

Chipless RFID: Design Advances and Measurement Challenges in Identification and Sensing Applications

Katelyn Brinker and Reza Zoughi

Applied Microwave Nondestructive Testing Laboratory

Center for Nondestructive Evaluation

Iowa State University

Ames, Iowa USA

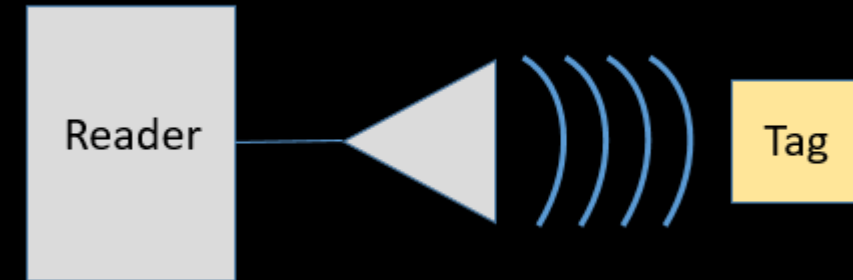
IOWA STATE UNIVERSITY

Center for Nondestructive Evaluation

This work was supported by a NASA Space
Technology Research Fellowship (NSTRF).

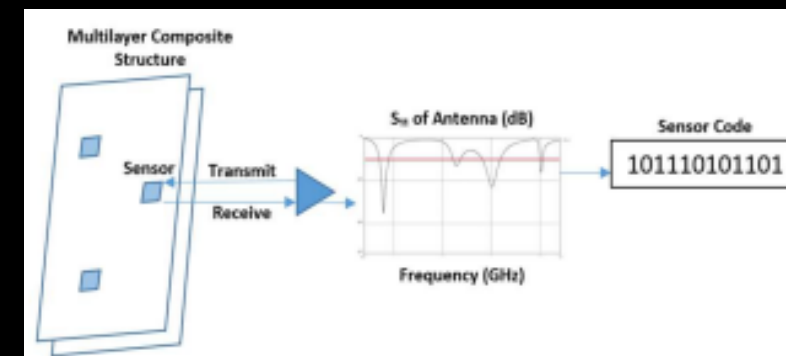
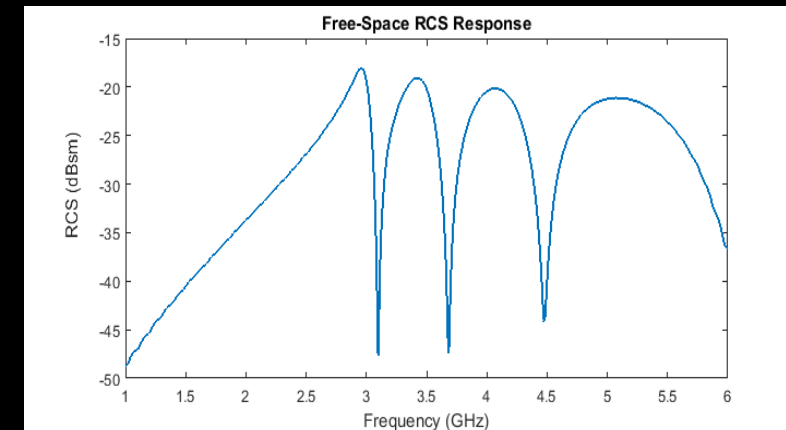
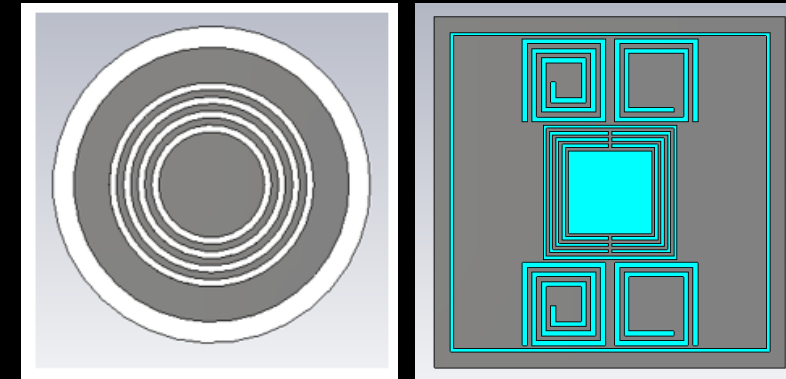
Radio Frequency Identification (RFID)

