

# Positive Feedback, Negative Feedback

## *A closer look at phase margin*

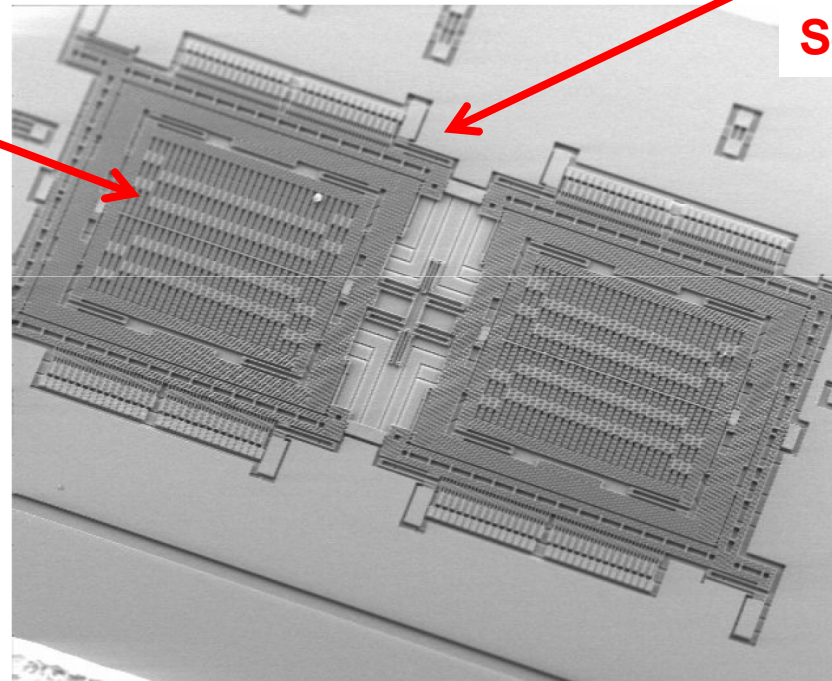
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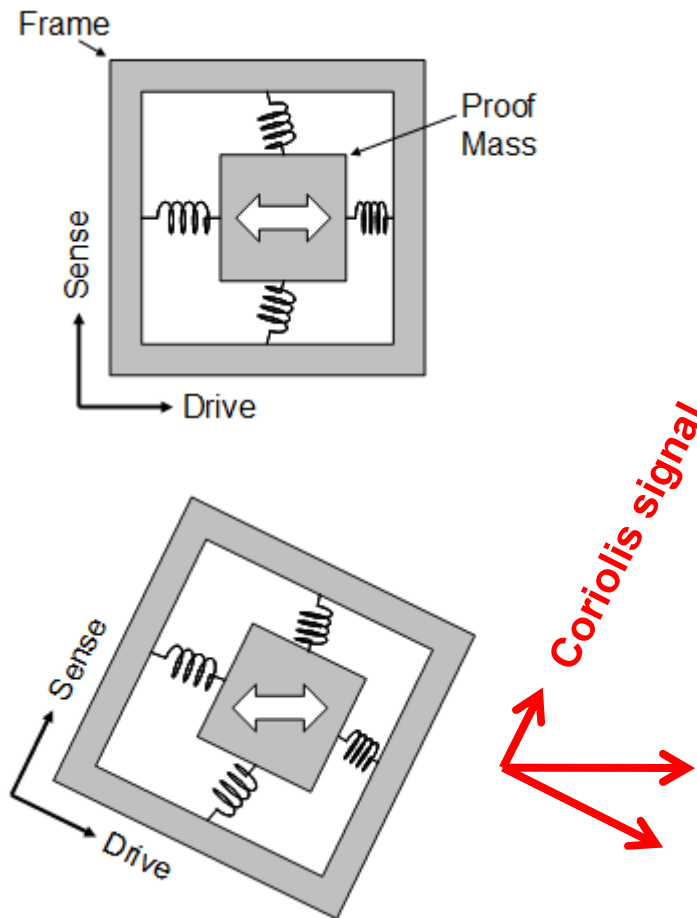
# MEMS Gyroscope

Electrostatic  
Drive



Electrostatic  
Sense Pickup

# Vibratory Gyroscope

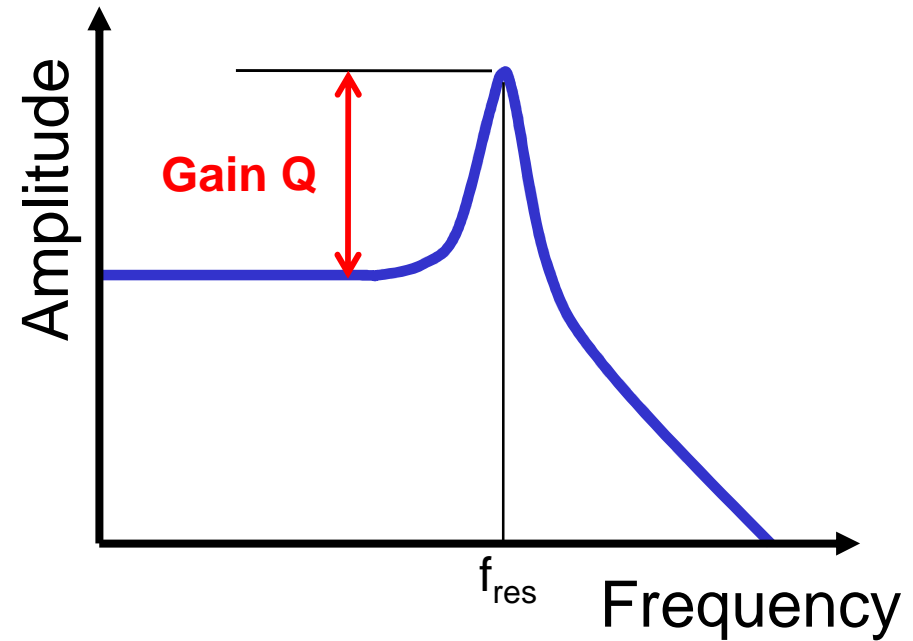
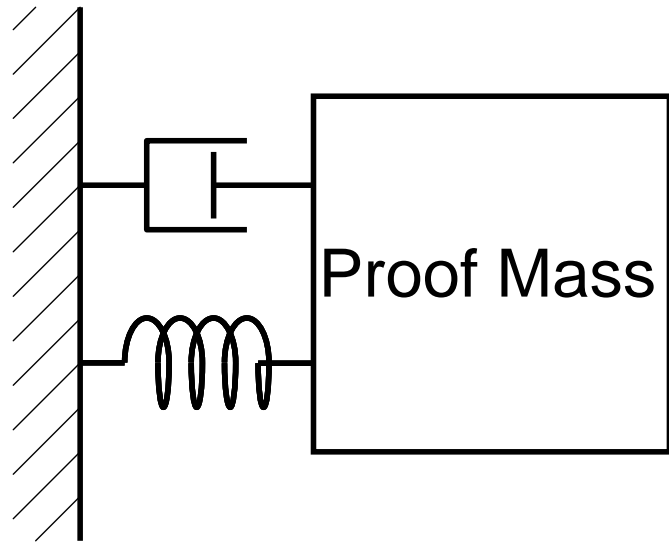


