

Project: IEEE P802.15 Working Group for Wireless Personal Area Networks (WPANs)

Submission Title: [A PHY proposal for PAC operating in synchronous mode (ppt)]

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Re: [In response to call for proposals to TG8]

Abstract: [This document contains a PHY proposal for PAC operating in synchronous mode]

Purpose: [Materials for Proposal in 802.15.8 TG]

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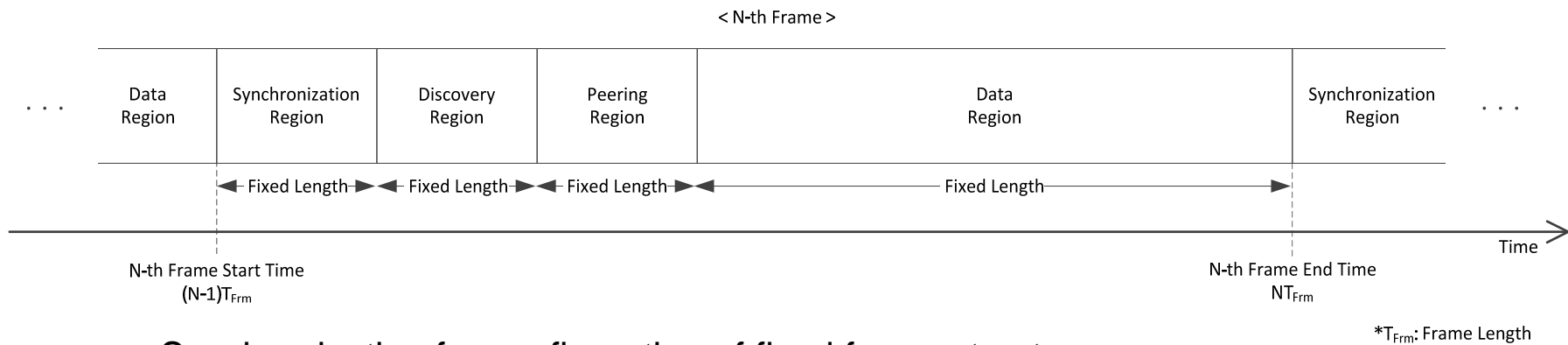
Proposal outline

- In May, we presented a preliminary example in licensed bands for PAC in synchronous mode.
 - The presentation(DCN: 15-13-0273-00-0008) covered both PHY and MAC for PAC in licensed bands operates in synchronous mode
- In July, we propose both PHY and MAC in unlicensed bands for PAC in synchronous mode.
 - DCN 15-13-0391-00-0008 or the latest version: Overview of proposal (ppt)
 - DCN 15-13-0393-00-0008 or the latest version: PHY proposal (This document)
 - DCN 15-13-0390-00-0008 or the latest version: MAC proposal (ppt)
 - DCN 15-13-0392-00-0008 or the latest version: Proposal details (doc)

PHY Overview

Fixed and Sectionized Frame Structure

- PAC Operation with fixed and sectionized frame structure to meet PAC requirement
 - A large number of devices
 - High spectral efficiency
 - Low signaling overhead
 - Power saving



- Synchronization for configuration of fixed frame structure
 - Fully distributed synchronization scheme known as firefly synchronization

Coexistence Methodology

- Coexistence criteria
 - Avoidance of conflict between different kinds of devices
 - Prevention of exclusive resource occupancy of specific kinds of devices
 - No critical impact each other between different kinds of devices