- System consists of a reader and a tag
- The reader interrogates tags with an EM wave and receives the tag response
- The tag can be active, semi-active, passive, or chipless
 - Active and semi-active tags require a battery or another power source
 - Passive tags are the most common and harvest power from the interrogating wave
 - Active and passive tags modulate their scattered waves
 - Chipless is the newest and least explored type of tag



Chipless RFID Background and Applications

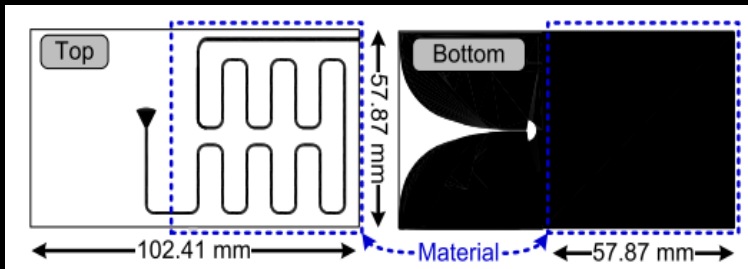
- Chipless RFID is a sub-set of RFID Technology
- Tags have no power source and no IC
 - Information is “stored” in the structure of the tag
- Tags are interrogated by an electromagnetic wave to produce a response (e.g., radar cross-section (RCS) or Complex Reflection Coefficient (S_{11}) vs. frequency)
- A binary code can be assigned to the response
 - Changing the response changes the code
- Tags can be used for ID or sensing applications
 - Changing the environment changes the response for sensing tags



Chipless Tag Architectures

Time – Domain

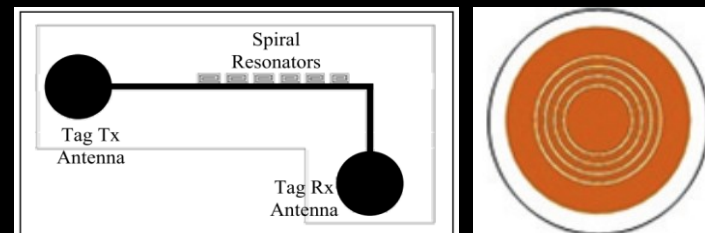
- Works based on Time Domain Reflectometry (TDR) principles
- Often incorporates meander lines
- Response can be transformed to the frequency domain for additional analysis



Time-domain tag for dielectric property sensing [1]

Frequency-Domain

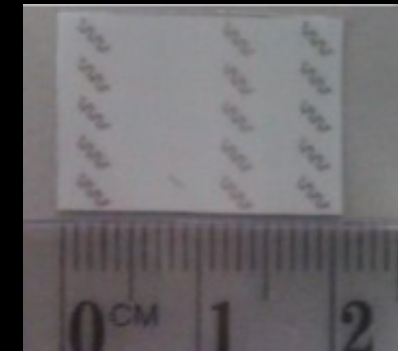
- Most common tag architecture
- Two Types: Tx/Rx and Backscatter
 - Tx/Rx tags have 2 cross-polarized antennas connected with a loaded microstrip line
 - Backscatter tags use different types of resonators to produce a desired response



Tx/Rx tag and backscatter tag [2-3]

Spatial-Domain

- Least common architecture
- Uses microwave imaging and creates a code from the generated image's features
- Easier to use at higher frequencies
- Requires a specialized reader system to make images quickly



