

High-Precision Low-Voltage Low-Power Analog-to-Digital Conversion

**Hyunsik Park
Feb. 12, 2009**

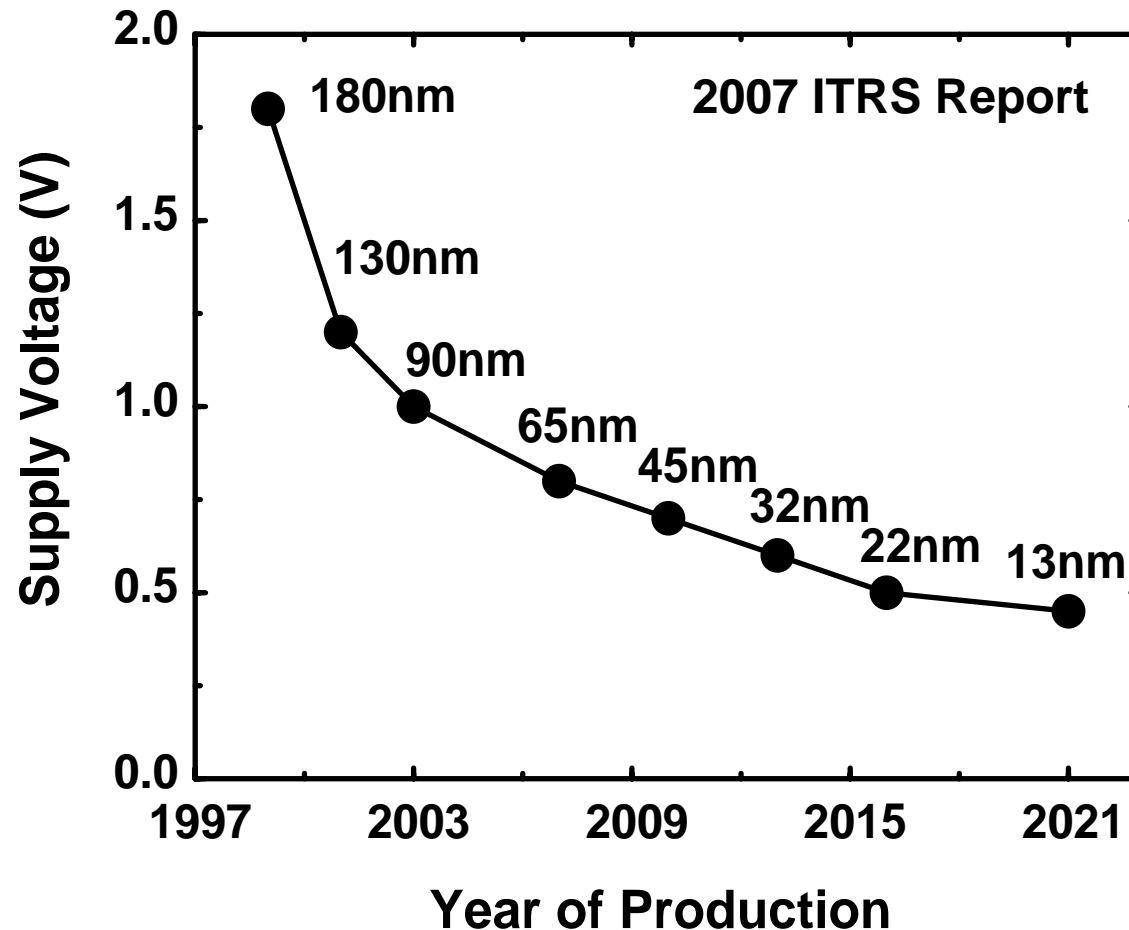


**Center for Integrated Systems
Stanford University**

Outline

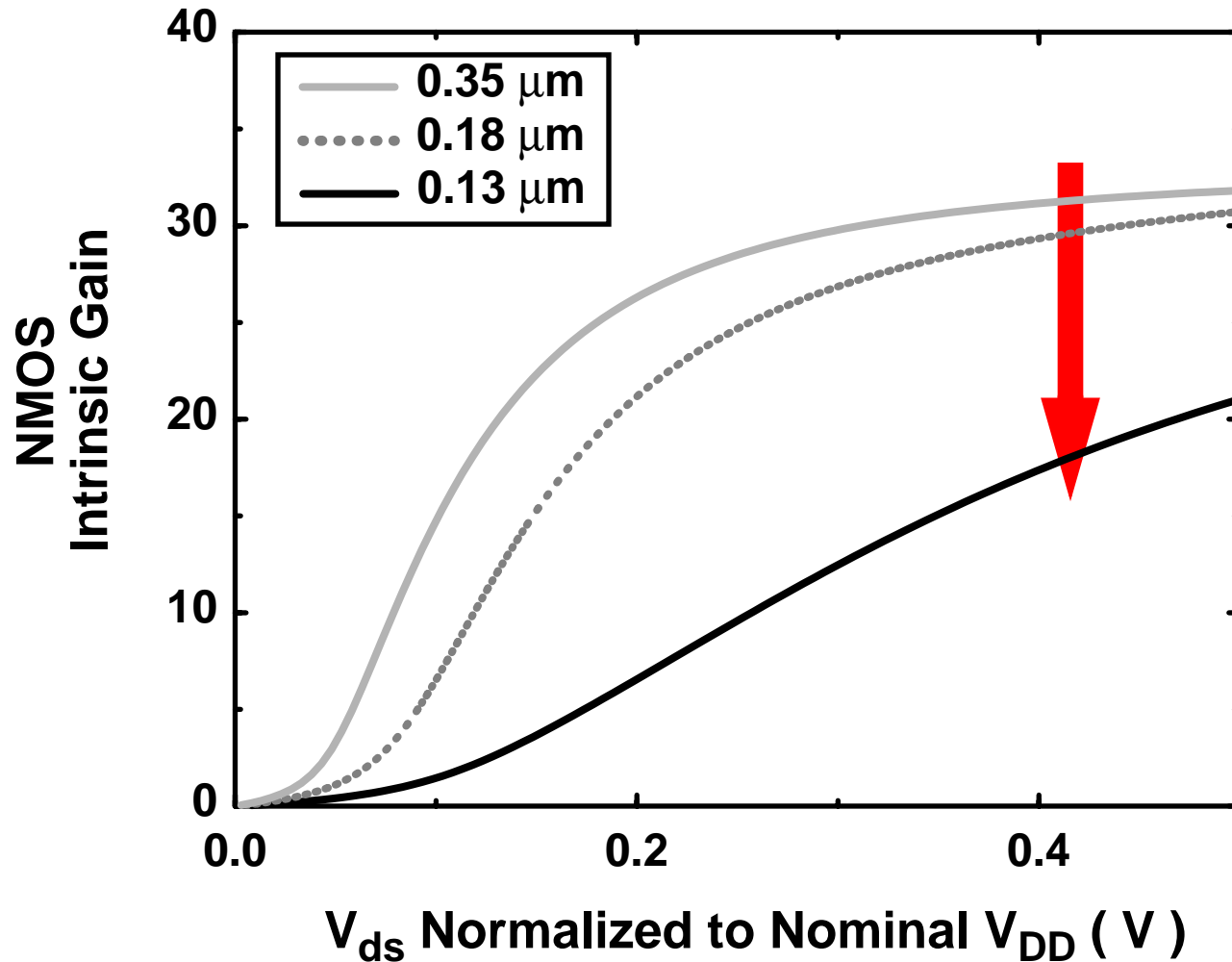
- **Introduction**
- **Proposed ADC architecture**
- **Implementation**
- **Experimental results**
- **Conclusion**

Toward Lower Supply Voltage



- **Reduced voltage headroom: limited circuit topologies**
- **Reduced dynamic range: higher power for the same DR**

Reduced Device Intrinsic Gain



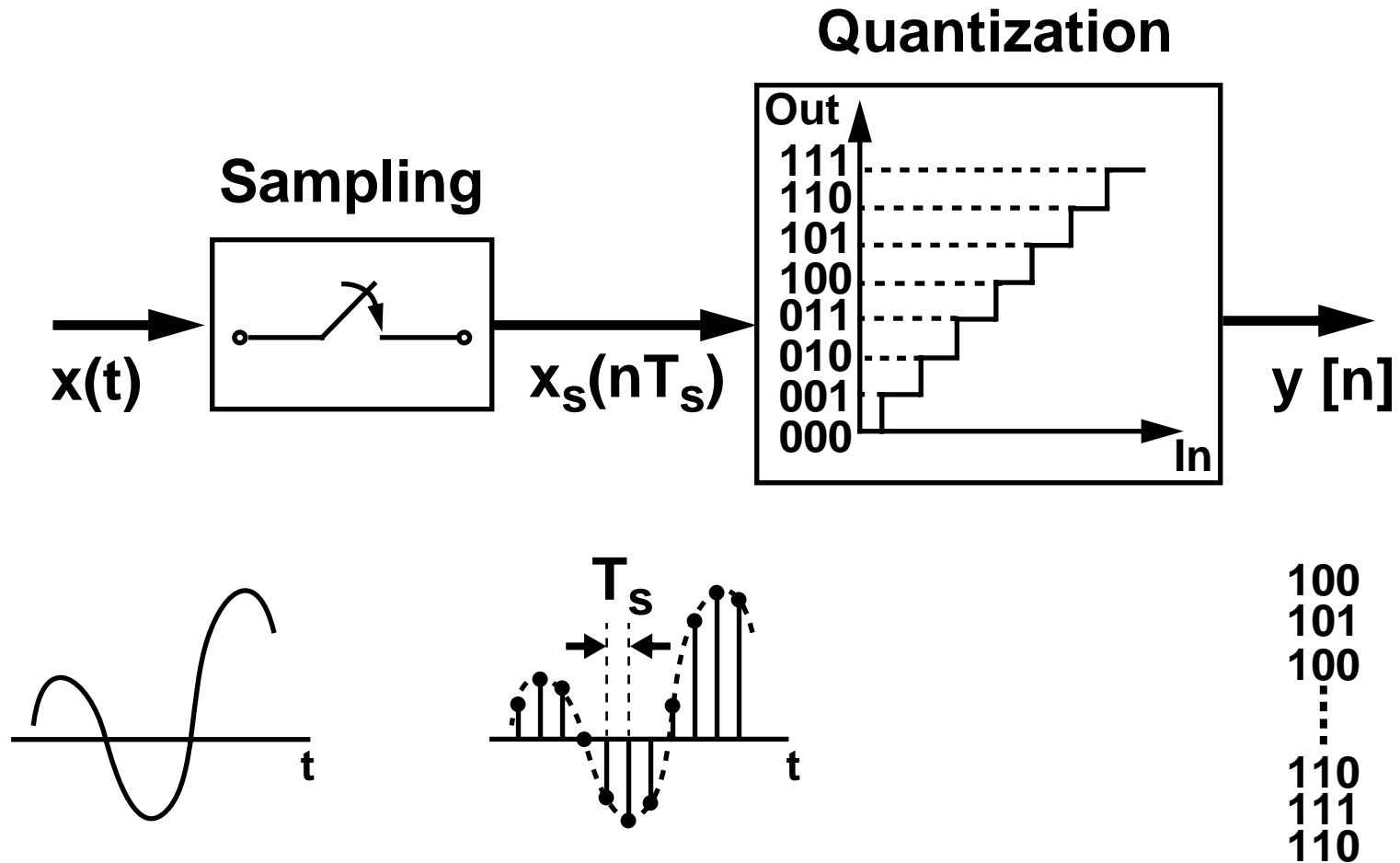
- **Difficult to build precision analog blocks**
- **System robustness becomes important**

Research Objectives

- **Goal: Explore novel architectures and circuits for realizing high-precision, low-voltage, low-power CMOS ADCs**
- **Target application: Portable digital audio devices, sensor, instrumentation**
- **Target performance**

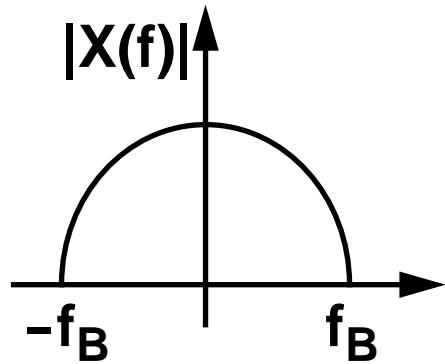
Supply Voltage	0.7 V
Technology	CMOS 0.18-μm
Dynamic Range	> 95 dB
Signal Bandwidth	25 kHz
Power Dissipation	Minimize

Analog-to-Digital Conversion

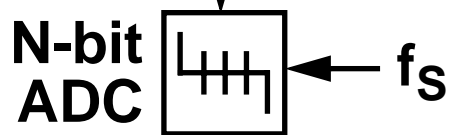


- **Sampling in time**
- **Quantization in amplitude**

Nyquist-Rate ADC vs. Oversampling ADC



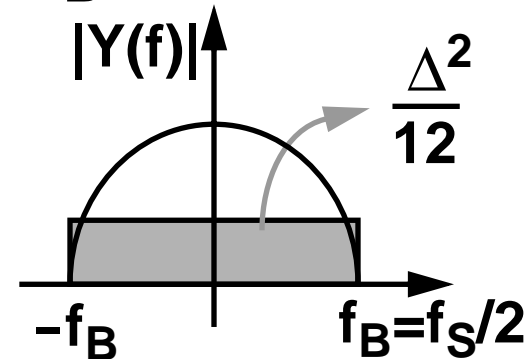
$x(t)$



$$y[n] = x[n] + e_q[n]$$

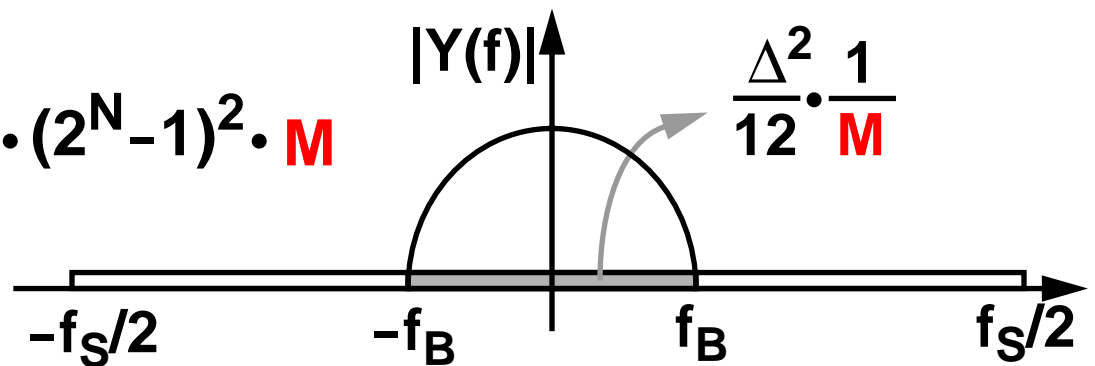
Nyquist-rate ($f_s = 2 \cdot f_B$)

$$DR = \frac{3}{2} \cdot (2^N - 1)^2$$

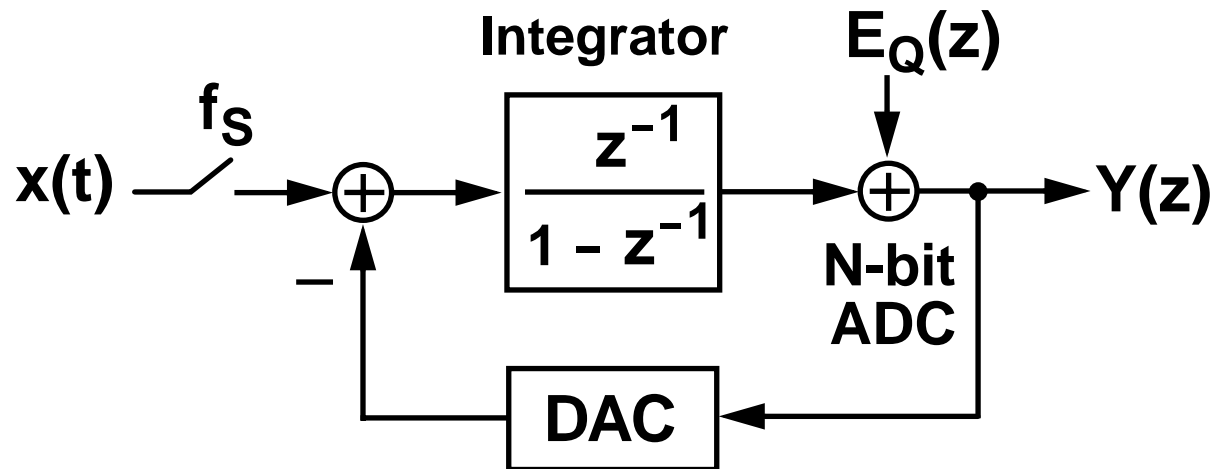


Oversampling ($f_s = 2 \cdot f_B \cdot M$)

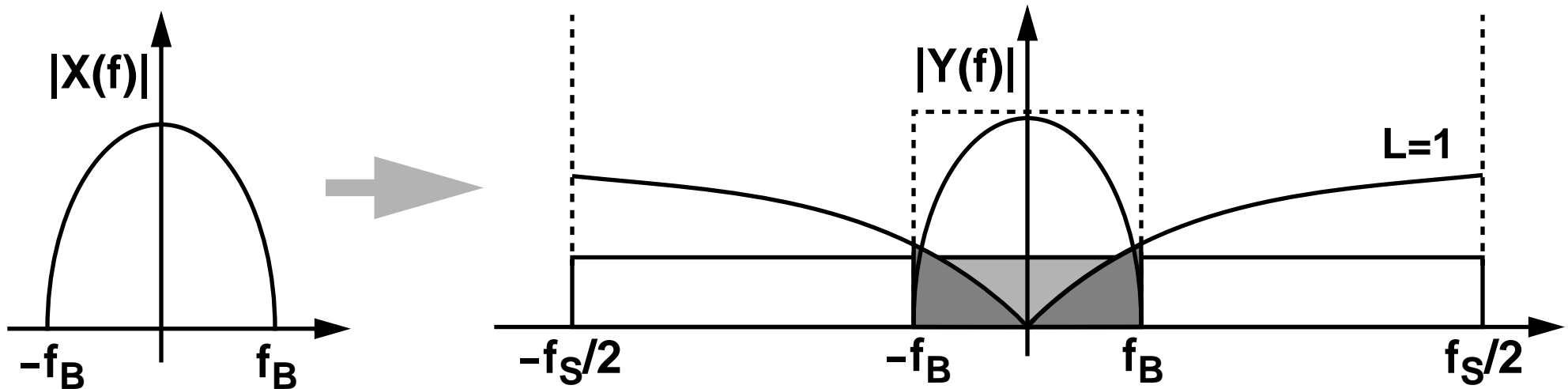
$$DR = \frac{3}{2} \cdot (2^N - 1)^2 \cdot M$$



