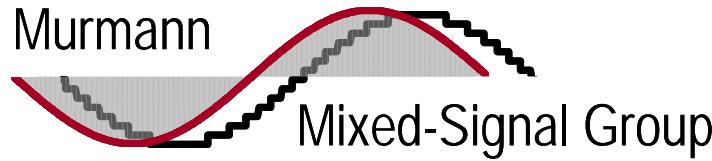


Future Directions in Mixed-Signal IC Design

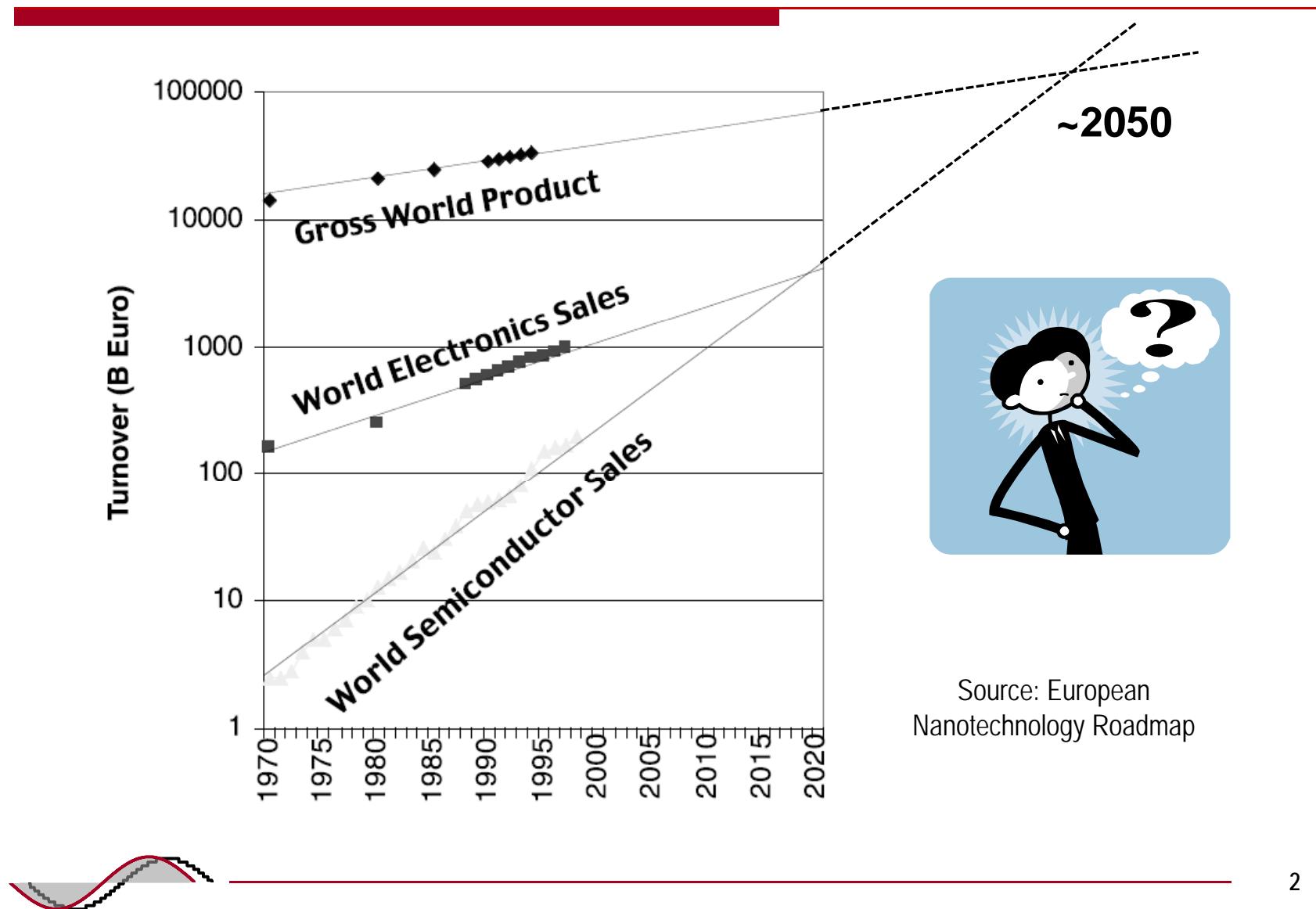
December 12, 2008

Boris Murmann

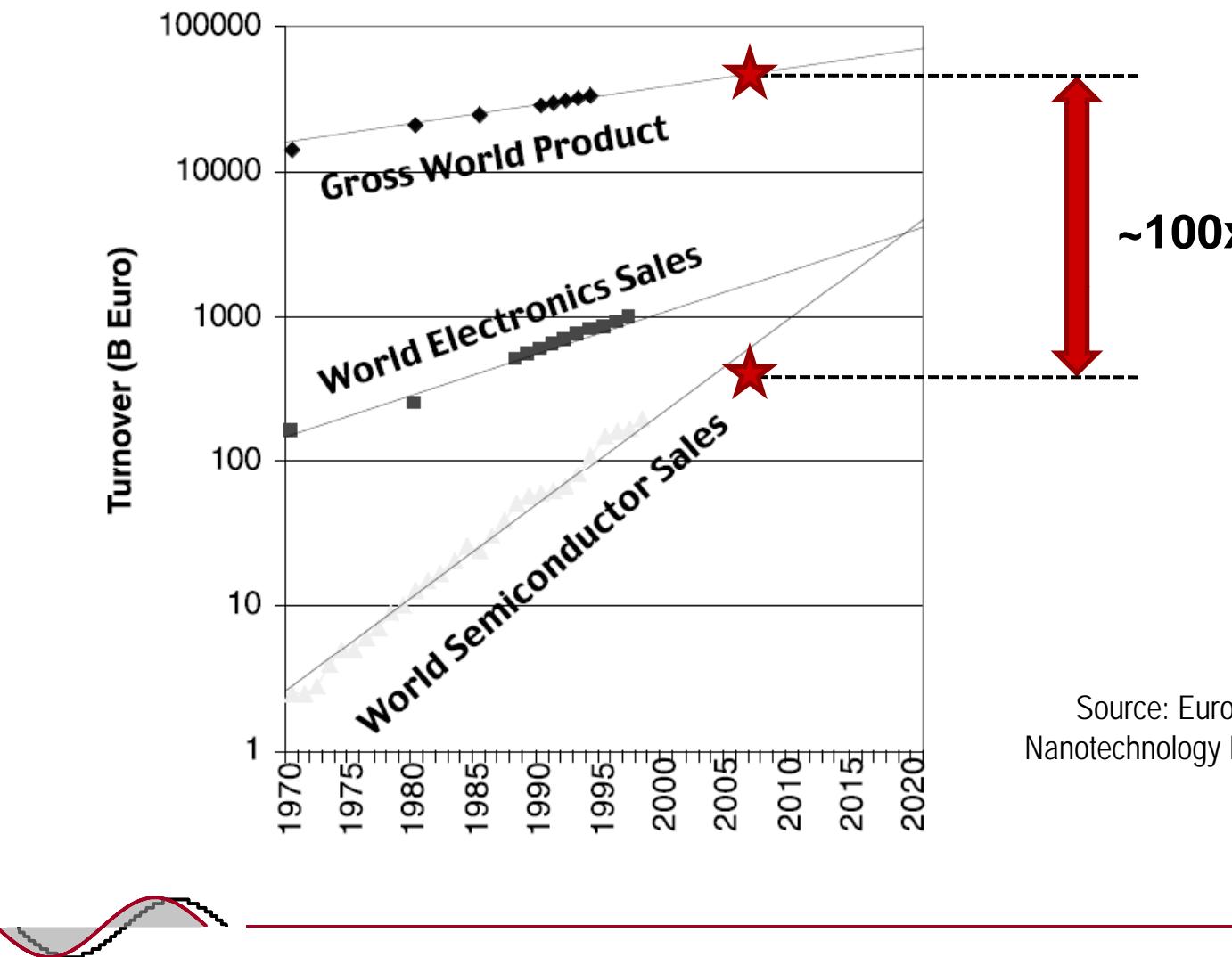
murmann@stanford.edu



Growth



Business as Usual?

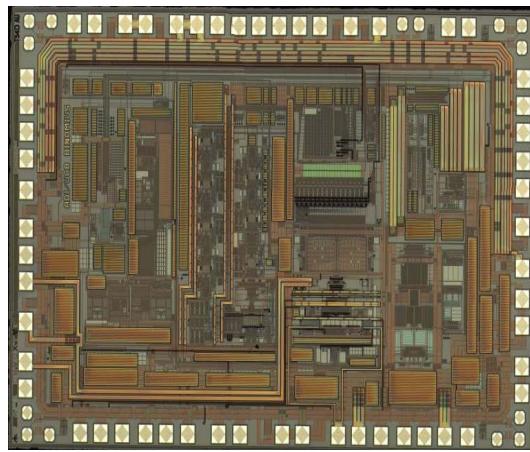
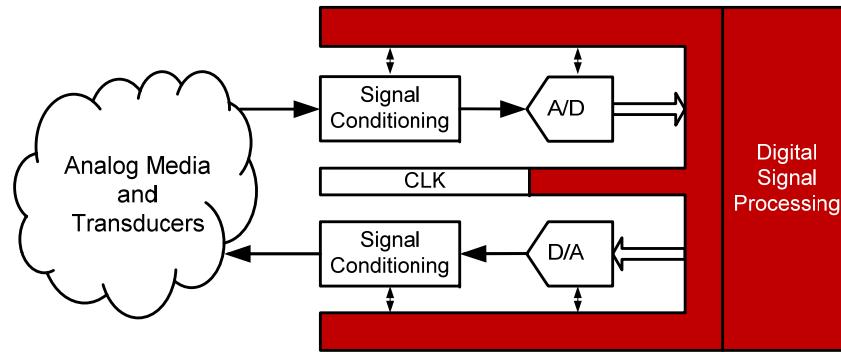


Murmann Mixed-Signal Group

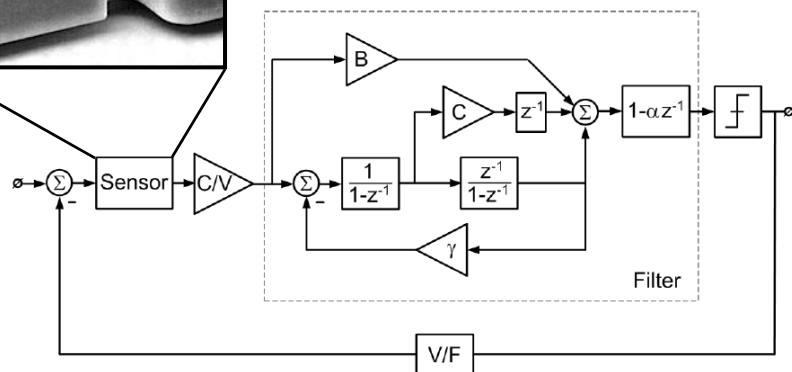
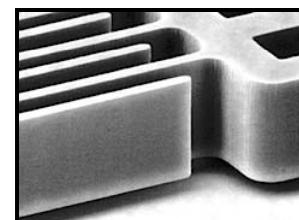
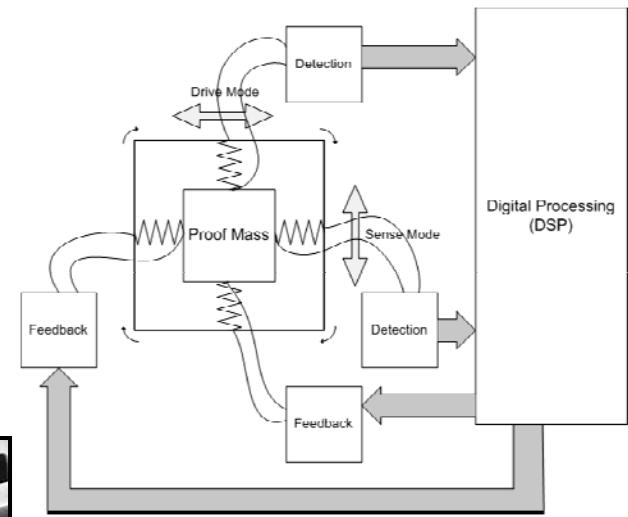


Research Overview (1)

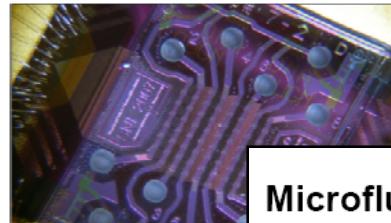
Digital Assisted Data Converters



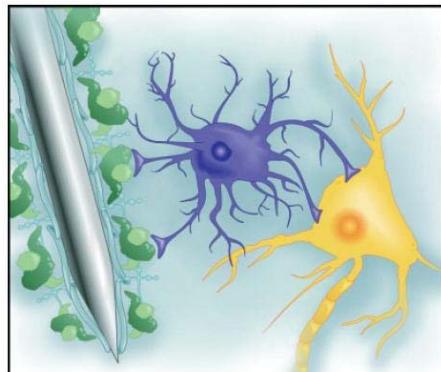
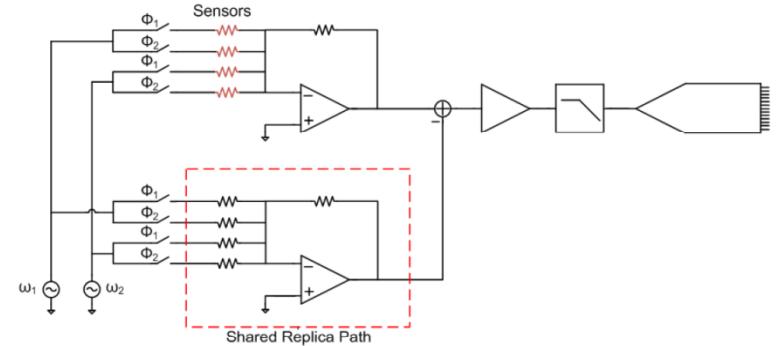
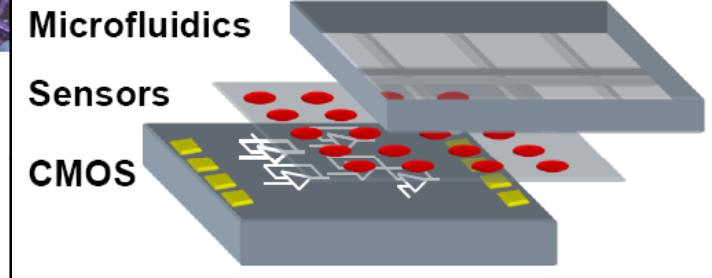
MEMS/Sensor Interface Electronics



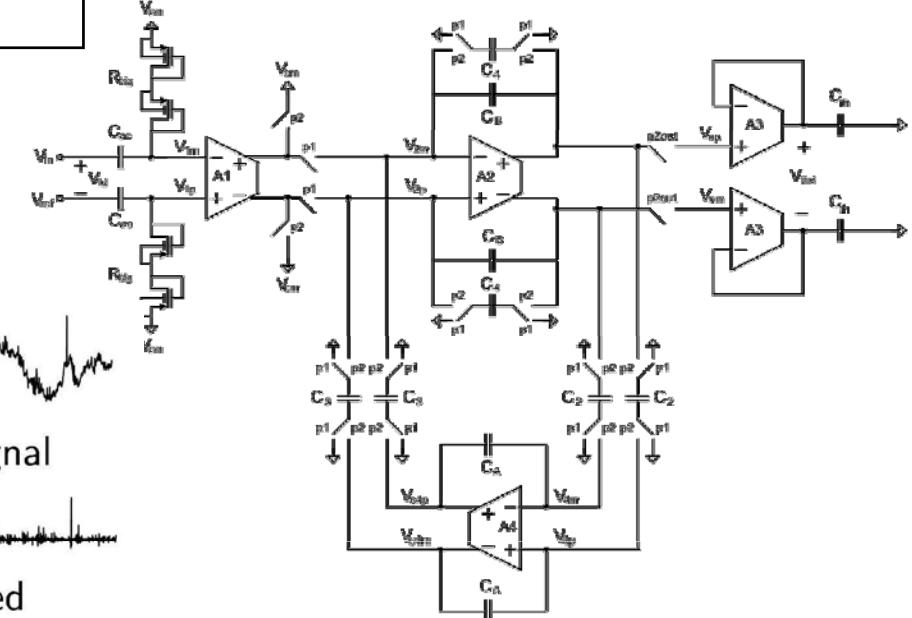
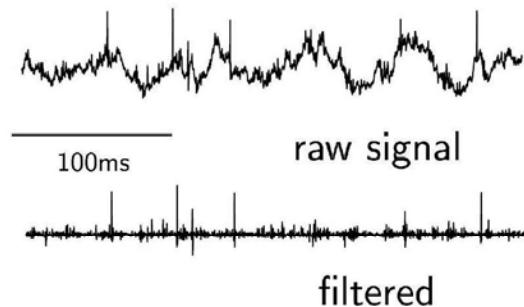
Research Overview (2)