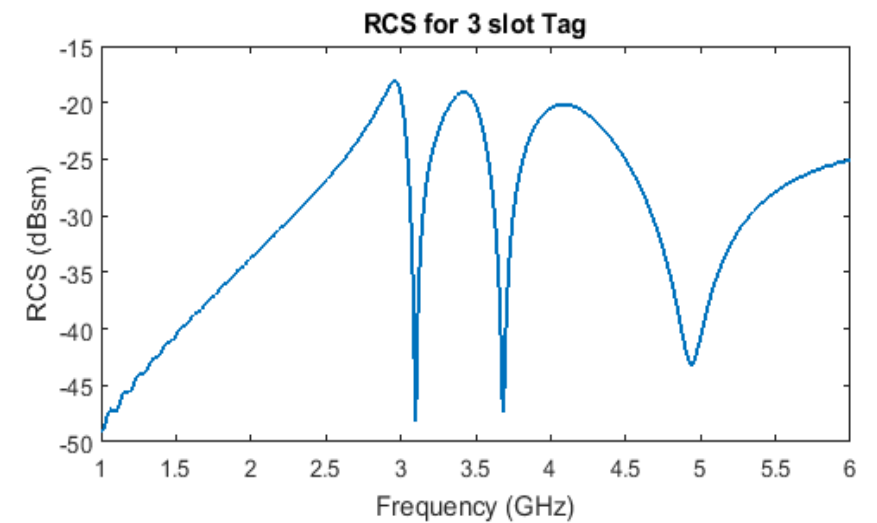
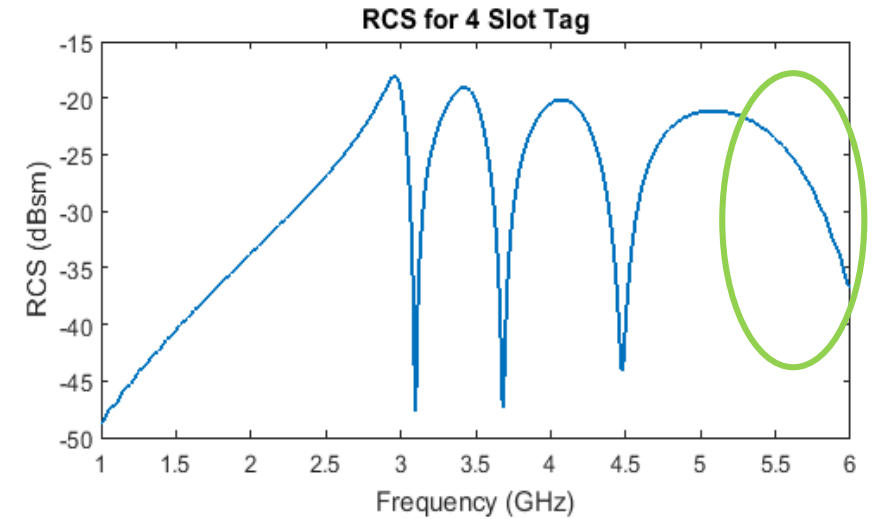
Spatial-domain depolarizing tag [4]

Encoding Methods

Coding Method Examples for 4 to 3 Slot Tag:

- Method 1: Notches are 1's, removing a notch shortens the code [5]
 - [1111]->[111]
- Method 2: Notches are 1's, removing a notch adds a 0 to the code [3]
 - [1111]->[1110]
- Method 3: Notches are 1's, elsewhere are 0's [6]
 - [01010101]->[01010100]