- Vibrate along drive axis with **oscillator @  $f_{\text{drive}}$**

- Detect vibration @  $f_{\text{drive}}$  about sense axis with **accelerometer**

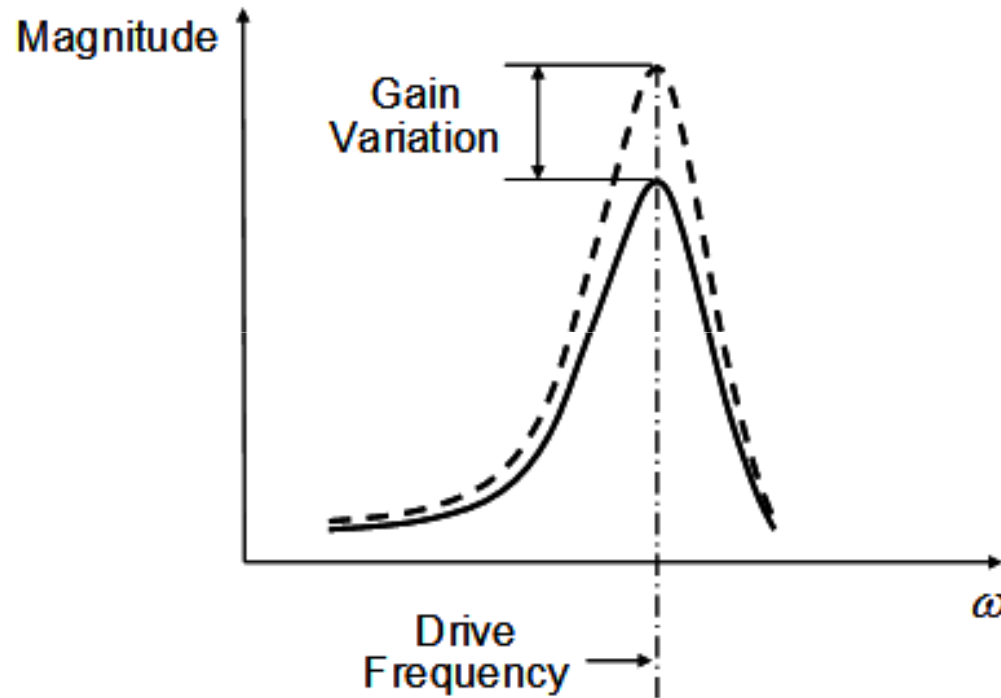
$$x \cong \frac{1}{4000} \text{ Angstrom}$$

# Operation at Resonance



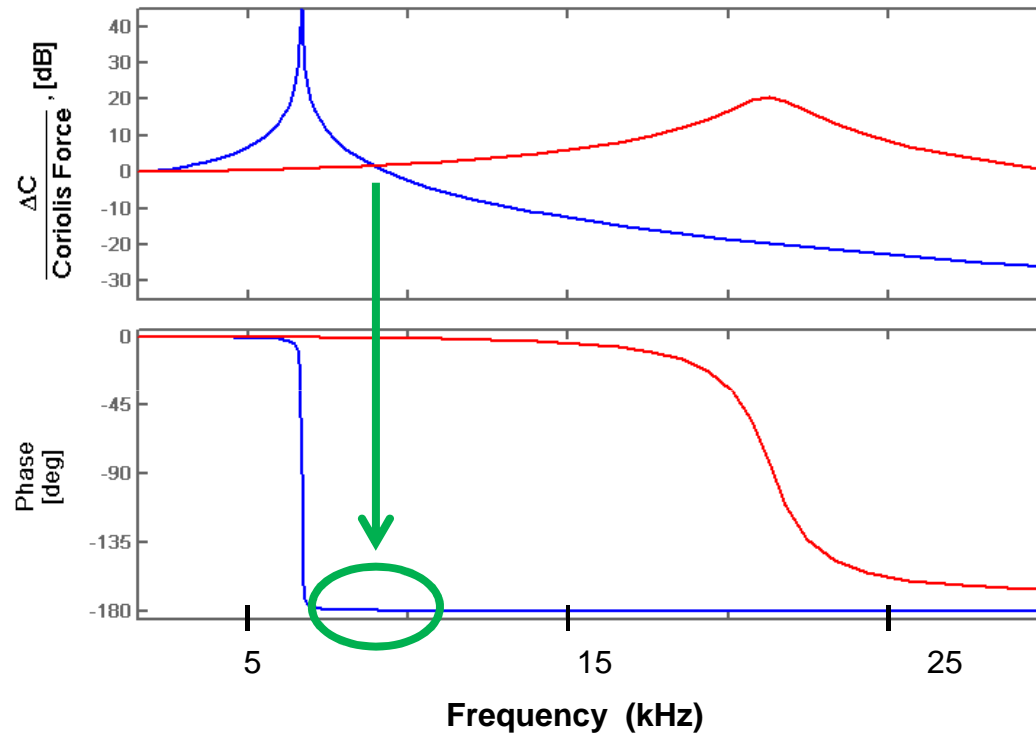
- Signal amplification at resonance
- $Q_{gyro} > 1000$

