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| Re: |  |
| Abstract | This contribution illustrates the JSON schema structure for representing input device data in the physical world in a standardized data format. The semantics and examples of the input device data are presented. |
| Purpose | To start discussion on purpose of the standard |
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# Introduction

This contribution illustrates the JSON schema structure for representing input device data in a standardized data format in the physical world. The semantics and examples of the input device data are presented.

# Input device sensor data

## Button sensor

### General

This subclause specifies a sensor data type, which describes a button sensor.

### Syntax

|  |
| --- |
| "buttonSensorData": {  "type": "object",  "properties": {  "messageTime": {  "$ref": "#/definitions/messageTimeType"  },  "button": {  "type": "number"  },  "state": {  "type": "boolean"  }  },  "additionalProperties": false  }, |

### Semantics

The semantics of the buttonSensor:

|  |  |
| --- | --- |
| Name | Definition |
| buttonSensorData | Tool for describing button sensor data |
| messageTime | Describes sensor data acquisition time refer to messageTimeType |
| button | It describes the number of the button (numbered from zero). |
| state | Describes the current state of the button(True = on, False = off) |

### Examples

This example describes that the 7th button is on.

|  |
| --- |
| {  “sensedInfoBaseAttributes”: {},  “buttonSensorData”: {  “button”: 7,  “state”: true  }  } |

## Analog sensor

### General

This subclause specifies a sensor data type, which describes an analog sensor.

### Syntax

|  |
| --- |
| "analogSensorData": {  "type": "object",  "properties": {  "messageTime": {  "$ref": "#/definitions/messageTimeType"  },  "numberOfChannels": {  "type": "number"  },  "channel": {  "type": "array",  "items": {  "type": "number"  }  }  },  "additionalProperties": false  }, |

### Semantics

The semantics of the analogSensor:

|  |  |
| --- | --- |
| Name | Definition |
| analogSensorData | Tool for describing the analog sensor data. |
| messageTime | It describes sensor information acquisition time refer to messageTimeType |
| numberOfChannels | It describes the number of channels. |
| channel | It describes analog data for each channel. It is repeated as many as the number of channels. |

### Examples

In this example, there are four channels. Analog data are 10, 12, 14, 16.

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| --- |
| {  “sensedInfoBaseAttributes”: {},  “analogSensorData”: {  “numberOfChannels”: 4,  “channel”: [10, 12, 14, 16]  }  } |

## Dial sensor

### General

This subclause specifies a sensor data type, which describes a dial sensor.

### Syntax

|  |
| --- |
| "dialSensorData": {  "type": "object",  "properties": {  "messageTime": {  "$ref": "#/definitions/messageTimeType"  },  "dial": {  "type": "number"  },  "change": {  "type": "number"  }  },  "additionalProperties": false  }, |

### Semantics

The semantics of the dialSensor:

|  |  |
| --- | --- |
| Name | Definition |
| dialSensorData | Tool for describing the dial sensor data. |
| messageTime | It describes sensor information acquisition time refer to messageTimeType |
| dial | It describes the number of the dial sensor. |
| change | It describes the fraction of a revolution it changed in a clock-wise |

### Examples

In this example, the 4th dial rotated 13.3 degrees.

|  |
| --- |
| {  “sensedInfoBaseAttributes”: {},  “dialSensorData”: {  “dial”: 3,  “change”: 13.3  }  } |

## Haptic sensor

### General

This subclause specifies a sensor data type, which describes a haptic sensor.

### Syntax

|  |
| --- |
| "hapticSensorData": {  "type": "object",  "properties": {  "messageTime": {  "$ref": "#/definitions/messageTimeType"  },  "force": {  "$ref: "#/definitions/float3DVectorType"  },  "position": {  "$ref: "#/definitions/float3DVectorType"  },  "quaternion": {  "$ref: "#/definitions/float4DVectorType"  }  },  "additionalProperties": false  }, |

### Semantics

The semantics of the hapticSensor:

|  |  |
| --- | --- |
| Name | Definition |
| dialSensorData | Tool for describing the haptic sensor data. |
| messageTime | It describes sensor information acquisition time refer to messageTimeType |
| force | It describes a sense of force in the three-axis direction from the force sensor (x, y, z). |
| position | It describes the position of the surface contact point of the virtual object (x, y, z). |
| quaternion | It describes a quaternion of the surface contact point of the virtual object (x, y, z, w). |

### Examples

In this example, the measured force from (30, 24, 10) is [10, 20, 30]

|  |
| --- |
| {  “sensedInfoBaseAttributes”: {},  “hapticSensorData”: {  “force”: [10, 20, 30],  "position": [30, 24, 10]  }  } |