modulations and coding

Table BG1—OFDM slot concatenation rule

Table BH1defines the basic sizes of the useful data payloads (in bytes) to be encoded in relation with the selected modulation type, encoding rate, and concatenation rule.

Table BH1—Useful data payload for an FEC Block

9a.8 Constellation mapping and modulation

9a.8.1 Data modulation

9.8.1 provides the details of data modulation. Table 227 in 9.8.1 is changed as Table BI1.

Table BI1—Number of coded bits per OFDM slot (*N***CBPS) and corresponding number of data bits for different modulation constellation and coding rate combinations**

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Table BI1—Number of coded bits per OFDM slot (*N***CBPS) and corresponding number of data bits for different modulation constellation and coding rate combinations**

9a.9 Control mechanisms

9a.9.3 Opportunistic upstream bursts

A ranging channel is composed of one or more groups of six adjacent subchannels, using the symbol structure defined in [9a.6.3.1,](#page-206-1) where the groups are defined starting from the first subchannel. Subchannels are considered adjacent if they have successive logical subchannel numbers. The indices of the subchannels that compose the ranging channel are specified in the US-MAP message. BS shall allocate ranging, bandwidth (BW) request or UCS notification allocation as a multiple of subchannels.

9a.9.3.1 CDMA bursts

The number of subchannels for the ranging channel and the number of symbols for each transmission (CDMA initial ranging, CDMA periodic ranging, CDMA BW request and CDMA UCS notification) are specified in the US-MAP_IE.

CPEs are allowed to collide on the ranging channel. To still provide reliable transmission, each CPE randomly chooses one ranging code from the subgroup of specified binary codes that is defined in [9a.9.3.1.1](#page-215-0). These codes are then BPSK modulated onto the subcarriers in the ranging channel. The length of these binary codes is the same as the number of subcarriers in the ranging channel.

9a.9.3.1.1 CDMA codes

The binary codes shall be the pseudo-noise codes produced by the PRBS generator described in Figure BT1, which illustrates the following polynomial generator: $1 + x^1 + x^4 + x^7 + x^{15}$. The PRBS generator shall be initialized by the seed b15...b1 = 0,0,1,0,1,0,1,1,s0,s1,s2,s3,s4,s5,s6 where s6 is the LSB of the PRBS seed, and s6:s0=US_PermBase, where s6 is the MSB of the US_PermBase.

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 transmissions). Each CDMA code shall be transmitted at the beginning of the corresponding slot. See

 Figure BY1 IEEE

13.1.1.1 Pilot allocation for 2 antennas

 In the case of two (2) transmit BS antennas, the DS data allocation to tile is changed [\(Figure BZ1\)](#page-220-1) to accommodate two antennas transmission for channel estimation. [Figure BZ1](#page-220-1) replaces Figure BN1 in [9a.6.1.1](#page-203-0) when MIMO is enabled.

Figure CC1—US tile structure for 4 TX antennas

13.2 Space Time Coding (STC)

13.2.1 Transmit diversity using 2 antennas (Alamouti O-STBC)

TBD

13.2.2 Transmit Diversity with Array-Interference Gain

The technique disclosed in this subsection is full rate based on array-interference constructive aggregation. Its objective is to improve the link reliability over conventional transmit diversity, i.e., Space-Time Block Codes (STBC). This technique intentionally creates aligned array interference so as to exploit its energy in the form of added array gain. As a result, the overall gain (diversity gain + array gain) reduces the bit-error probability (BEP) as compared to the diversity gain only yielded by conventional STBC [1], [2] based systems.

13.2.2.1 Transmit Diversity with Array-Interference Gain for 2 antennas

 In this subsection we describe the structure of a 2 transmit (TX) antennas $(n_t = 2)$ transmit diversity TDD system exploiting transmit array interference. Since the system is based on TDD, both transmitter and receiver operate in the same frequency channel, however, in different time-slots. In addition, in a communication system, transmitter and receiver alternate their roles, i.e., the transmitter in time " T_n " is the receiver in the consecutive time " T_{n+1} ". A direct consequence of the aforementioned, is that both transmitter and receiver can estimate the wireless channel **H** during the time in each they are acting as receiver.