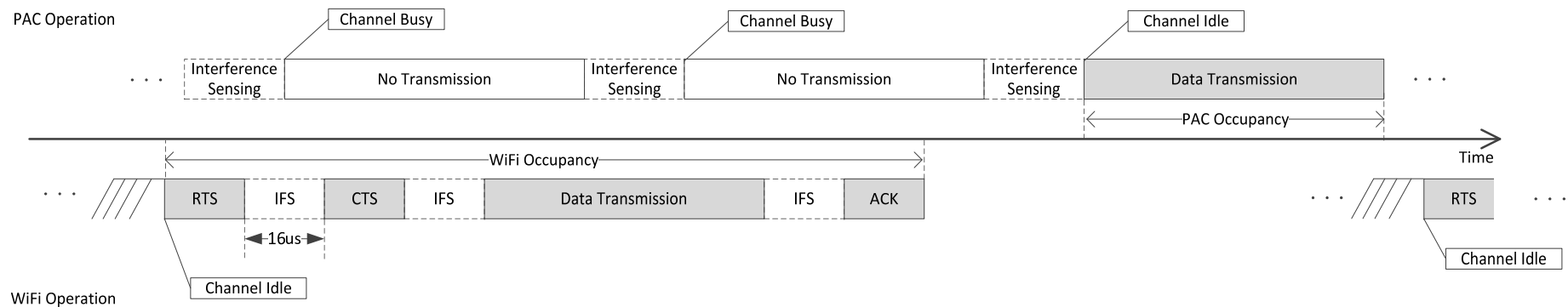
- Coexistence policy: Concession, Preoccupancy and low power transmission
 - Concession
 - if other devices are using a resource, PDs give up the transmission
 - Implemented by *'Interference Sensing'*

 - Preoccupancy
 - Before transmission, PDs conduct prior occupancy of a resource
 - Implemented by *'Blocking Signal'*

 - *'Low power transmission'*
 - If the transmit power is sufficiently low, PDs can use any resource whenever PDs need it
 - To guarantee the presences of essential control signal (i.e. synchronization) at the fixed position, this scheme can be applied
 - For reliability of the transmitted signal, time domain repetition can be applied

Interference Sensing

- Basic coexistence scheme using interference sensing
 - If other devices are using a resource, PDs give up the transmission
 - Recommended interference sensing interval: Short IFS interval(16us) of WiFi or longer