Bio-molecule detection



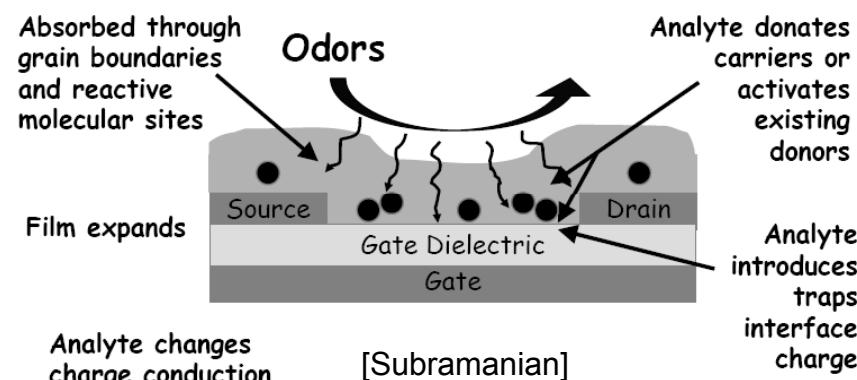
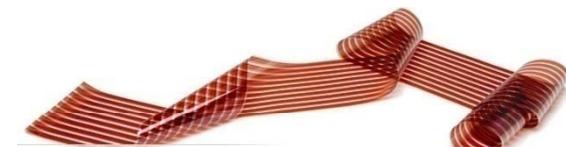
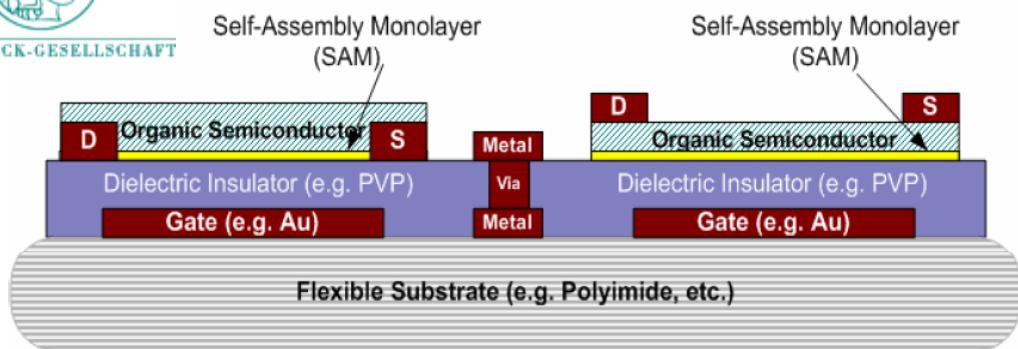
Neural signal acquisition



Research Overview (3)



MAX-PLANCK-GESELLSCHAFT

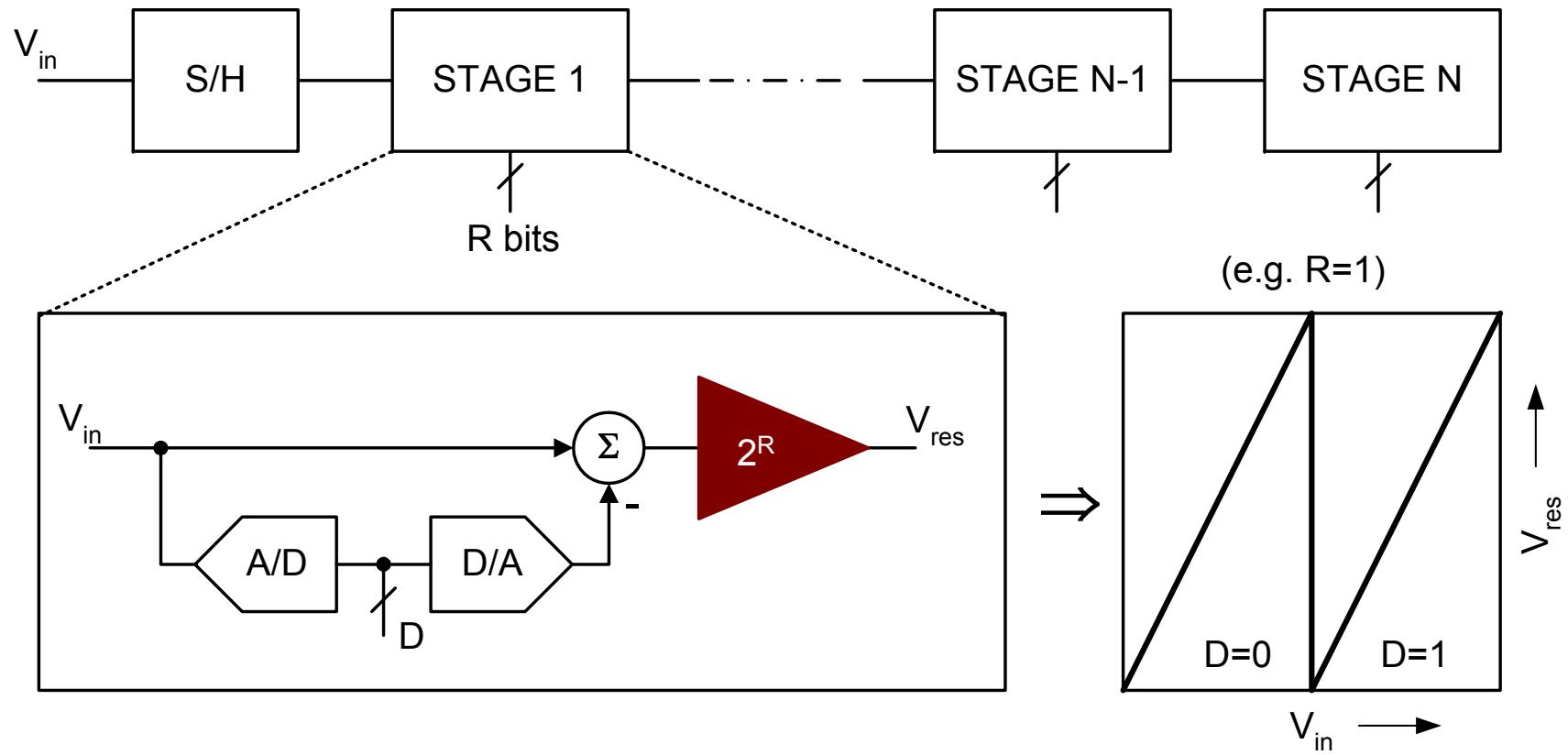


Specific Examples

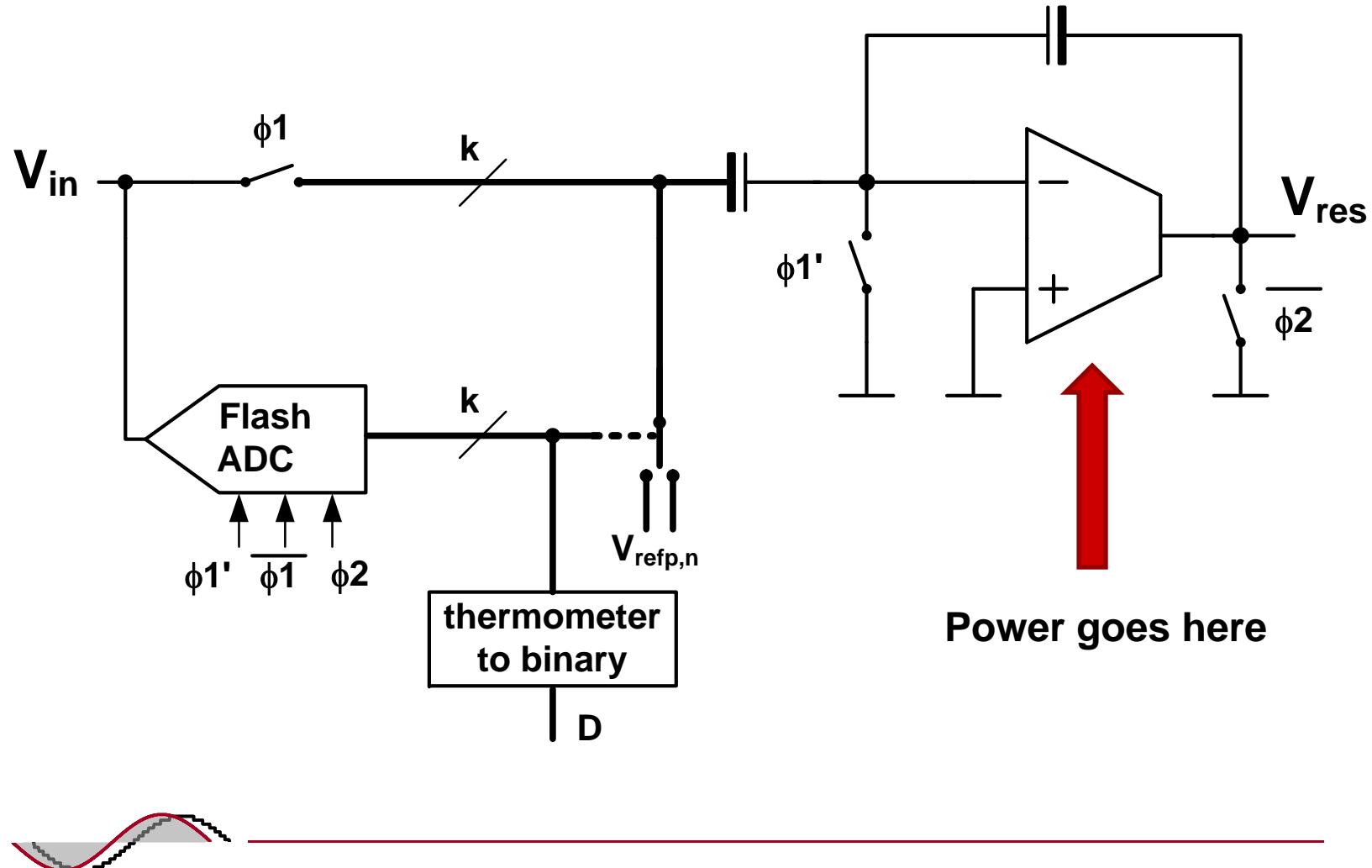
- Minimalistic pipeline ADC
 - Using a previously “unknown” amplification mechanism
- Digitally corrected track-and-hold circuit
 - Analog-digital co-design
- Offset-calibrated accelerometer
 - Electro-mechanical co-design
- Analog circuit design using organic thin film transistors
 - Designing analog circuits using “lousy” technology