Methods are designed for ID based tags where the response is very predictable



Tag Metrics

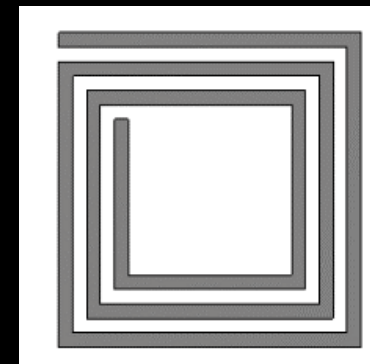
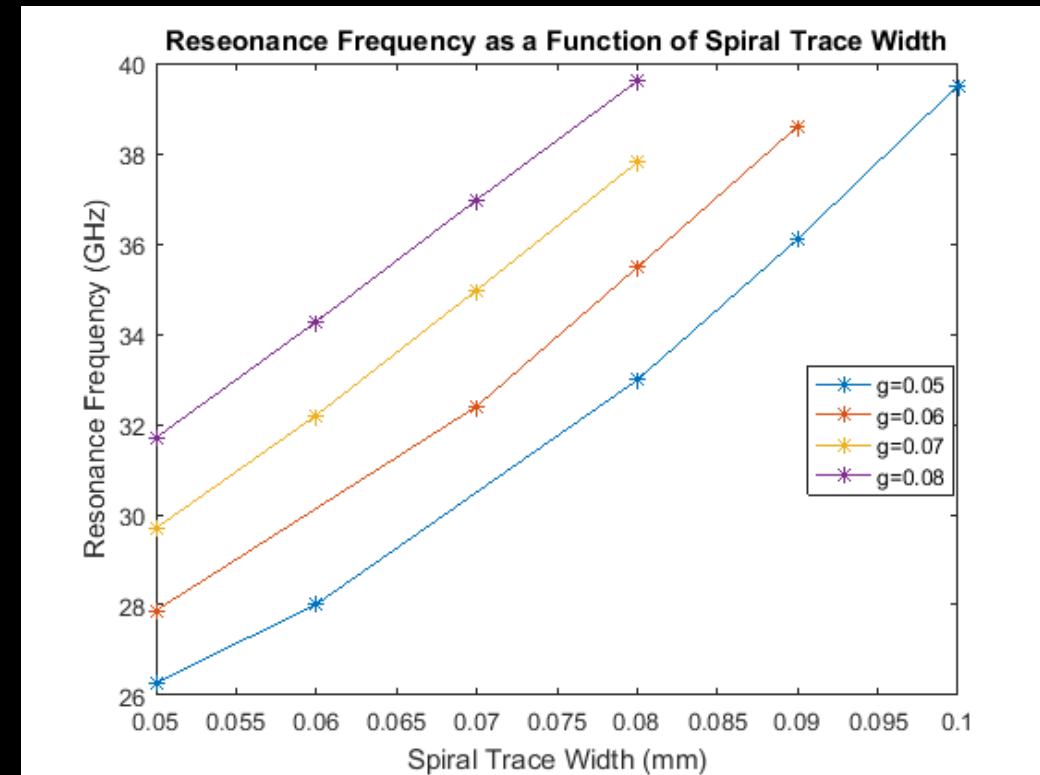
Metrics for ID application tags:

- Bit Density: number of bits in the code per square cm of tag area
- Data Density: number of bits in the code
- Spectral Density: number of bits in the code per bandwidth required for encoding
- Coding Capacity: multiple definitions, can refer to the number of possible unique codes

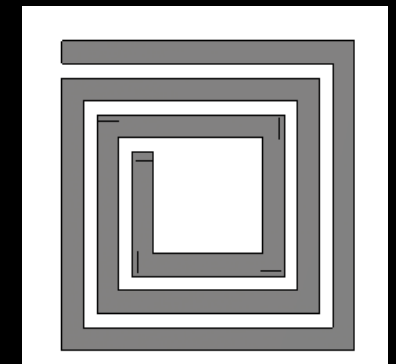
All of these metrics are highly dependent on the coding method used!

Tag Design Methodology

- Desire the ability to control the tag response so that tags can be engineered rather than designed through trial and error
- The following need to be taken into account :
 - The environment the tag will be in
 - Manufacturing options
 - Required tag metrics
- Combining multiple types of resonators can allow a greater variety of tag responses to be realized
 - Interactions between resonators can make it more challenging to discern what response characteristics are associated with what tag features
- Able to utilize design guidelines (design curves, equivalent circuits, and equations) to make purposeful changes to tag geometry