 The vector $H = [h_1, h_2]$ represents the multiple-input-single-output (MISO) channel between the base station and the single antennae receiver (RX) white space device. In the analyses presented hereafter, **H** is considered to be quasi-static.

 Symbols vectors are transmitted through **H** and noise is added at the receiver as shown in Fig. 1. The transmitter is composed of two blocks, namely, 'array gain maximization' and 'transmit vector selector'. On

 $arg max(I_{Am}), \forall m \in \{0,1\}$ *m*

in order to compare all the I_{Am} and selects the one that has the maximum value.

Following, the "array gain maximization" block at the transmitter sends *m* inherent to the maximum array interference to the "transmit vector selector" block, which selects G_m to be transmitted over the channel H <u>since G_m will yield the maximum array gain. In addition, "the array gain maximization" block at the receiver</u> sends the index *m*, in binary, to the 'combiner' block, which is collocated in the same RX device. For instance, if $m = 1$ ', the 'combiner' block will utilize the weight w_1 , when it receives the signal from TX.

The 'combiner block' provides symbol estimate to the 'maximum likelihood (ML) detector' block.

Array Gain Maximization Block

In the array gain maximization block, the array interference I_{Am} is stored as a function of **H**.

— Array Interference I_{A0} $I_{A0} = h_1^* h_2 + h_1 h_2^*$

— Array Interference I_{A1}

$$
I_{A1}=-h_1^*h_2-h_1h_2^*
$$

In order to select the most aligned interference, the 'array gain maximization' block performs

$$
\arg\max_{m}(I_{Am}), \forall m \in \{0,1\}
$$

The 'array gain maximization' block at the TX directly sends *m* to the collocated 'transmit vector selector' while the 'array gain maximization' block at the receiver sends *m* to the collocated 'combiner block'. For the following implementation examples consider that *m* is represented by 3 bits.

Combiner Block

Let $H = [\mathbf{h}_1 \ \mathbf{h}_2]$ and ^{*T*} denotes transpose operation and *n*, the zero-mean additive white Gaussian noise (AWGN).

 $-$ If the 'combiner' block receives $m = 000$ from the 'array gain maximization' block, the received signal is

 $y = G_0 \cdot H^T + n$

The combiner, then, utilizes

$$
w_0 = [1\;1]
$$

for the combination. However, for the specific case of $m = 000$, multiplying vector w_m is not necessary and left here for illustration purposes only. The 'combiner' block performs the following combination,

$$
\begin{array}{ll}\n56 & \overline{S} & \overline{S} & \overline{S} \\
57 & \overline{S} & \overline{S} & \overline{S} \\
58 & \overline{S} & \overline{S} & \overline{S} \\
59 & \overline{S} & \overline{S} & \overline{S} \\
60 & \overline{S} & \overline{S} & \overline{S} \\
61 & \overline{S} & \overline{S} & \overline{S} \\
62 & \overline{S} & \overline{S} & \overline{S} \\
63 & \overline{S} & \overline{S} & \overline{S} \\
64 & \overline{S} & \overline{S} & \overline{S} \\
65 & \overline{S} & \overline{S} & \overline{S} \\
66 & \overline{S} & \overline{S} & \overline{S} \\
67 & \overline{S} & \overline{S} & \overline{S} \\
68 & \overline{S} & \overline{S} & \overline{S} \\
69 & \overline{S} & \overline{S} & \overline{S} \\
61 & \overline{S} & \overline{S} & \overline{S} \\
62 & \overline{S} & \overline{S} & \overline{S} \\
63 & \overline{S} & \overline{S} & \overline{S} \\
64 & \overline{S} & \overline{S} & \overline{S} \\
65 & \overline{S} & \overline{S} & \overline{S} \\
67 & \overline{S} & \overline{S} & \overline{S} \\
68 & \overline{S} & \overline{S} & \overline{S} \\
69 & \overline{S} & \overline{S} & \overline{S} \\
61 & \overline{S} & \overline{S} & \overline{S} \\
62 & \overline{S} & \overline{S} & \overline{S} \\
63 & \overline{S} & \overline{S} & \overline{S} \\
64 & \overline{S} & \overline{S} & \overline{S} \\
65 & \overline{S} & \overline{S} & \overline{S} \\
67 & \overline{S} & \overline{S} & \overline{S} \\
68 & \overline{S} & \overline{S} & \overline{S} \\
69 & \overline{S} & \overline{S} & \overline{S} \\
61 & \overline{S} & \overline{S} & \overline{S} \\
62 & \overline{S
$$

.