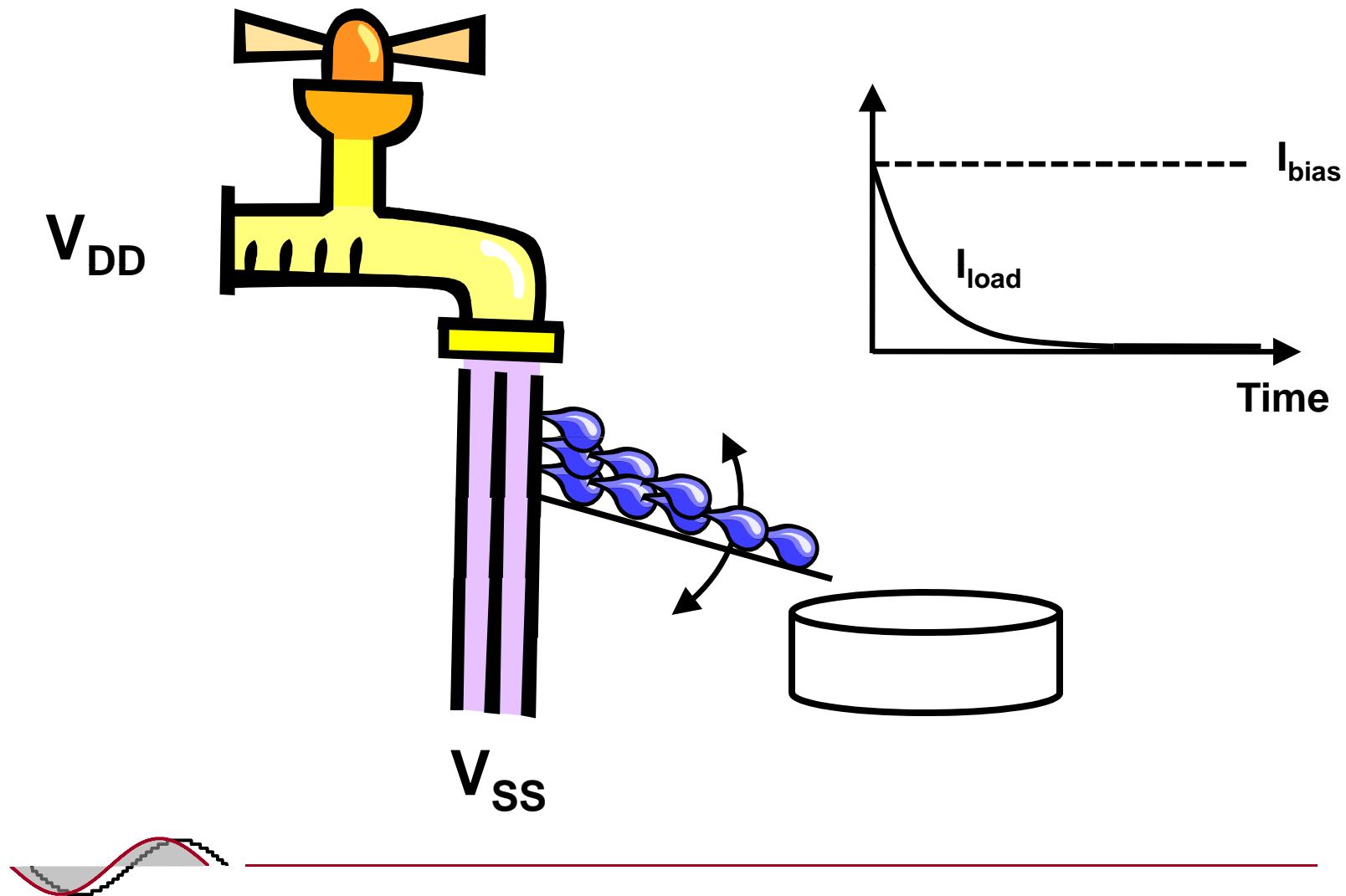
Pipeline ADC



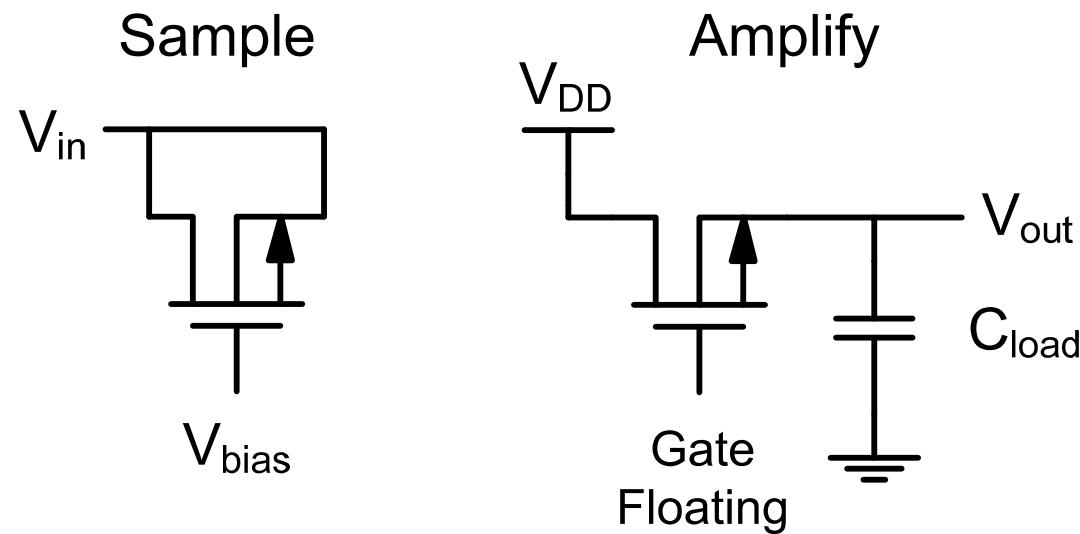
Stage of a Conventional Pipeline ADC



Inefficiency of Class-A Amplifiers



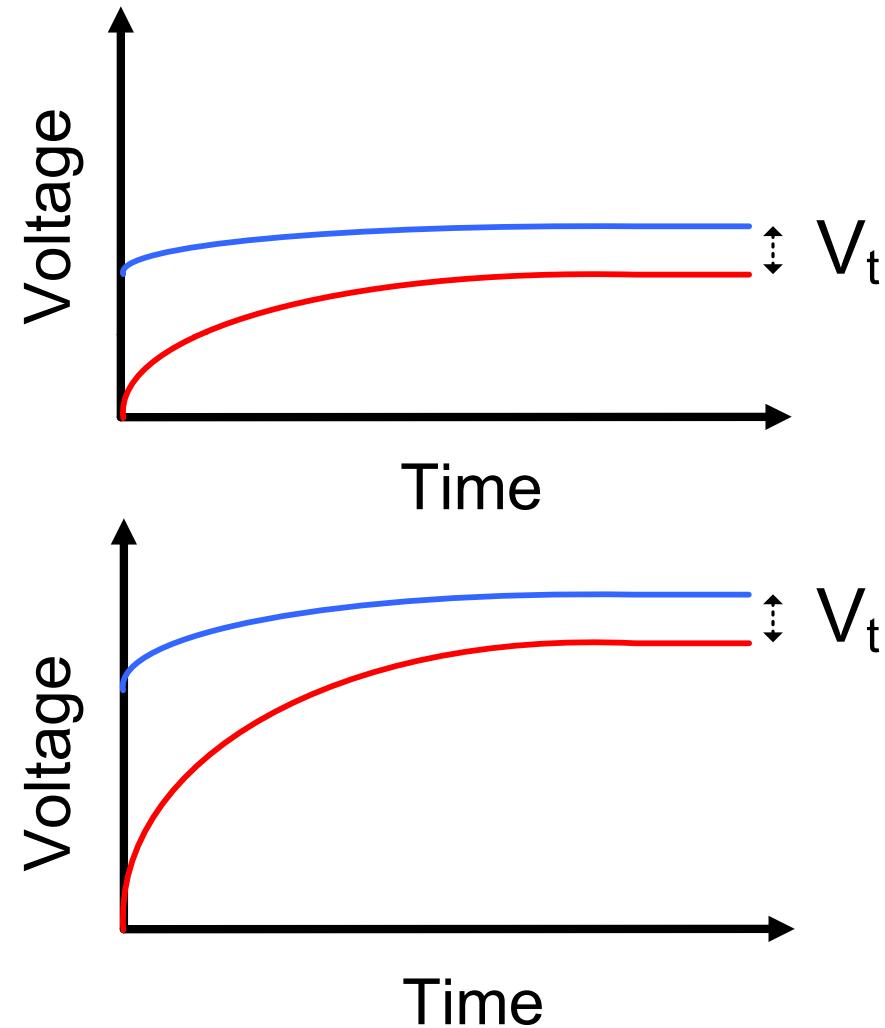
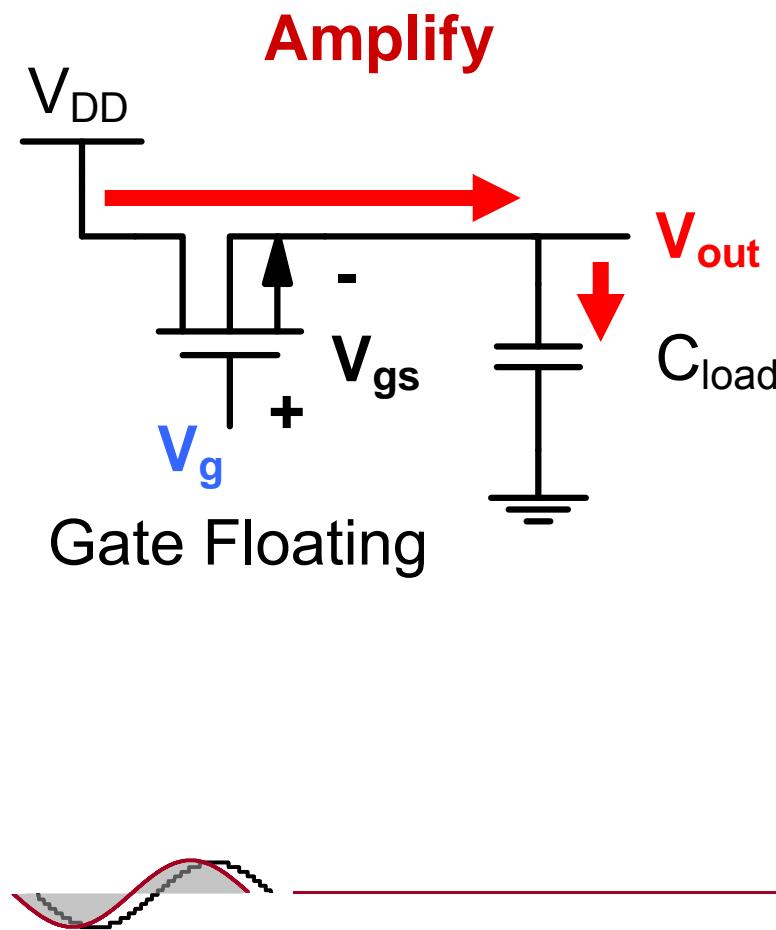
The World's Most Efficient SC Amplifier (?)



[Hu, Dolev & Murmann, VLSI Symposium 2008]

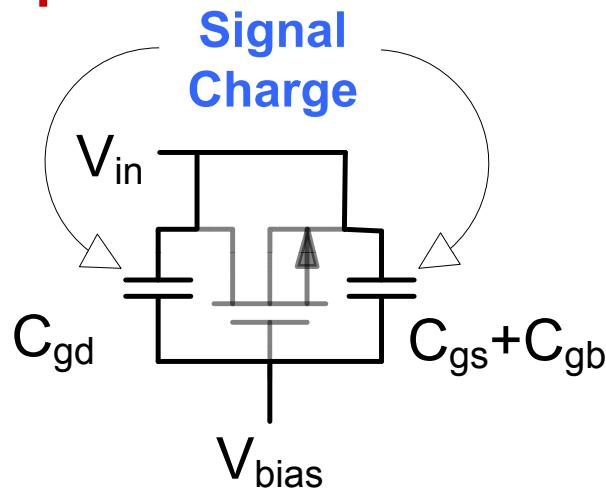


Settling in Amplify Phase

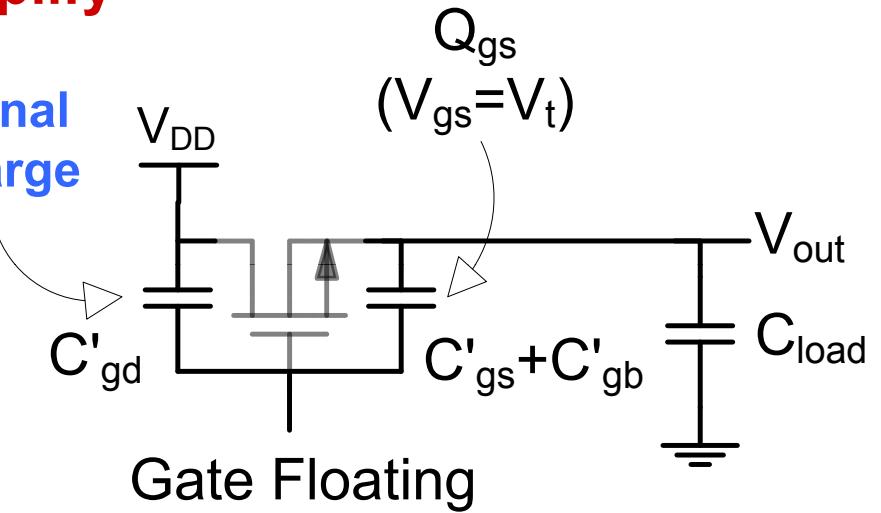


Amplification Principle

Sample



Amplify



$$\text{Incremental Gain} \cong \frac{C_{gs} + C_{gd} + C_{gb}}{C'_{gd}}$$



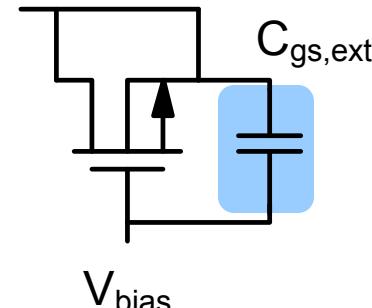
Basic Amplifier Modifications

- Add $C_{gs,ext}$ in parallel to C_{gs} for gain control

$$G = \frac{C_{gs,ext} + C_{gs} + C_{gd} + C_{gb}}{C_{gd}}$$

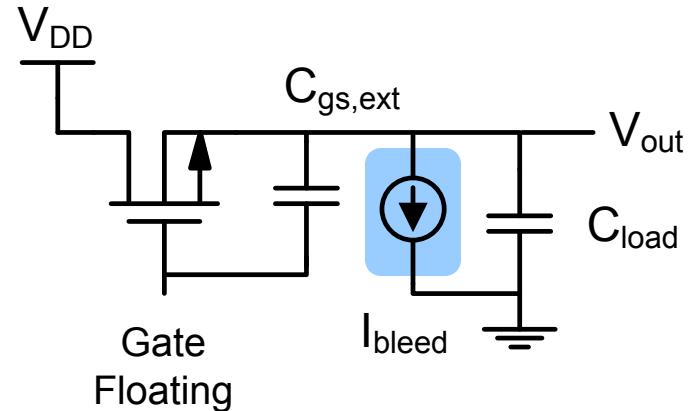
- Add I_{bleed} during amplify phase

Sample



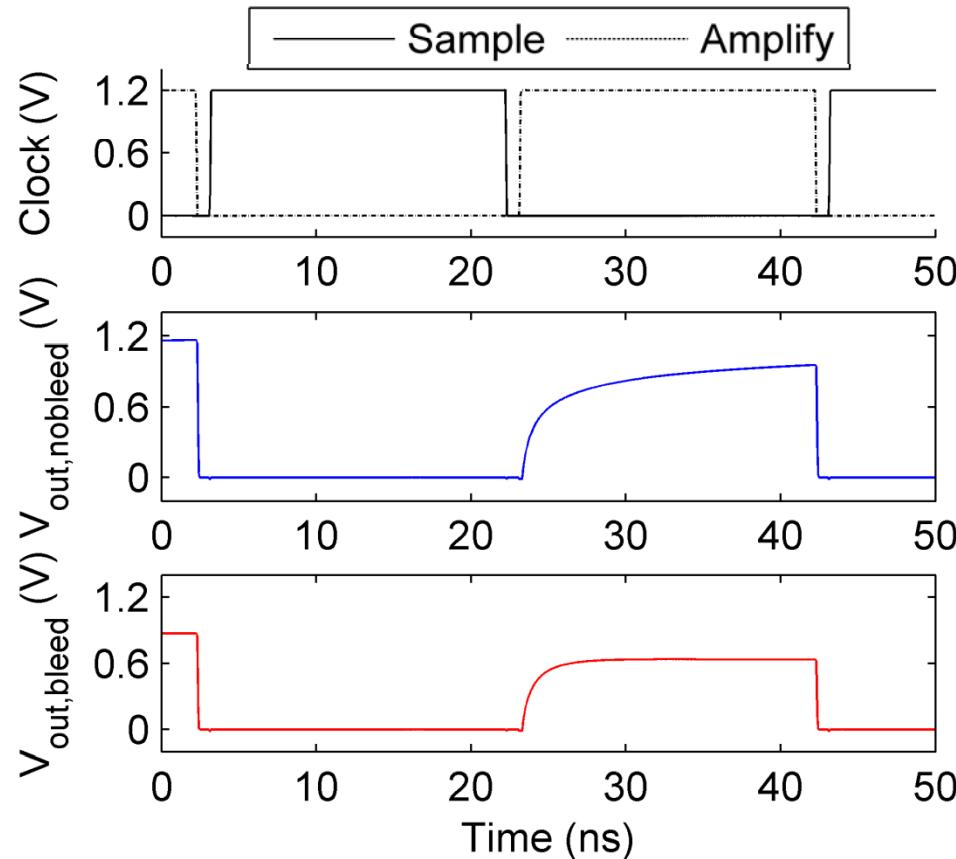
V_{bias}

Amplify



Gate
Floating

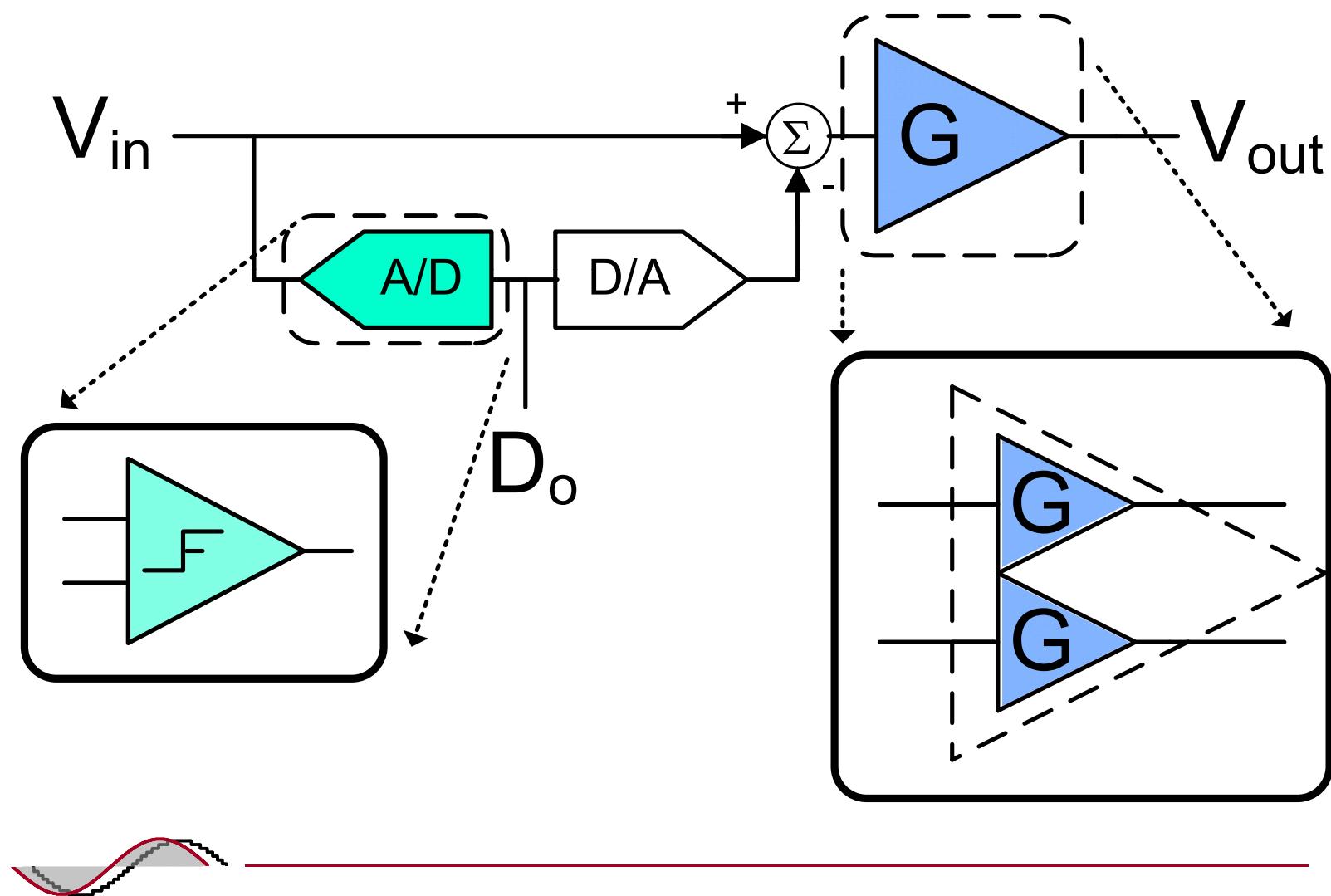
Impact of I_{bleed} (Simulation)



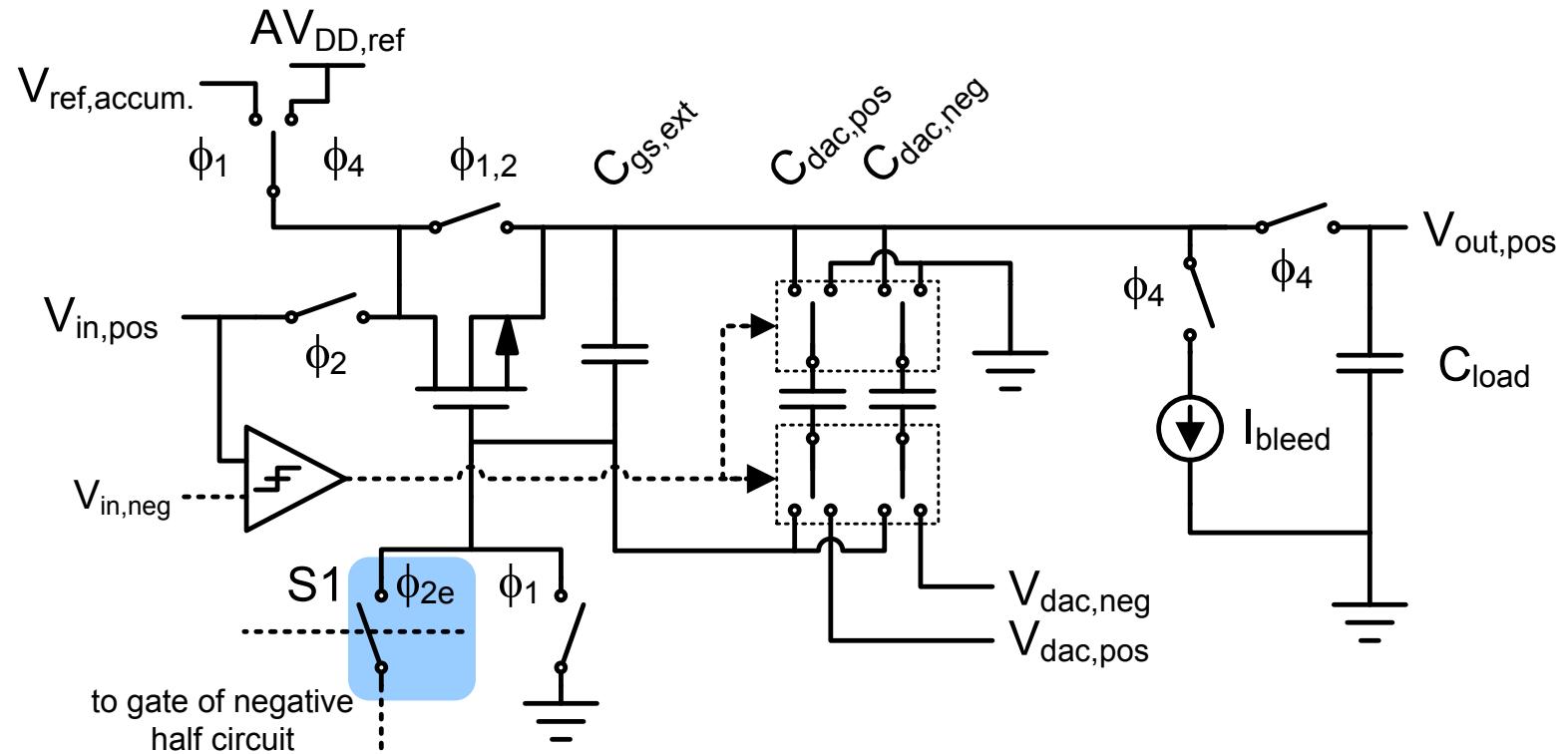
- Bleed current small, about $5\mu\text{A}$