$\Sigma\Delta$ Oversampling ADC

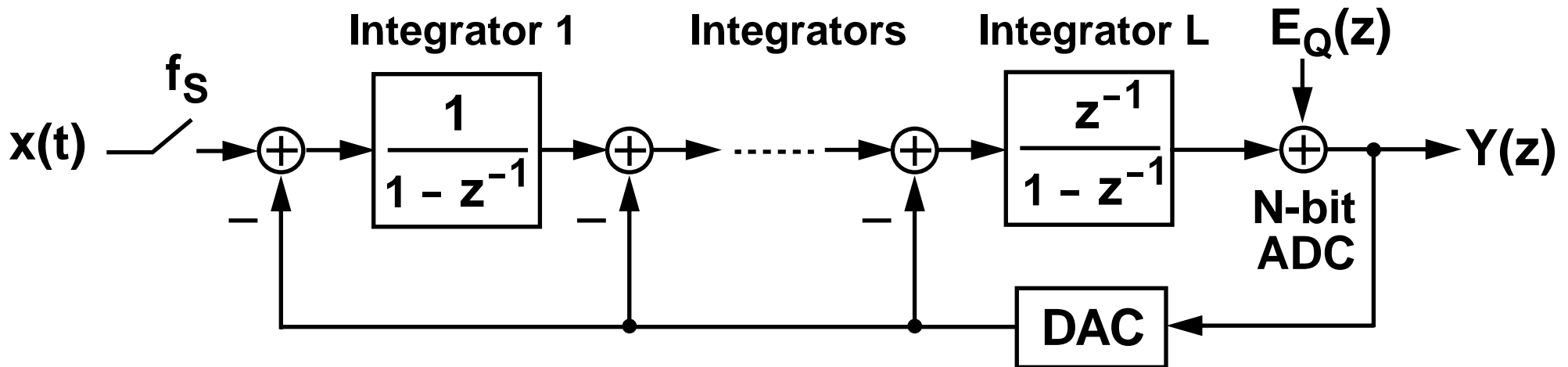


$$Y = z^{-1} \cdot X + (1 - z^{-1}) \cdot E_Q$$



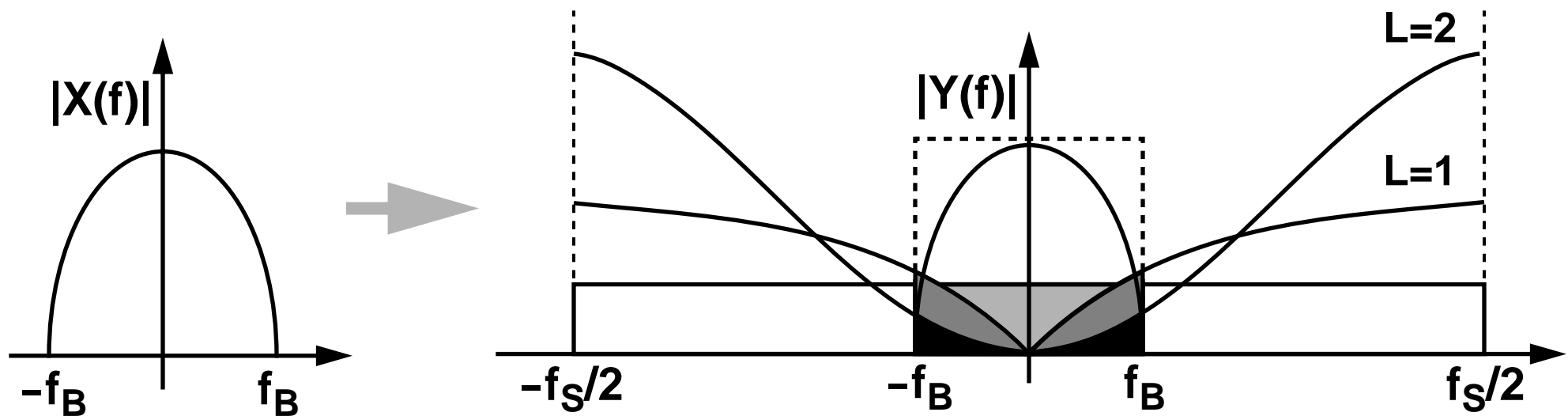
- Filtering and feedback \rightarrow Noise shaping

$\Sigma\Delta$ Oversampling ADC: Higher Order



$$Y = z^{-1} \cdot X + (1 - z^{-1})^L \cdot E_Q$$

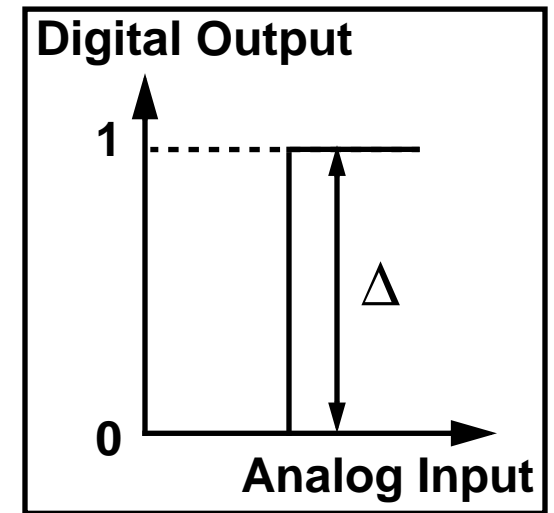
$$DR \sim \frac{3 \cdot 2L+1}{2 \cdot \pi^{2L}} \cdot M^{2L+1} \cdot (2^N - 1)^2$$



Quantization

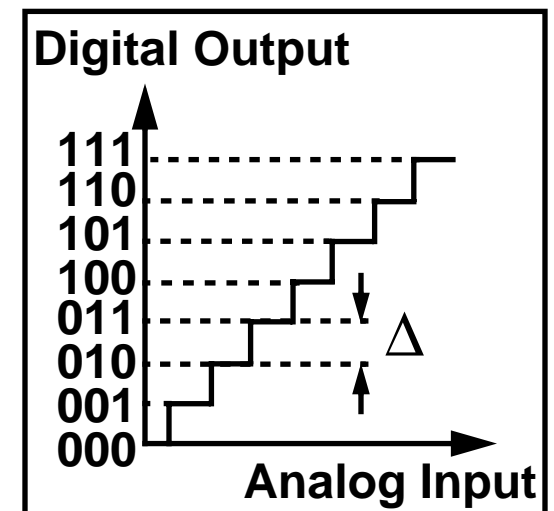
- **Single-bit quantization**

- (+) Inherent DAC linearity
- (+) Relaxed comparator design constraints
(power, loading, offset, complexity, ...)
- (-) Increased integrator swings



- **Multi-bit quantization**

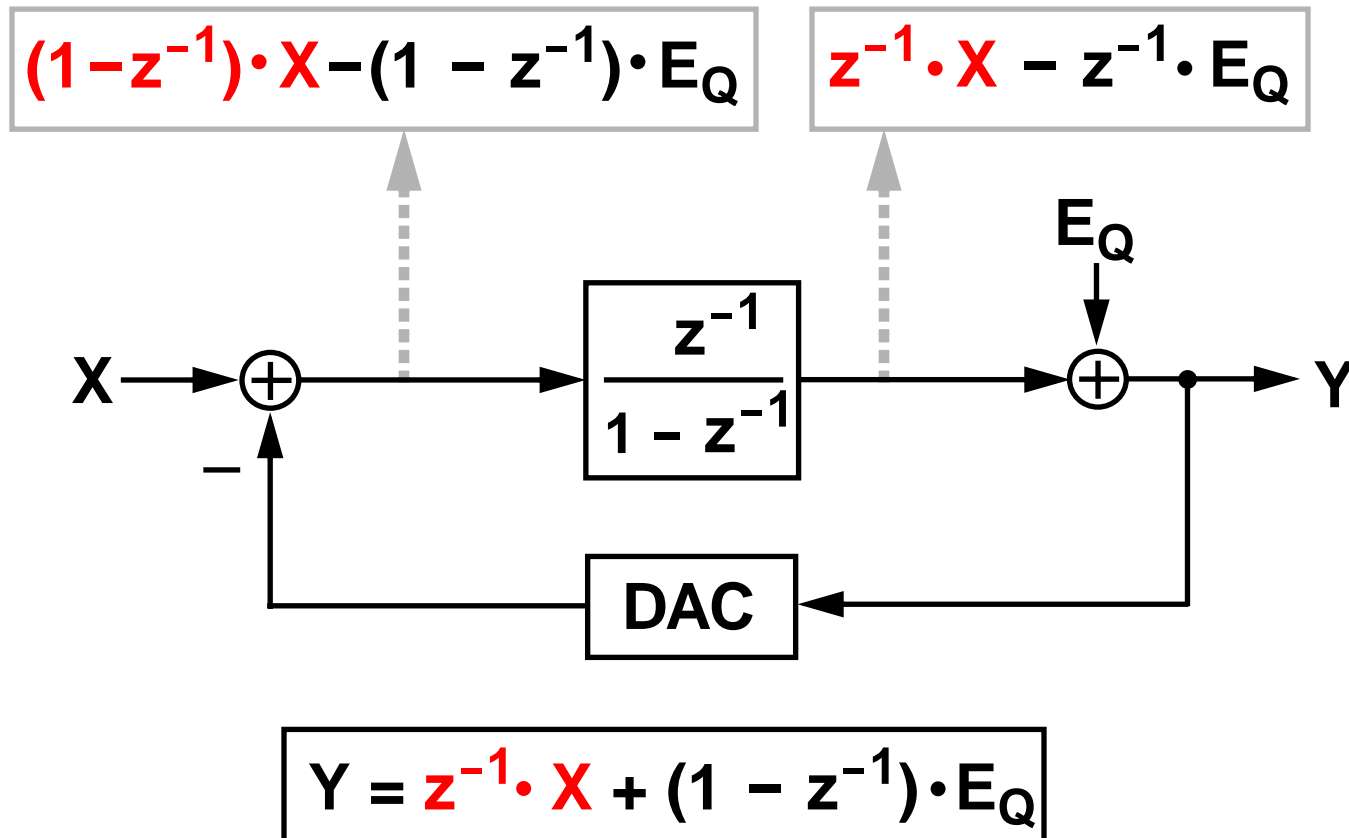
- (+) Reduced integrator swings
- (+) Higher performance
without order or OSR increase
- (-) Feedback DAC linearity issues
- (-) Higher performance comparator needed



Outline

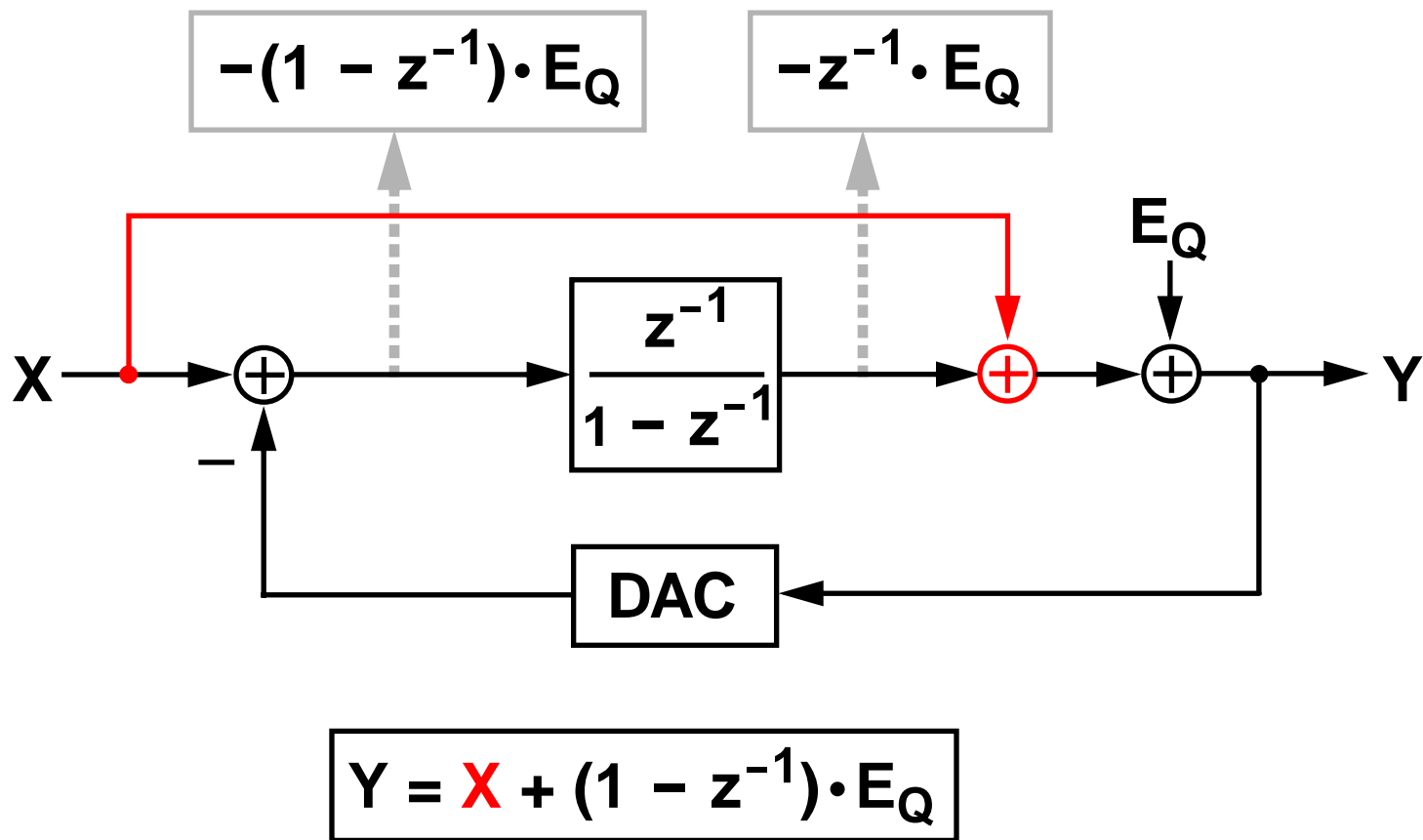
- Introduction
- **Proposed ADC architecture**
- Implementation
- Experimental results
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Conventional $\Sigma\Delta$ Modulator



- Integrator swings depend on input
- Large input \rightarrow nonlinear operation of integrator op amp

Input Feedforward $\Sigma\Delta$ Modulator*



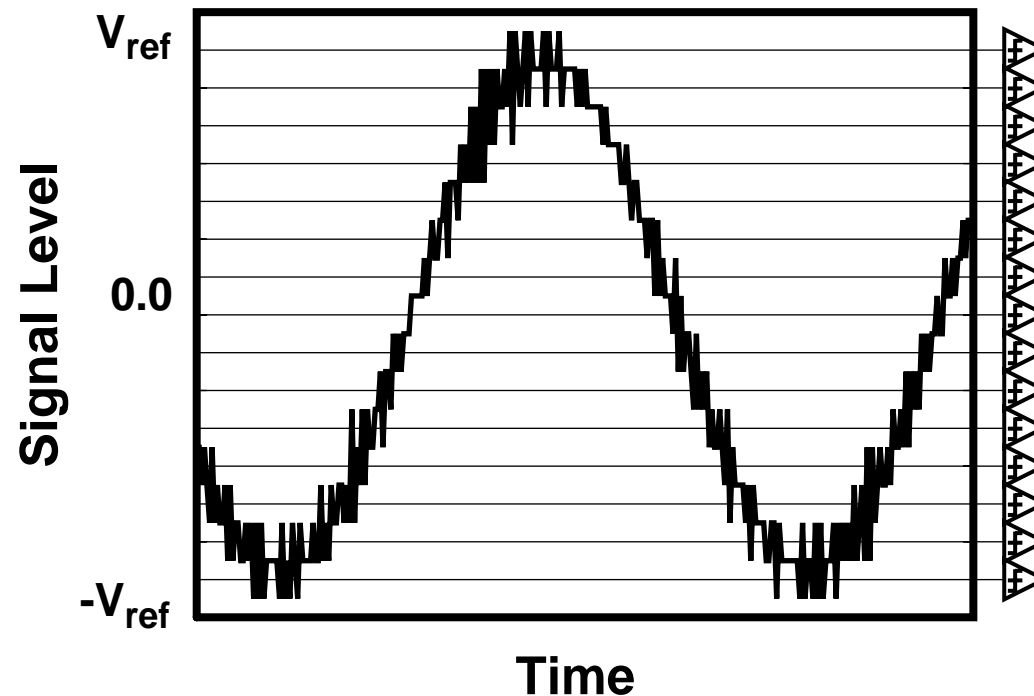
- Input independent integrator swings
- **Analog summation and timing overhead issues**

* K. Nam, et al., CICC 2004

Oversampling ADC with Multi-bit Quantization

Multi-bit Quantizer Output (4-bit, OSR=100)

Horizontal Lines: Comparator Threshold

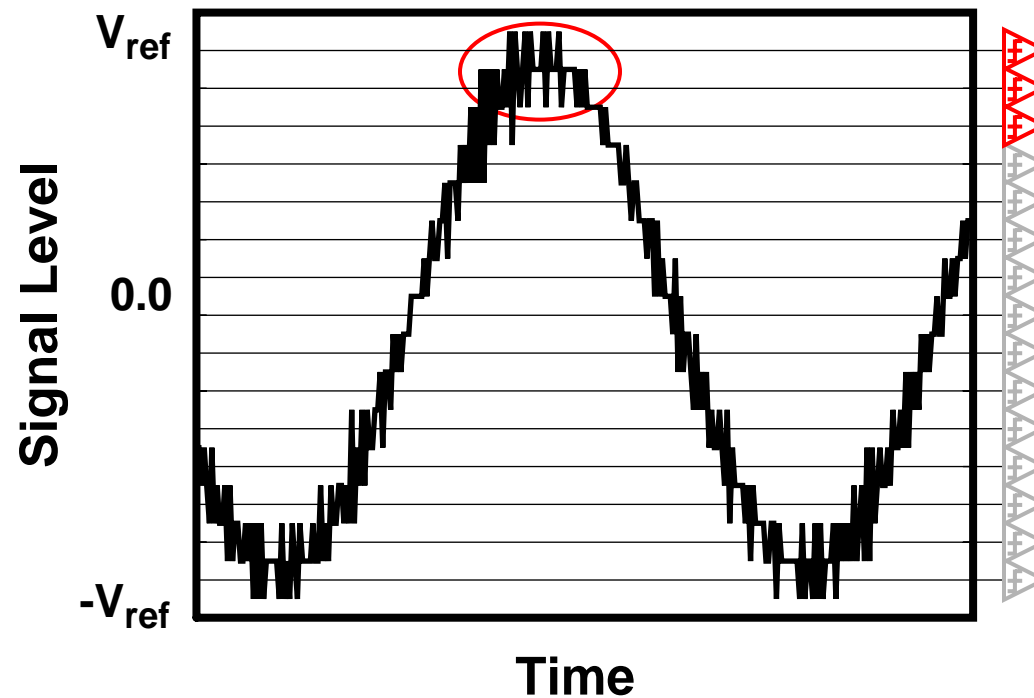


- Reduced integrator swings
- Higher power dissipation

Multi-bit Quantization: Idling Comparators

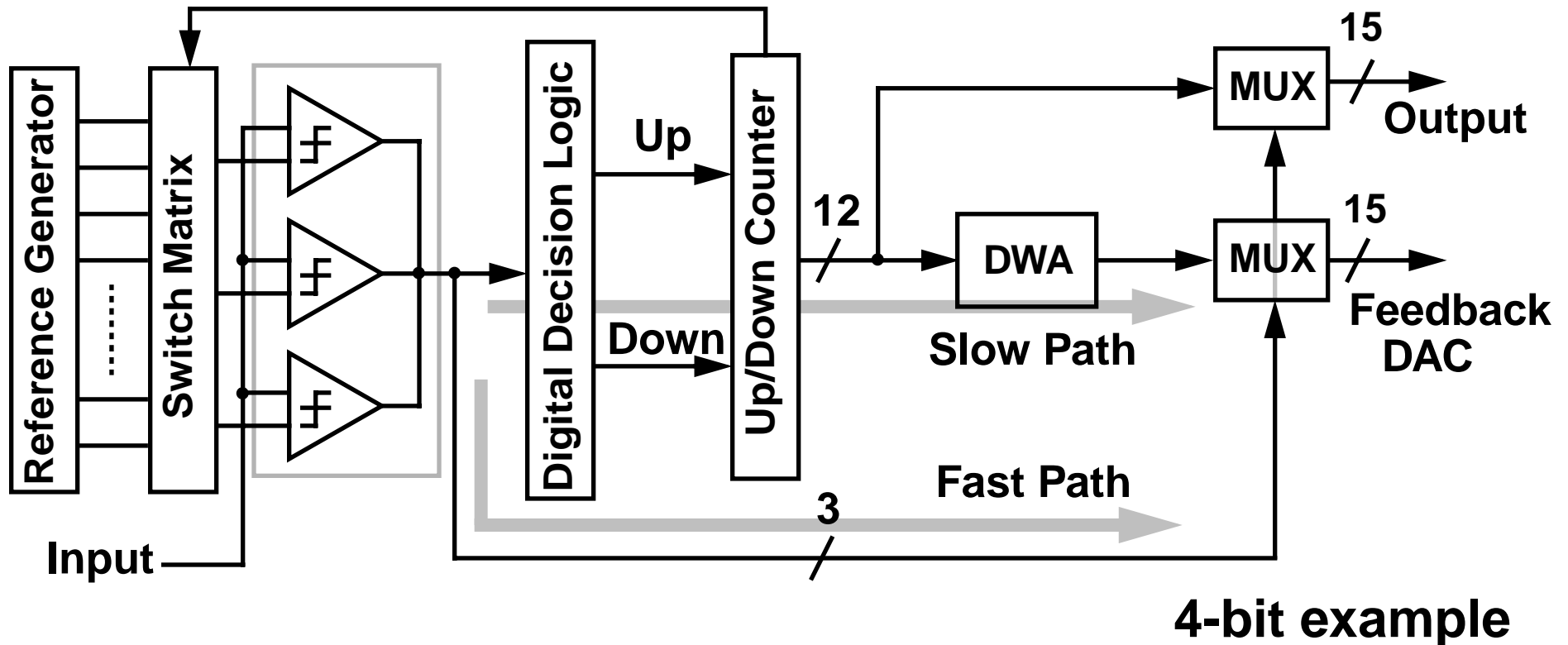
Multi-bit Quantizer Output (4-bit, OSR=100)