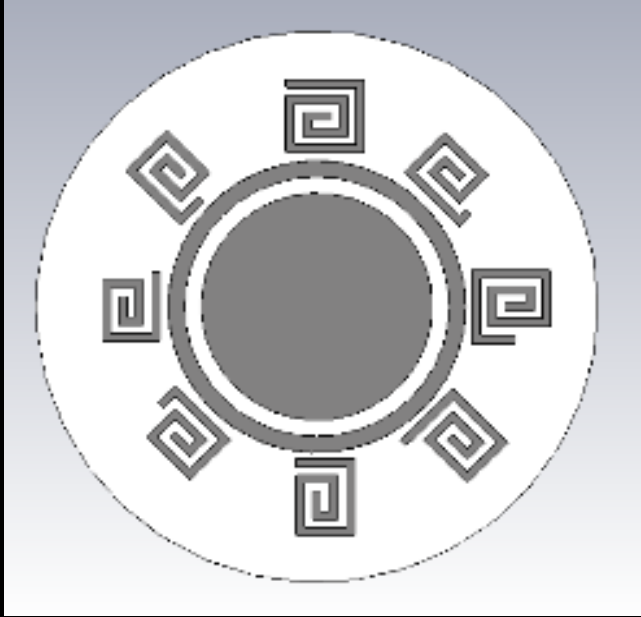


$g=0.05$ mm, $w=0.05$ mm

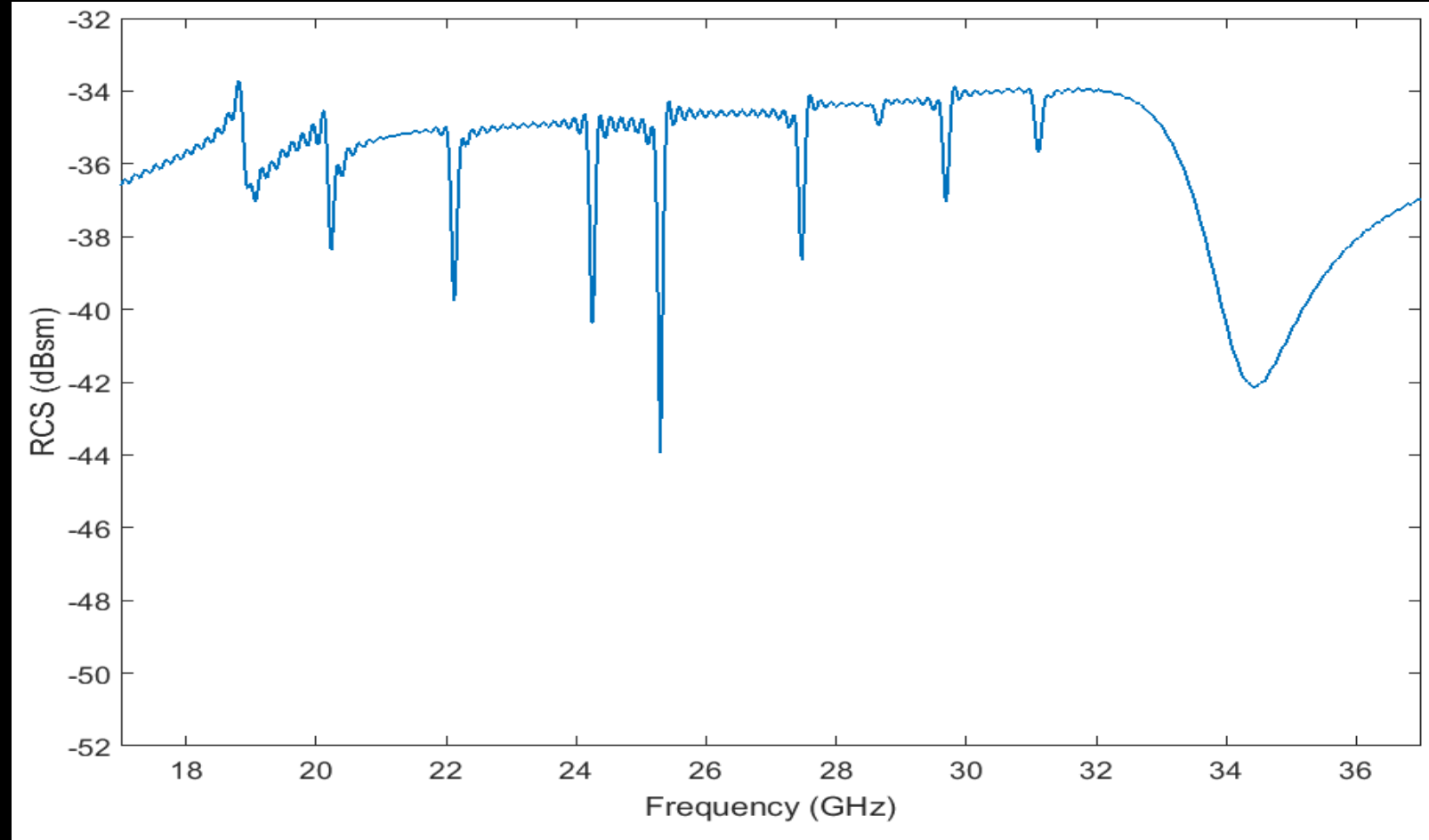


$g=0.05$ mm, $w=0.08$ mm

8-Spiral Tag

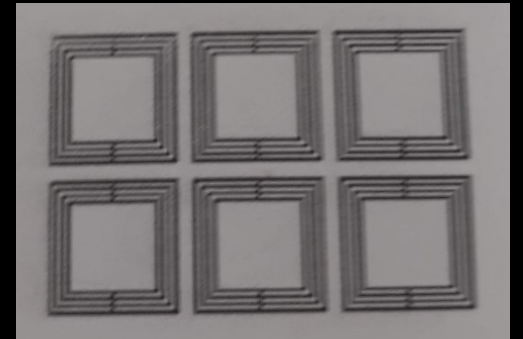
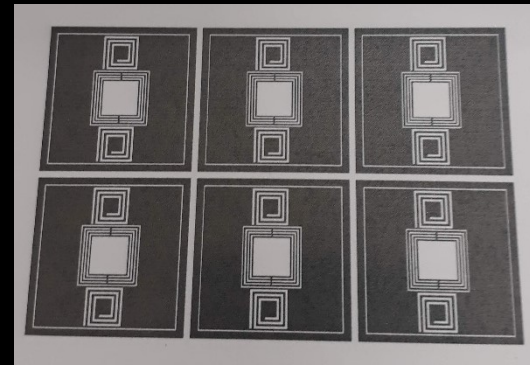