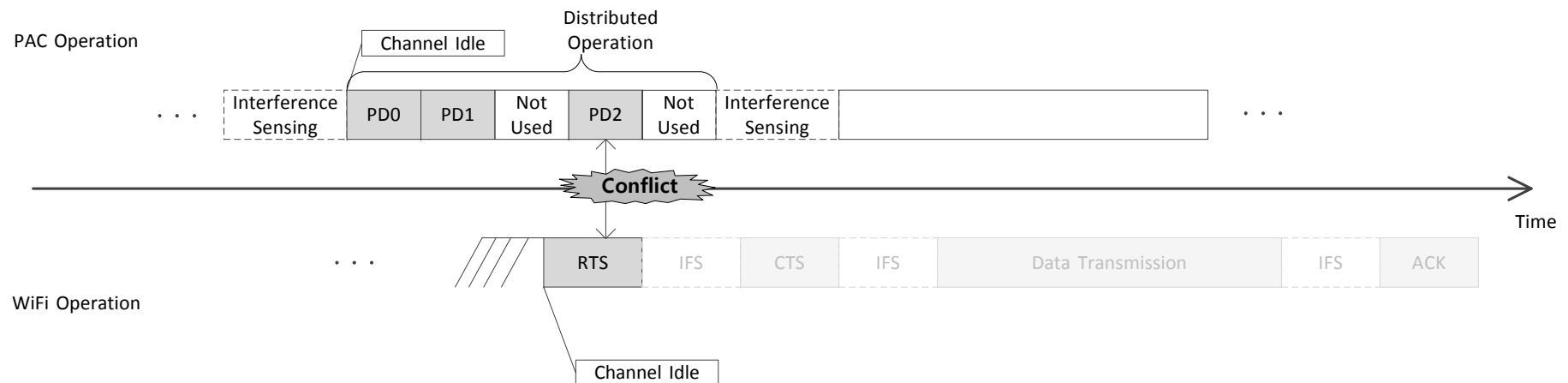


- Applied throughout the frame

Blocking Signal

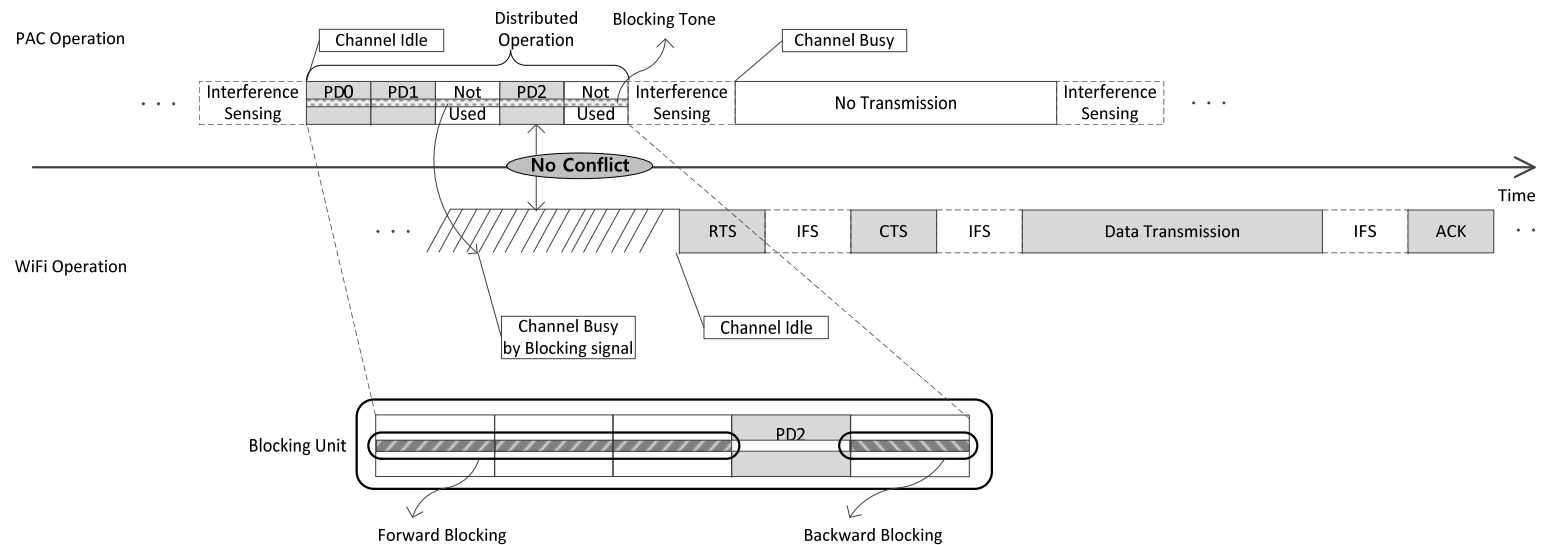
- Issue

- Because of the fully distributed operation of PAC devices, there may be some unused resources
- In this case, other kinds of devices can try to occupy the resources, even though the PAC devices already begin the data transmission after interference sensing



Blocking Signal

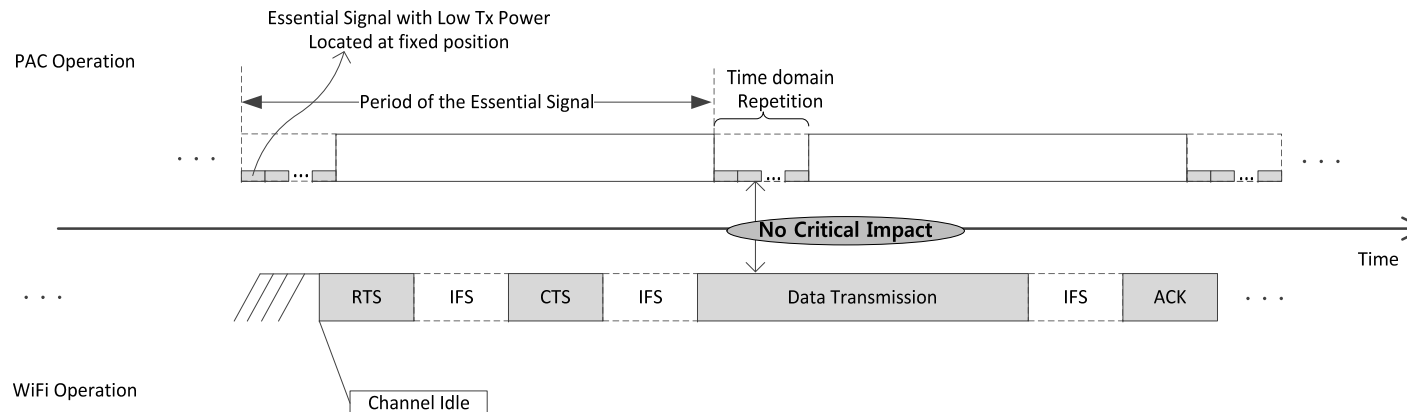
- Blocking scheme
 - To prevent resource occupancy of different kinds of devices, Blocking signal can be transmitted by PAC devices which is going to use the resource within a blocking unit
 - Blocking unit
 - Size of the resource which PAC devices want to reserve prior to different kinds of devices
 - Consist of multiple resource blocks for multiple PAC devices but not too long
 - One or more subcarriers can be allocated for transmission of blocking signal
 - PAC devices can transmit the blocking signal, before data transmission(Forward Blocking) and after data transmission(Backward Blocking)