Horizontal Lines: Comparator Threshold



- Comparator redundancy

Tracking Multi-bit Quantizer*

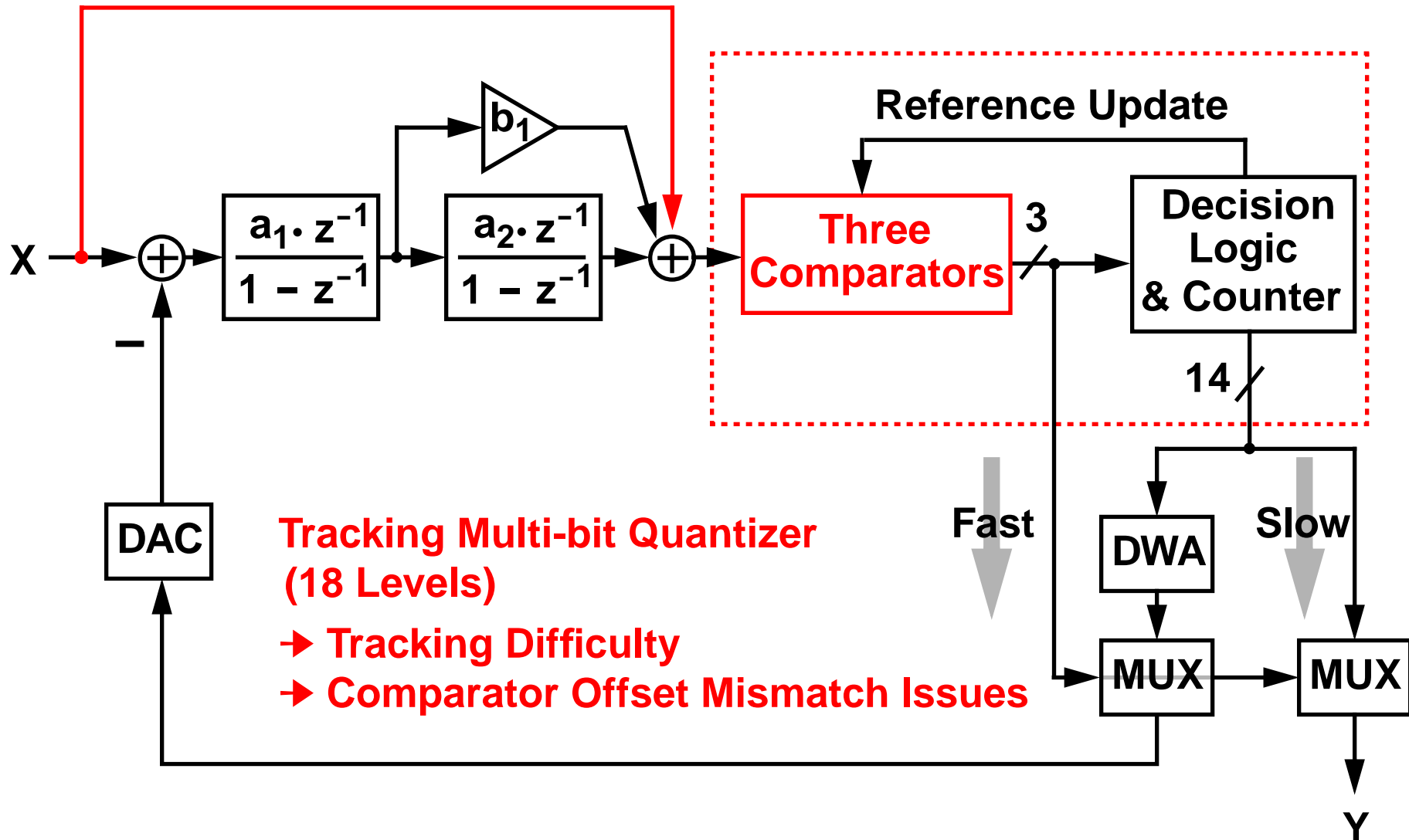


- Multi-bit quantizer with a few comparators
- Tracking difficulty
- Comparator offset mismatch problem

* L. Dorrer, et al., ISSCC 2005

Low-Voltage Low-Power Architecture

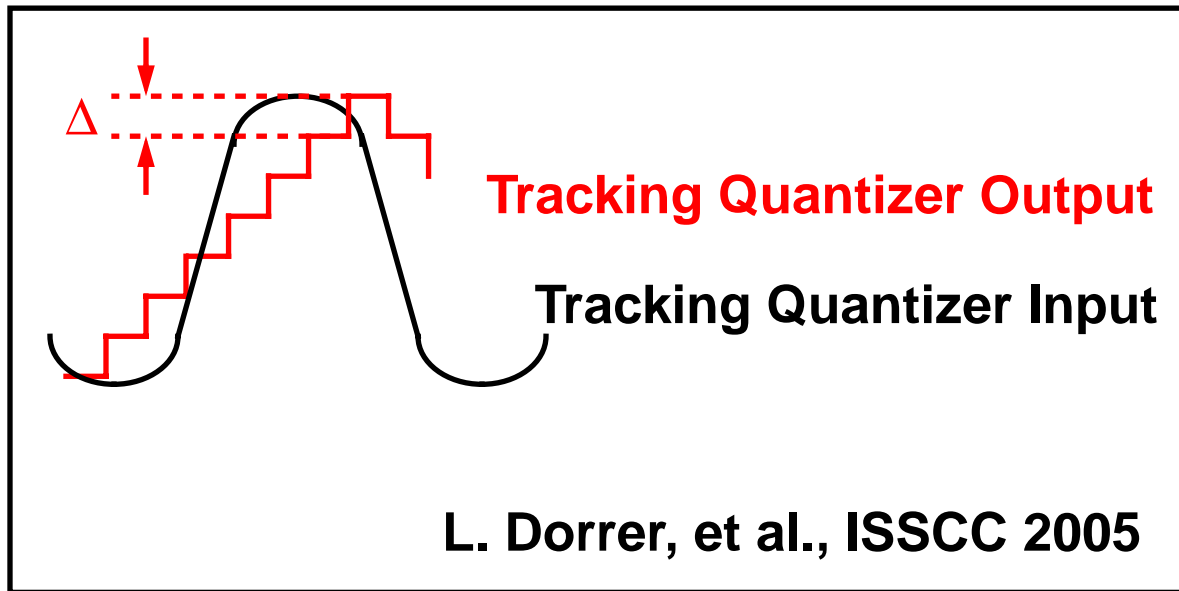
Input Feedforward \rightarrow Timing Overhead Issues



Tracking Multi-bit Quantizer
(18 Levels)

- \rightarrow Tracking Difficulty
- \rightarrow Comparator Offset Mismatch Issues

Tracking Difficulty (1 of 2)



$$V_{\text{ref}} \cdot 2\pi \cdot f_{\text{BWmax}} < \frac{\Delta}{T_{\text{clk}}}$$

$$\left(\Delta = \frac{V_{\text{FS}}}{2^N} = \frac{V_{\text{ref}}}{2^{N-1}} \right)$$

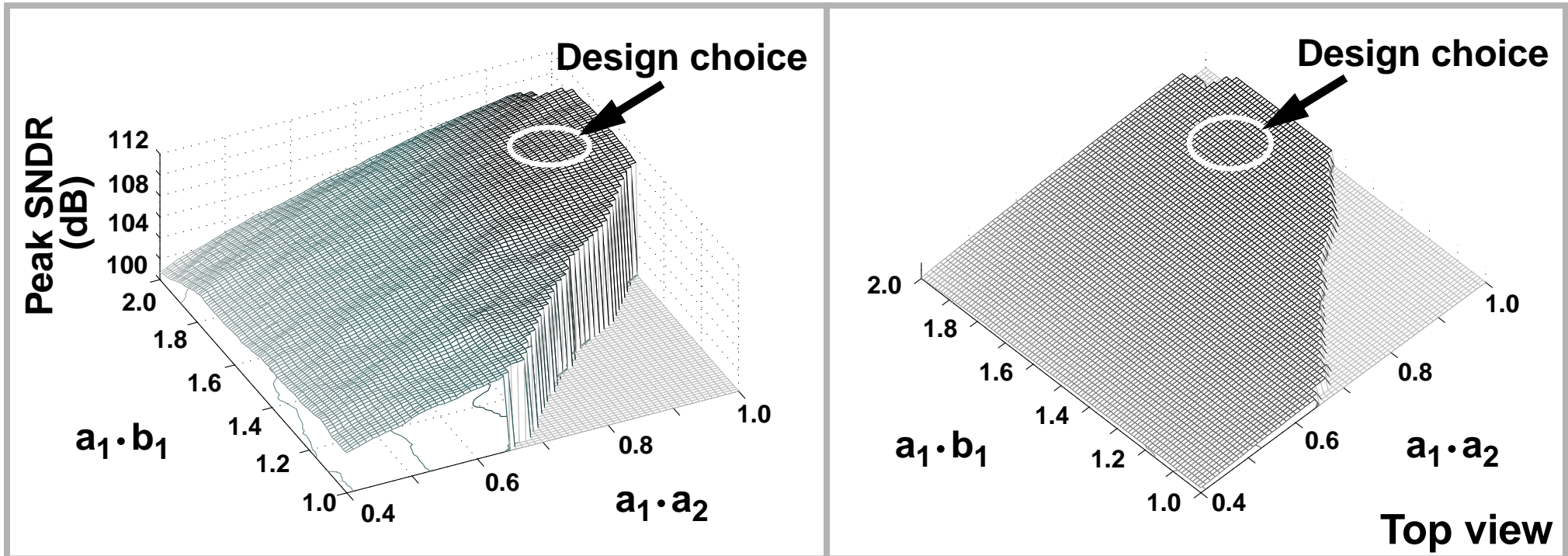
$$\text{OSR} > \pi \cdot 2^{N-1}$$

$$\left(\text{OSR} = \frac{1}{2 \cdot f_{\text{BWmax}} \cdot T_{\text{clk}}} \right)$$

- OSR and number of bits trade-off
 - 4-bit quantization requires minimum OSR of 26
- Quantization error degrades tracking operation

Tracking Difficulty (2 of 2)

Modulator coefficient vs. peak SNDR



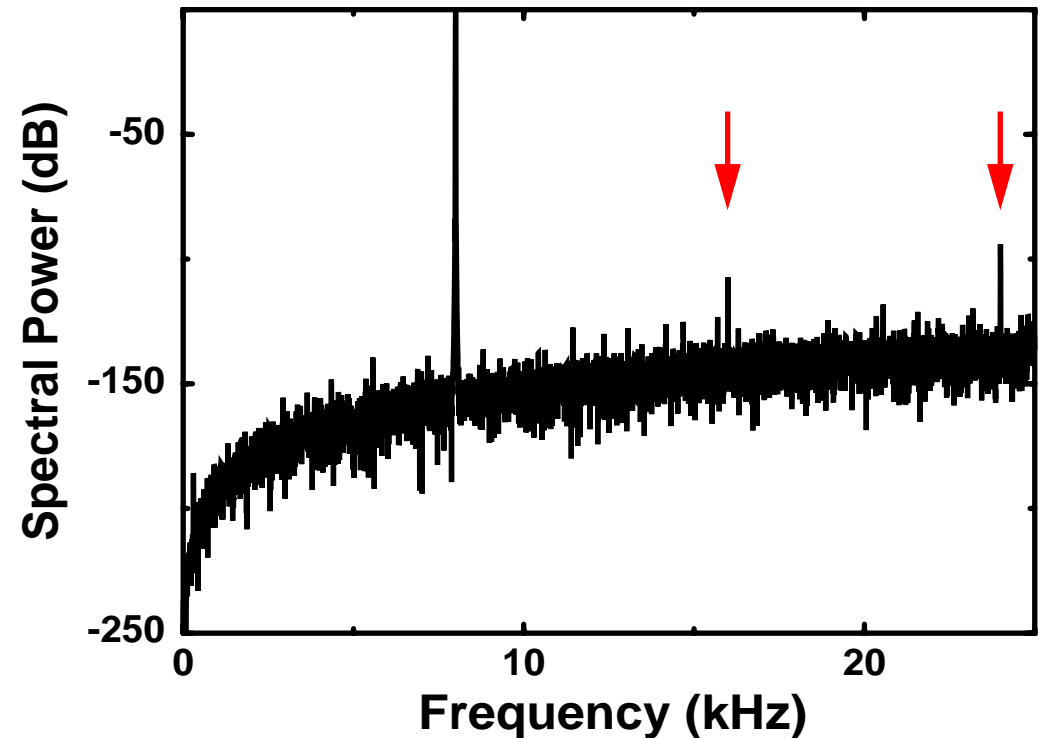
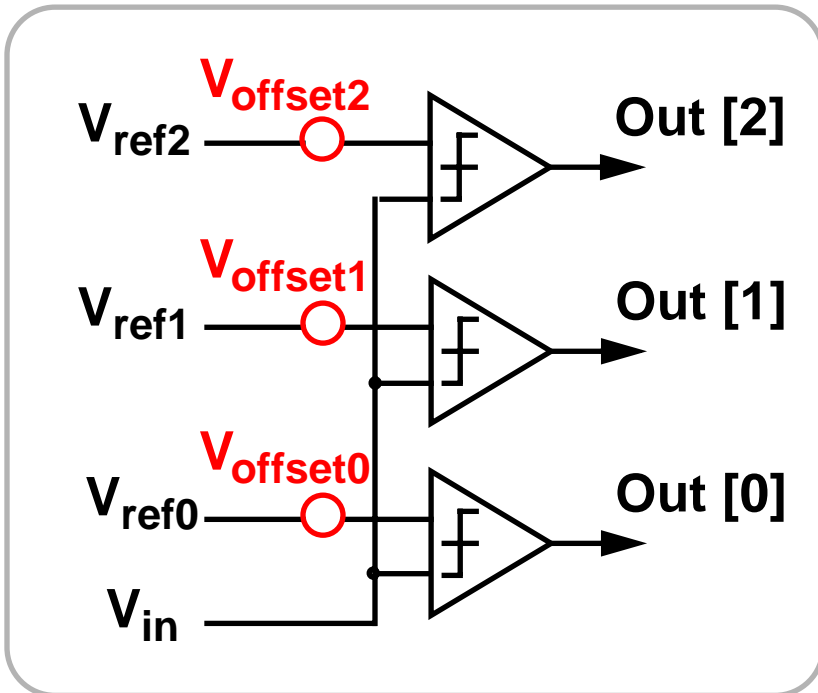
a_1 : 1st integrator gain
 a_2 : 2nd integrator gain
 b_1 : 1st integrator output feedforward gain

(-1 dB, 24.5 kHz input sinusoid)

- Integrator gain scaling helps tracking operation

Comparator Offset Mismatch

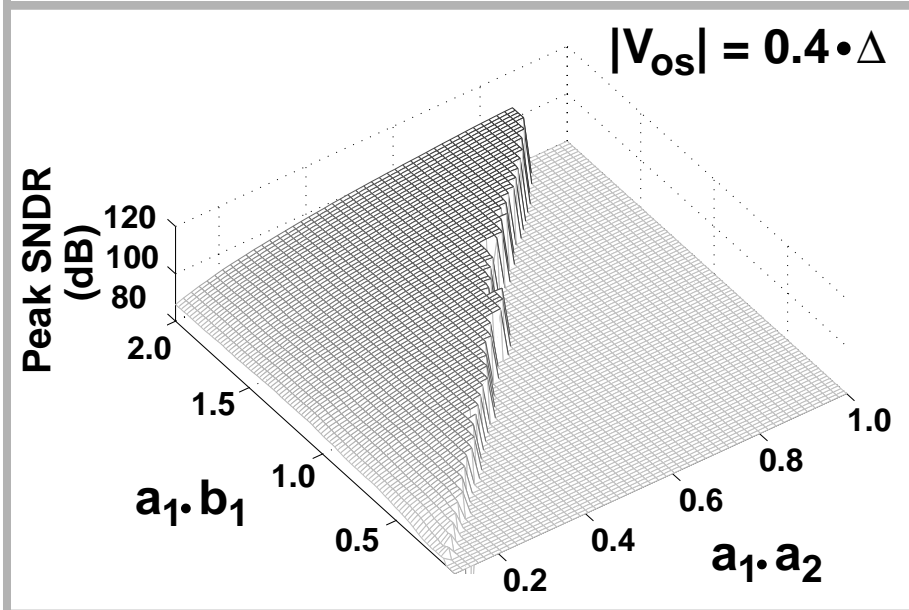
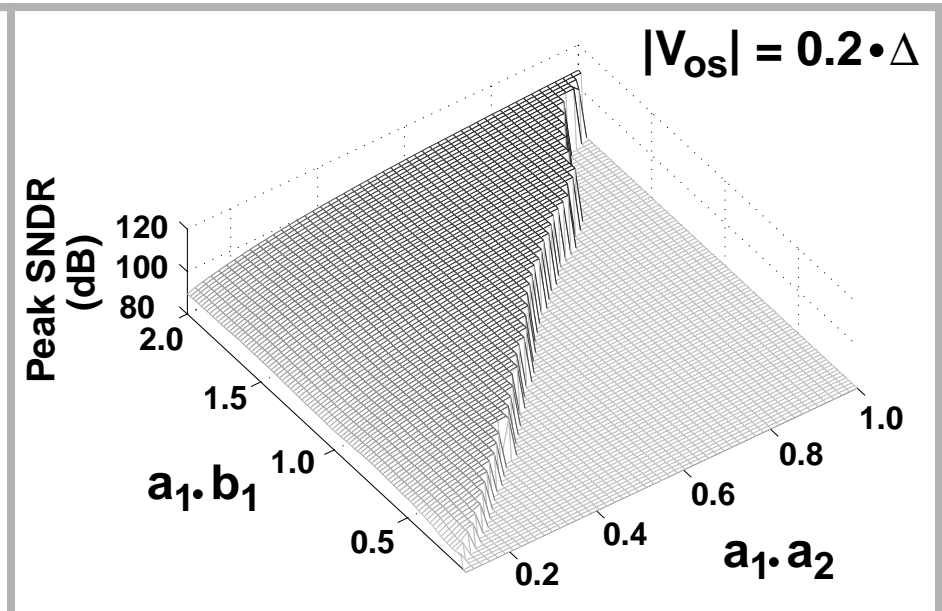
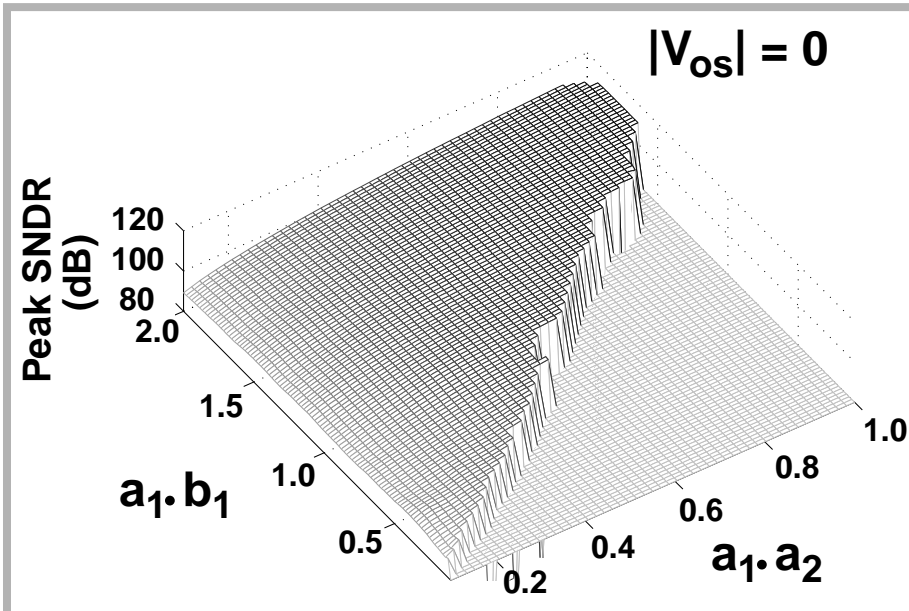
Modulator Baseband Output Spectrum*