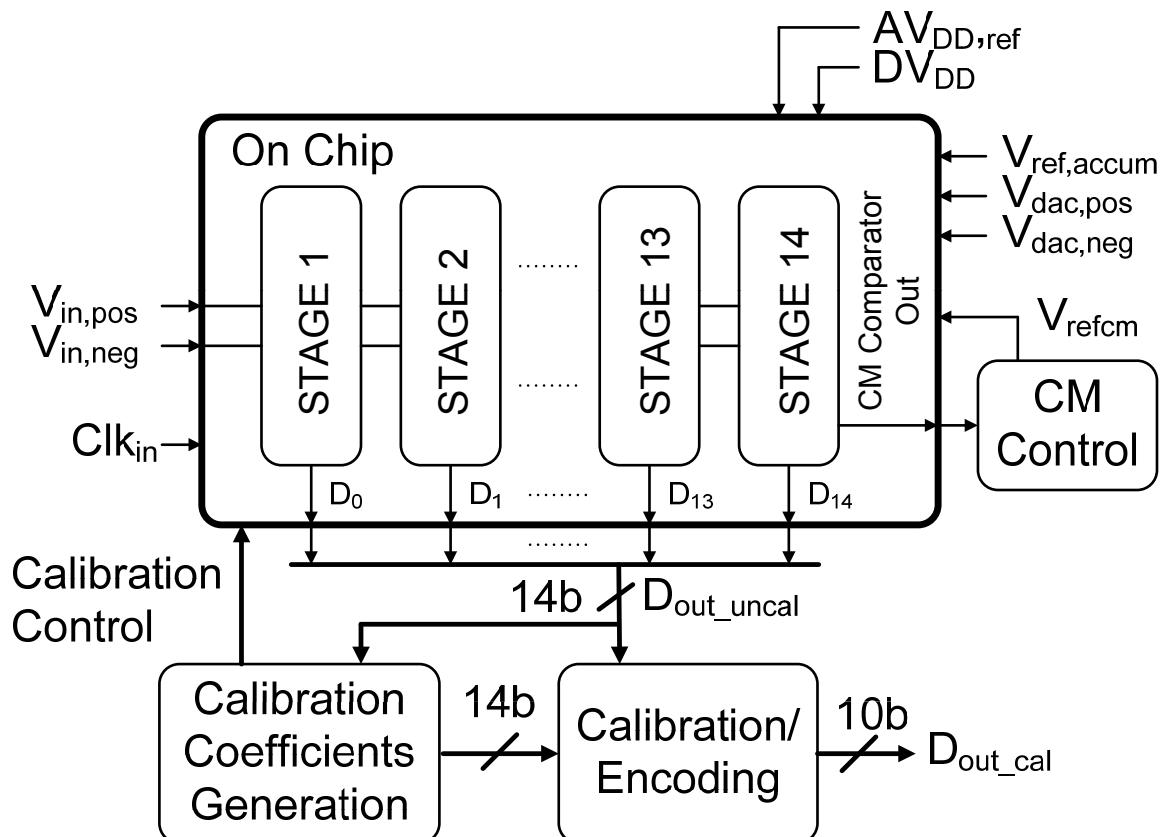
Pseudo-Differential Stage



Stage Schematic



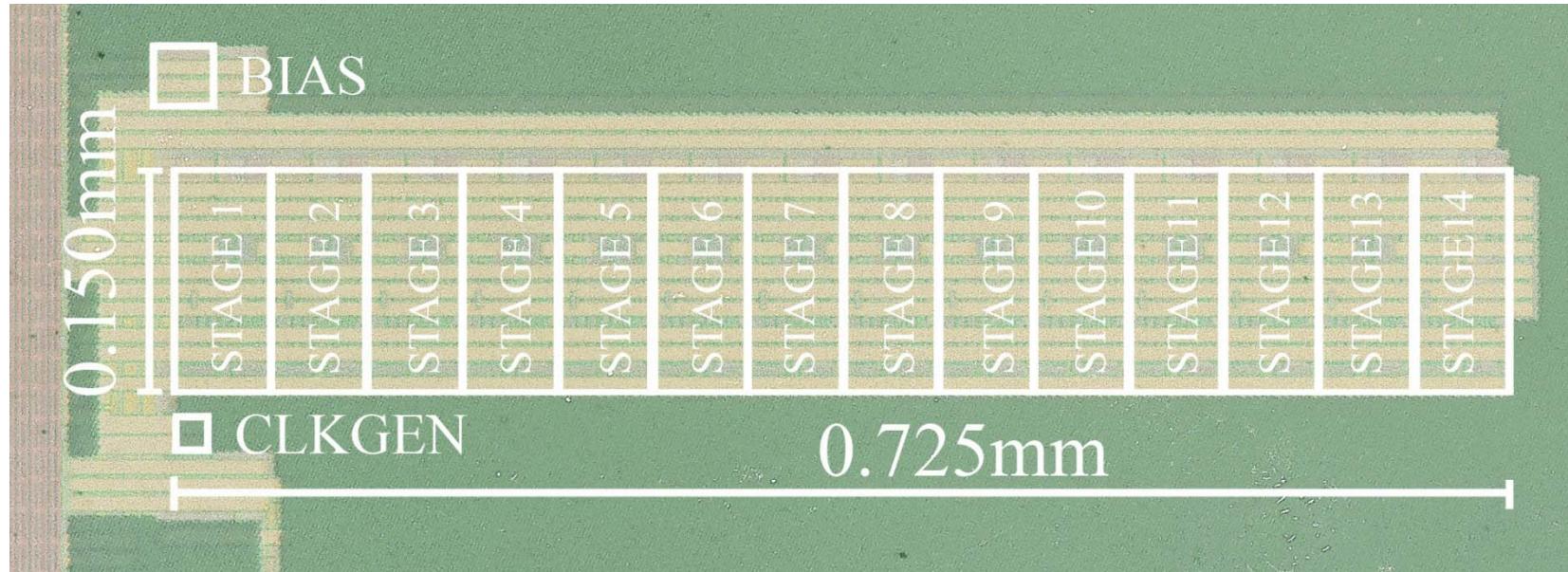
Testchip Architecture



- Target 8-9 bits of resolution
- 1-bit per stage
- Reduced radix ($G=1.7$) for offset tolerance
- Digital gain calibration [Karanicolas, 1993]
- 14 stages, no scaling
- Calibrated output encoded to 10 bits



Prototype ADC

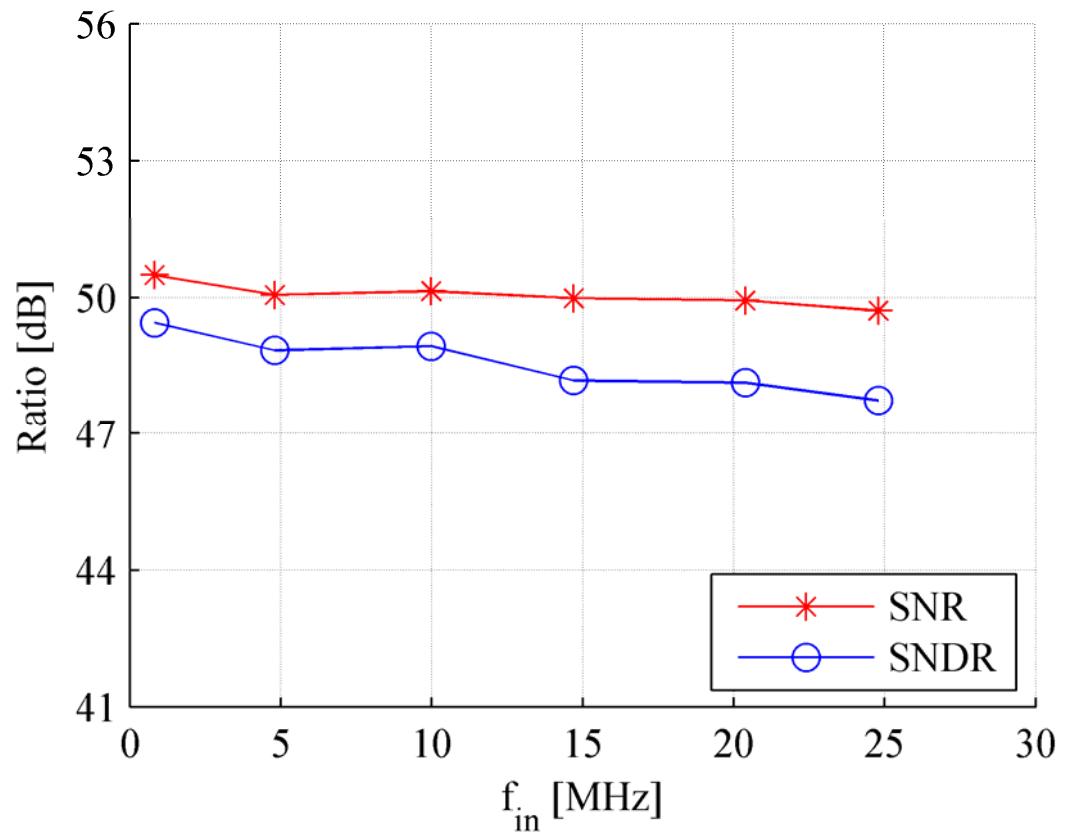


- UMC 90-nm CMOS process
- 0.123mm² (excluding off-chip reference generators)
- 9.4 bits (685 levels), $f_s = 50\text{MHz}$

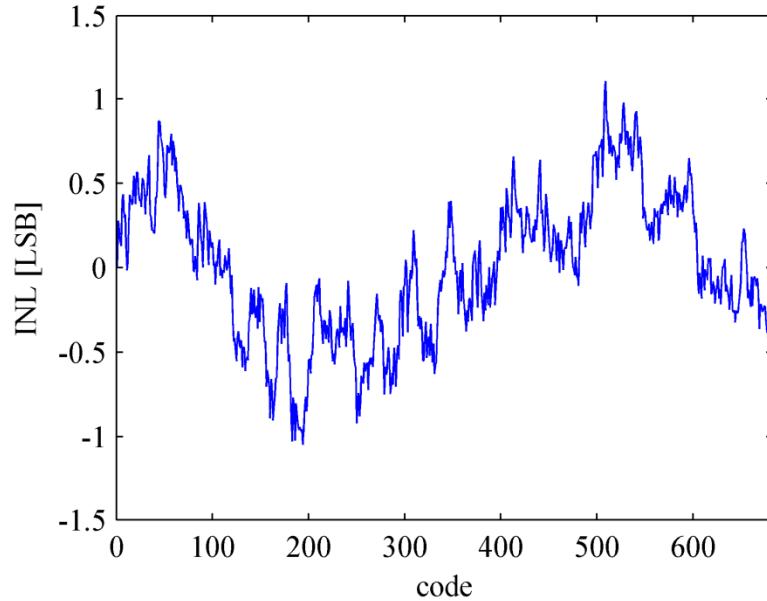
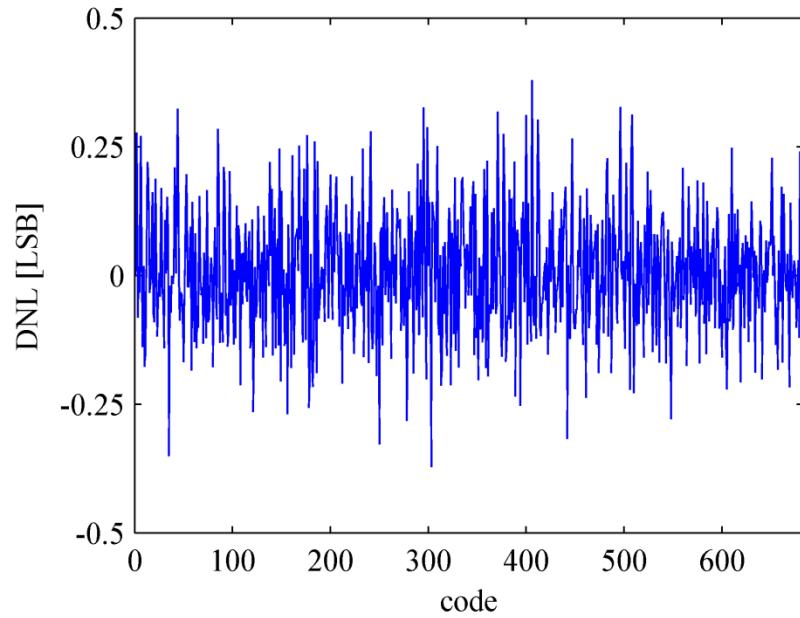


SNDR vs Input Frequency

- $f_s = 50 \text{ MHz}$
- At low f_{in}
 - SNDR = 49.4 dB
 - ENOB = 7.9 bits
- SNDR degrades by 1.7 dB at high f_{in}



INL and DNL

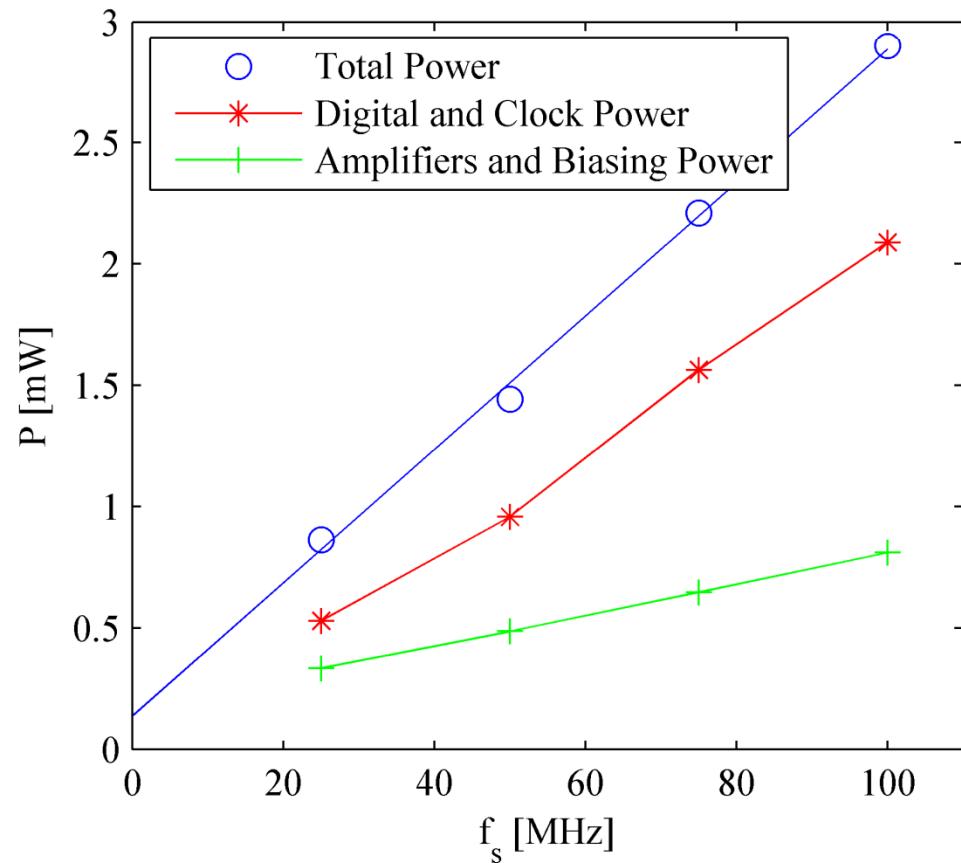


- 9.4 bit resolution (685 levels), $f_s = 50$ MHz
- DNL = +0.4/-0.4 LSB
- INL = +1.3/-0.9 LSB