65 which is, then, passed to the MML detector to perform the symbol estimation.

 $\frac{1}{\text{If the 'combiner' block receives m = 001, then}}$ The combiner, then, utilizes yielding, $y = G_1 \cdot H^T + n$ $w_1 = [1 -1]$ $\widetilde{S} = yH^* \cdot w_1^T$ $\tilde{\mathbf{S}}$ = \mathbf{S} \mathbf{L}^* \mathbf{L}^* 1^{\prime} ¹2 $\tilde{S} = y[h_1^* h_2^*] \begin{pmatrix} 1 \\ -1 \end{pmatrix}$ $\tilde{S} = S(|h_1|^2 + |h_2|^2) + S(-h_1^*h_2 - h_1h_2^*) + nh_1^* - nh_2^*$

This is, then, passed to the MML detector to perform the symbol estimation.

13.2.2.2 Transmit Diversity with Array-Interference Gain for 4 antennas

Array Gain Maximization Block

In the case of 4 TX antennas, there are eight unique G_m together with their respective I_{Am} as well as w_m , m $\in \{0,1,2,3,4,5,6,7\}.$

$$
I_{A0} = h_{1}^{*}h_{2} + h_{1}h_{2}^{*} + h_{1}^{*}h_{3} + h_{1}h_{3}^{*} + h_{1}^{*}h_{4} + h_{1}h_{4}^{*} + h_{2}^{*}h_{3} + h_{2}h_{3}^{*} + h_{2}^{*}h_{4} + h_{2}h_{4}^{*} + h_{3}^{*}h_{4} + h_{3}h_{4}^{*}
$$
\n
$$
I_{A1} = -h_{1}^{*}h_{2} - h_{1}h_{2}^{*} - h_{1}^{*}h_{4} - h_{1}h_{4}^{*} - h_{2}^{*}h_{3} - h_{2}h_{3}^{*} - h_{3}^{*}h_{4} - h_{3}h_{4}^{*} + h_{1}^{*}h_{3} + h_{1}h_{3}^{*} + h_{2}^{*}h_{4} + h_{2}h_{4}^{*}
$$
\n
$$
I_{A2} = -h_{1}^{*}h_{3} - h_{1}h_{3}^{*} - h_{1}^{*}h_{4} - h_{1}h_{4}^{*} - h_{2}h_{3}^{*} - h_{2}h_{3}^{*} - h_{2}h_{4}^{*} - h_{2}h_{4}^{*} + h_{1}^{*}h_{2} + h_{1}h_{2}^{*} + h_{3}^{*}h_{4} + h_{3}h_{4}^{*}
$$
\n
$$
I_{A3} = -h_{1}^{*}h_{2} - h_{1}h_{2}^{*} - h_{1}^{*}h_{3} - h_{1}h_{3}^{*} - h_{2}h_{4}^{*} - h_{2}h_{4}^{*} - h_{2}h_{4}^{*} - h_{3}h_{4}^{*} - h_{3}h_{4}^{*} - h_{3}h_{4}^{*} + h_{1}^{*}h_{4} + h_{1}h_{4}^{*} + h_{2}^{*}h_{3} + h_{2}h_{3}^{*}
$$
\n
$$
I_{A4} = -h_{1}^{*}h_{4} - h_{1}h_{4}^{*} - h_{2}h_{4}^{*} - h_{2}h_{4}^{*} - h_{3}h_{4}^{*} - h_{3}h_{4}^{*} - h_{3}h_{4}^{*} + h_{1}^{*}h_{
$$

In order to select the most aligned interference, the 'array gain maximization' block performs,

 $arg max(I_{Am}), \forall m \in \{0, 1, 2, 3, 4, 5, 6, 7\}$ I_{Am} , $\forall m \in$

m

 The 'array gain maximization' block at the transmitter sends *m* to the 'transmit vector selector' block collocated at the transmitter while the 'array gain maximization' block at the receiver sends *m* to the 'combiner' block collocated at the receiver.