# Gyro Sensitivity



- Limited bandwidth
- Sensitivity is a function of Q, temperature

# Feedback



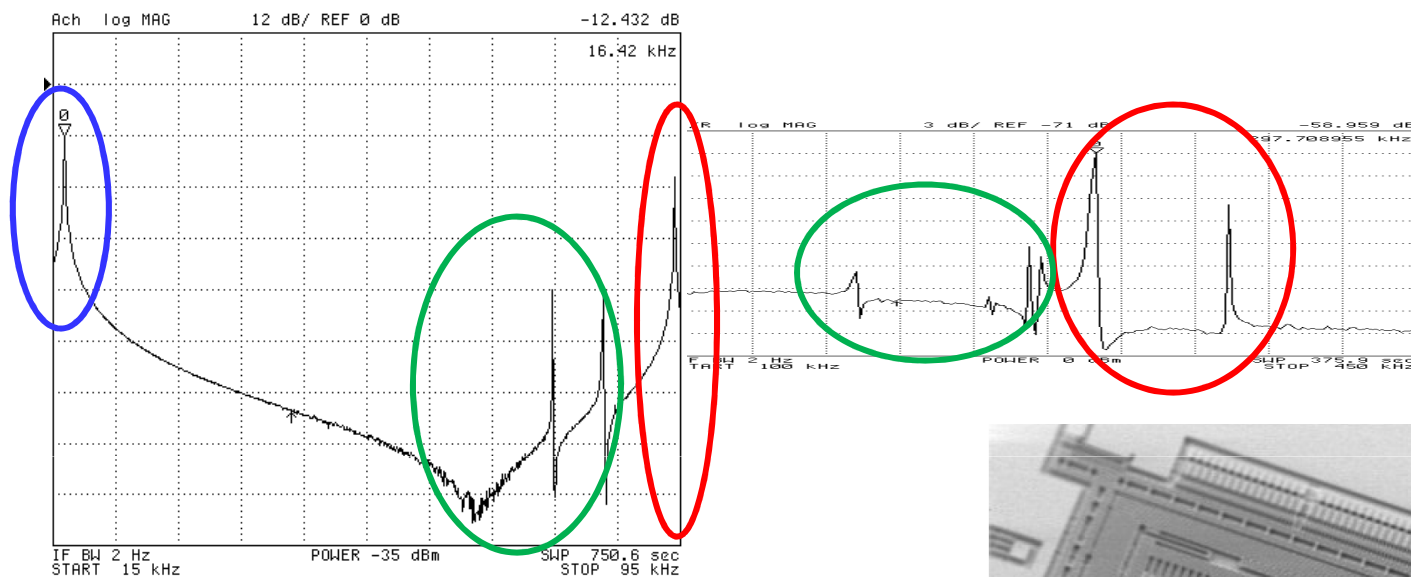
Open-loop

Feedback

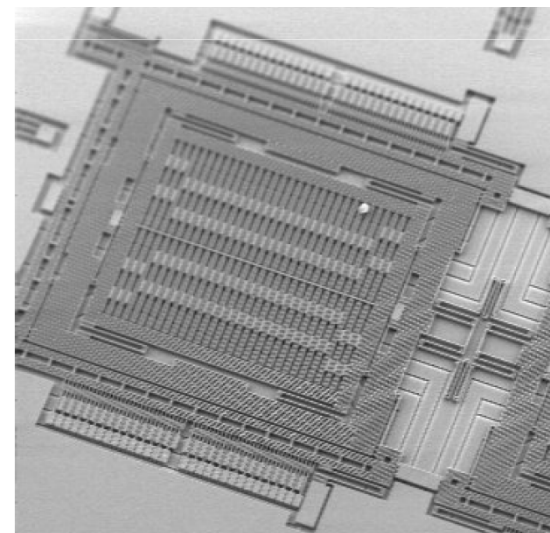
Stability?

Virtually no phase margin

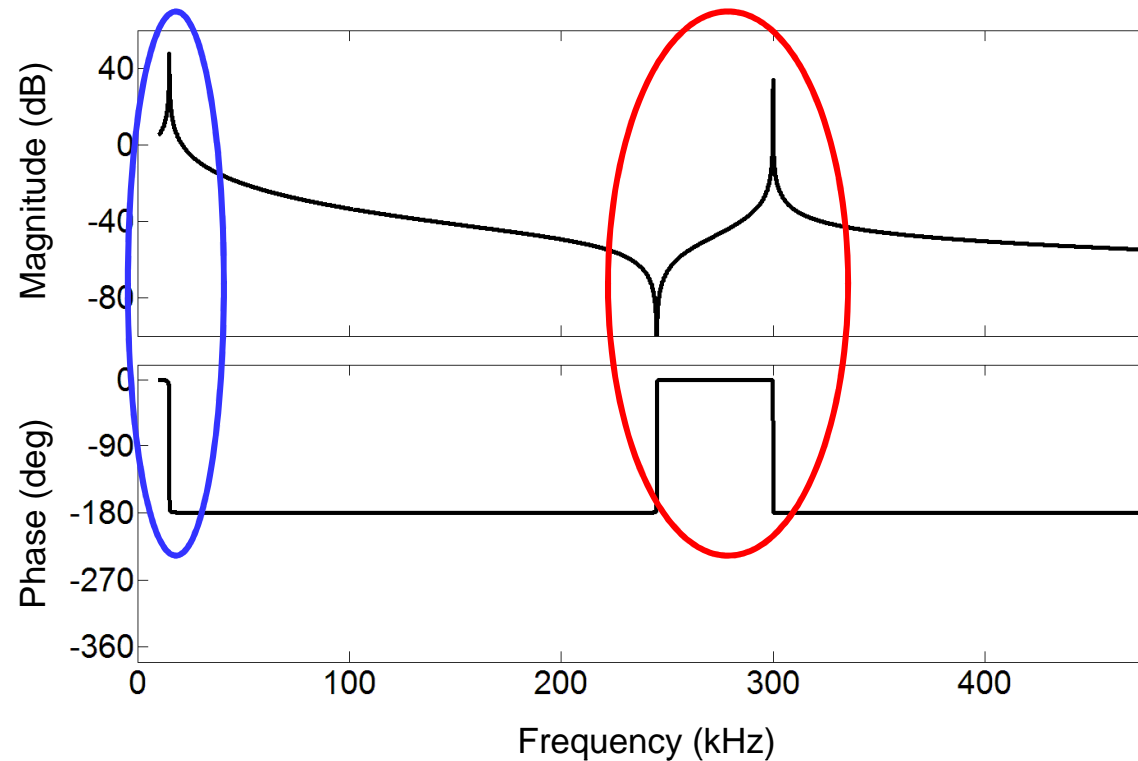
# Sensor Frequency Response



- Main mode near 15kHz
- Big parasitic modes near 95kHz and 300kHz
- Smaller parasitic modes all over