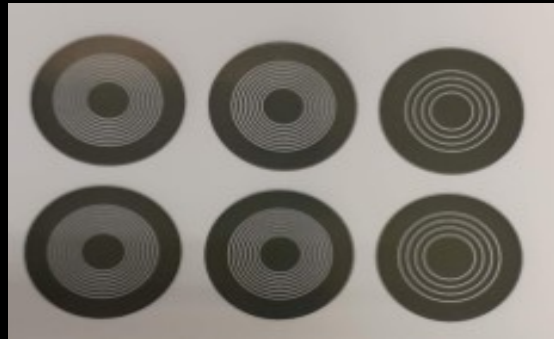
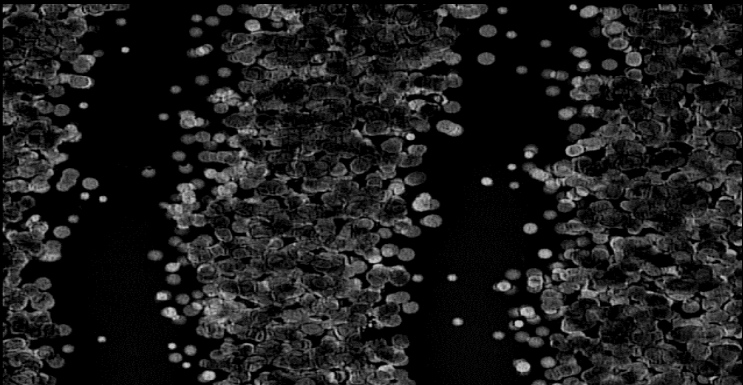
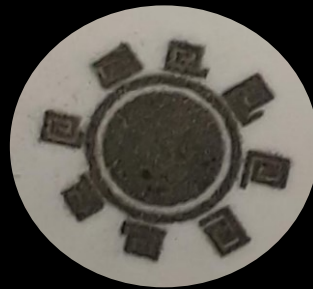


Method	Bit Density (bits/cm ²)	Coding Capacity
1	27.54	1024
2	27.54	1024
3	55.07	1048576