*| $0.4 \cdot \Delta$ | offset mismatch

- Offset mismatch increases harmonics and noise floor
- Degraded tracking operation

Comparator Offset Mismatch: Tracking



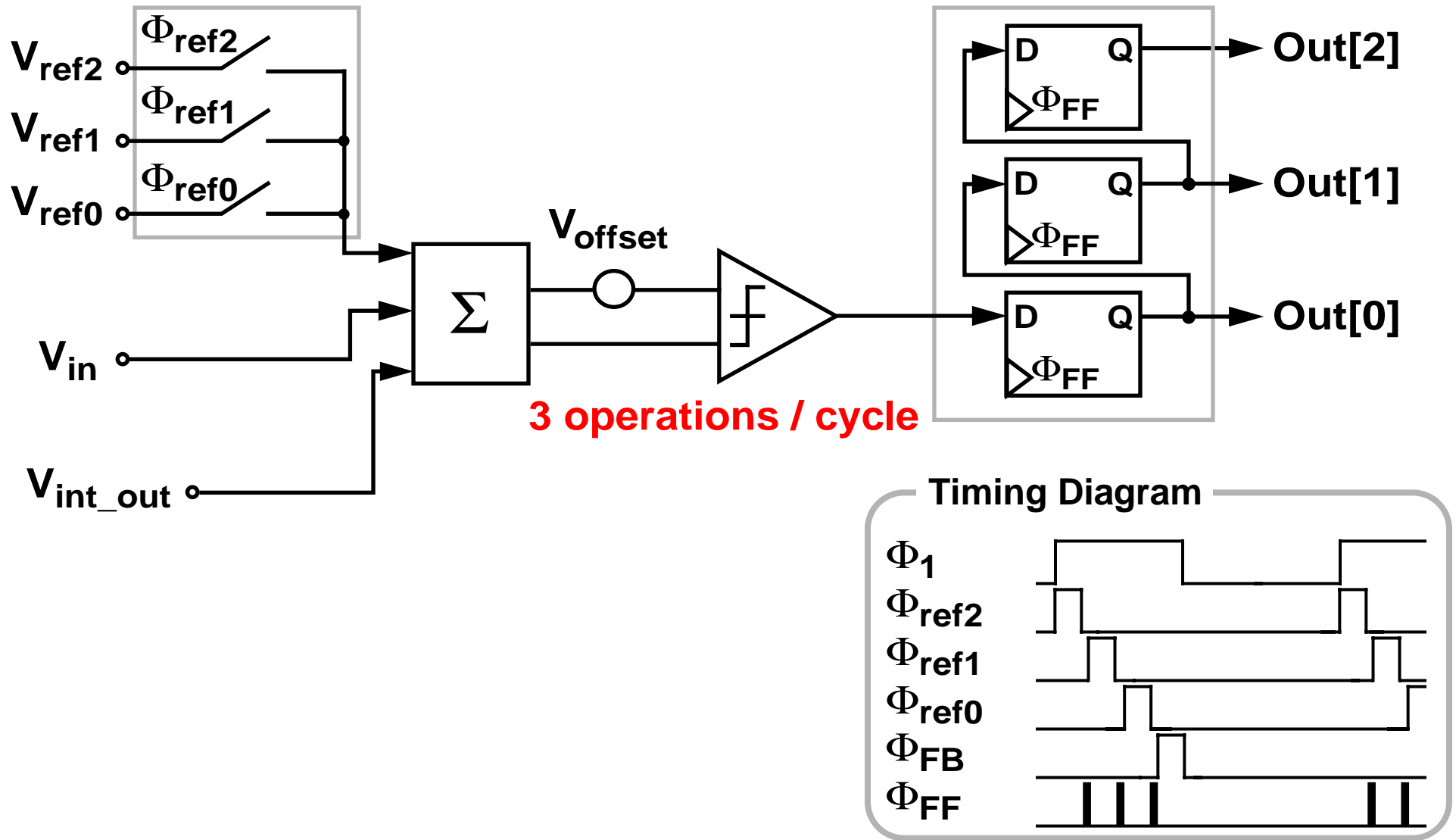
(-1 dB, 24.5 kHz input sinusoid)

a_1 : 1st integrator gain

a_2 : 2nd integrator gain

b_1 : 1st integrator output
feedforward gain

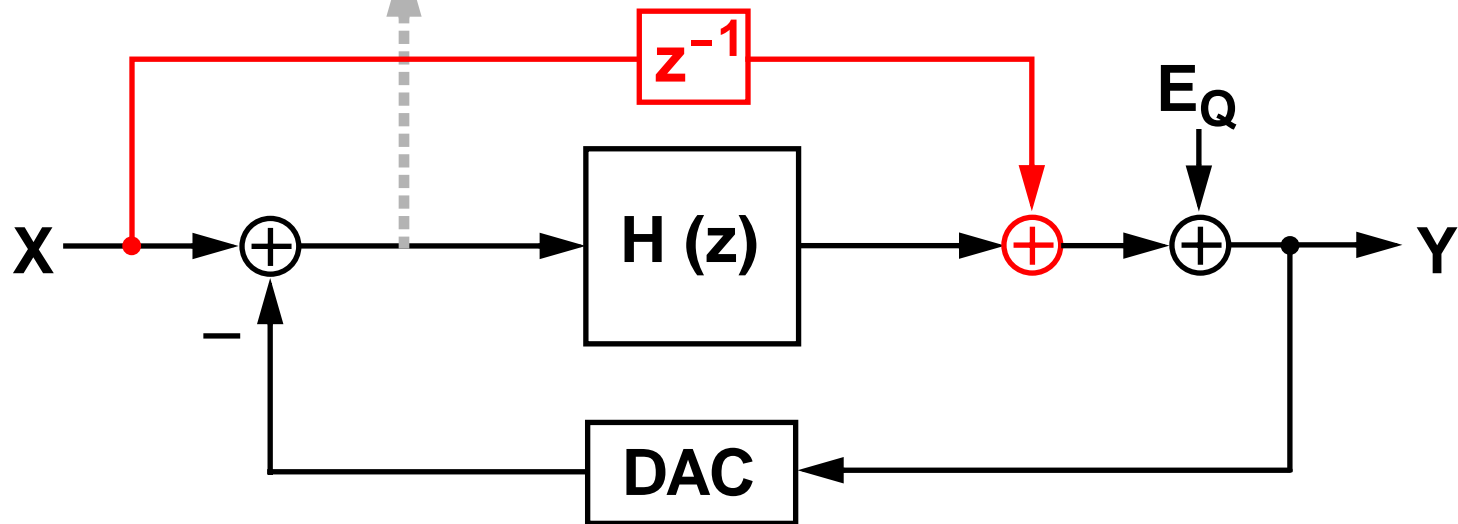
Single Comparator Tracking Multi-bit Quantizer



- **Timing overhead worse with input feedforward**

Delayed Input Feedforward

$$(1-z^{-1})^{L+1} \cdot X - (1-z^{-1})^L \cdot E_Q$$

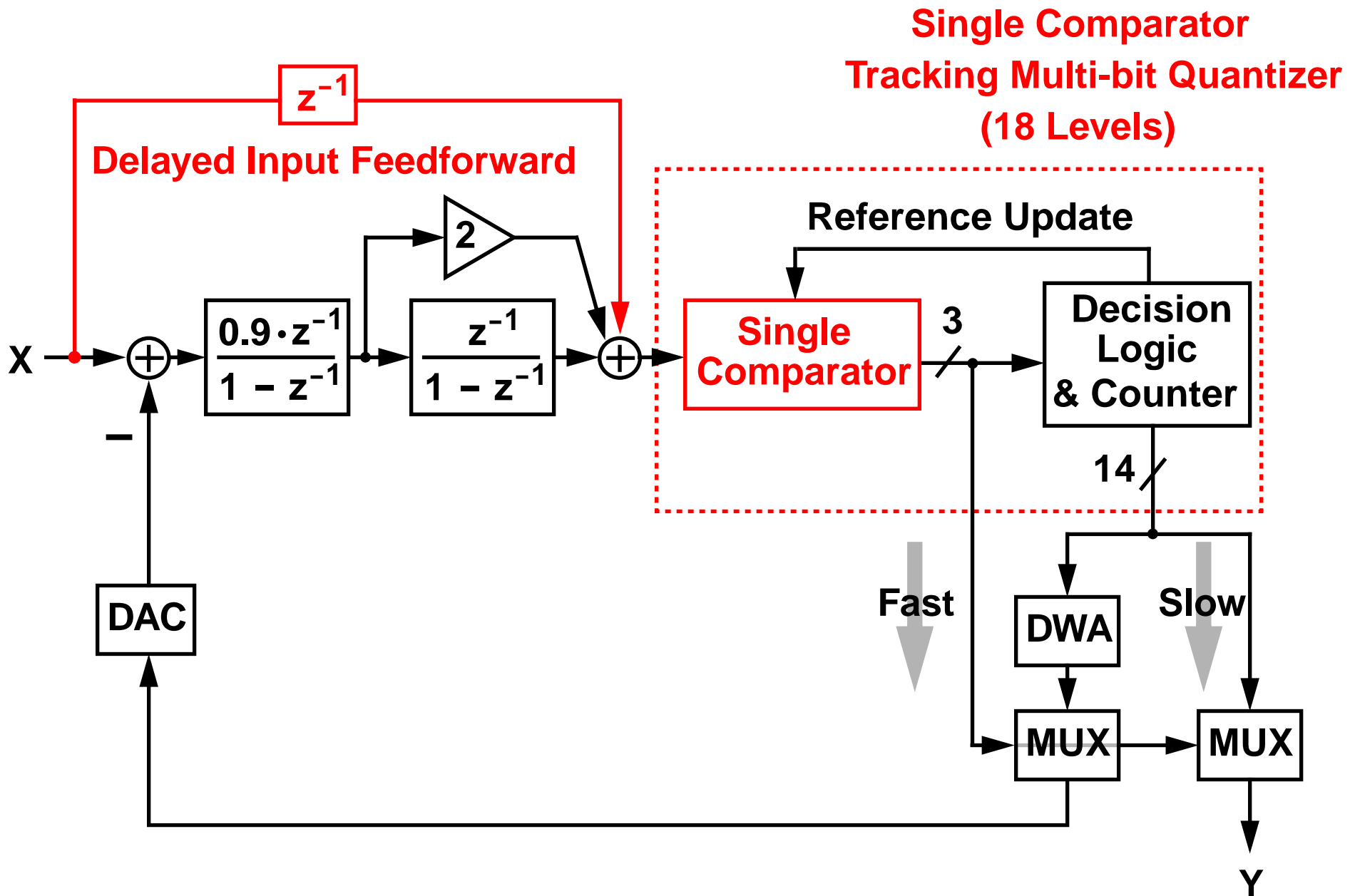


$$Y = \frac{z^{-1} + H(z)}{1 + H(z)} \cdot X + \frac{1}{1 + H(z)} \cdot E_Q$$

$$\text{if } \frac{1}{1 + H(z)} = (1 - z^{-1})^L$$

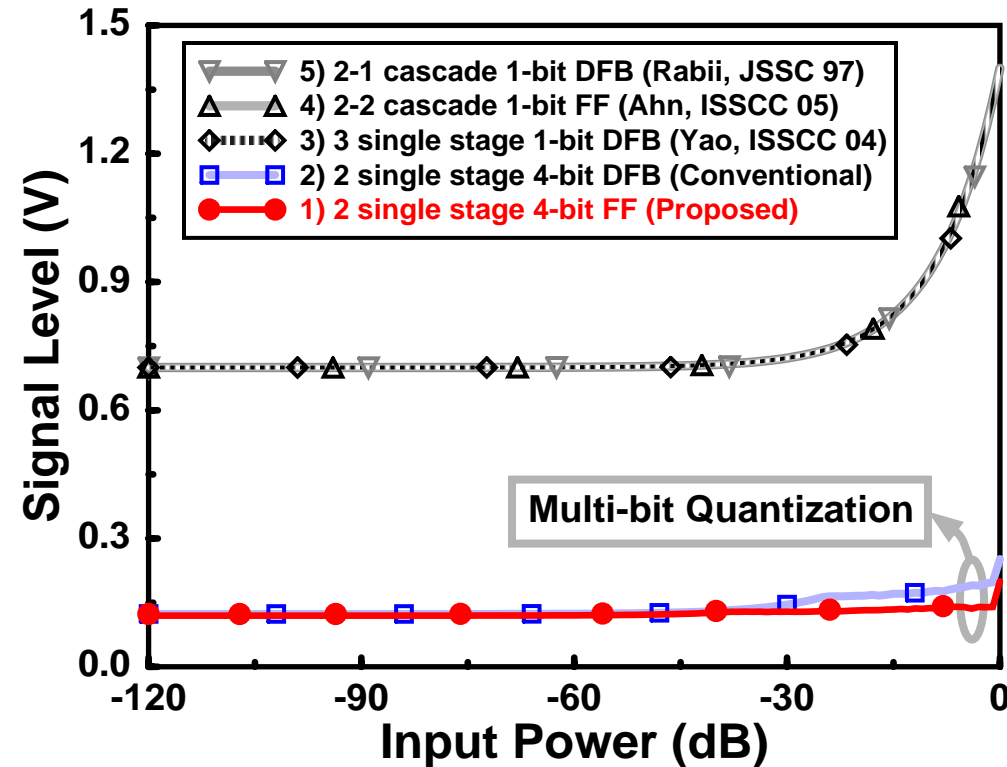
$$Y = (1 - (1 - z^{-1})^{L+1}) \cdot X + (1 - z^{-1})^L \cdot E_Q$$