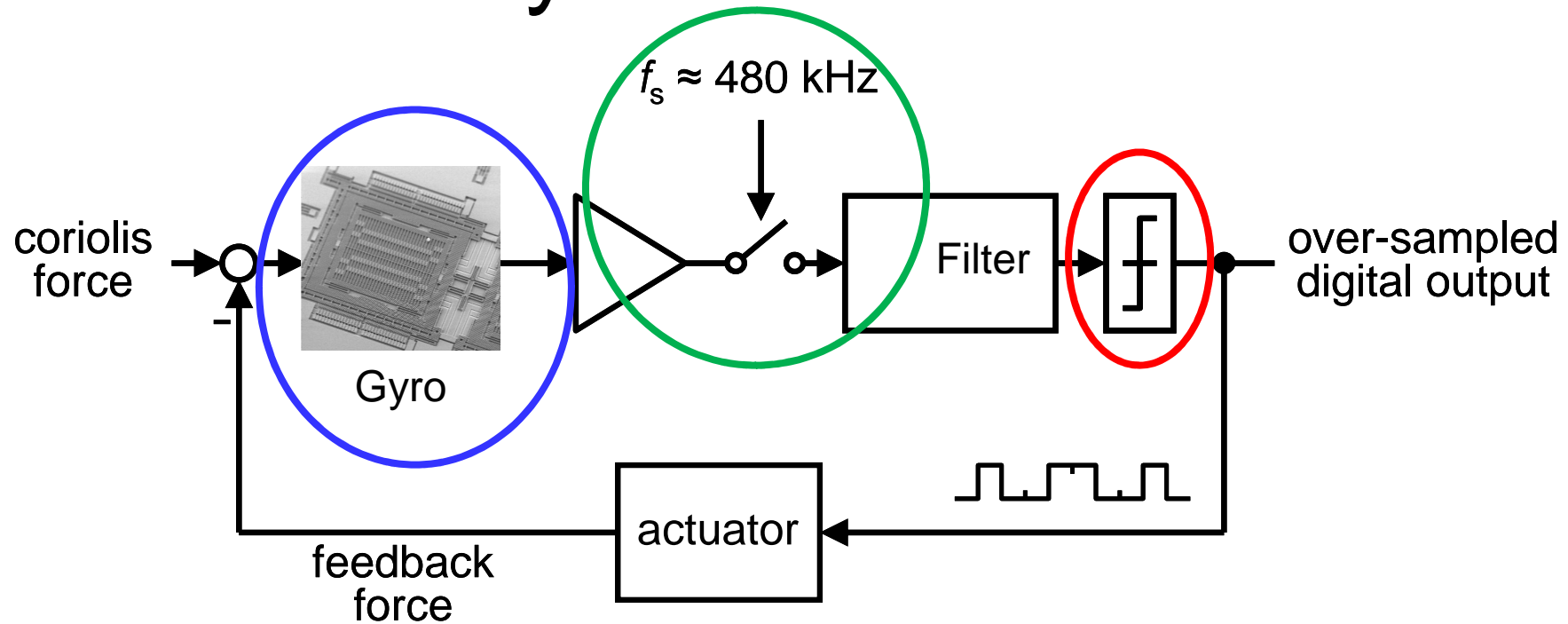
# Example Frequency Response



- Main resonance
- Single parasitic mode

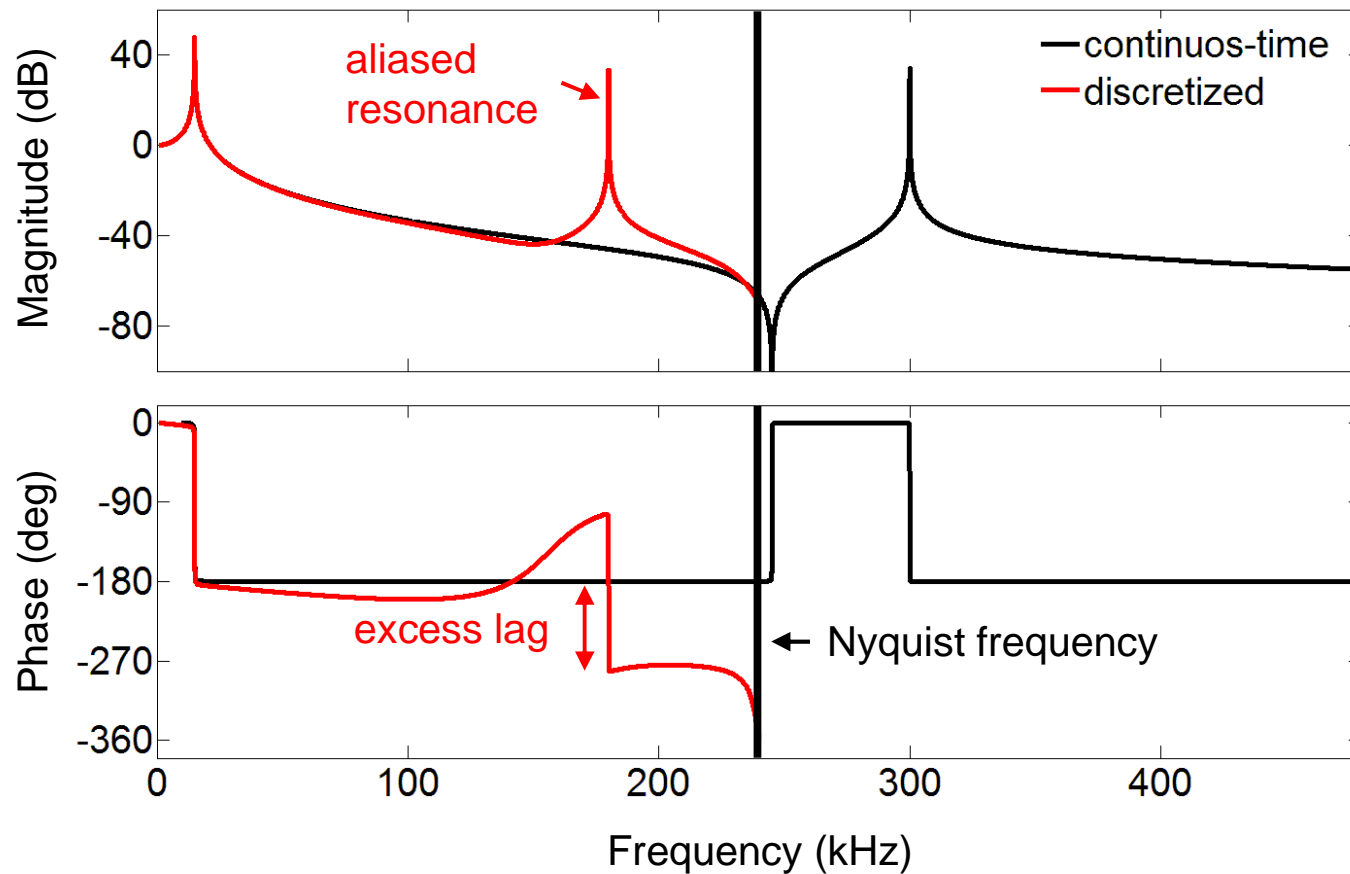