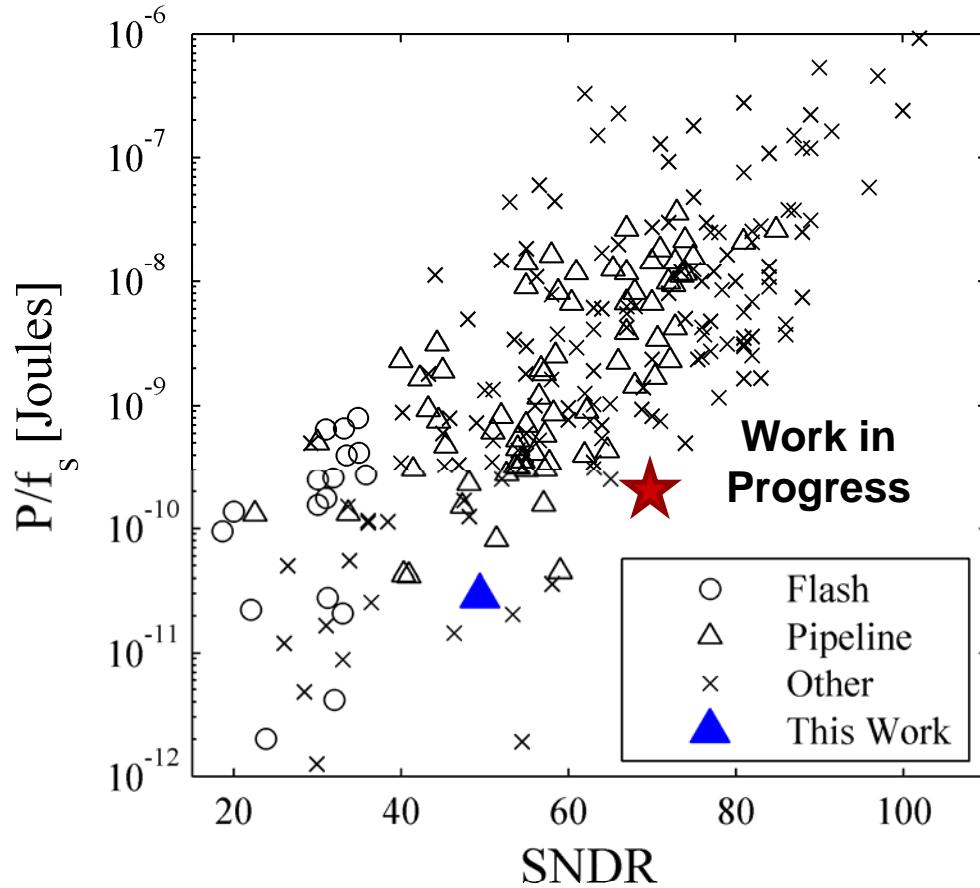


Power

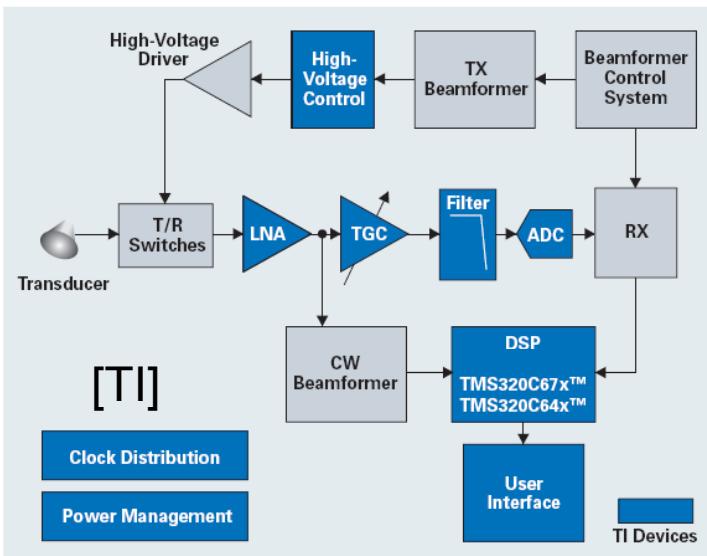
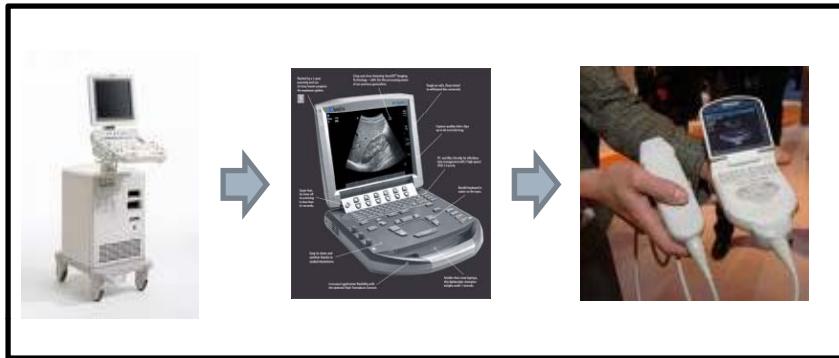
- 1.44 mW at $f_s = 50$ MHz
 - 0.49 mW amplifiers and biasing
 - 0.95 mW comparators and clocks
- At $f_s = 50$ MHz, only 9% of power is static



Comparison and Outlook



Driver Application

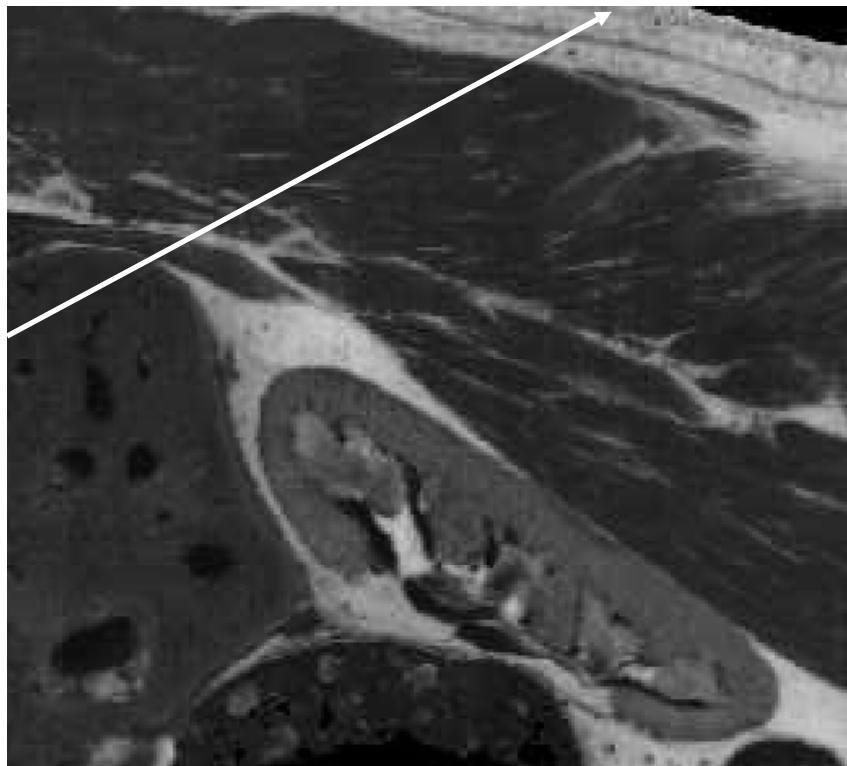


- Medical ultrasound
- Want to implement 64+ high speed ADCs on a single chip
- Approach
 - Minimalistic, digitally assisted pipeline ADC
 - Exploit specific signal and system properties!

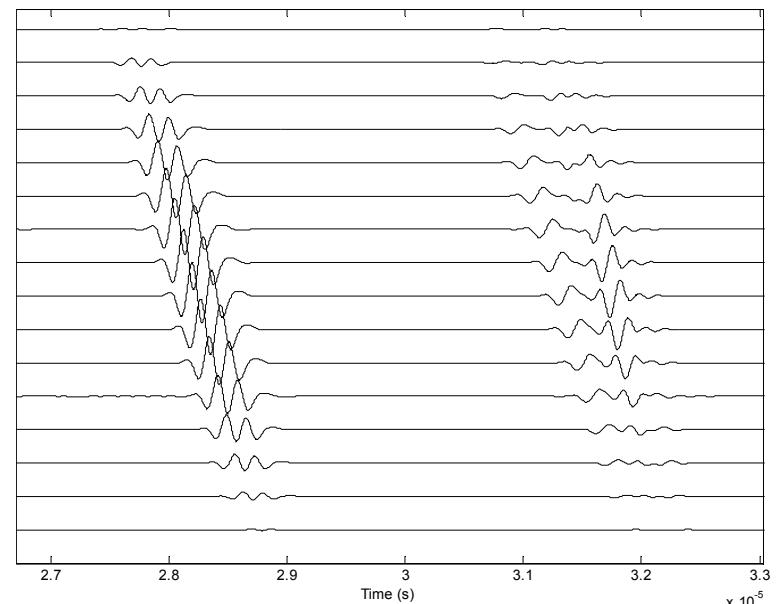


Received Signals Are Highly Correlated

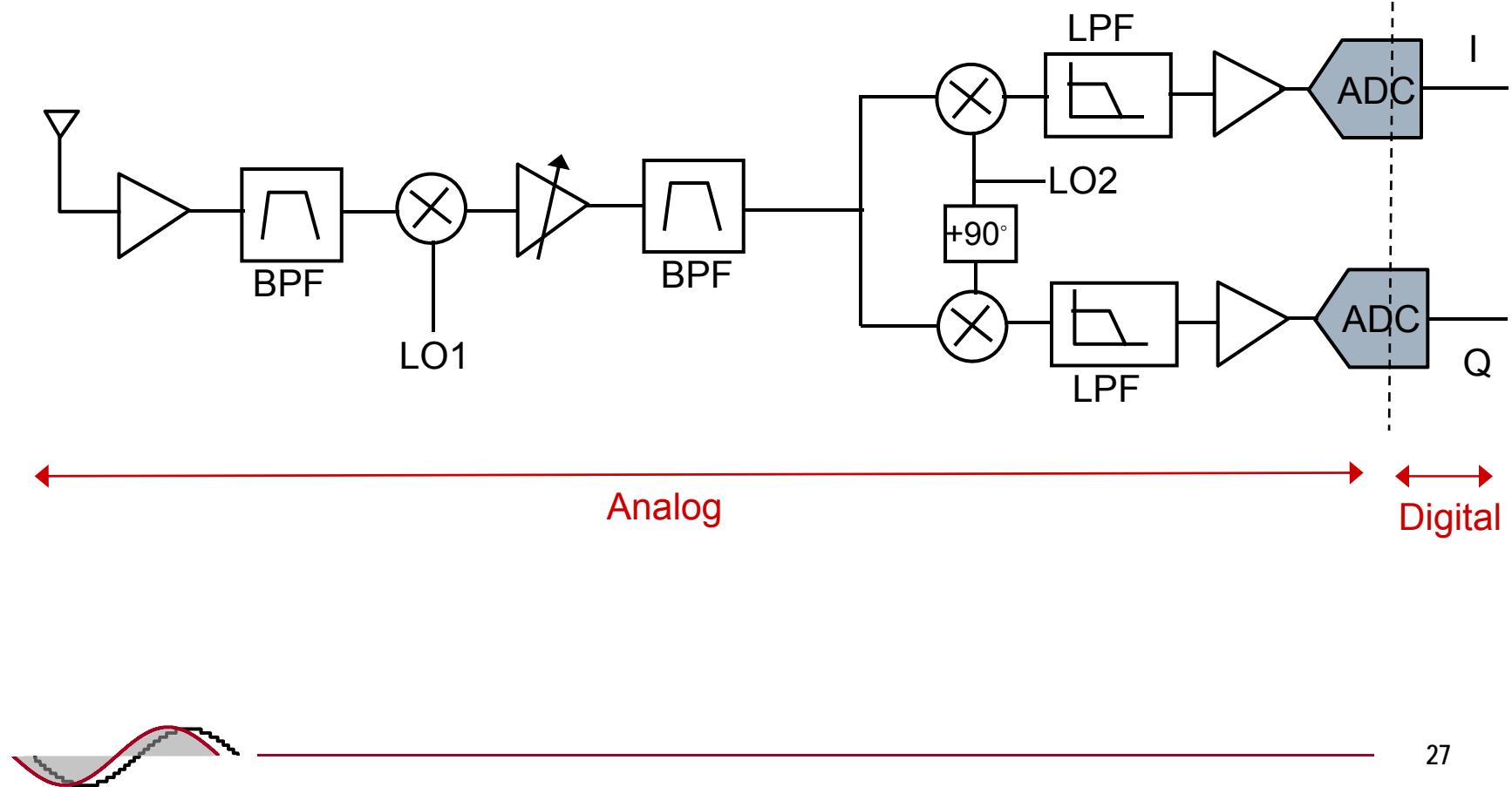
Phantom Image of Kidney



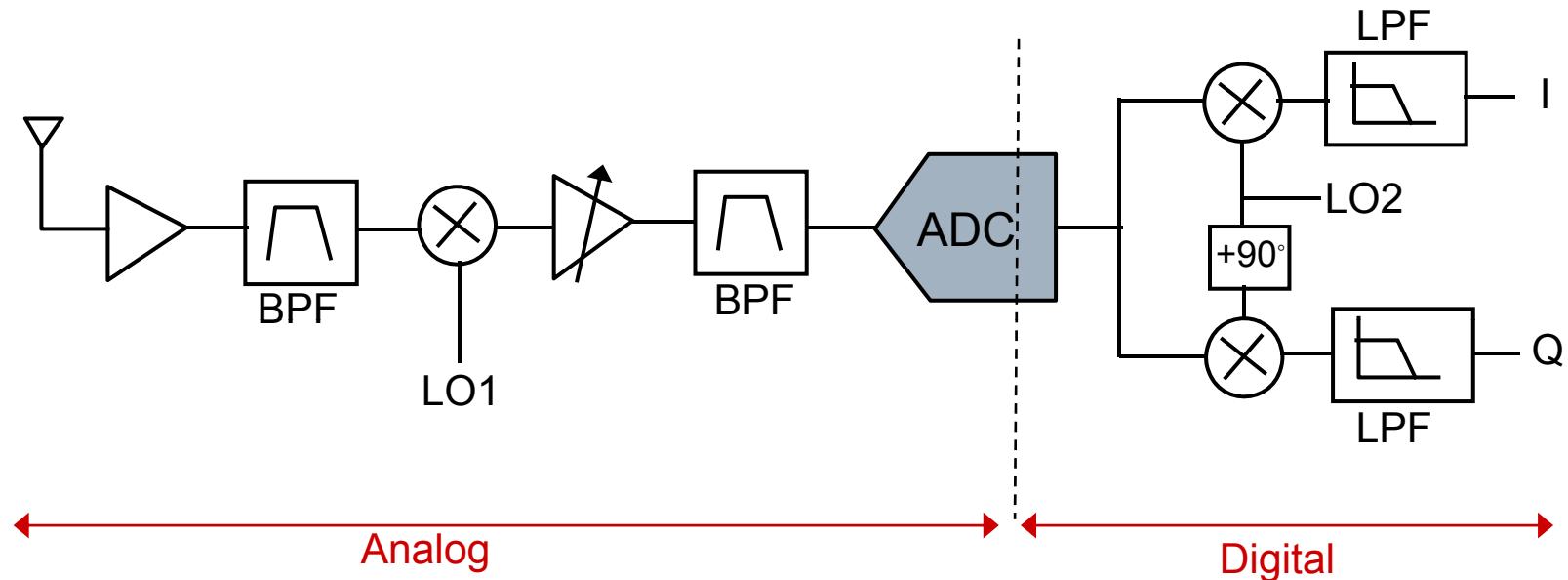
Received Signal Traces



Typical Heterodyne Receiver

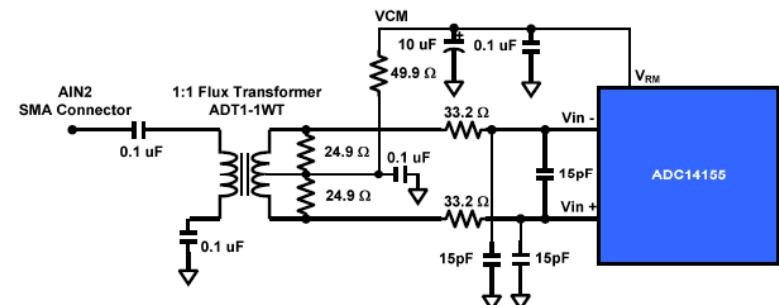
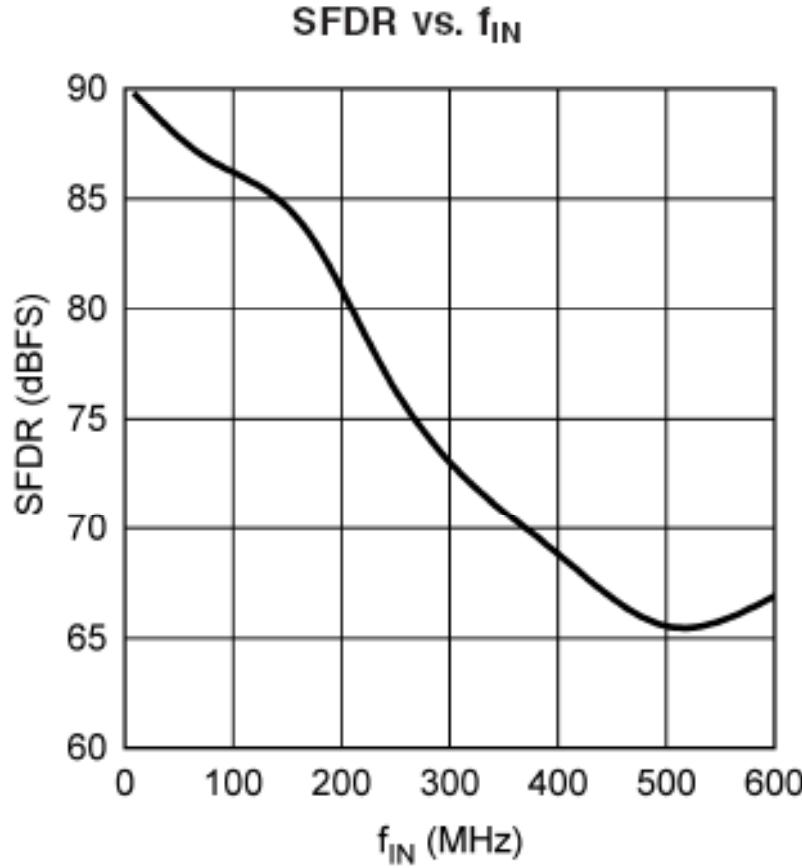


IF Subsampling Receiver



- Need ADC with high linearity at IF input frequencies

SFDR of Typical CMOS ADC

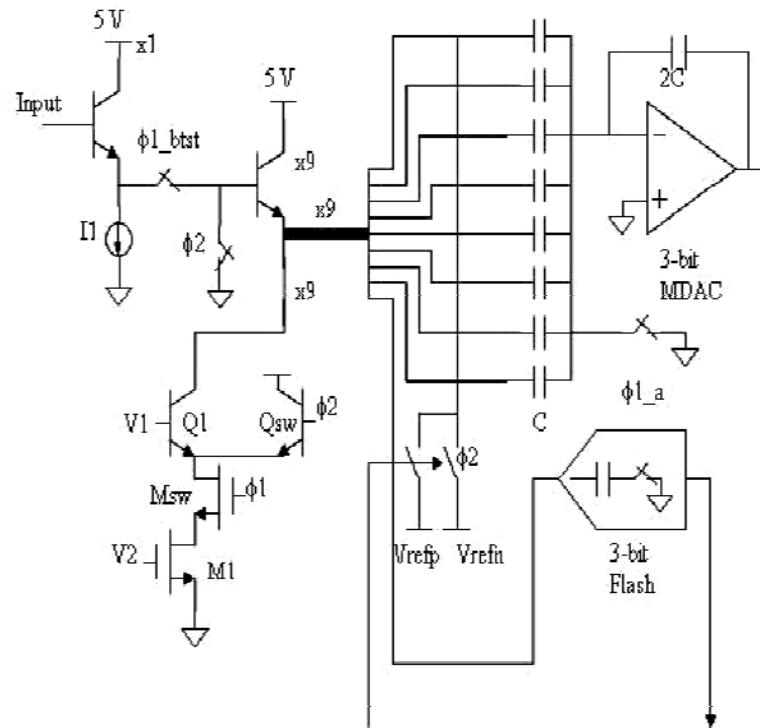


National ADC14155: 14bit, 155 MS/s,
1.1 GHz Bandwidth A/D converter



Achieving High SFDR (1)