Proposed $\Sigma\Delta$ Modulator Architecture

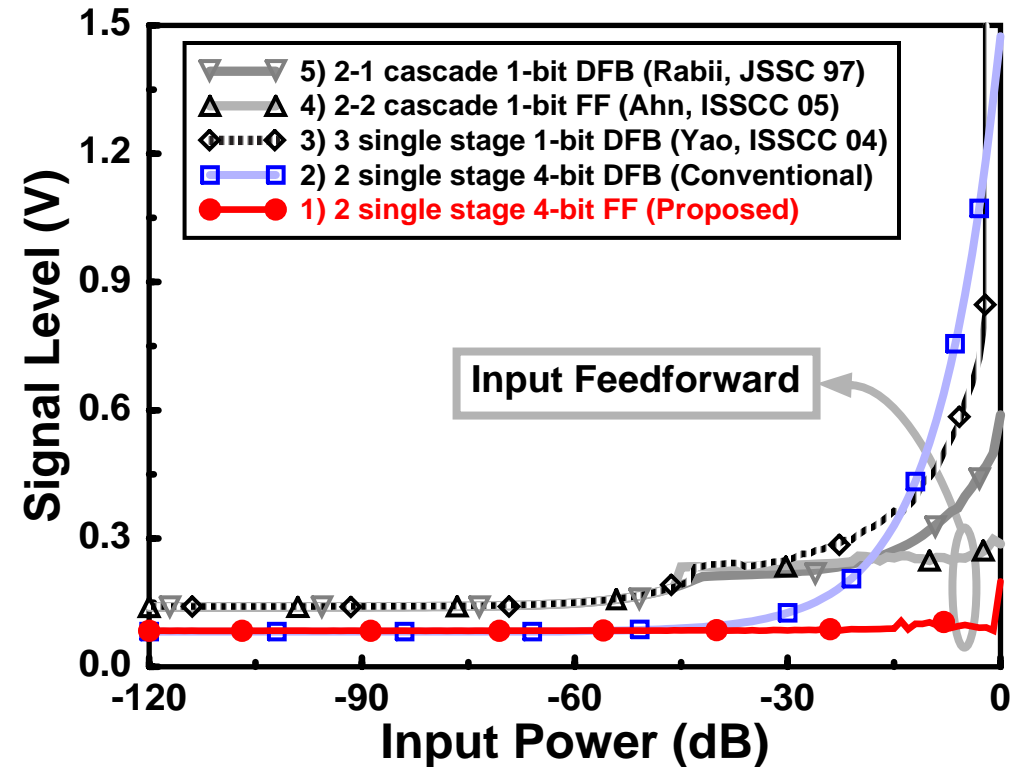


Integrator Swing Comparison*

First Integrator Max. Input Swing



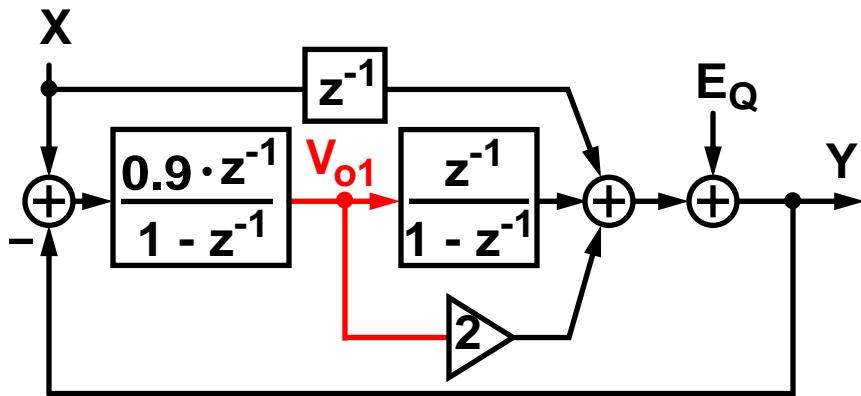
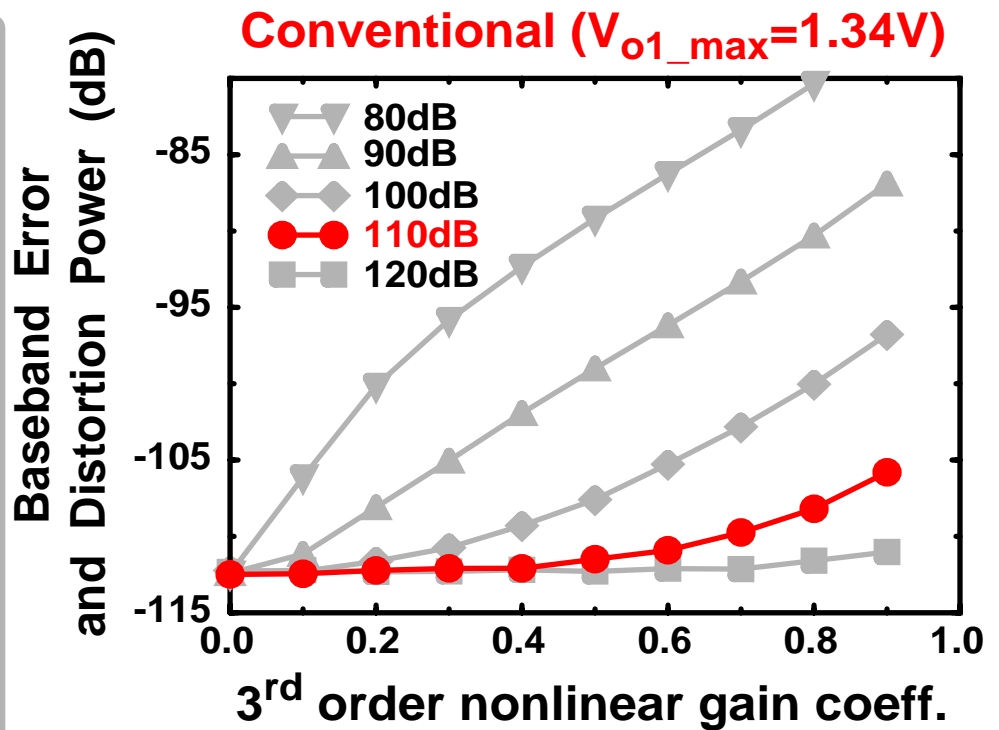
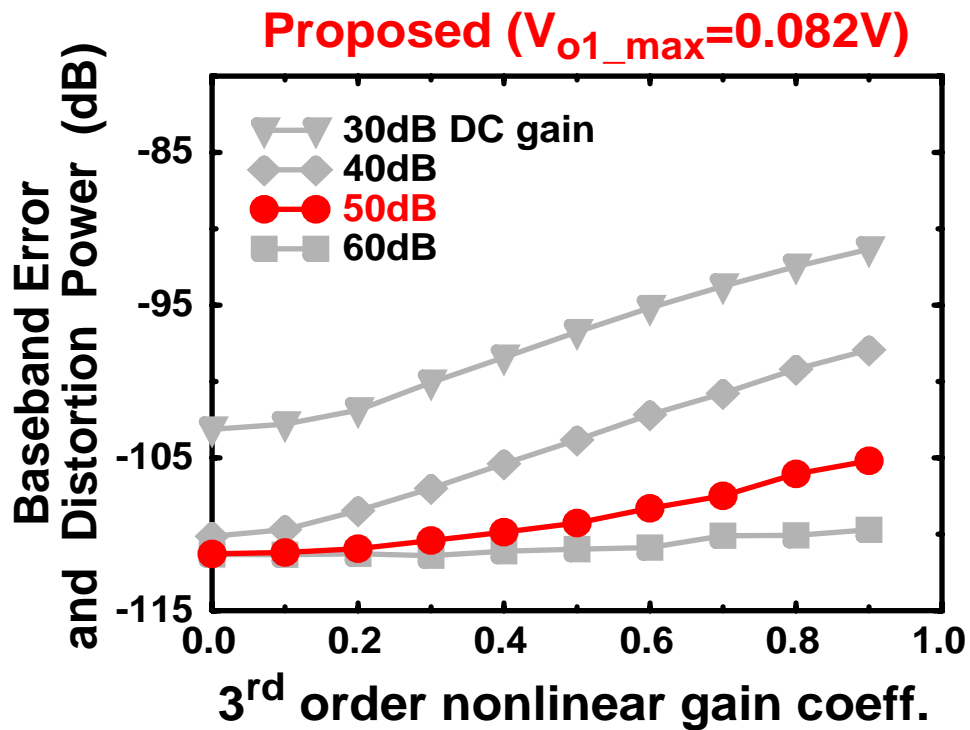
First Integrator Max. Output Swing



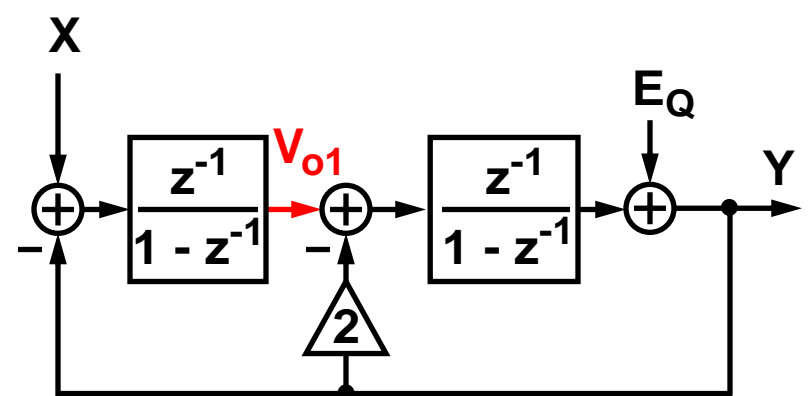
- FF (Feedforward), DFB (Distributed Feedback)
- Multi-bit quantization → input swing reduction
- Input feedforward → output swing reduction

* 24.5 kHz input sinusoid, OSR=100, $V_{ref}=0.7V$

System Robustness: Amplifier Gain Nonlinearity *



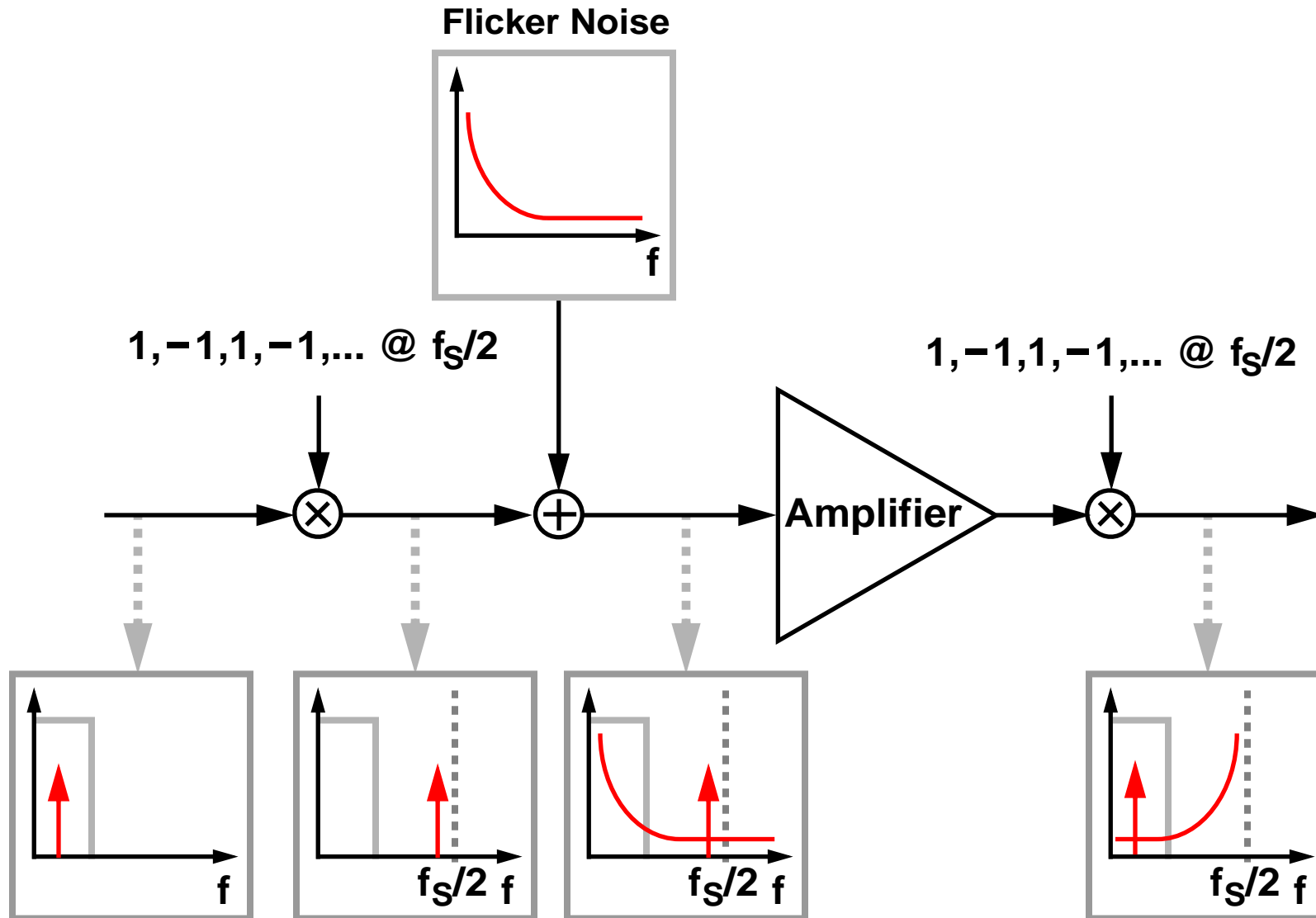
$$V_{o1} \sim z^{-1}(1-z^{-1})^2 \cdot X - z^{-1}(1-z^{-1}) \cdot E_Q$$



$$V_{o1} = (1+z^{-1}) \cdot X - z^{-1}(1-z^{-1}) \cdot E_Q$$

* -1 dB, 8 kHz input sinusoid ($V_{ref}=0.7V$)

Flicker Noise Reduction

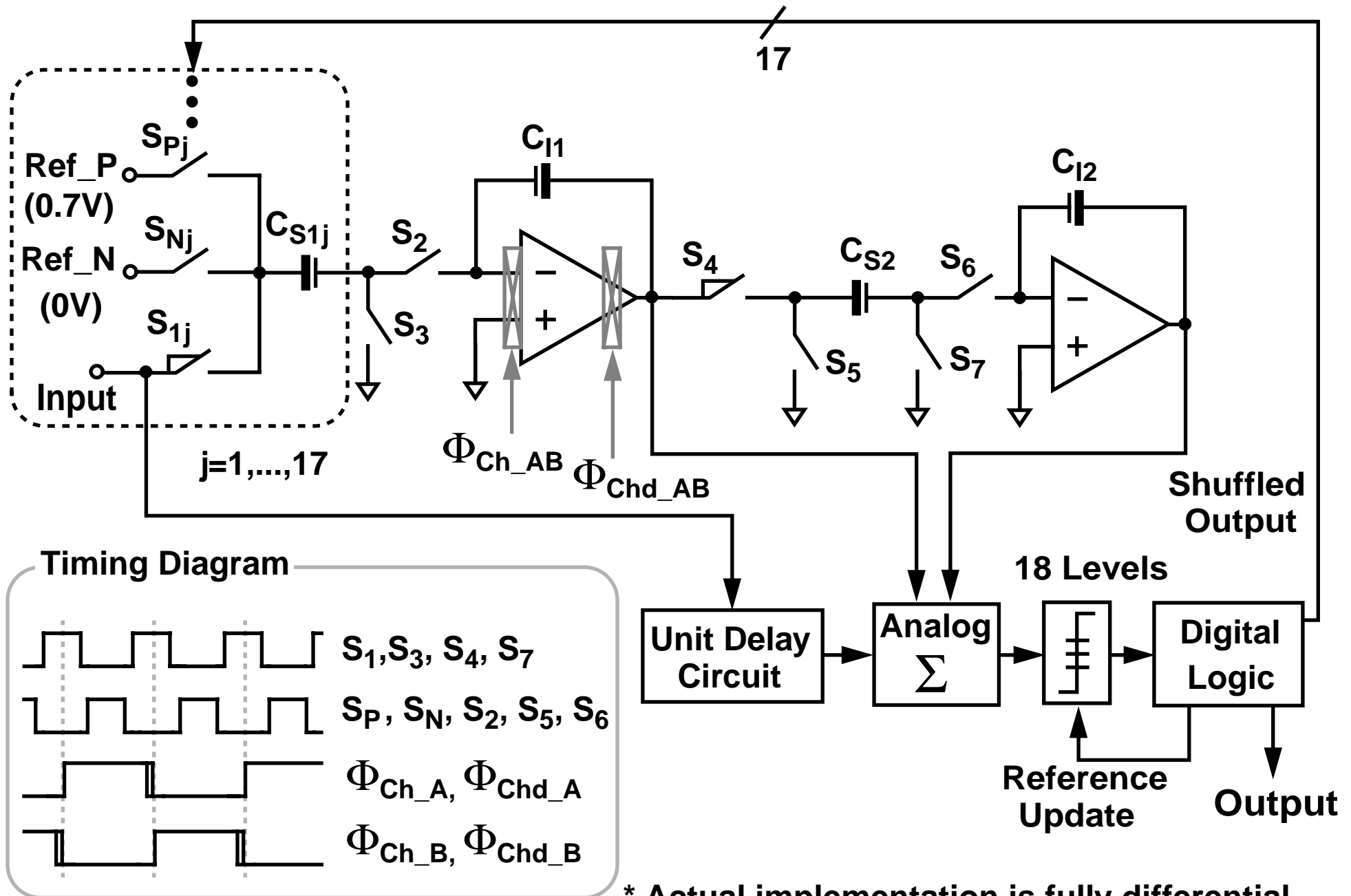


- Chopper stabilization

Outline

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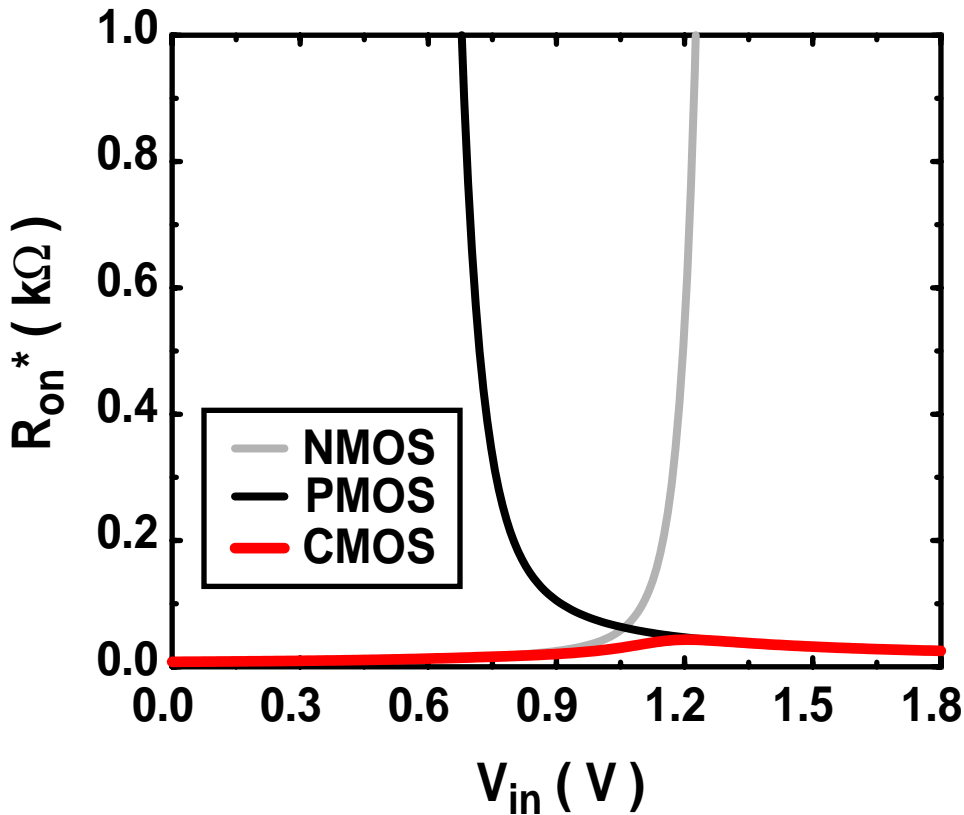
Modulator Architecture*



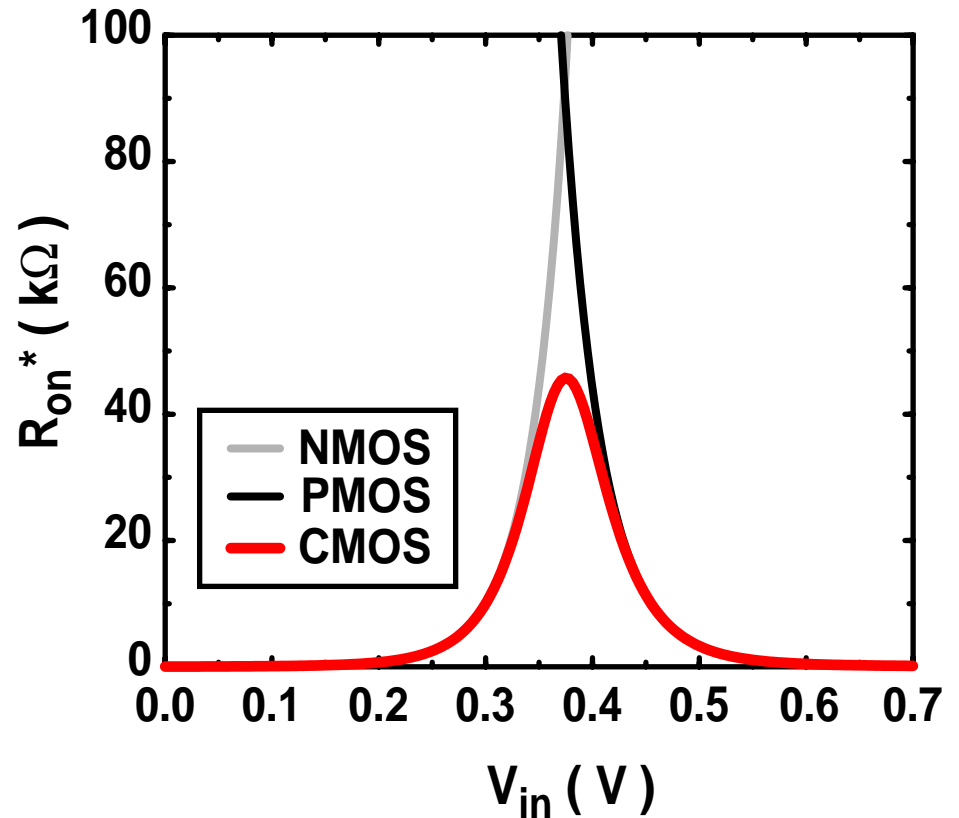
* Actual implementation is fully differential

