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| Source(s) | Sang-Kyun Kim, [goldmunt@gmail.com](mailto:goldmunt@gmail.com) (Myongji University)  Kyoungro Yoon, [yoonk@konkuk.ac.kr](mailto:yoonk@konkuk.ac.kr) (Konkuk University)  Sangkwon Jeong, [ceo@joyfun.kr](mailto:ceo@joyfun.kr) (Joyfun) |
| Re: |  |
| Abstract | Location sensors like a compass, a gyro, an accelerometer, GPS are the basic sensors for acquiring the position and posture information of the physical world objects, and the data through them are important information for determining the characteristics and motion of cyber objects in the cyber world. This contribution proposes a schema for defining sensor data input from location-related sensors. |
| Purpose | To start discussion on purpose of the standard |
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# Introduction

Location sensors like a compass, a gyro, an accelerometer, GPS are the basic sensors for acquiring the position and posture information of the physical world objects, and the data through them are important information for determining the characteristics and motion of cyber objects in the cyber world. This contribution proposes a schema for defining sensor data input from location-related sensors.

# Schema for location sensor data

## Compass sensor

### Syntax of compass sensor data format

    "compassSensorType": {

      "type": "object",

      "properties": {

        "azimuth": {

          "type": "number",

          "minimum": 0,

          "maximum": 360

        },

        "unit": {

          "$ref": "#/definitions/unitType"

        }

      },

      "additionalProperties": false

    },

figure 1. Schema for compass sensor

Figure 1 shows the data schema of a compass sensor. The compass sensor has *azimuth* and *unit* values as properties. The *azimuth* value is a value between 0 and 360. The *unit* is a property that represents the unit of azimuth, referring to unitType.

### Example of compass sensor data instance

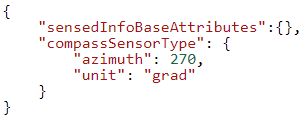


figure 2. Example of compass sensor data JSON instance

Figure 2 shows the JSON instance of the compass sensor. azimuth is 270 and the unit is grad (gradian).

## Orientation sensor

### Syntax of orientation sensor data format

    "orientationSensorType": {

      "type": "object",

      "properties": {

        "orientation": {

          "type": "array",

          "items": {

            "type": "number",

            "minItems": 3,

            "maxItems": 3

          }

        }

      }

    },

figure 3. Schema for orientation sensor

Figure 3 shows the data schema of the orientationSensor. Represents yaw, pitch, and roll. You must represent all three values by setting *minItems* and *maxItems* to 3.

### Example of orientation sensor data instance

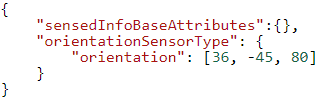


figure 4. Example of orientation sensor data JSON instance

Figure 4 shows an example JSON instance of an orientationSensor. Orientation has yaw, pitch, and roll values of 36, -45, and 80, respectively.

## Position sensor

### Syntax of position sensor data format

    "positionSensorType": {

      "type": "object",

      "properties": {

        "position": {

          "$ref": "#/definitions/float3DVectorType"

        },

        "unit": {

          "$ref": "#/definitions/unitType"

        }

      }

    },

figure 5. Schema for position sensor

Figure 5 shows the data schema of positionSensor. The 3D value of the position sensor is described in meters (m). The coordinate origin is the position of the object detected when the sensor is activated.

### Example of position sensor data instance



figure 6. Example of position sensor data JSON instance

Figure 6 shows the JSON instance of positionSensor. The sensor sensed that it moved 20 meters in the x direction, 20 meters in the y direction, and 1 meter in the z direction.

## Distance sensor

### Syntax of distance sensor data format

    "distanceSensorType": {

      "type": "object",

      "properties": {

        "value": {

          "type": "number"

        },

        "unit": {

          "$ref": "#/definitions/unitType"

        }

      }

    },

figure 7. Schema for distance sensor

Figure 7 shows the data schema of the distanceSensor. The value indicates the distance from the target in meters.

### Example of distance sensor data instance

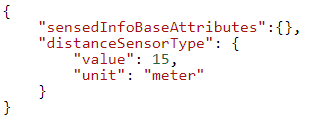


figure 8. Example of distance sensor data JSON instance

Figure 8 shows the JSON instance of the distanceSensor. The distance from the distanceSensor to the object is 15 meters.

# Conclusion

It is recommended to adopt the JSON-based schema proposed in this contribution as the location-related sensor data schema of IEEE 2888.1. In addition, it is recommended to improve the data schema in the future by adding location-related sensor data information actually used in the industry.