Transmit Vector Selector Block

Transmit $G_0 = [S \ S \ S \ S]$ if *m* is '000'; Transmit $G_1 = [s - s s - s]$ if *m* is '001'; Transmit $G_2 = [s \ s - s - s]$ if *m* is '010'; Transmit $G_3 = [S - S - S S]$ if *m* is '011'; Transmit $G_4 = [S \ S \ S \ S - S]$ if *m* is '100';

Transmit $G_5 = [S \ S - S \ S]$ if m is '101';

Transmit $G_6 = [S - S S S]$ if *m* is '110';

 $\frac{1}{\text{Transmit}} G|_{7} = [-s \ s \ s \ s] \underbrace{\text{if } m \text{ is '111'}};$

Combiner Block

.

Let $H = [\mathbf{h}_1 \ \mathbf{h}_2 \ \mathbf{h}_3 \ \mathbf{h}_4]$ and for the sake of simplicity in the example, the channel estimation be perfect, i.e.,

 $H = H$

 $-$ If the 'combiner' block receives $m = 000$ from the 'array gain maximization' block, it utilizes

 $w_0 = [11111]$ to perform the combination

$$
\frac{\tilde{S} = yH^* \cdot w_0^T}{\tilde{S} = y[h_1^*h_2^*h_3^*h_4^*]\begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}}
$$
\n
$$
\frac{\tilde{S} = S(|h_1|^2 + |h_2|^2 + |h_3|^2 + |h_4|^2) + S(h_1^*h_2 + h_1h_2^* + h_1^*h_3 + h_1^*h_4 + h_1^*h_4^* + h_2^*h_3 + h_2h_3^*}{h_1^*h_4 + h_2h_4^* + h_3^*h_4 + h_3h_4^* + h_1^*h_4^* + h_2^*h_3 + h_1^*h_4^* + h_1^*h_4^* + h_2^*h_4^* + h_3^*h_4^* + h_3^*h_4^* + h_3^*h_4^* + h_3^*h_4^* + h_4^*h_5^* + h_4^*}
$$

which is, then, passed to the MML detector to perform the symbol estimation.

If the 'combiner' block receives $m = 001$ from the 'array gain maximization' block, it utilizes ¹ *w* [1 -1 1 -1]

$$
W_1 = [1 - 1 - 1 - 1]
$$
 and performs the following combination.

 $\widetilde{S} = yH^* \cdot w_1^T$

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$$
\tilde{S} = y[h_1^*h_2^*h_3^*h_4^*]\begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}
$$
\n
$$
\tilde{S} = S([h_1]^2 + |h_2|^2 + |h_3|^2 + |h_4|^2) + S(-h_1^*h_2 - h_1h_4^* - h_1h_4^* - h_2^*h_3 - h_2h_3^* - h_2^*h_4^* - h_3^*h_4^* - h_1^*h_3^* + h_1h_3^* + h_2^*h_4^* + h_2h_4^* + h_2h_4^* + h_3h_4^* + h_3h_4^* + h_3h_4^* + h_1h_3^* - h_1h_4^* - h_1h_4^* - h_1h_4^* - h_1h_4^* - h_2h_3^* - h_2h_3^* - h_1^*h_4^* - \frac{\text{If } \text{the 'complex force}}{\text{if } \text{the 'complex force}}}{\text{if } \text{the 'complex force}} = 010 \text{ from the 'array gain maximumization' block, it utilizes}
$$
\n
$$
\frac{S}{S} = y[h_1^*h_2^*h_3^*h_4^* \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix}
$$
\n
$$
\tilde{S} = S([h_1]^2 + |h_2|^2 + |h_3|^2 + |h_4|^2) + S(-h_1^*h_3 - h_1h_3^* - h_1^*h_4 - h_1h_4^* - h_2^*h_3^* - h_2^*h_3^* - h_2^*h_4^* - h_2
$$