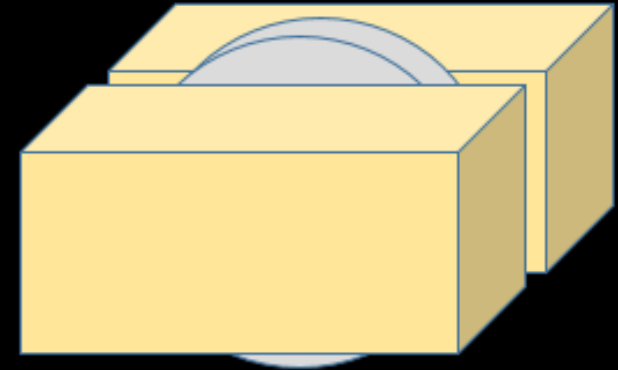
Tag Manufacturing

- In order for chipless RFID tags to become ubiquitous, they need to be able to be manufactured in an inexpensive and quick way
- Two Common manufacturing methods:
 - PCBs
 - Advantages: high conductivity of metallic features, capable of realizing small features
 - Disadvantages: Can be expensive
 - Ink-jet Printing
 - Advantages: Inexpensive and quick manufacturing process.
 - Disadvantages: Difficult to integrate a ground plane or use thick substrates. Prints can have low conductivity.



Measurement Methods

- Tag responses need to be measured accurately so that the code is properly assigned
- Common measurement methods include:
 - S-parameters – distance dependent
 - Monostatic with standoff distance
 - Monostatic loaded waveguide
 - Bistatic with standoff distance
 - Bistatic transmission measurement
 - RCS – distance independent
 - Monostatic
 - Bistatic



RCS Measurement

- Method 1: Using the Radar Range Equation [7]

$$P_r = \frac{P_t G_t G_r \sigma_{target} \lambda^2}{(4\pi)^3 R^4}$$

- Method 2: Using S_{11} measurements without calibration targets [8]

$$\sigma = |S'_{11}|^2 \frac{(4\pi)^3 R^4}{G_t^2 \lambda^2}$$

- Method 3: Combining S_{11} measurements with the Radar Range Equation [9]

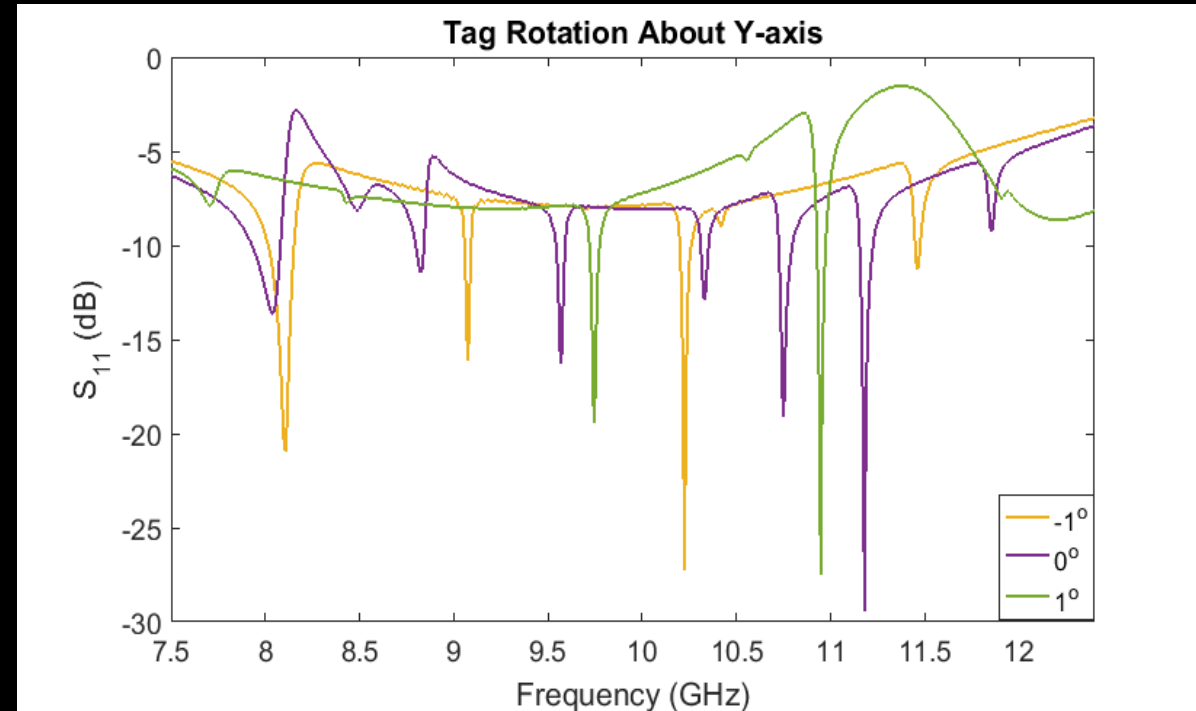
$$\sigma = \left| S_{11}^{target} - S_{11}^{mount} \right|^2 \frac{(4\pi)^3 R^4}{G^2 \lambda^2 \left(1 - \left| S_{11}^{Tx/Rx} \right|^2 \right)^2}$$