# System Model

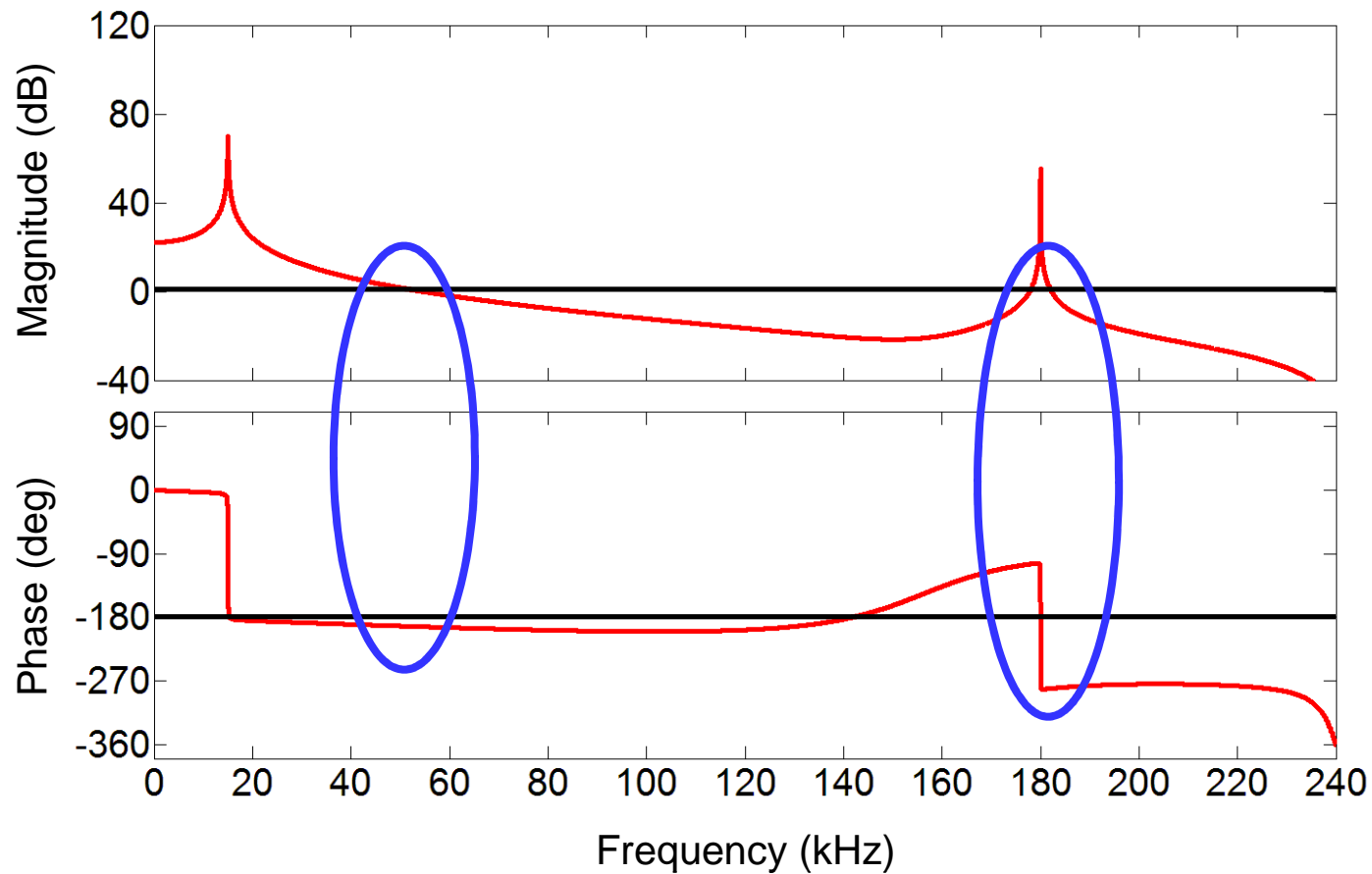


- MEMS Gyroscope
- Sampler
- Two-level ( $\Sigma\Delta$ ) feedback (linearize)