- BiCMOS front-end
 - BJTs used as buffer for linear signal tracking and sampling
 - Can achieve SFDR>90dB up to 4th Nyquist zone at 125MS/s
- \$\$\$

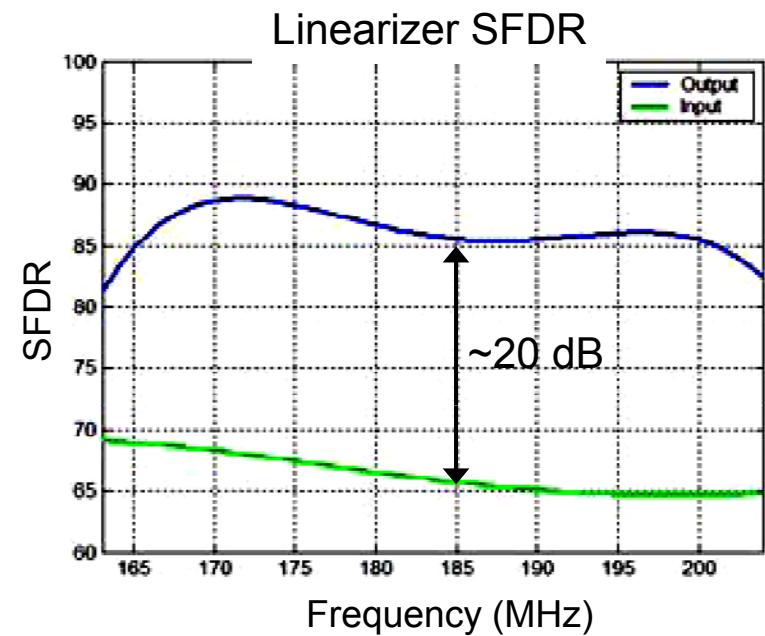
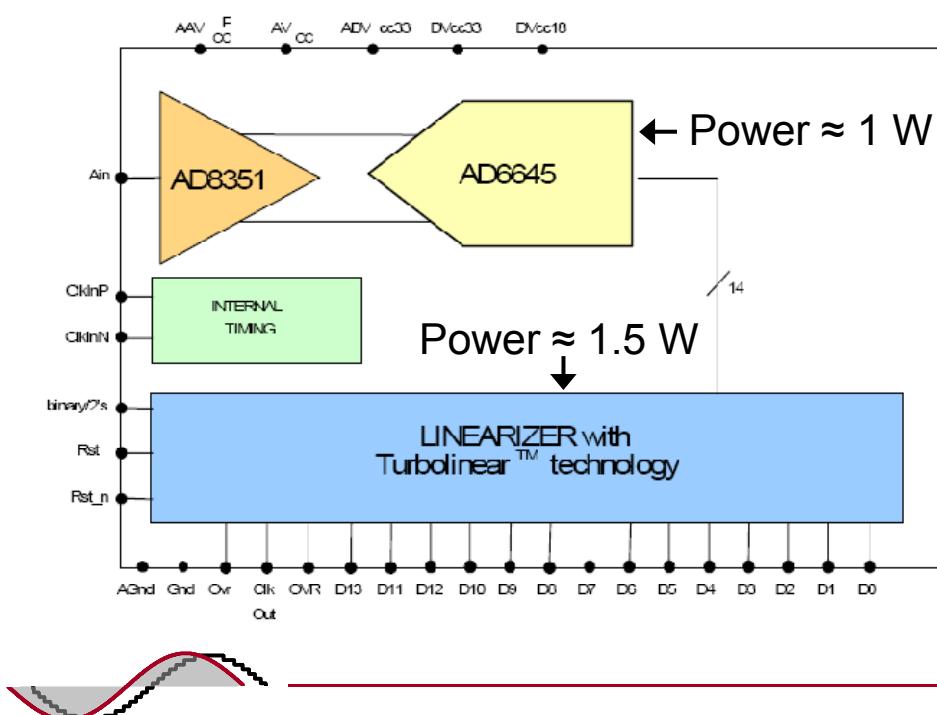


A.M.A. Ali et al. "A 14 bit 125 Ms/s IF/RF Sampling Pipelined A/D Converter," IEEE CICC, Sep. 2005



Achieving High SFDR (2)

- Compensate nonlinearities by applying inverse nonlinear function to the digital output
 - Roy Batruni, www.optichron.com
- Issue: complexity, power

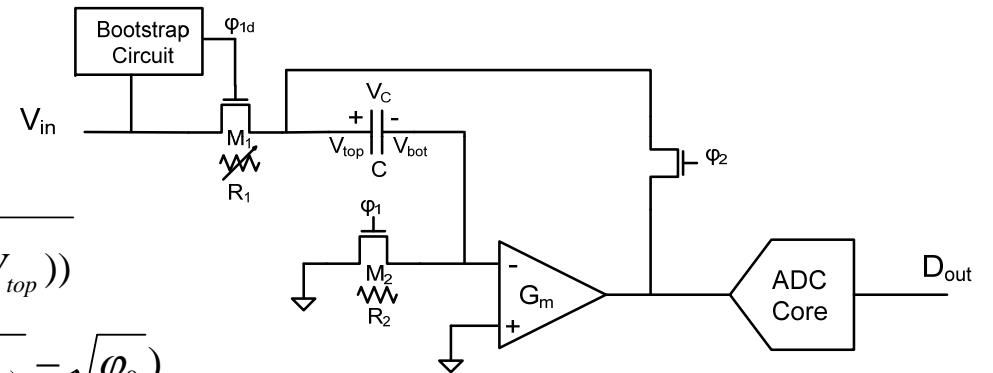


Judicious Modeling

- During tracking mode, the track-and-hold can be modeled as an RC circuit with an input dependent resistance

$$V_{in} = V_C + (R_1 + R_2)C \frac{dV_{out}}{dt}$$

$$\left\{ \begin{array}{l} R_1 = R_1(V_{in}) = \frac{1}{\mu_n C_{ox} \frac{w}{l} (V_{gs} - V_{th}(V_{in}, V_{top}))} \\ V_{th}(V_{in}, V_{top}) = V_{th0} + \gamma (\sqrt{\varphi_0 + (V_{in}, V_{top})} - \sqrt{\varphi_0}) \end{array} \right.$$



Flip-around track-and-hold circuit

↓
At the sampling instant

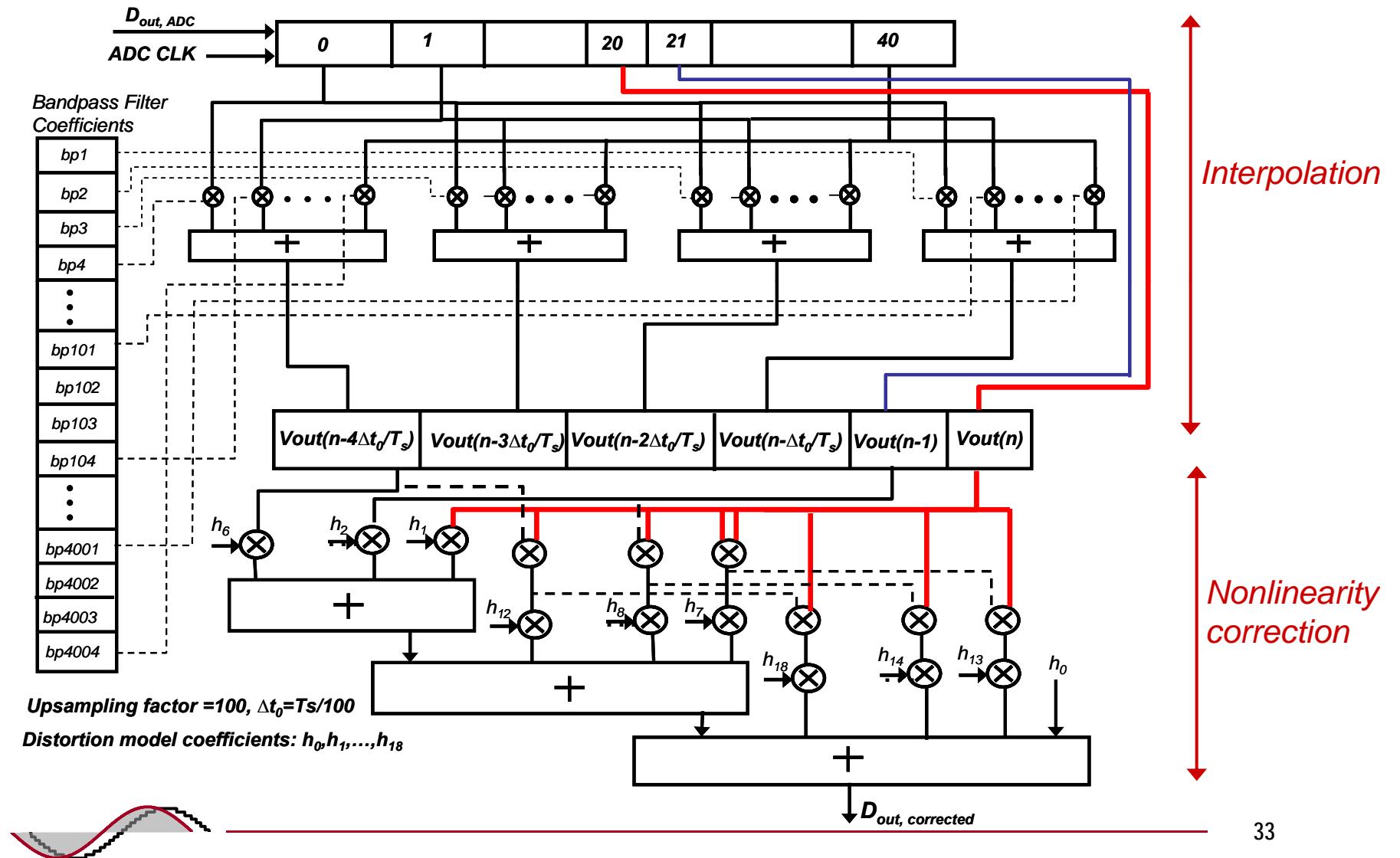
$$V_{in}(k) = V_{out}(k) + (a_0 + a_1 V_{out}(k) + a_2 V_{out}^2(k) + \dots) \times \frac{dV_{out}(k)}{dt}$$

nonlinearity *memory*



Nikaeen & Murmann
CICC 2008

Digital Processor Diagram



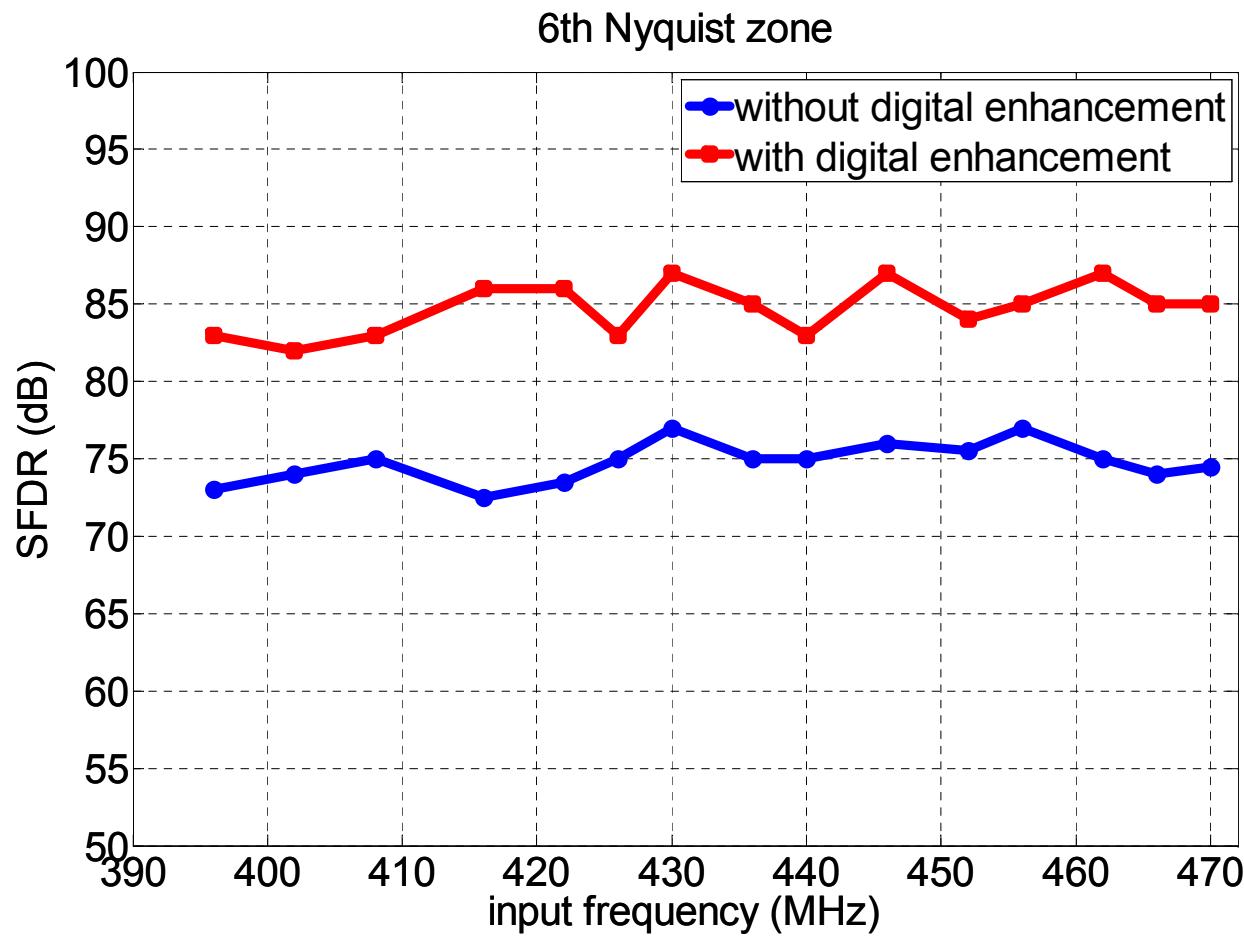
Hardware Requirements

- The algorithm was implemented in Verilog and synthesized using standard CMOS cells in 90nm

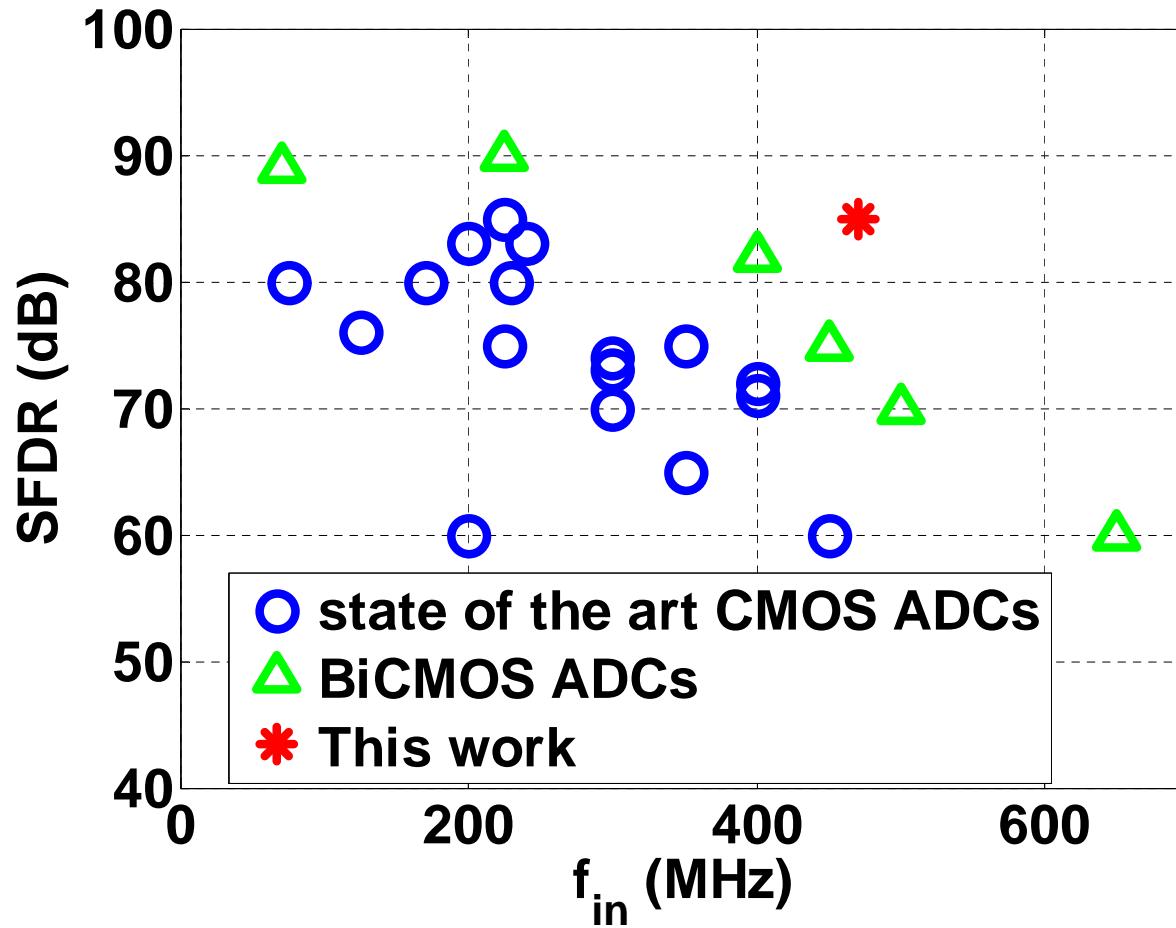
Technology	90-nm CMOS
Clock speed	155 MHz
Latency	33 clock cycles
Number of logic cells	61,339
Area	0.54mm ²
Power	52 mW
ADC power (ADC14155)	967 mW