$$
\vec{S} = \frac{1}{2} \left(\frac{h_1^2 h_2^2 h_3^2 h_4^2 \right) \left(\frac{1}{1} \right)}{\hat{S} = S(\left| h_1 \right|^2 + \left| h_2 \right|^2 + \left| h_3 \right|^2 + \left| h_4 \right|^2) + S(-h_1^2 h_4 - h_1 h_4^2 - h_2^2 h_4 - h_2 h_4^2 - h_3^2 h_4 - h_1 h_4^2 + h_1^2 h_2 + h_1 h_2^2
$$
\n
$$
+ h_1^2 h_3 + h_1 h_3^2 + h_2 h_3 + h_2 h_3^2) + nh_1^2 + nh_2^2 + nh_3^2 - nh_4^2
$$
\nwhich is, then, passed to the MML detector to perform the symbol estimation.\n
$$
= \frac{\left[\text{the 'combine'} \text{ block receives } m = 101 \text{ from the 'array gain maximization' block, it utilizes}\right]}{\hat{S} = \frac{1}{2} \left(\frac{1}{1} \right)^2 \left(\frac{1}{1} \right)^2 \left(\frac{1}{1} \right)^2}
$$
\n
$$
\vec{S} = \frac{1}{2} \left(\frac{h_1^2 h_2^2 h_3^2 h_4^2 \right) \left(\frac{1}{1} \right)^2 \left(\frac{1}{1} \right)^2 \left(\frac{1}{1} \right)^2 \left(\frac{1}{1} \right)^2 \left(\frac{1}{1} \right)^2
$$
\n
$$
\vec{S} = \frac{1}{2} \left(\frac{h_1^2 h_2^2 h_3^2 h_4^2 \right) \left(\frac{1}{1} \right)^2 \left(\frac{1}{1} \right)^2
$$
\n
$$
\vec{S} = \frac{1}{2} \left(\frac{h_1^2 h_2^2 h_3^2 h_4^2 \right) \left(\frac{1}{1} \right)^2 \left(\frac{1}{1} \right)^2 \left(\frac{1}{1} \right)^2 \left(\frac{1}{1} \right)^2 \left(\frac{1}{
$$

$$
\tilde{S} = y[h_1^*h_2^*h_3^*h_4^*]\begin{pmatrix} -1 \\ 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}
$$

$$
\tilde{S} = S(|h_1|^2 + |h_2|^2 + |h_3|^2 + |h_4|^2) + S(-h_1^*h_2 - h_1h_2^* - h_1^*h_3 - h_1h_3^* - h_1^*h_4 - h_1h_4^* + h_2^*h_3 + h_2h_3^*
$$

$$
\overline{h_2^*h_4 + h_2h_4^* + h_3^*h_4 + h_3h_4^*} - nh_1^* + nh_2^* + nh_3^* + nh_4^*
$$

The above procedure describes how to obtain diversity added with array gain for systems with multiple antennas at the transmitter, however, with single antenna at the receiver. Bellow, extension to system configuration consisting of multiple receiving antennas is presented.

If more than one antenna is available in the receiver terminal, maximum ratio combining (MRC) can be utilized to significantly enhance link reliability. For simplicity, in the following example consider that the number of antennas available at the receiver is 2. The technique, however, can be utilized for any number of receive antennas.

In order to use MRC, little modification is necessary to what has been presented. The 'Array Gain Maximization' block, now, performs

$$
\arg \max(I_{4m}+I_{4m}), \forall m \in \{0,1\}
$$

for 2 TX antennas, and

m

$$
\underbrace{\arg\max_{m}(I_{Am}+I^{'}_{Am}), \forall m \in \{0,1,2,3,4,5,6,7\}}_{m}
$$

for 4 TX antennas. Here, I_{Am} is the array interference in the first RX antenna, given in the previous sections and I'_{Am} represents the array interferences in the second RX antenna. Since the channel to the second RX antenna is given by $H = [h_3 \ h_4]$, for two TX antennas, and $H = [h_5 \ h_6 \ h_7 \ h_8]$, for 4 TX antennas, Γ_{Am} becomes