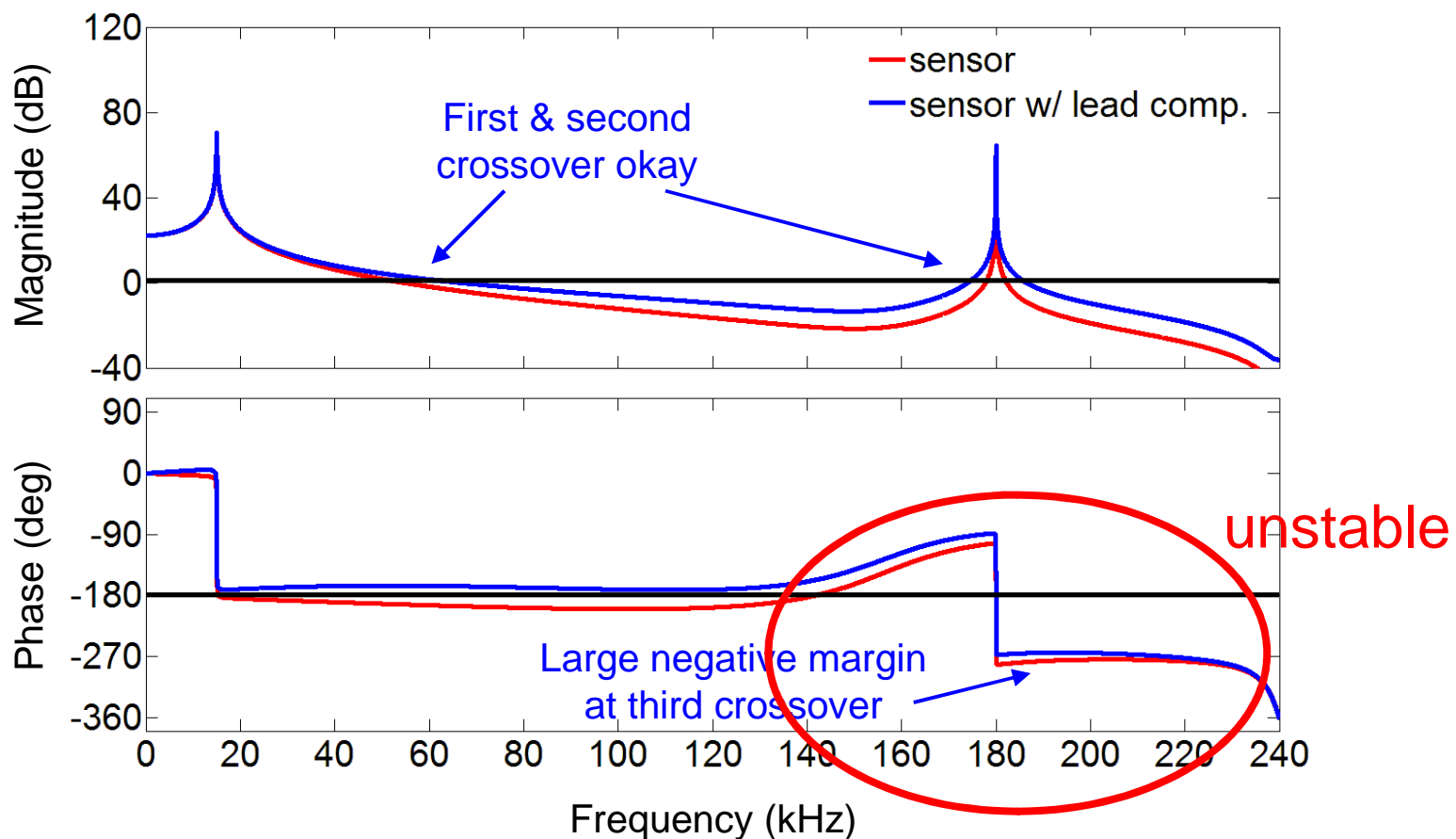
# Sampled Frequency Response



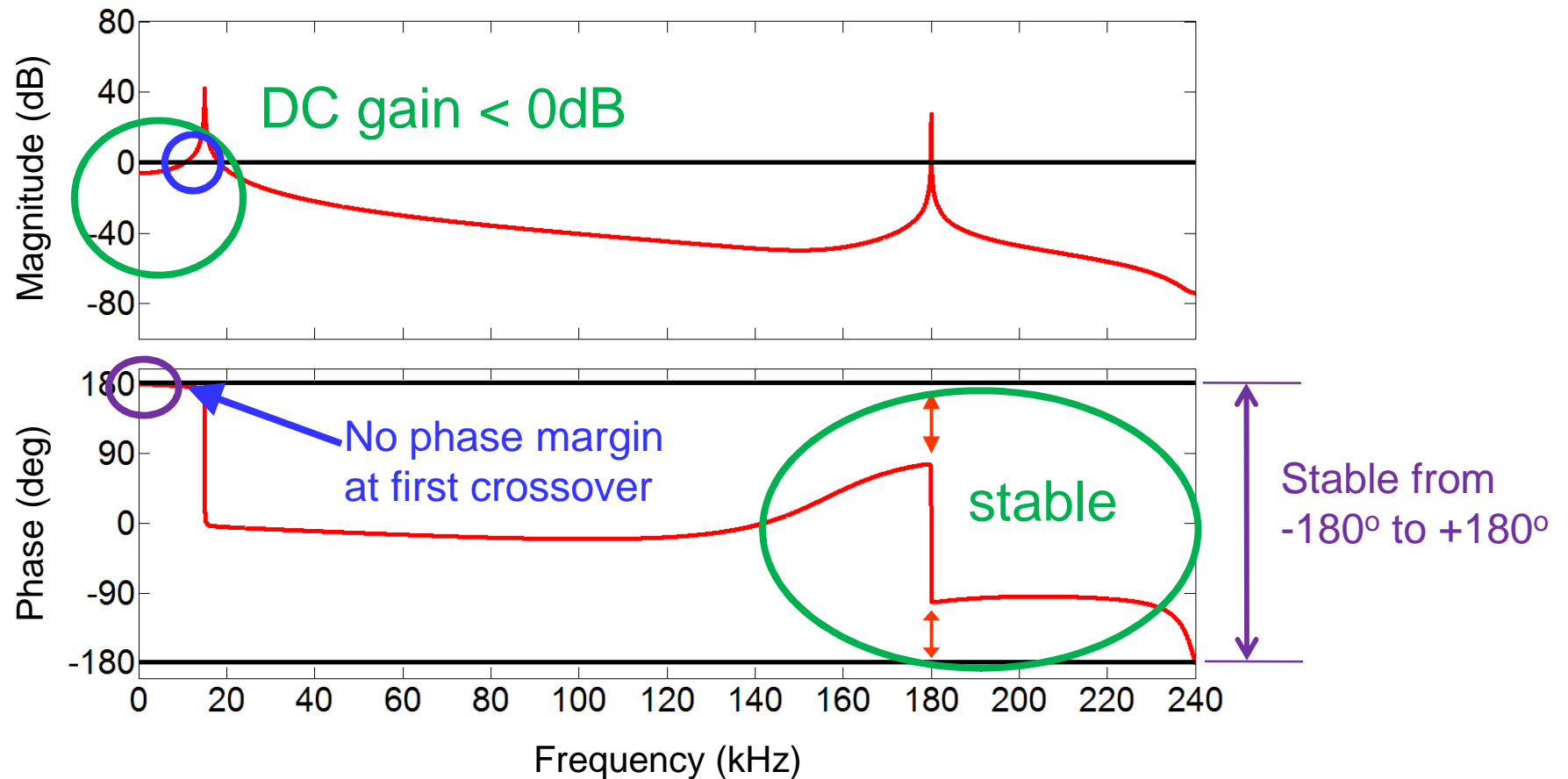