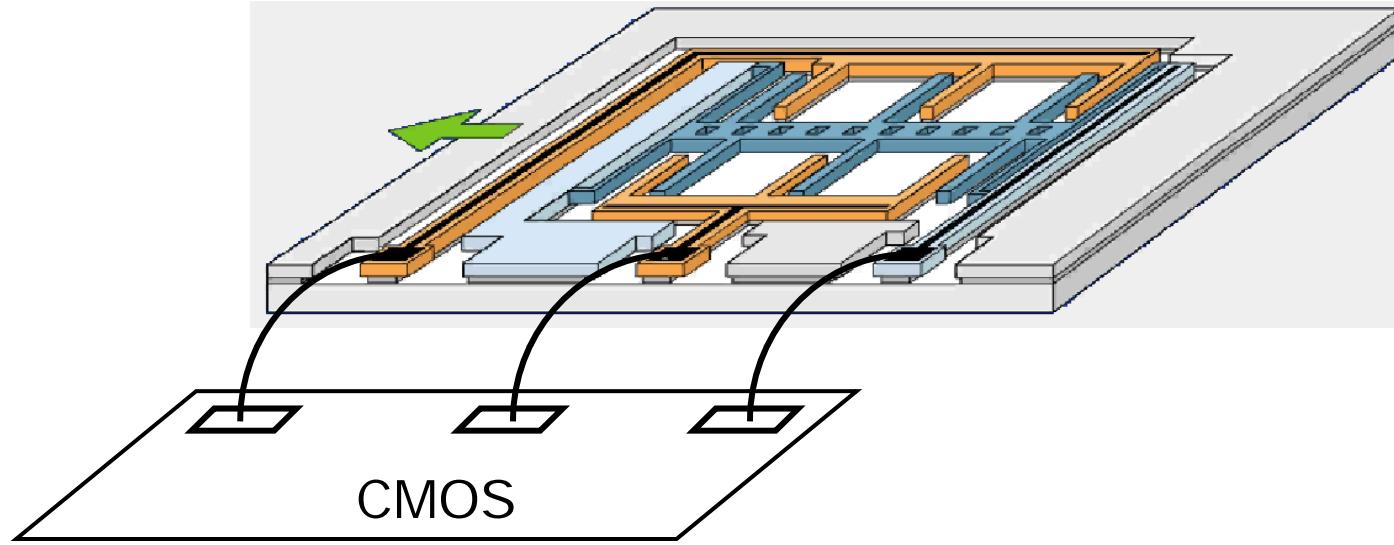
Measured Results



SFDR Comparison

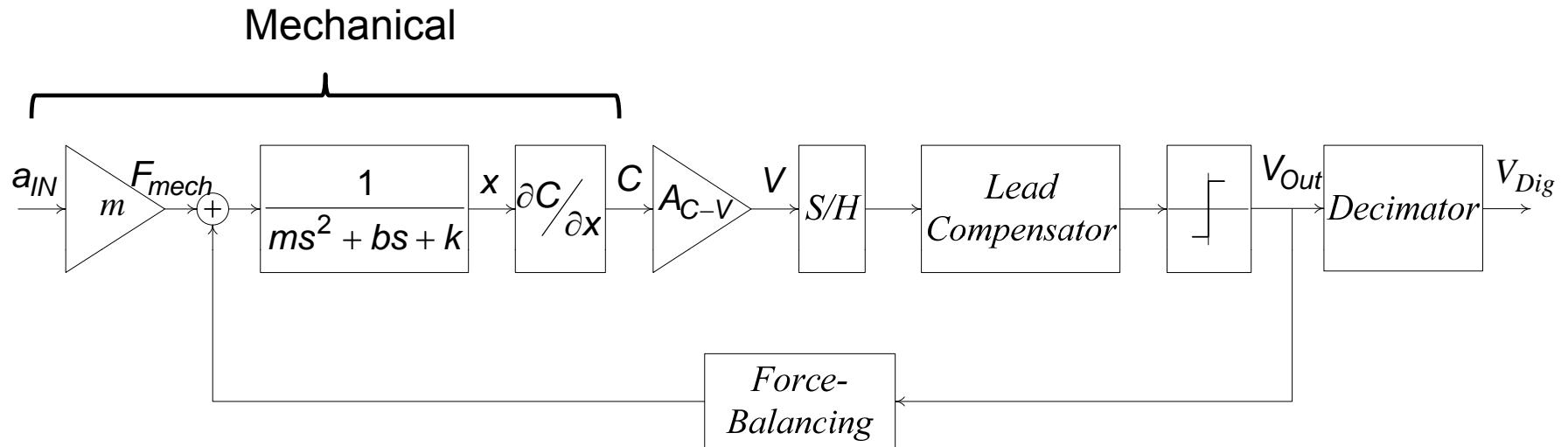


MEMS Accelerometer



- Capacitance change $\sim 10 \text{ fF/g}$
- Desired resolution $\sim 10 \text{ mg}$ for airbags and ESP
 - Must resolve capacitance changes of $\sim 100 \text{ aF}$
- Problem: Drift in parasitic bondwire capacitance

Sigma-Delta Interface

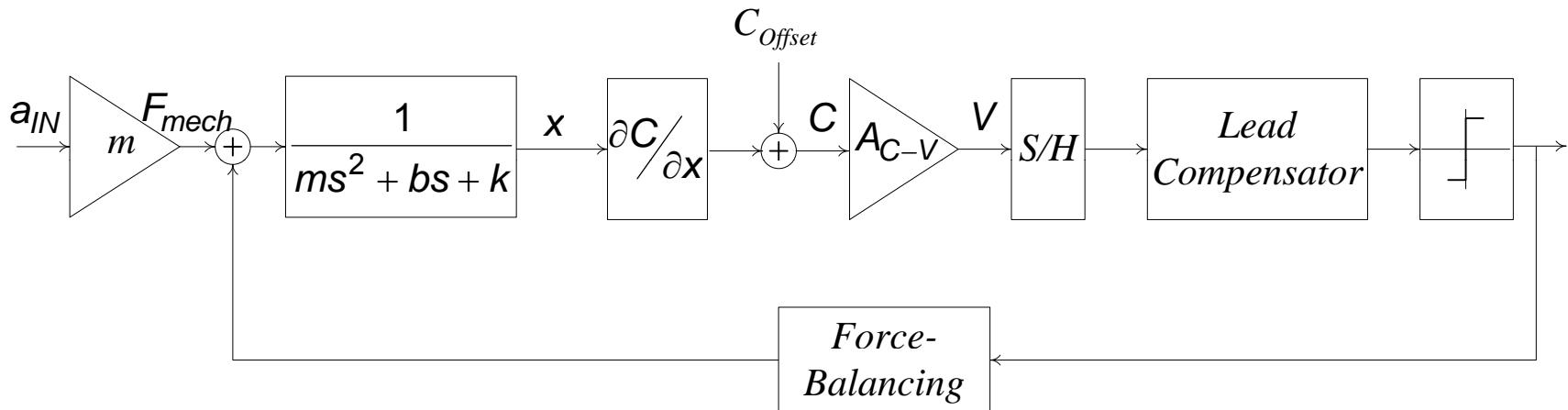


M. Lemkin and B. E. Boser, "A three-axis micromachined accelerometer with a CMOS position-sense interface and digital offset-trim electronics," *IEEE J. Solid-State Circuits*, vol. 34, pp. 456-468, April 1999.



Offset

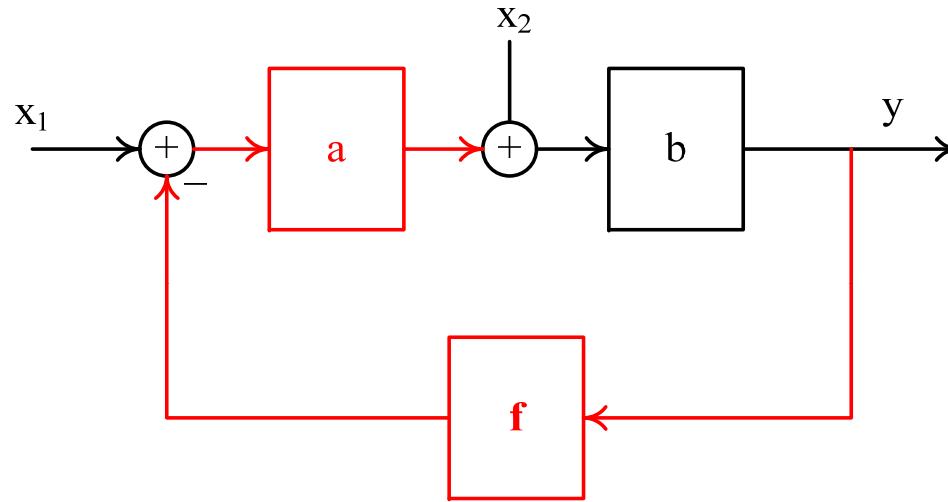
Offset due to bond
wire deformation



- Drifts over time
- Indistinguishable from DC acceleration



Linear Feedback System with Two Inputs



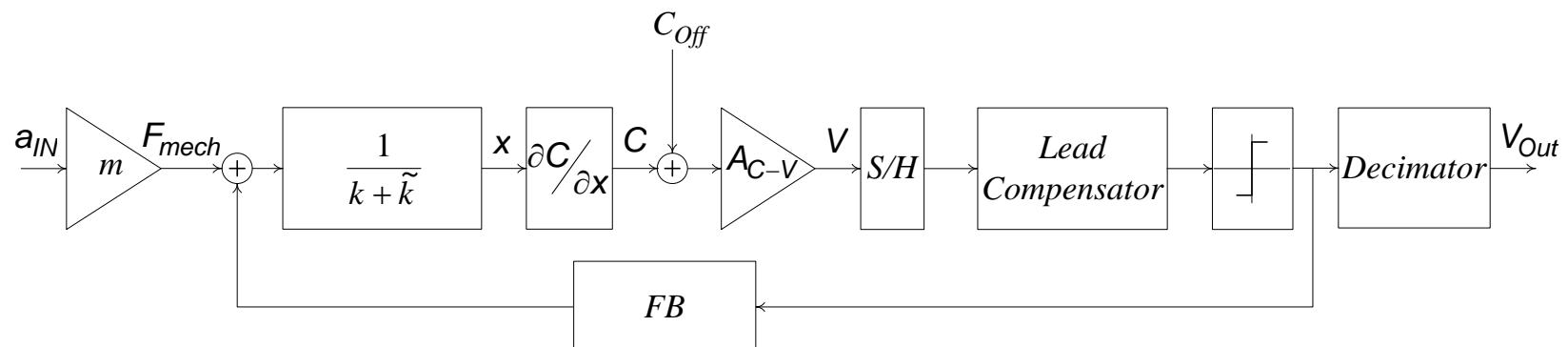
$$y \cong x_1 \cdot \frac{1}{f} + x_2 \cdot \frac{1}{f \cdot a}$$



Spring Constant Modulation

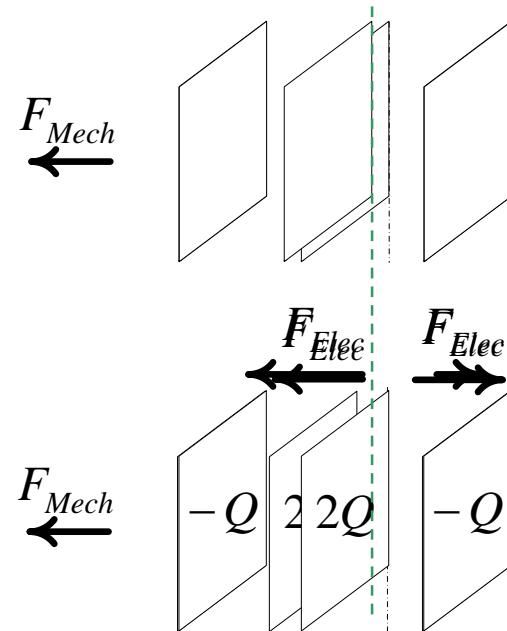
- The output due to C_{off} can be modulated to higher frequencies by modulating k

$$V_{Out} \cong F_{mech} \cdot \frac{1}{FB} + C_{off} \cdot \frac{k + \tilde{k}}{FB \cdot \frac{\partial C}{\partial x}}$$



Spring softening effect

No electrostatic force



With electrostatic force

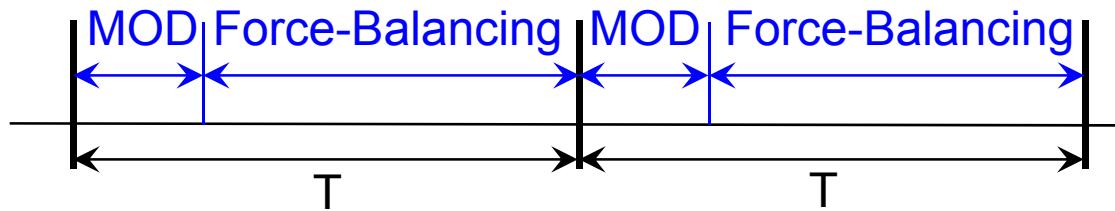
Larger displacement than expected

- Can be used to modulate spring constant

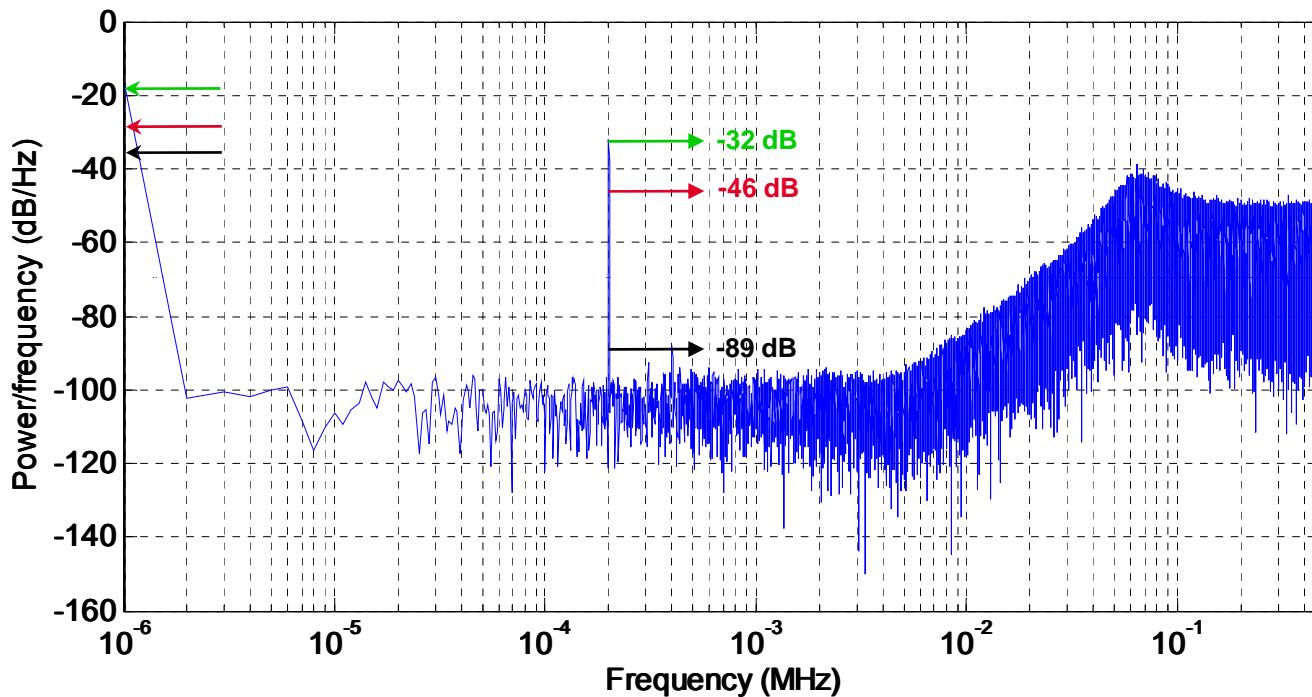


Time-Multiplexed Feedback

- Phase 1
 - Spring constant modulation
- Phase 2
 - Sigma-delta force-balancing



Simulated Output Spectrum

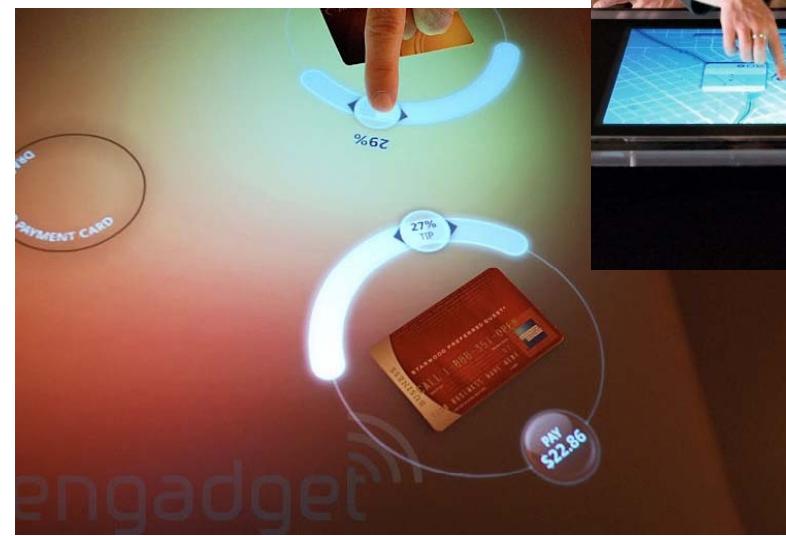


DC Acceleration	Offset Capacitance
9.1 m/s ²	0 fF
9.1 m/s ²	10 fF
9.1 m/s ²	50 fF