Switch at Low Supply Voltage

$V_{DD} = 1.8V$



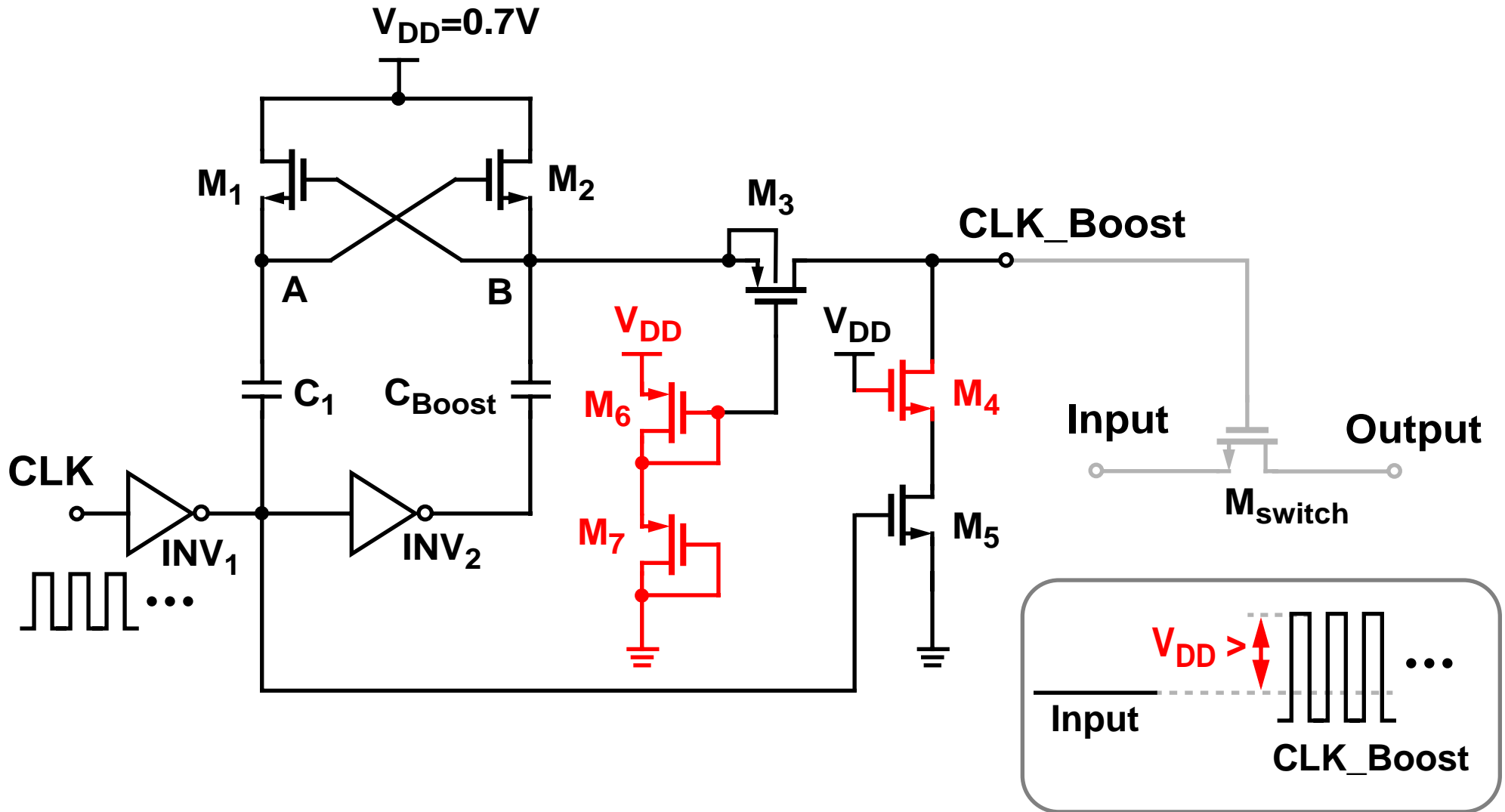
$V_{DD} = 0.7V$



*CMOS 0.18 μm , $L=0.18\mu m$, $W=100\mu m$, $V_{ov}=0.2V$

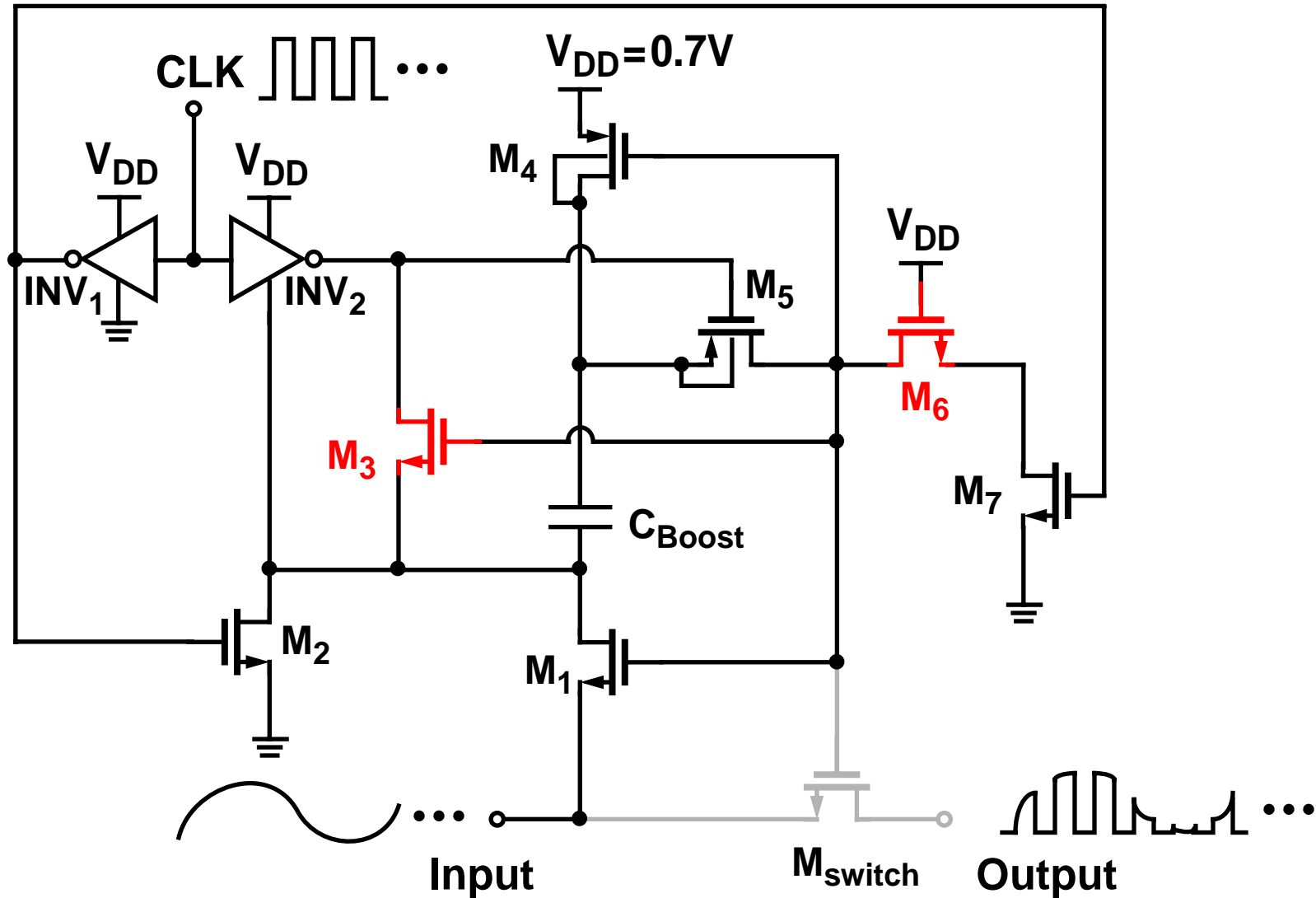
- Limited switch input range at low supply voltage

Low-Voltage Switch: Local Boosting



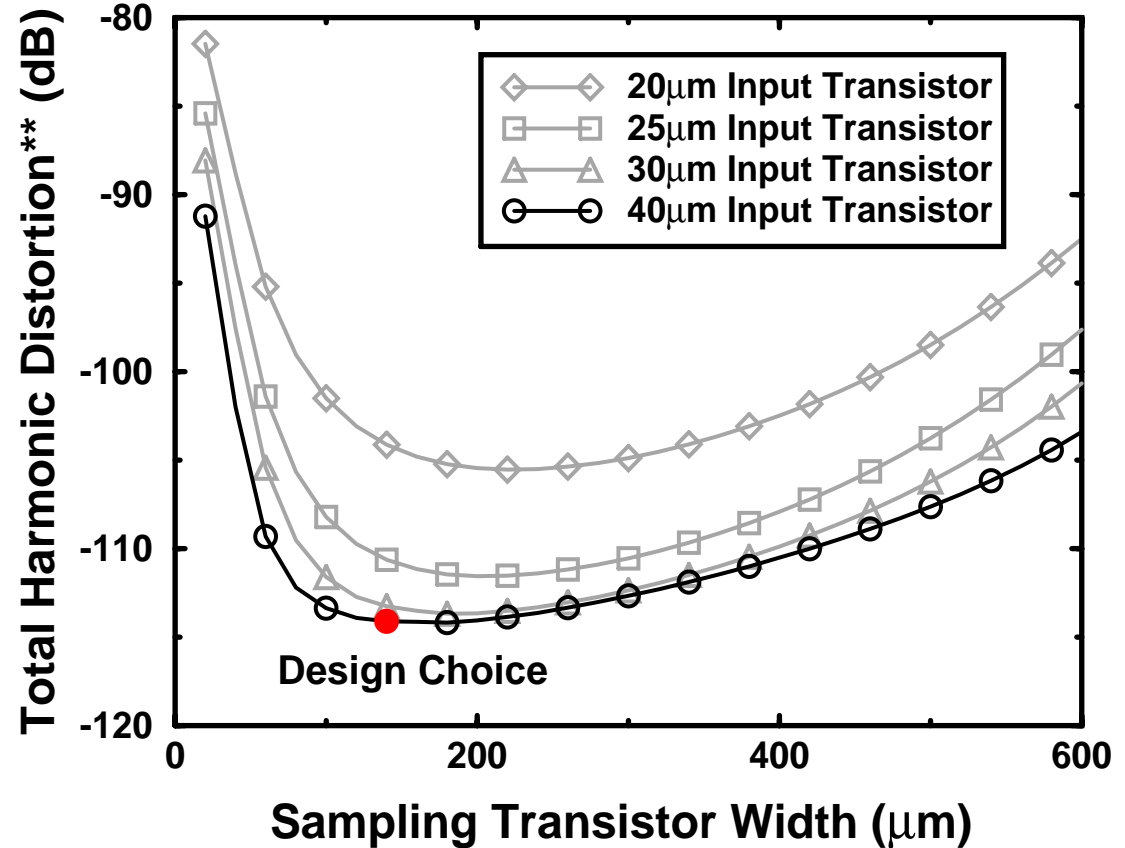
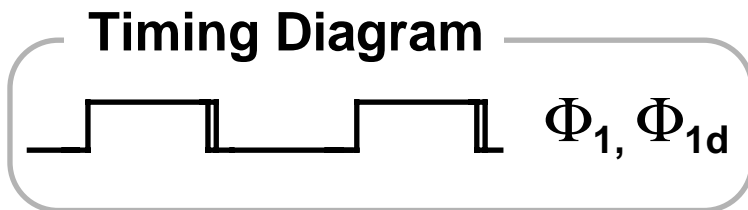
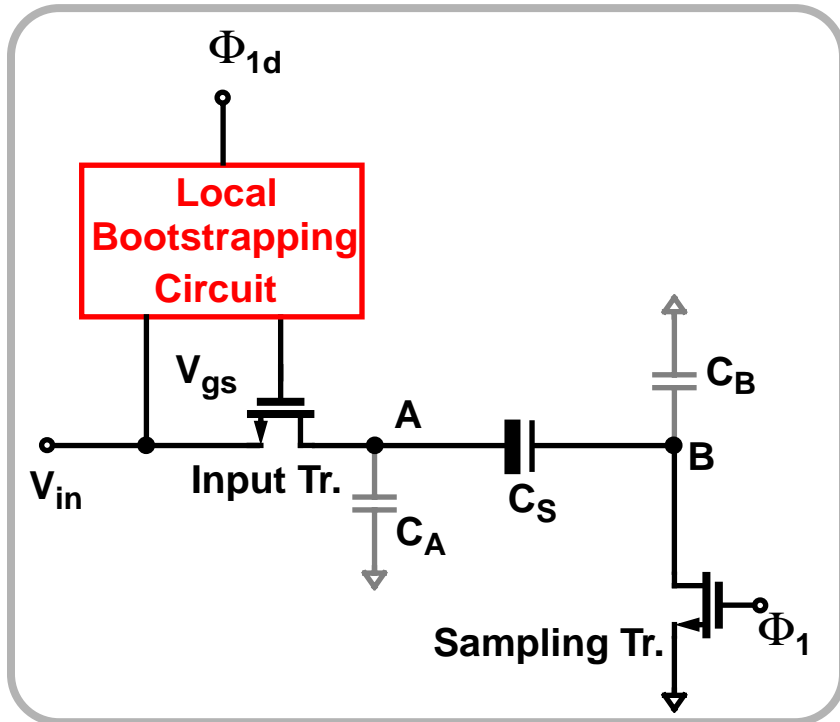
- Used to process DC signals

Low-Voltage Switch: Local Bootstrapping*



- Used to process dynamic signals with high-precision

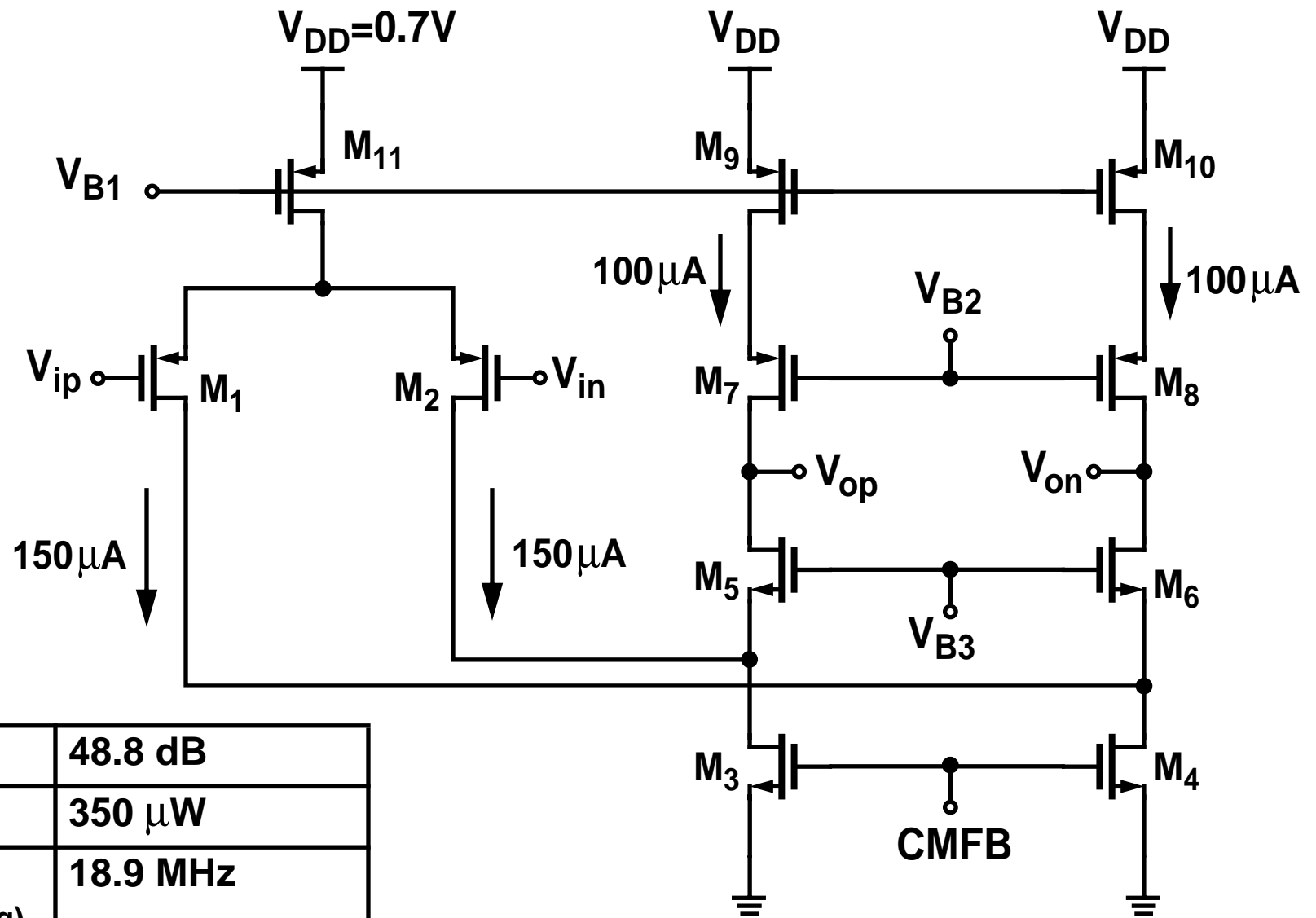
Input Sampling Network Design*



* Actual implementation is fully differential
 **0 dB, 7.328 kHz Input Sinusoid ($V_{ref} = 0.7V$)

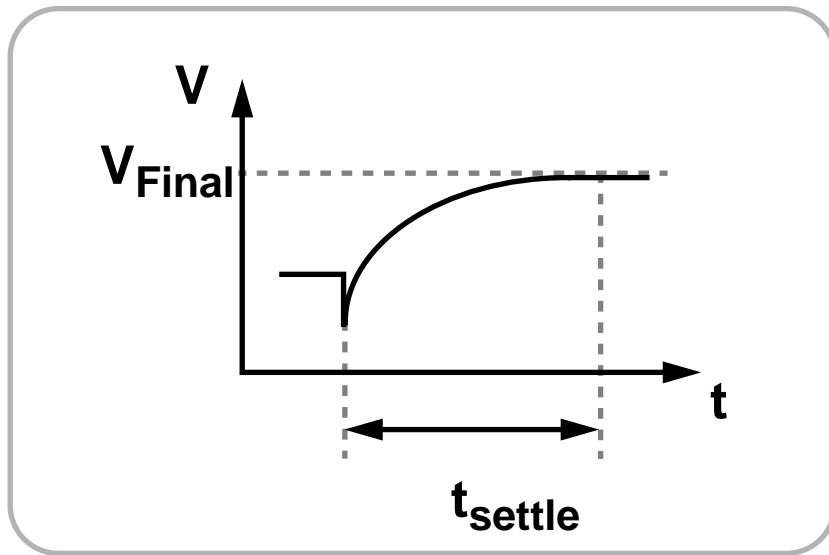
- **-113 dB THD with 18pF input sampling capacitor (C_S) @ 0.7-V supply**

First Integrator Op Amp



DC Gain	48.8 dB
Power	350 μW
BW_u (@ 18pF loading)	18.9 MHz
V_{CM}	0V (Input), 0.35V (Output)