- Applied to control(Discovery, Peering, Scheduling) signal transmission

Low Power Transmission

- Issue
 - There are important signal which need to be always presence at fixed position such as synchronization signal
 - In the basic operation based on the interference sensing, the presence of the essential signal cannot be guaranteed
- Low power transmission scheme
 - Essential control signal is always transmitted at the fixed position regardless of the different kinds of devices
 - To minimize inference between different kinds of device, the essential signal is transmitted with low power
 - To enhancement reliability of the signal, it is repeatedly transmitted in time domain

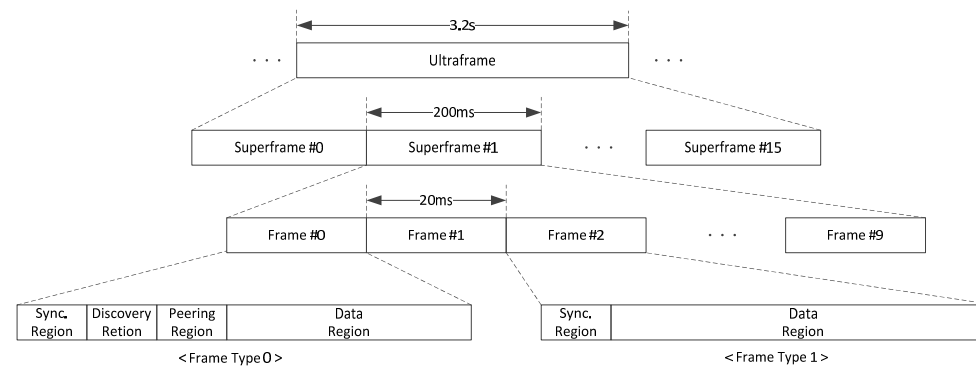


- Applied to synchronization preamble transmission

PHY Proposals

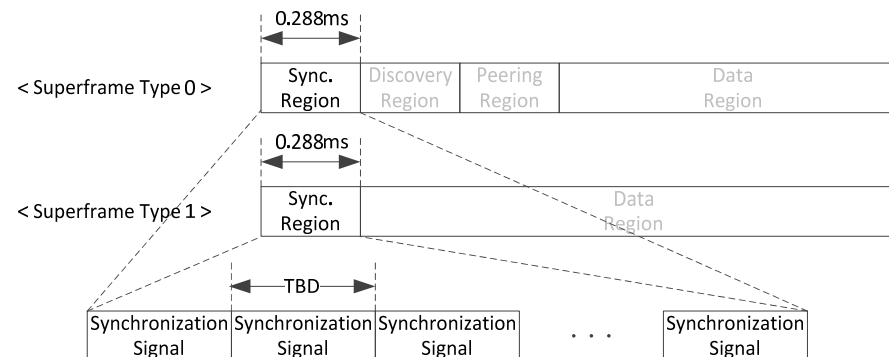
Frame Structure

- Ultraframe
 - Consist of 16 superframes
- Superframe
 - Consist of 10 frames
- Frame
 - Consist of Synchronization, Discovery, Peering and Data region
 - Two kinds of frame: Type 0 and Type 1
 - Type 0 is used if frame number is 0
 - Type 1 is used Otherwise