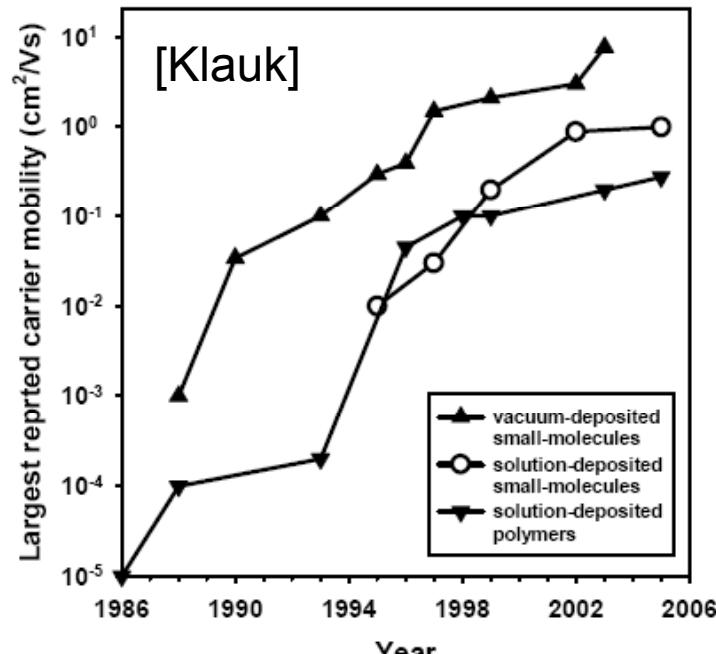
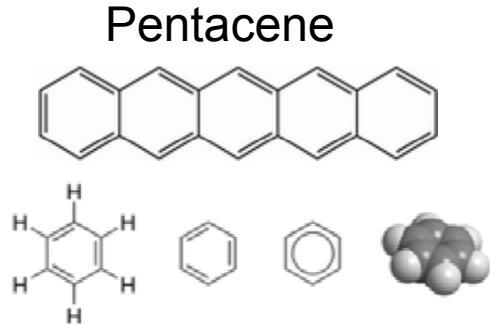
- Currently working on IC prototype



The Future?



Organic Semiconductors

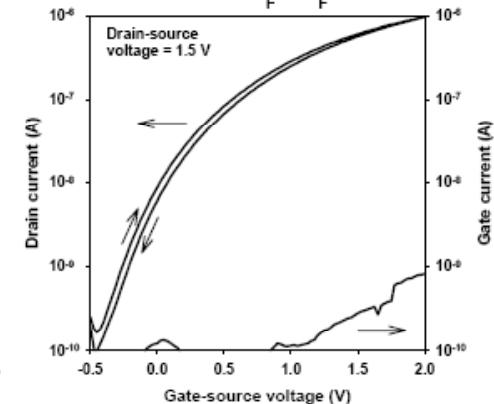
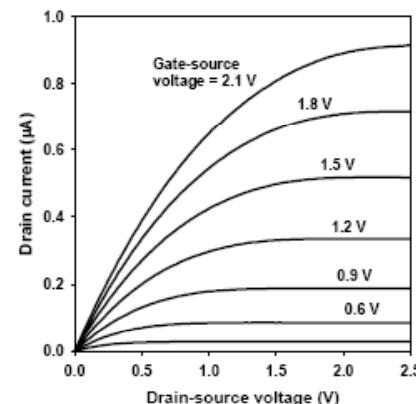
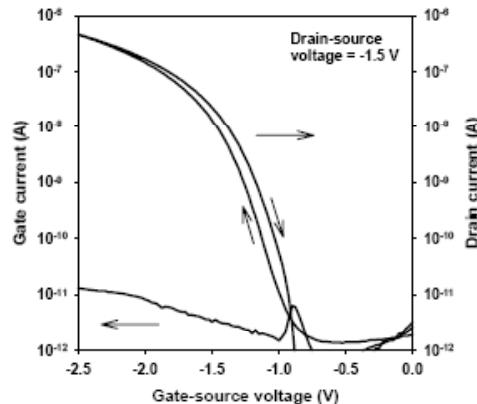
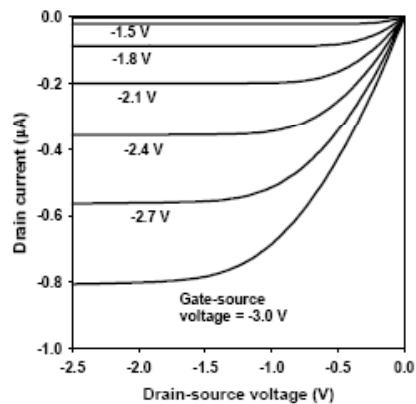
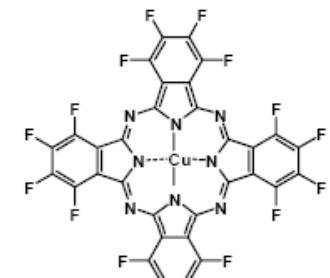
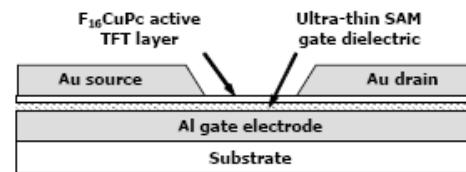
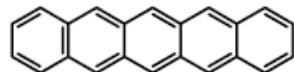
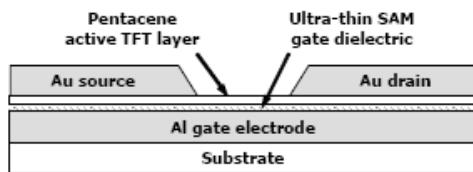


- Mechanically flexible
- Suitable for solution processing
 - Cheap to cover large areas
 - Make disposable devices



Applied Films

Organic Transistors



[Klauk]



Displays (1)



Plastic Logic

**Sony's 1,000,000:1 contrast ratio
27-inch OLED HDTV**



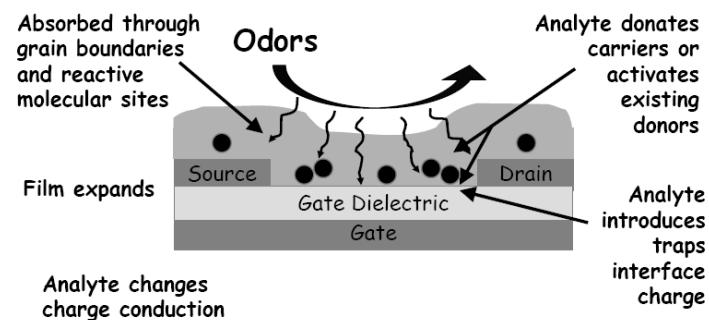
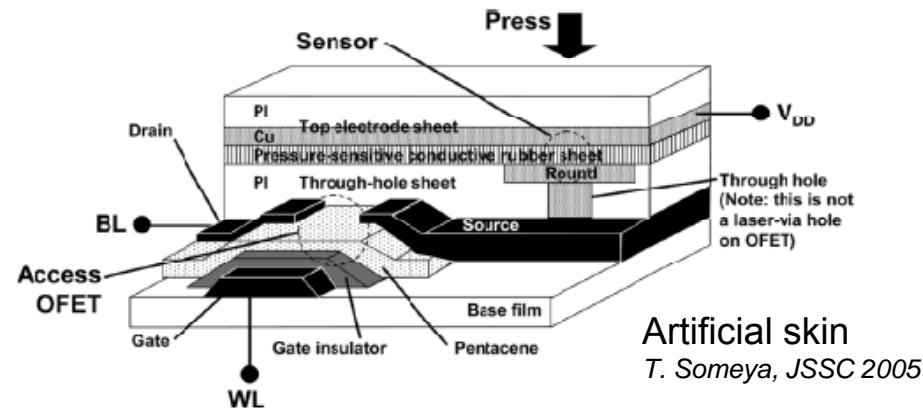
Displays (2)

Plastic Logic

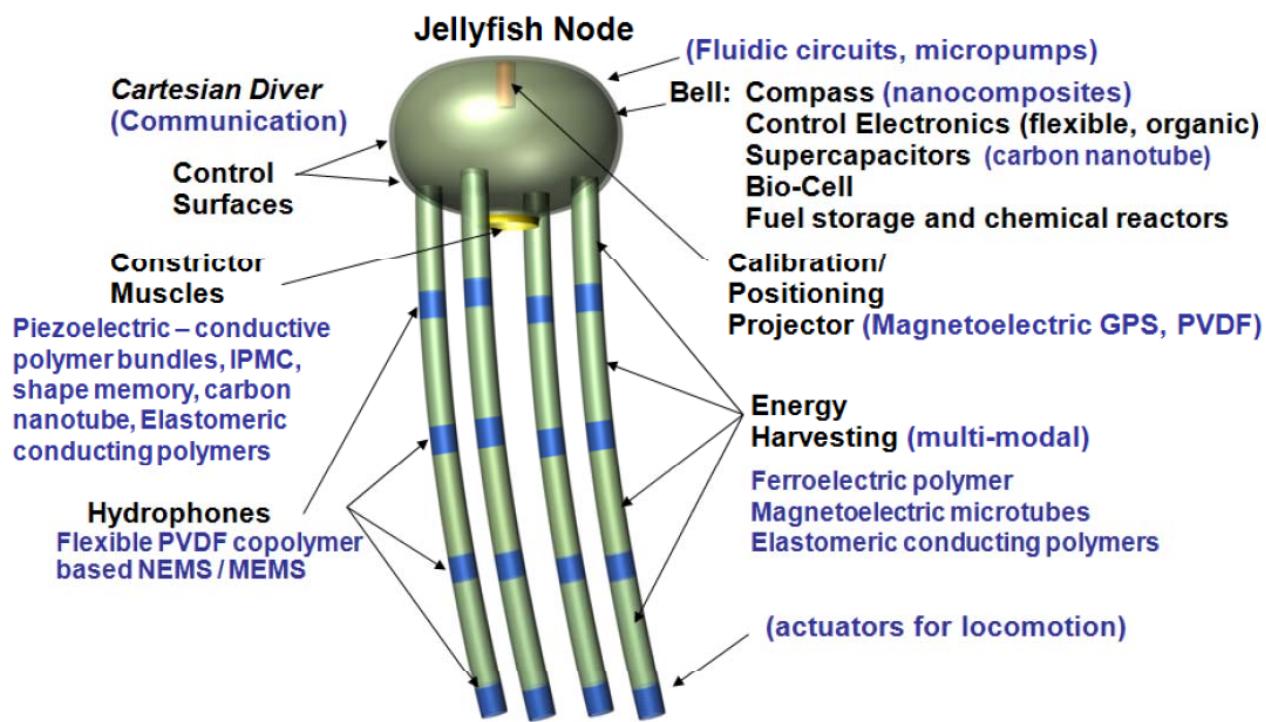
Why Flexible
Displays?



Sensor Applications



Jelly Fish Autonomous Node

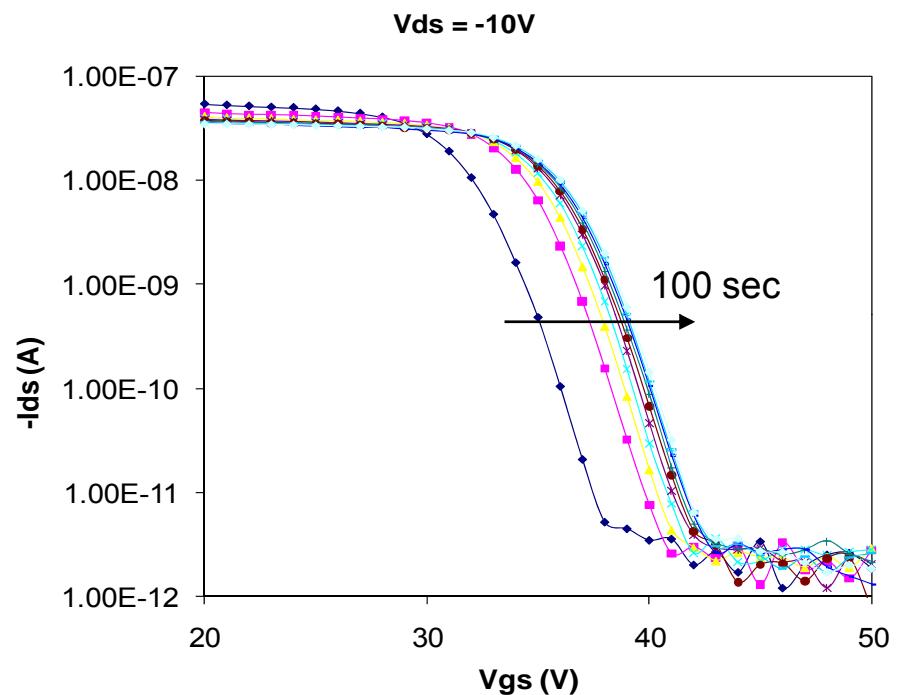


<http://muri.mse.vt.edu/>

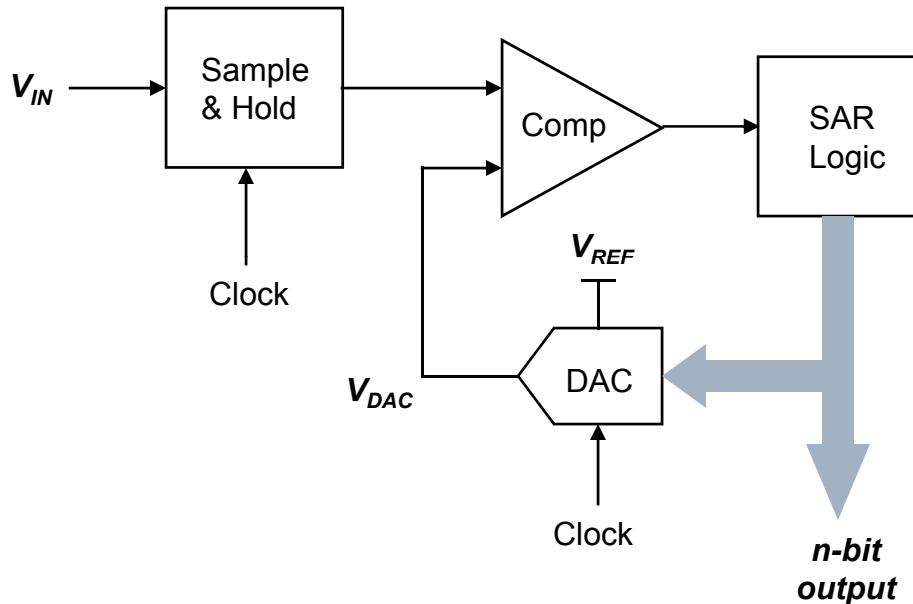


Organic Circuit Design Challenges

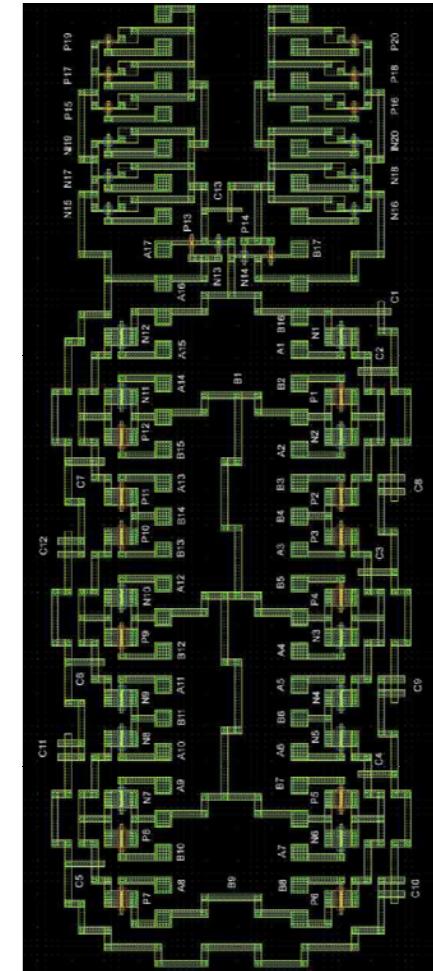
- Poor mobility
- Age degradation
- Bias stress effects
- Device-to-device variations
- Dielectric leakage
- To date, very little work on analog circuits using organic transistors



Work in Progress: ADC using OTFTs



30 mm



- Leverage experience from Si-CMOS to create a robust OTFT design



Summary

- Mixed-signal IC design is no longer business as usual
 - Expect less return from pure “scaling” of decade-old circuits
 - Time to become creative
- Many opportunities for innovation fall into the “cracks” between traditional boundaries of analog & digital, circuit & algorithm, mechanical & electrical partitioning
- Trend toward “More than Moore” will likely bring diversification of device technologies
 - MEMS/NEMS, large area device technologies, novel sensor devices, ...



Sponsors