Op Amp Power Reduction



$$n = \frac{t_{\text{settle}}}{\tau}$$

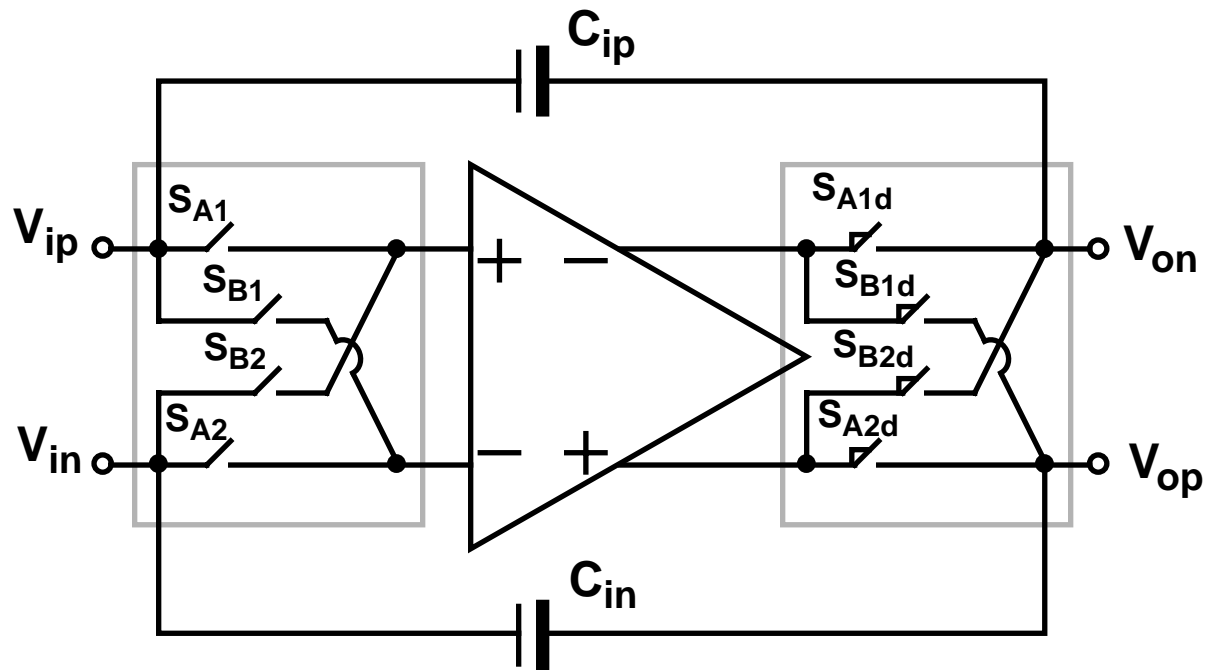
n	Gain Error
1	0.632
2	0.865
3	0.950
4	0.982
5	0.993
6	0.998

$$V(t_{\text{settle}}) = V_{\text{Final}} \cdot \left(1 - e^{-\left(\frac{t_{\text{settle}}}{\tau}\right)}\right)$$

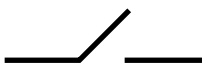
Fixed Integrator Gain Error

- Reduced integrator input swing → op amp never slews
- Incomplete but linear settling op amp → low power
- In implementation, $n \sim 3.8$

Chopper Stabilization Circuit

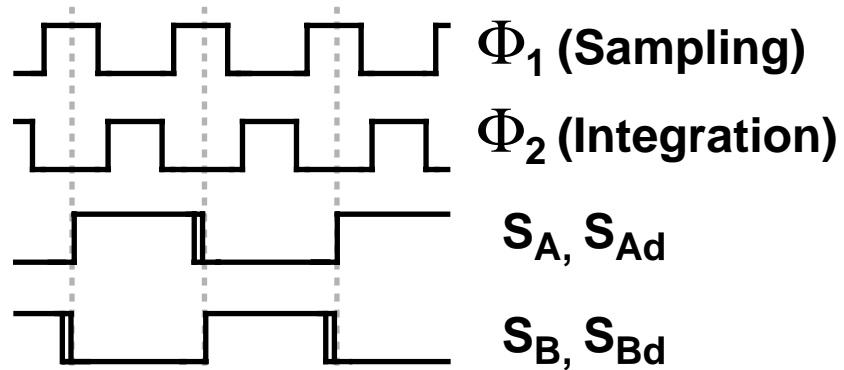


Switch Symbols


 NMOS switch

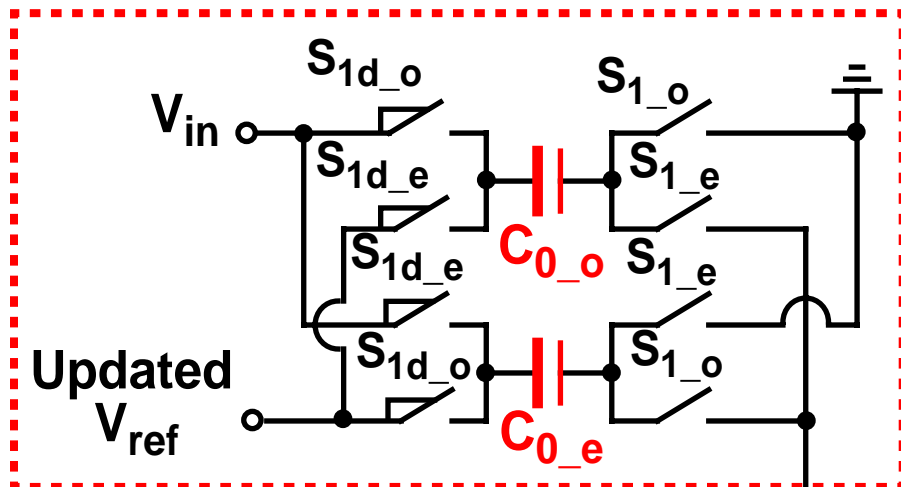

 NMOS switch
 with local gate
 bootstrapping

Timing Diagram

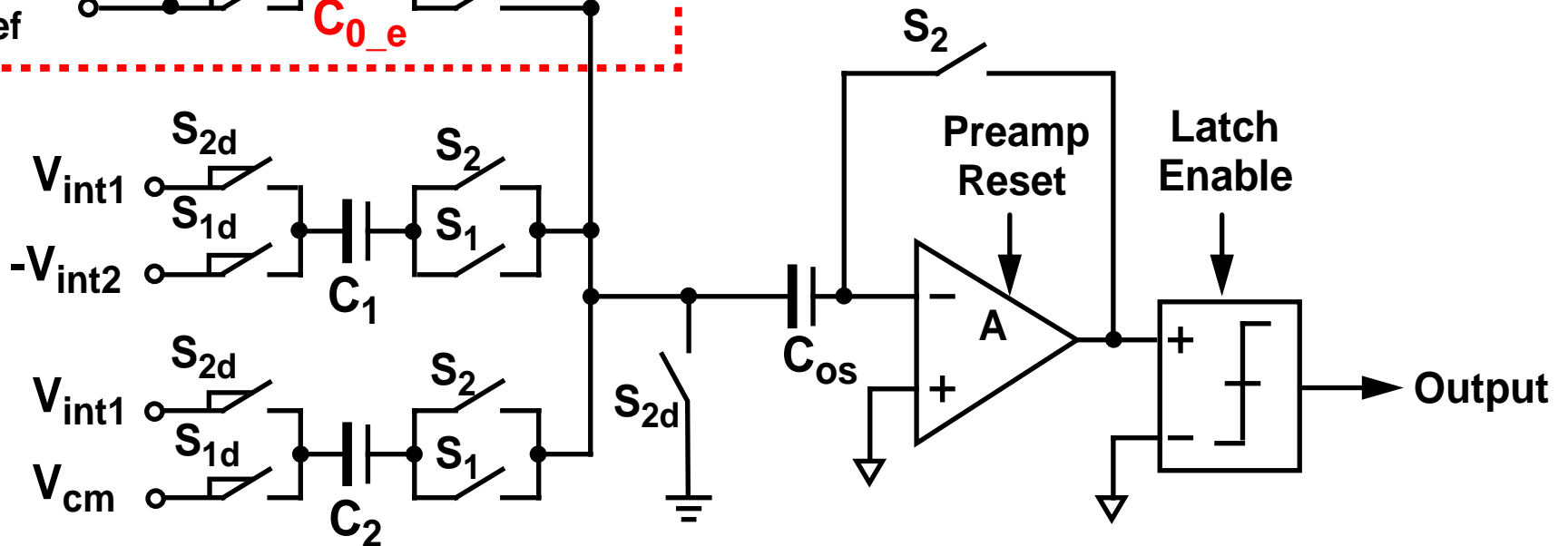
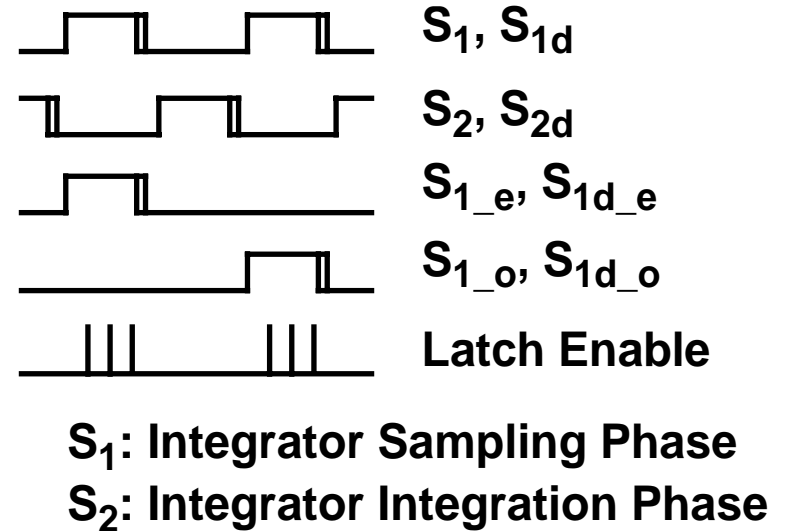


Analog Summation and Quantizer

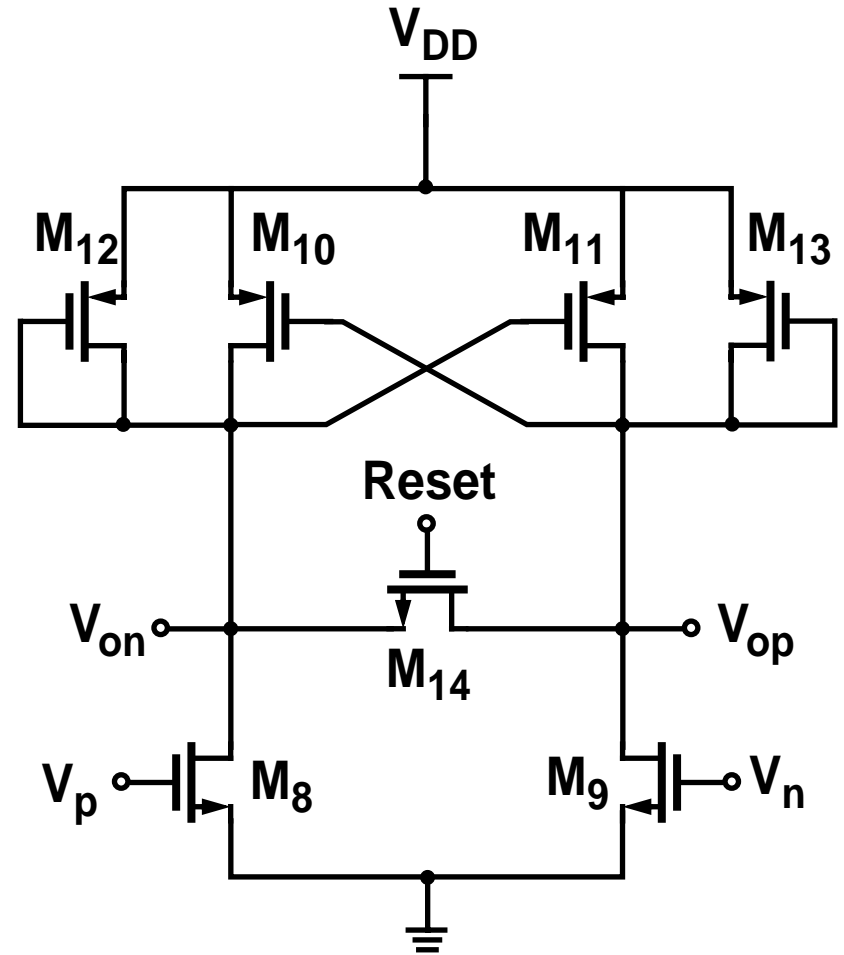
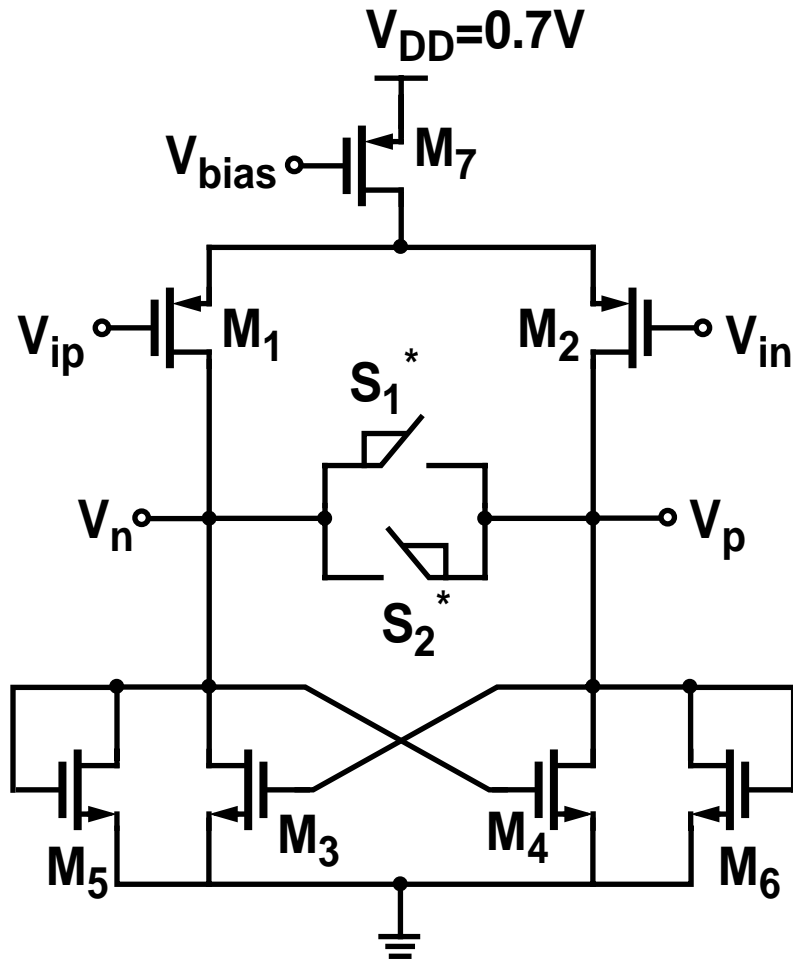
Delayed Input Feedforward



Timing Diagram



Comparator Preamps

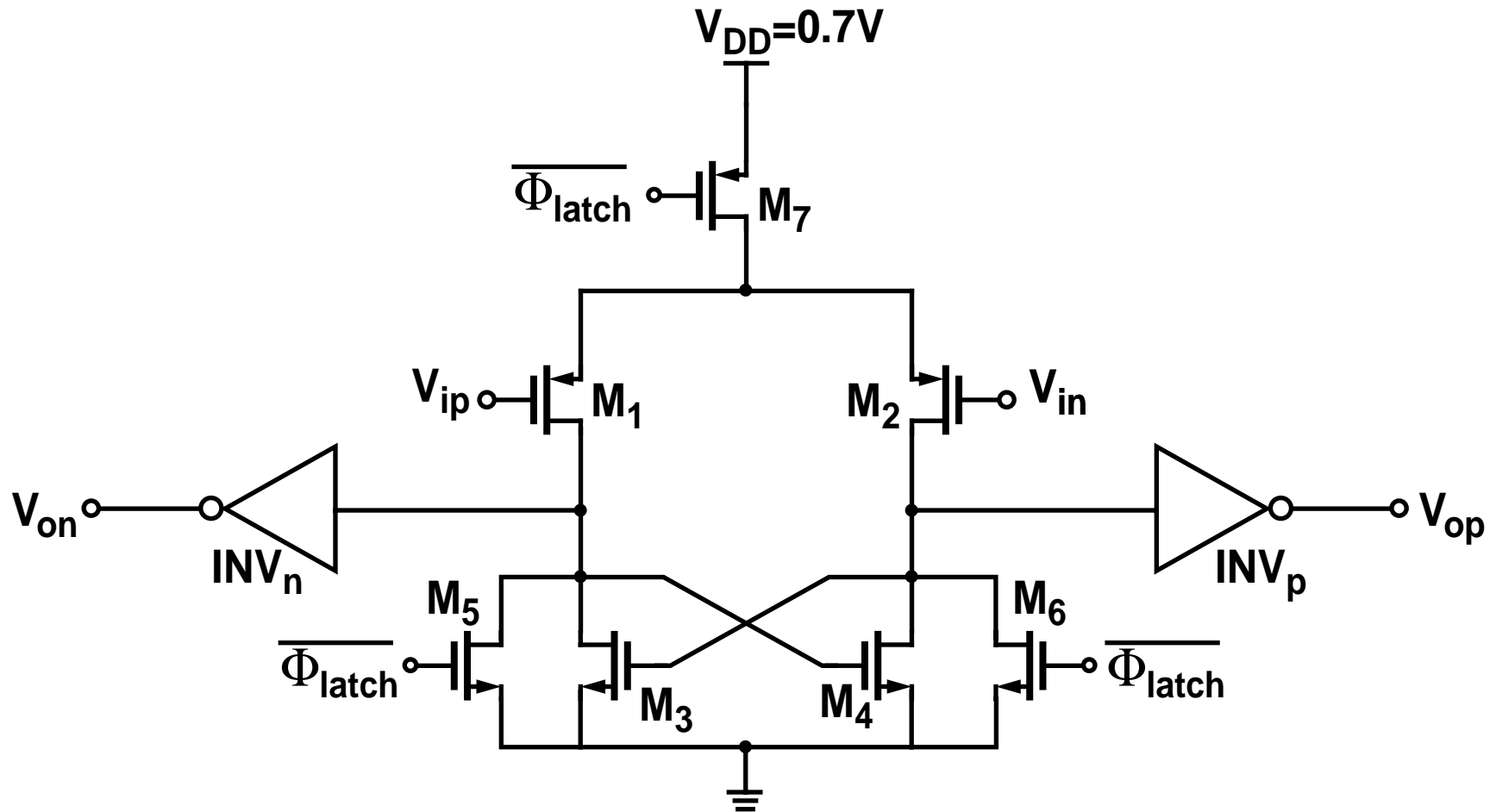


When cascaded,

* S_1, S_2 : Bootstrapped NMOS Switch

DC Gain	6.8	$BW_{\text{open-loop 3dB}}$	174 MHz
Power	149 μW	$BW_{\text{closed-loop unity}}$	140 MHz
3- σ V_{os}	19 mV	Phase Margin	58 Degree

