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| Title | **Human body key point data format for Mixed Reality Motion Recognition** |
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| Source(s) | **Yoon, Kyoungro**  yoonk@konkuk.ac.kr **(Konkuk Univ.)****Bae, Hyo Chul**  th1q@nate.com **(Konkuk Univ.)****Jeong, Sangkwon Peter** ceo@joyfun.kr **(JoyFun Inc.)****Nam, HyeonWoo** hwnam@dongduk.ac.kr **(Dongduk Women’s University)** |
| Re: |  |
| Abstract | This standard defines an interface that the basis for the transfer of human body keypoint information between applications in virtual reality and users in the physical world. |
| Purpose | The purpose of this standard is a body keypoint data format for transferring user body keypoint information from the physical world to the virtual world. |
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Human body key point data format for Mixed Reality Motion Recognition

1. Coverage

This standard is applied to a system using human body key point. Human body key point format is composed of environmental information' and 'key point information'.

1. Human body key point data format
	1. Introduction



(Figure 1) Various systems using human body key point



(Figure 2) Human pose estimation

Human body key point is used in various systems that recognize human motion, such as sign language recognition, home training, and abnormal behavior detection, as shown in (Figure 1). Human body key point generally extracts human body key point information through various methods through RGB camera or depth camera sensor, as shown in (Figure 2). However, each of these pose estimation methods differ in the image size, coordinate system, and number of body key points. (Table 1) shows the number of body key points according to each human pose estimation method.

(Table 1) Number of body key points in human pose estimation method



If a standard for the format of human body key point data extracted through various human pose estimation techniques is established, human body key point data required in mixed reality applications can be utilized in various application software regardless of the extraction tool.

This proposal intends to establish a standard for the representation of human body key point information extracted through various posture estimation techniques for systems using human body key points.

* 1. Structure of Human body key point data format

The human body key point data format consists of an 'environmental information' and a 'key point information' as shown in (Figure 3).

The 'environmental information' consists of image size, coordinate system (world coordinate system, camera coordinate system, pixel coordinate system, normalized coordinate system) and camera calibration information such as extrinsic parameter and intrinsic parameters.

The 'key point information' consists of the location of the user's key points, connection information between key points, and the type of key points.



(Figure 3) Human body key point data format structure

* + 1. Environmental information

| Name | Definition | Unit | Value Type |
| --- | --- | --- | --- |
| Image Size | Describe the width and height of the image size used for human pose estimation. | Pixel | Integer |
| Coordinate system | Describe the four coordinate systems.Select one of the world coordinate system, camera coordinate system, normal coordinate system, and pixel coordinate system. | - | String |
| Camera Calibration | Describes the transformation relationship between 3D spatial coordinates and 2D image coordinates, or a parameter describing the transformation relationship | - | - |
|  Extrinsic parameter | Describes the transformation relationship between the camera coordinate system and the world coordinate system. | - | - |
|  Rotation | Describes the rotation between the camera coordinate system and the world coordinate system. |  | Matrix (float) |
|  Translation | Describes the origin of the world coordinate system expressed in the coordinates of the camera-centered coordinate system. |  | Matrix (float) |
|  Intrinsic parameters | Parameter for obtaining the projected position on the image or restoring the 3D spatial coordinate from the image coordinate | - | - |
|  Focal length (fx, fy) | Describe the distance between the center of the lens and the image sensor (CCD, CMOS, etc.). | Pixel | Float |
|  Principal point (cx, cy) | Describe the position of the center(pinhole) of the camera lens. | Pixel | Float |
|  Skew coefficient | Describe the distortion coefficient between the x-axis and y-axis of the image sensor. | Degree | Float |

* + 1. Key point information

|  |  |  |  |
| --- | --- | --- | --- |
| Name | Definition | Unit | Value Type |
| Key point type | Describe list of names and numbers of available key points. |  | Array (String) |
| Key point location | Describe the location of key points.For 2D key points, X, Y are described, and for 3D key points, X, Y, Z are described. | pixel | Array (Integer) |
| Key point connection | Describes connection information between key points. |  | Array (Integer) |

1. summary

Human body key point data format is used in various systems that recognize human motion, such as sign language recognition, home training, and abnormal behavior detection. Human body key point generally extracts human body key point information through various methods through RGB camera or depth camera sensor. However, each of these pose estimation methods differ in the image size, coordinate system, and number of body key points. This proposal intends to establish a standard for the representation of human body key point information extracted through various posture estimation techniques for systems using human body key points.