 $I_{A0} = h_3^* h_4 + h_3 h_4^*$ $I_{A1} = -h_3^* h_4 - h_3 h_4^*$

or

$$
I_{A0} = h_{5}^{*}h_{6} + h_{5}h_{6}^{*} + h_{5}^{*}h_{7} + h_{5}h_{7}^{*} + h_{5}^{*}h_{8} + h_{5}h_{8}^{*} + h_{6}^{*}h_{7} + h_{6}h_{7}^{*} + h_{6}^{*}h_{8} + h_{6}h_{8}^{*} + h_{7}^{*}h_{8} + h_{7}h_{8}^{*}
$$
\n
$$
I_{A1} = -h_{5}^{*}h_{6} - h_{5}h_{6}^{*} - h_{5}^{*}h_{8} - h_{5}h_{8}^{*} - h_{6}^{*}h_{7} - h_{6}h_{7}^{*} - h_{7}^{*}h_{8} - h_{7}h_{8}^{*} + h_{5}^{*}h_{7} + h_{5}h_{7}^{*} + h_{6}^{*}h_{8} + h_{6}h_{8}^{*}
$$
\n
$$
I_{A2} = -h_{5}^{*}h_{7} - h_{5}h_{7}^{*} - h_{5}^{*}h_{8} - h_{5}h_{8}^{*} - h_{6}^{*}h_{7} - h_{6}h_{7}^{*} - h_{6}^{*}h_{8} - h_{6}h_{8}^{*} + h_{5}^{*}h_{6} + h_{5}h_{6}^{*} + h_{7}^{*}h_{8} + h_{7}h_{8}^{*}
$$
\n
$$
I_{A3} = -h_{5}^{*}h_{6} - h_{5}h_{6}^{*} - h_{5}^{*}h_{7} - h_{5}h_{7}^{*} - h_{6}^{*}h_{8} - h_{6}h_{8}^{*} - h_{7}^{*}h_{8} - h_{7}h_{8}^{*} + h_{5}^{*}h_{8} + h_{5}h_{8}^{*} + h_{5}h_{7}^{*} + h_{6}h_{7} + h_{6}h_{7}^{*}
$$
\n
$$
I_{A4} = -h_{5}^{*}h_{8} - h_{5}h_{8}^{*} - h_{6}^{*}h_{8} - h_{6}h_{8}^{*} - h_{7}^{*}h_{8} - h_{7}h_{8}^{*} + h_{5}^{*}h_{6} + h_{5}h_{6}^{*} + h_{5}^{*}h_{7} +
$$

$$
\frac{I_{A6} = -h_{5}^{*}h_{6} - h_{5}h_{6}^{*} - h_{6}^{*}h_{7} - h_{6}h_{7}^{*} - h_{6}^{*}h_{8} - h_{6}h_{8}^{*} + h_{5}h_{7} + h_{5}h_{7}^{*} + h_{5}h_{8}^{*} + h_{7}h_{8} + h_{7}h_{8}^{*}}{I_{A7} = -h_{5}^{*}h_{6} - h_{5}h_{6}^{*} - h_{5}^{*}h_{7} - h_{5}h_{7}^{*} - h_{5}^{*}h_{8} - h_{5}h_{8}^{*} + h_{6}h_{7}^{*} + h_{6}h_{7}^{*} + h_{6}h_{8}^{*} + h_{7}h_{8} + h_{7}h_{8}^{*}}
$$

The 'array gain maximization' block at the transmitter sends *m* to the collocated 'transmit vector selector' block while the 'array gain maximization' block at the receiver sends *m* to the collocated 'combiner block'. The 'combiner block' will combine the received signal, just as described in the previous sections, in order to The 'combiner block' will combine the received signal, just as described in the previous sections, in deliver $S + S'$ to the ML detector. Note that S is given in the previous sections and S is given by

.

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$$
\widetilde{\mathbf{S}}' = \mathbf{y}' H^* \cdot \mathbf{w}_m^T
$$

with y' being the signal received by the second RX antenna and $H = [h_3 h_4]$, for 2TX, or $H = [h_5 h_6 h_7 h_8]$, for 4 TX.

The technique described above is full rate and yields full spatial diversity added to antenna array gain thus yielding better link reliability.

13.2.3 Spatial multiplexing

13.2.3.1 Spatial multiplexing using 2 antennas

TBD

13.2.3.2 Spatial multiplexing using 4 antennas

TBD

13.2.4 Relaying

13.2.4.1 Relaying for 2 antennas

TBD

13.2.4.2 Relaying for 4 antennas

TBD

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