Comparator Latch*



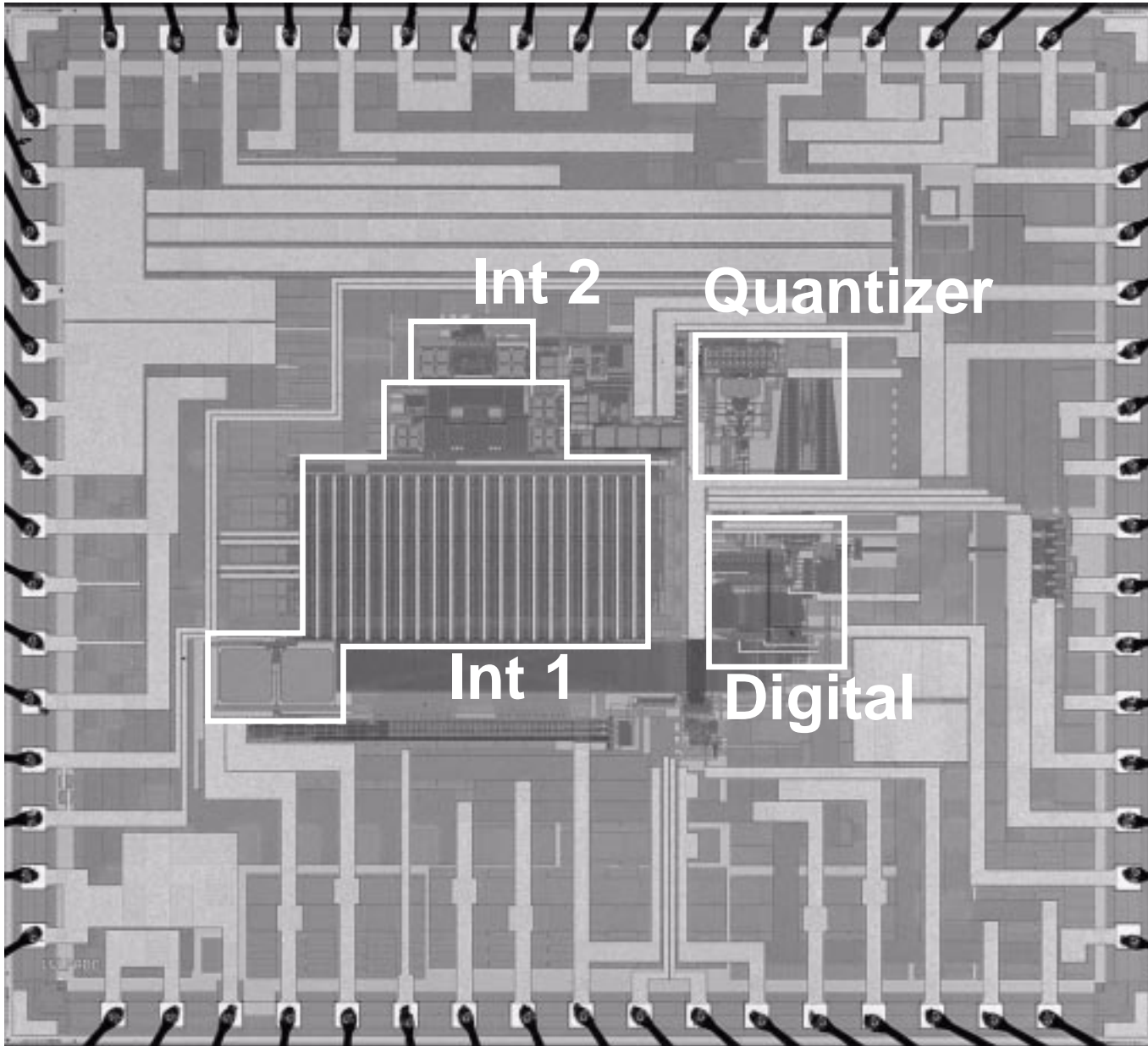
Average Power	~14 μW
t_{regen} @ 5 mV _{pp} input	~2.1 nsec
3- σ V_{os}	23 mV

*S. Limotyrakis, ISSCC 2004

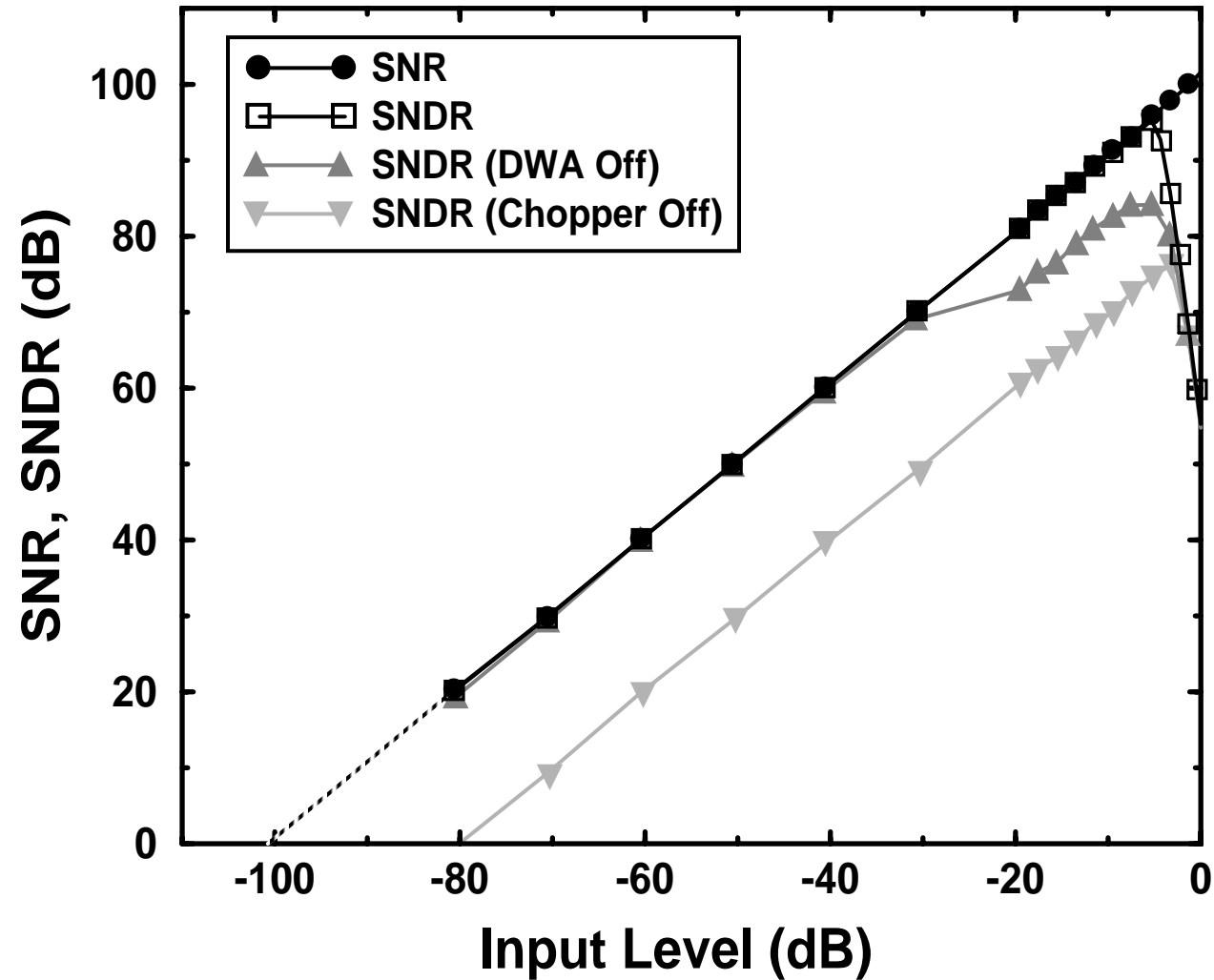
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Prototype Chip Photograph

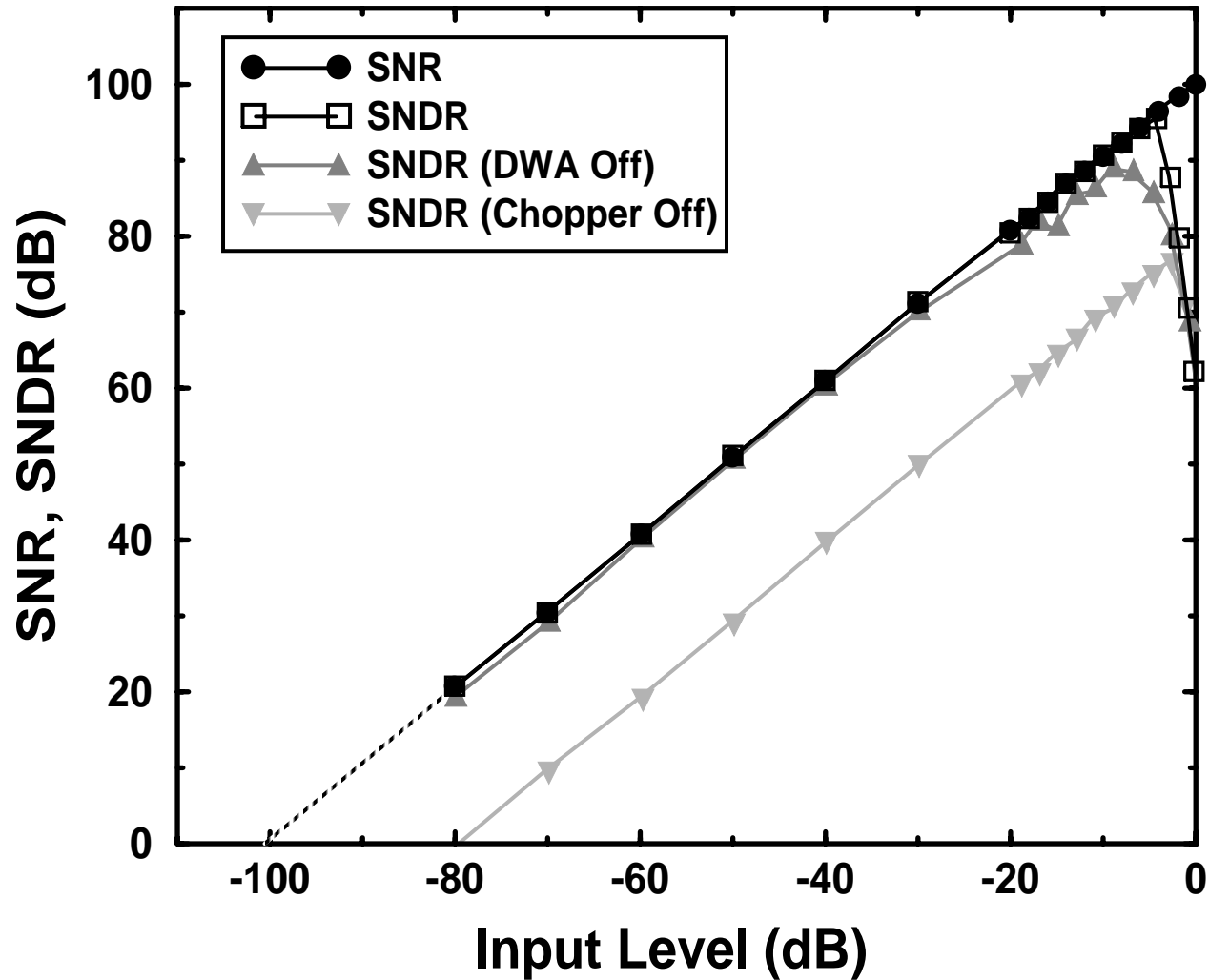


Measured SNDR (1 of 2)



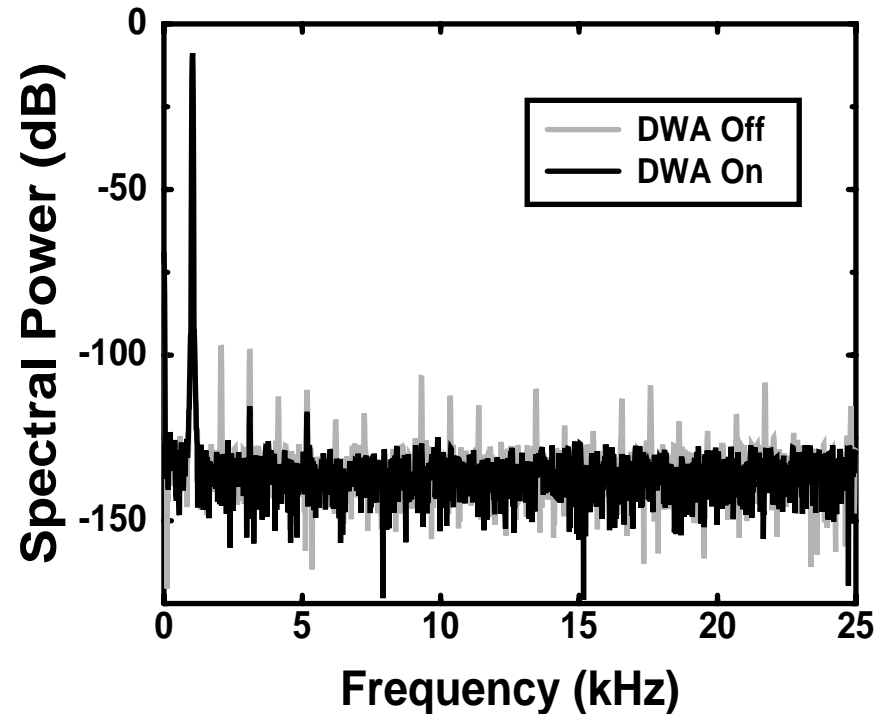
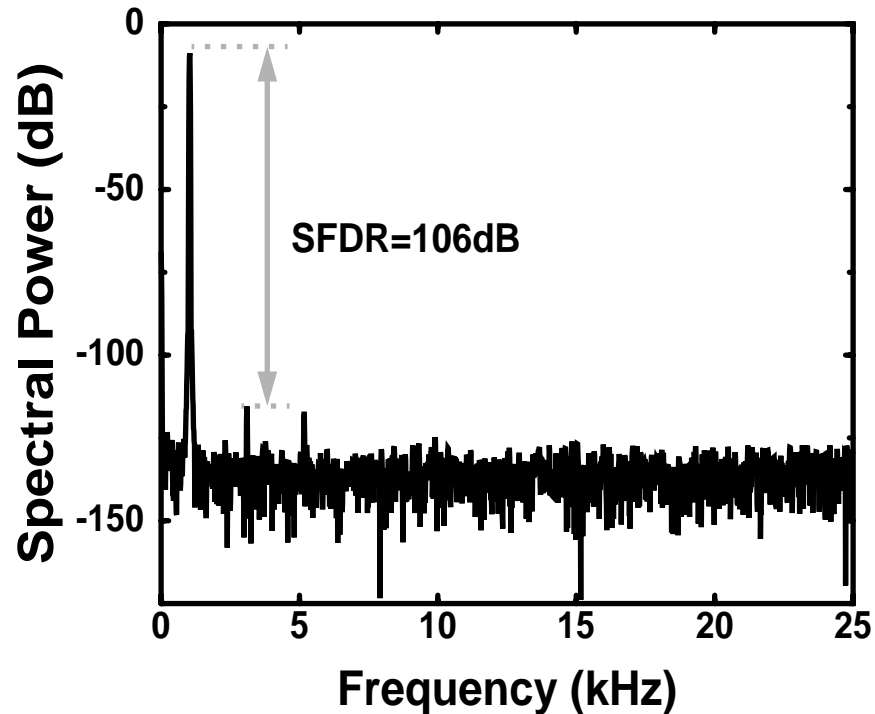
- 1 kHz input sinusoid

Measured SNDR (2 of 2)



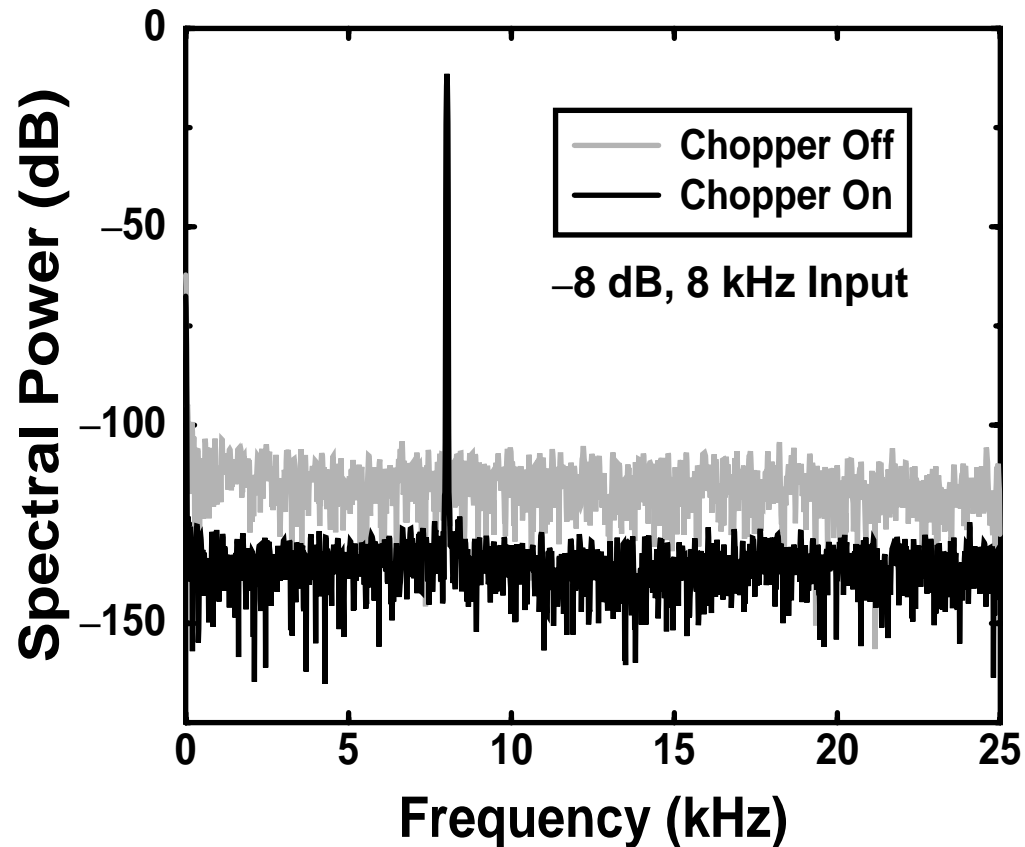
- 8 kHz input sinusoid

Measured Output Spectrum (1 of 2)



- **-5 dB, 1 kHz input sinusoid**
- **DWA provides required linearity**

Measured Output Spectrum (2 of 2)



- **-8 dB, 8 kHz input sinusoid**
- **Chopper stabilization effectively removes flicker noise**

Performance Summary

Supply Voltage	0.7 V
Sampling Rate	5 MHz
References	0 V, 0.7 V
Signal Bandwidth	25 kHz
Dynamic Range	100 dB
Peak SNR	100 dB
Peak SNDR	95 dB
Power: Analog	680 μW
 Digital	190 μW
Area (excluding decoupling capacitors, pads & output drivers)	2.16 mm²
Technology	0.18-μm CMOS

Comparison

	This Work	G. Ahn, et al., ISSCC 05	K. Poon, et al., ISSCC 06	M. Kim, et al., VLSI 06
Power Supply (V)	0.7	0.6	0.5	0.9
Signal Bandwidth (kHz)	25	24	25	24
Clock Frequency (MHz)	5	3.072	3.2	6.144
OSR	100	64	64	128
Total Power (μ W)	870 (Analog : 680)	1000	300	1500
Input Range (V _{pp})	1.4	0.8	1	1.1
Dynamic Range (dB)	100	78	N/A	92
Peak SNR (dB)	100	77	76	91
Peak SNDR (dB)	95	77	74	89
Active Die Area (mm ²)	1.8 x 1.2	1.8 x 1.6	0.6	1.6 x 0.9
Technology	0.18μm CMOS	0.35 μ m CMOS Low V _{th}	0.18 μ m CMOS Triple Well	0.13 μ m CMOS
Type	Switched Cap	Switched Cap	Continuous	Switched Cap
Order	2	2 - 2	3	3
Quantization	Multi-bit (18 levels)	1.5-bit	1-bit	1.5-bit

Outline

- Introduction
- Proposed ADC architecture
- Implementation
- Experimental results
- **Conclusion**

Conclusion

- **Low-voltage strategies**
 - Input feedforward + Multi-bit quantization
 - Locally boosted or bootstrapped switches
- **Low-power strategies**
 - Tracking multi-bit quantization
 - Delayed input feedforward
 - Incomplete but linear op amp settling
- **High-precision strategies**
 - Input feedforward
 - Single comparator multi-bit quantization scheme
 - Chopper stabilization
- **Analog-to-digital interface design challenges imposed by technology scaling can be overcome by architecture level innovation and circuit level solutions**