# Negative Feedback



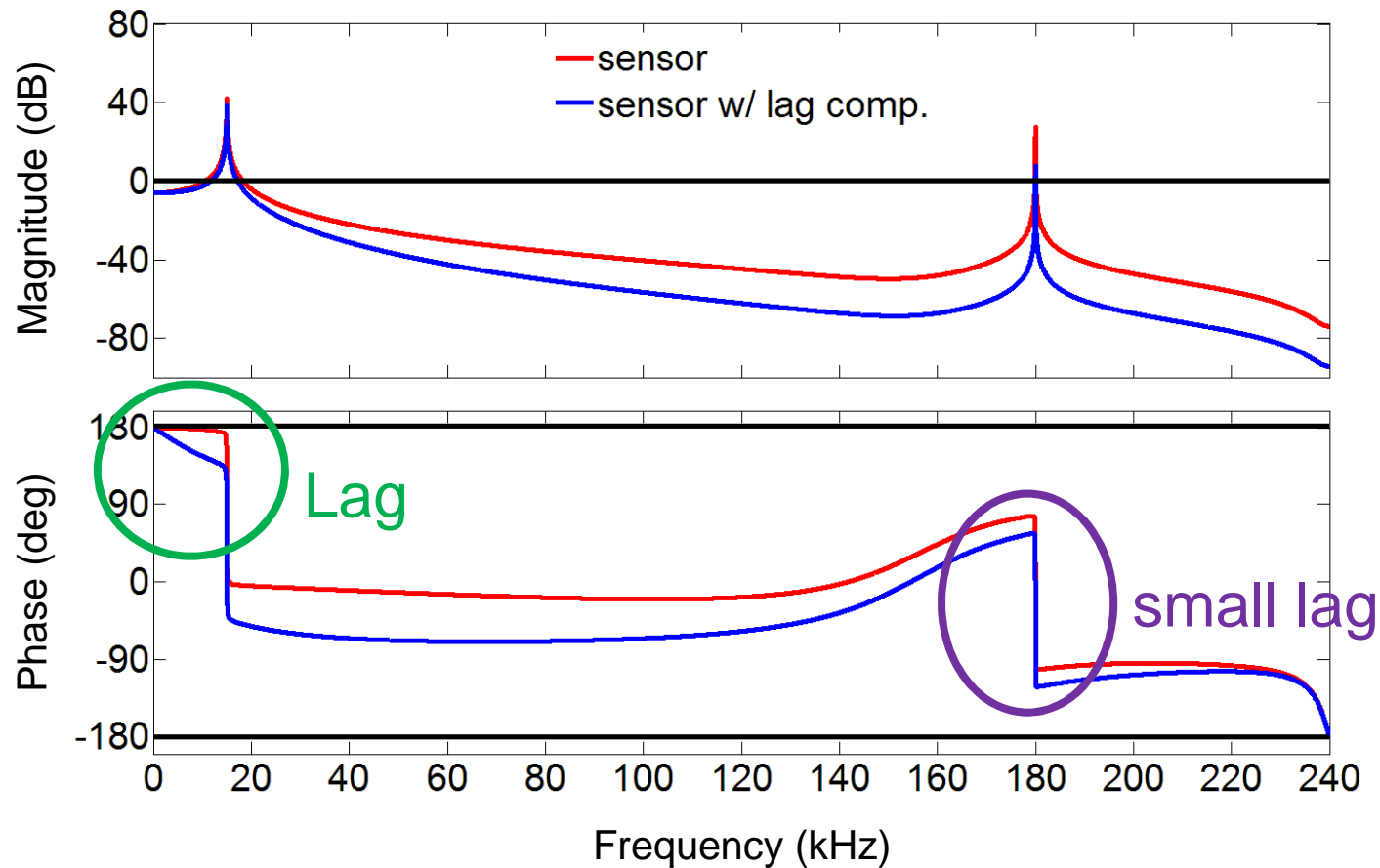
# Negative Feedback w/ Lead Comp.