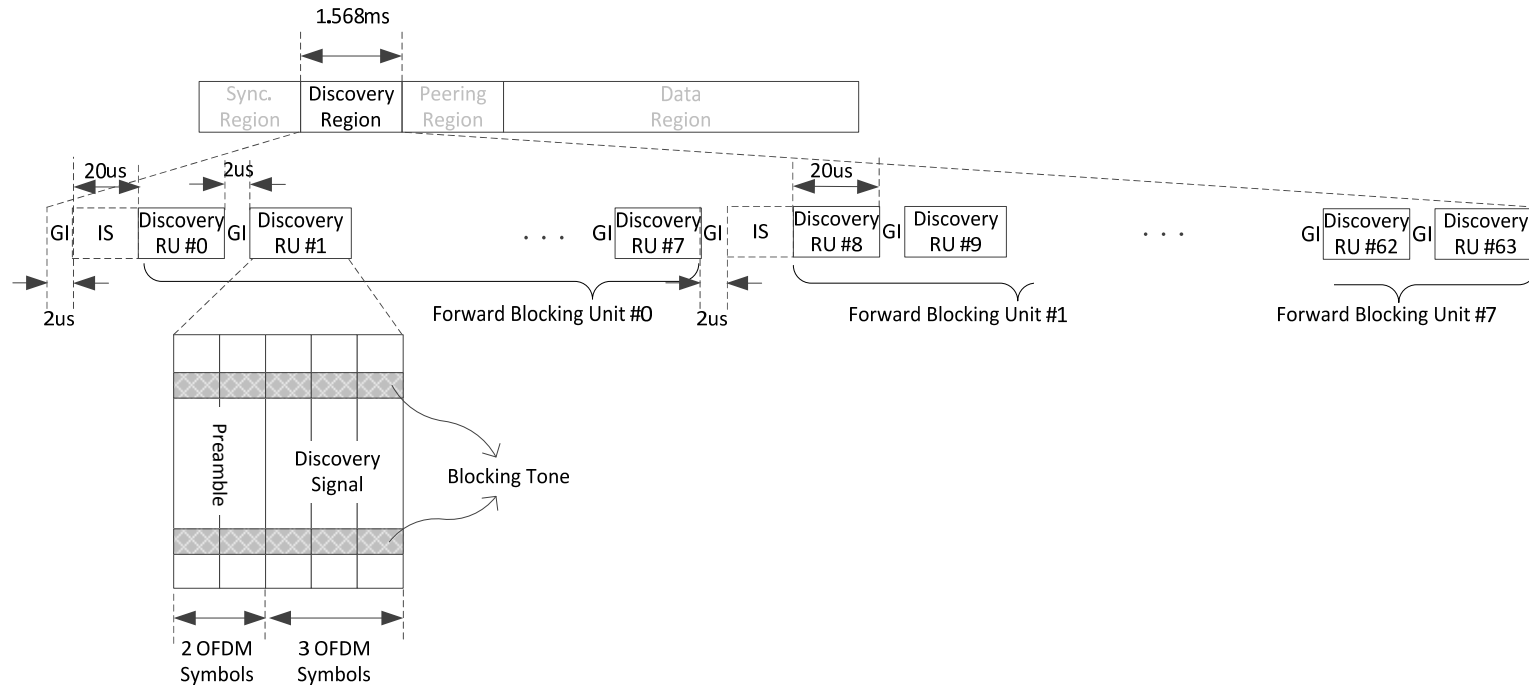
Synchronization Region

- Located at the head of a frame
- Conduct distributed synchronization procedure by transmitting or receiving synchronization signal during the synchronization region
- Synchronization signal can be transmitted whenever PDs need it, regardless of the difference kinds of devices
 - Low power transmission scheme is applied
 - Synchronization preamble is transmitted repeatedly([TBD] times) for reliability of synchronization
 - Transmit power is [TBD] deboosted
- Two kinds of synchronization signals are used to distinguish start of ultraframe



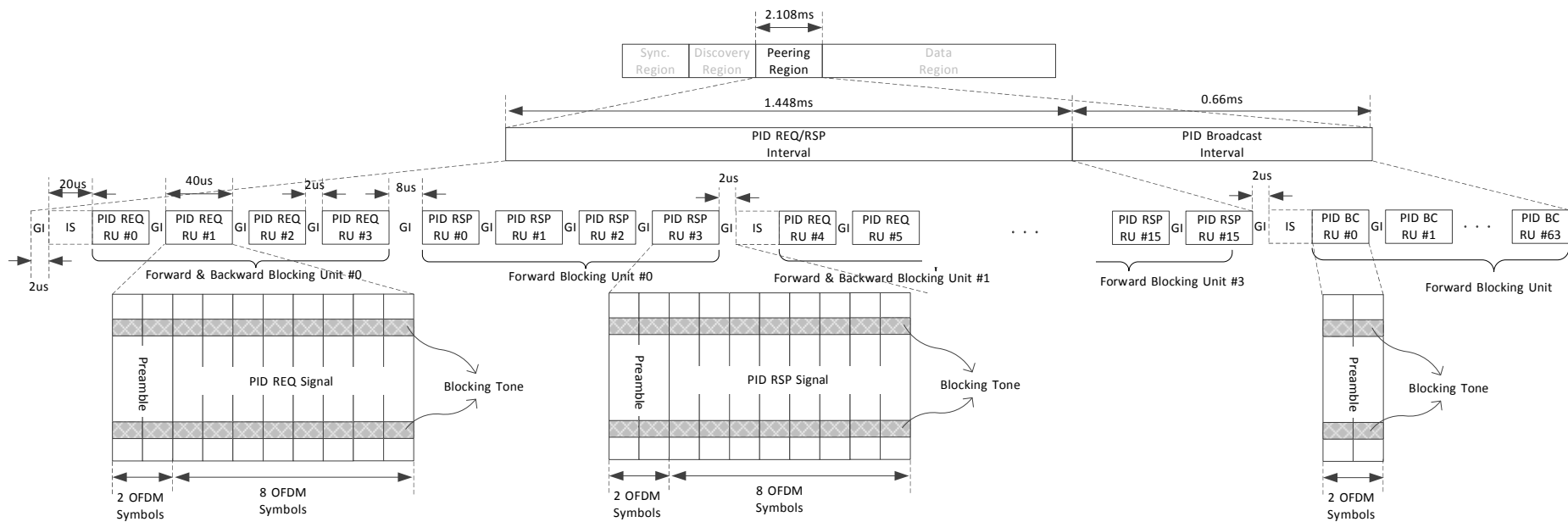
Discovery Region

- Consist of IS, GI, Preamble and Discovery signal
 - IS: Interference Sensing
 - GI: Transition time, Propagation delay and Synchronization error
 - Preamble: AGC, Timing and Frequency Sync. and Channel estimation
 - Discovery Signal: Payload(61 bits) + CRC (8bits)



Peering Region

- Consist of IS, GI, PID REQ/RSP interval and PID broadcasting interval
 - IS: Interference Sensing
 - GI: Transition time, Propagation delay and Synchronization error
 - Preamble: AGC, Timing and Frequency Sync. and Channel estimation
 - PID REQ signal: Payload(176 bits) + CRC (8 bits)
 - PID RSP signal: Payload(176 bits) + CRC (8 bits)
 - PID Broadcast RU: only preamble for indication of used PID