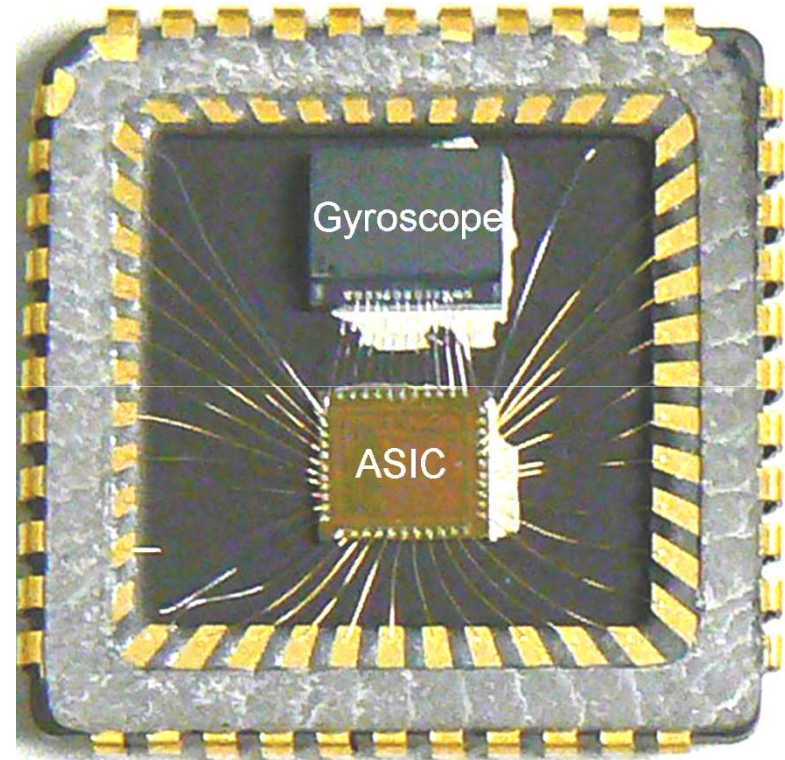
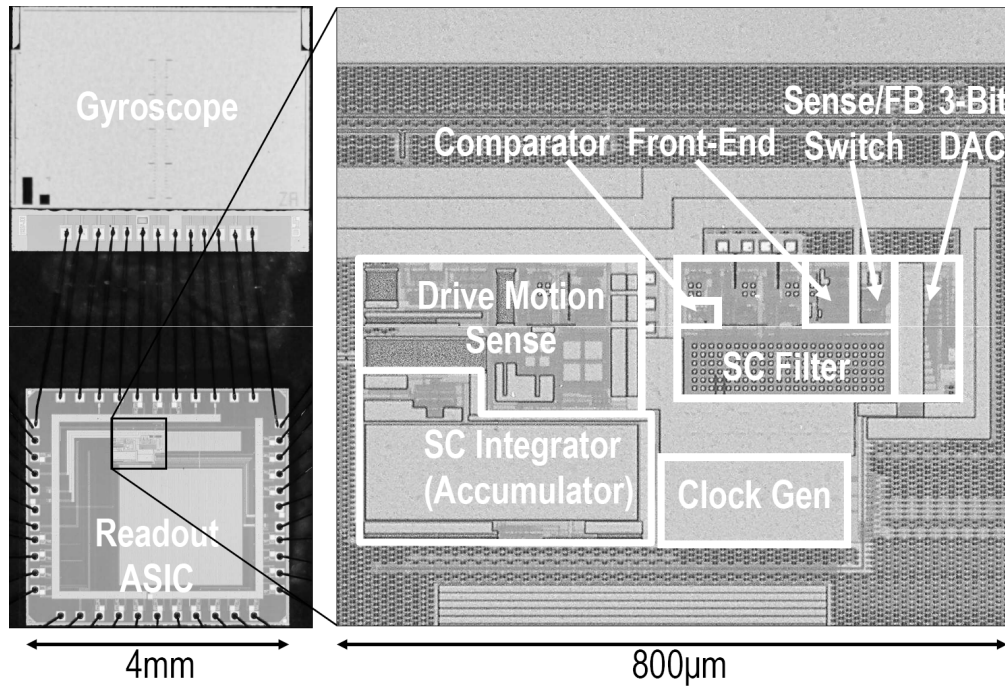
# Positive Feedback



# Positive Feedback w/ Lag Comp.



# Results



# Comparison to previous work

Reference	Power (mW)	Noise ( $^{\circ}/\text{sec}/\sqrt{\text{Hz}}$ )	BW (Hz)	Tuning Time (sec)
[1]	30	0.05	20	-
[2]	13	1	40	-
[3]	31	0.05	36	-
[4]	6	-	0.2	140
<b>This work</b>	<b>1</b>	<b>0.004</b>	<b>50</b>	<b>0.3</b>

[1] Geen, JSSC 2002

[2] Petkov, ISSCC 2004

[3] Saukoski, ESSCIRC 2006

[4] Sharma, ISSCC 2007



# Conclusions

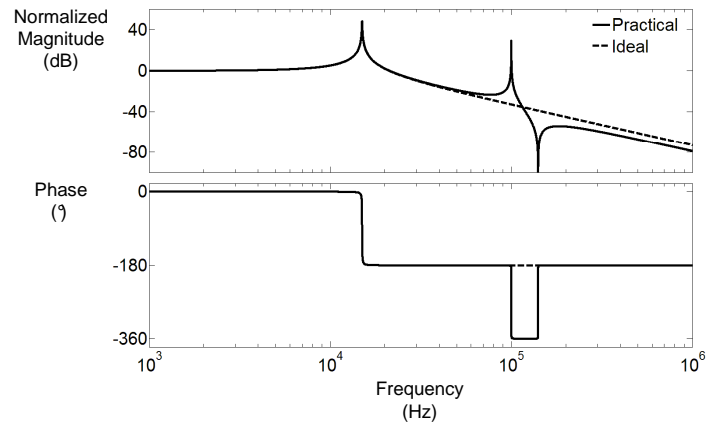
- Stable phase range is  $-180^\circ$  to  $+180^\circ$
- Negative feedback phase starts at  $0^\circ$ 
  - Accommodates only  $180^\circ$  phase lag
- Positive feedback phase starts at  $+180^\circ$ 
  - Accommodates up to  $360^\circ$  phase lag
  - Unstable for DC gain  $\geq 1$

# Acknowledgements

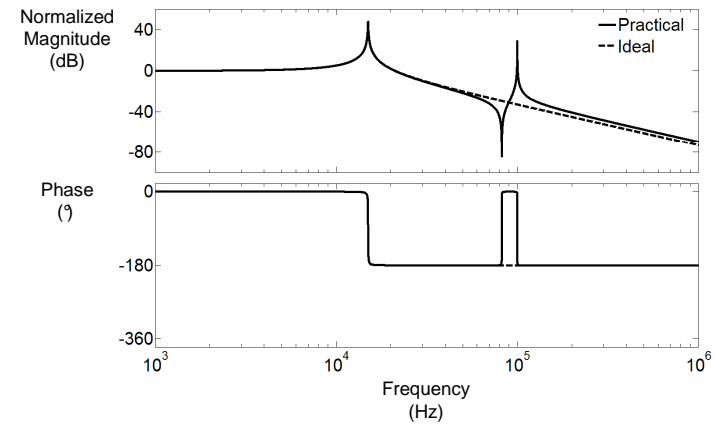
- Chinwuba Ezekwe  
Christoph Lang  
Vladimir Petkov
- Robert Bosch Corporation  
Gyroscope and financial support



# Parasitic Resonances



Non-collocated Control  
(separate electrodes)



Collocated Control  
(same electrode)