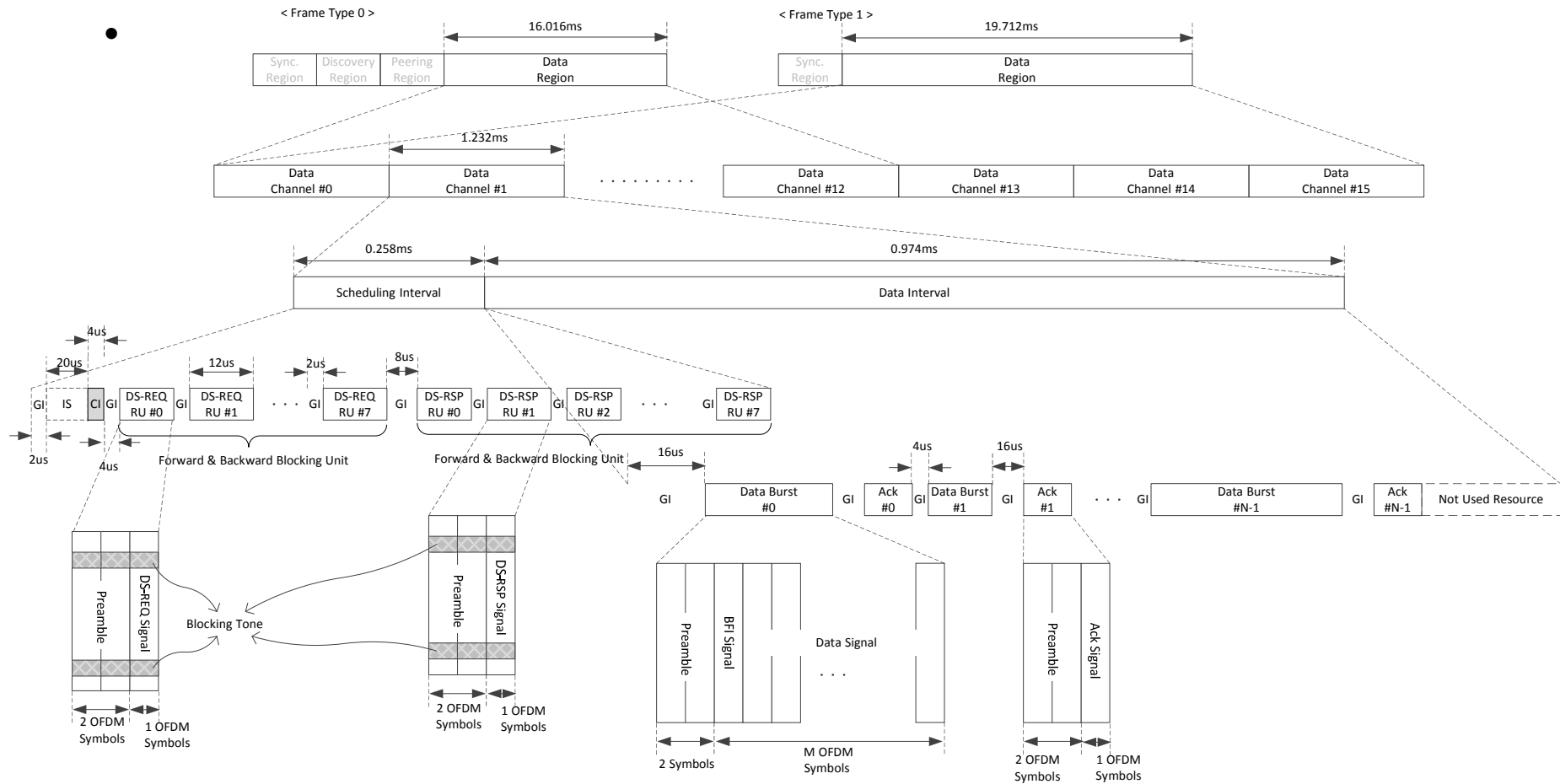


Data Region

- Consist of IS, CI, GI, DS-REQ/RSP Interval and Data Interval
 - IS: Interference Sensing
 - CI: Contention Indicator
 - GI: Processing delay, Transition time, Propagation delay and Synchronization error
 - Preamble: AGC, Timing and Frequency Sync. and Channel estimation
 - DS-REQ Signal: Payload(15 bits) + CRC (8 bits)
 - DS-RSP Signal: Payload(15 bits) + CRC (8 bits)
 - BFI (Burst Format Indicator): MCS Index (7 bits) + Length (10 bits) + Parity (1 bits) + Reserved (6 bits)
 - Data Signal: Payload(variable bits) + CRC (8 bits)
 - Ack Signal: Payload(15 bits) + CRC (8 bits)

- Distributed scheduling
 - Multiple pairs of data burst and Ack can be allocated
 - The number of pair and burst size depend on the result of the distributed scheduling

Data Region



Conclusion

Conclusion

- PAC operation with fixed and sectionized frame structure to meet PAC requirement
- Fully distributed operation and synchronization
- Signaling resource
 - 1024 Discovery per 3.2 sec => up to 1024 PDs / 3.2s
 - 128 PIDs broadcasting per 0.8 sec => up to 256 active PDs
 - 16 PID REQ and RSP per 0.2 sec => average 29.6 paring / s
- Signaling overhead: 26.5%
 - Interference sensing + CI + GI + Synchronization + Discovery + Peering + Scheduling + Ack + Preamble + BFI
- Consideration of coexistence
 - Interference sensing, blocking signal and low power transmission