- Method 4: Using a reference target with S-parameter measurements [10]

$$\sigma_{tag} = \left[\frac{S_{21}^{tag} - S_{21}^{support}}{S_{21}^{ref} - S_{21}^{support}} \right]^2 \sigma_{ref}$$

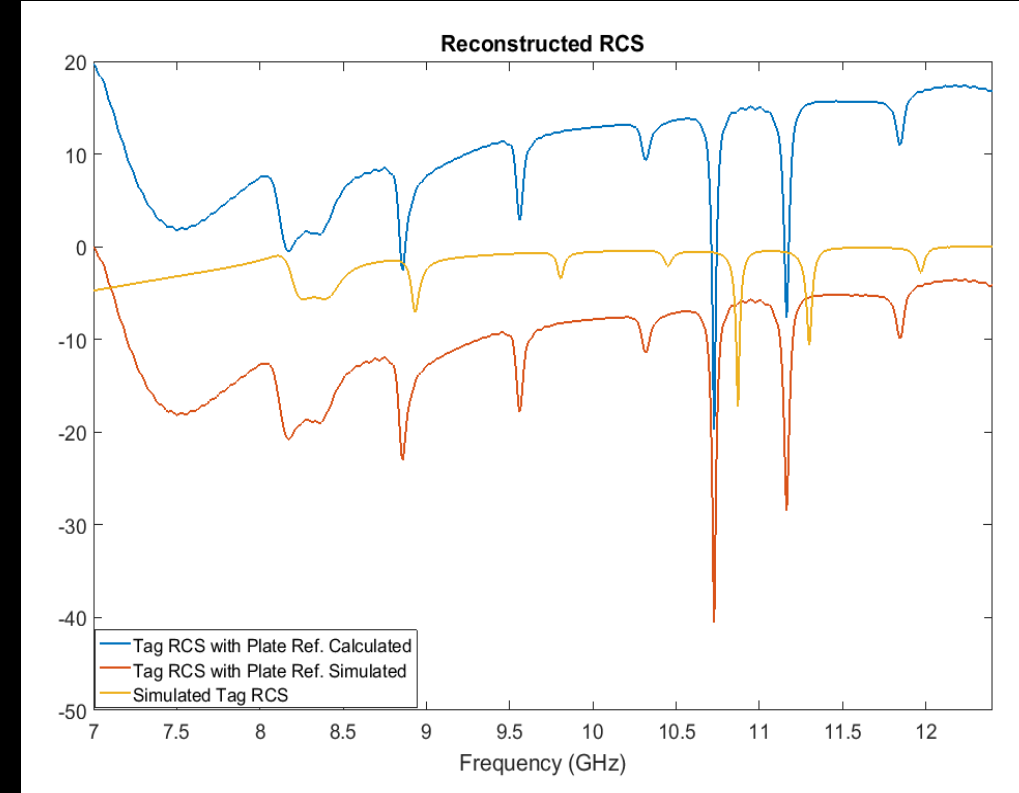
Measurement Challenges

- Distance dependency
 - Small changes in distance between tag and reader antenna cause response differences
- Orientation sensitivity
 - Small rotations of the tag with respect to the reader antenna can cause large response differences
- Small read range
 - Ability to discern the tag response diminishes as the distance between the tag and reader antenna increases



Measurement Challenges

- Need for calibration targets
 - Makes it difficult to measure RCS outside of a laboratory environment
- Tag localization
 - Responses from tags close to each other can interfere with each other
- Environmental effects
 - Reflections from the tag background can interfere with the tag response
 - Ex. superposition of scattering from tag and from what the tag is attached to

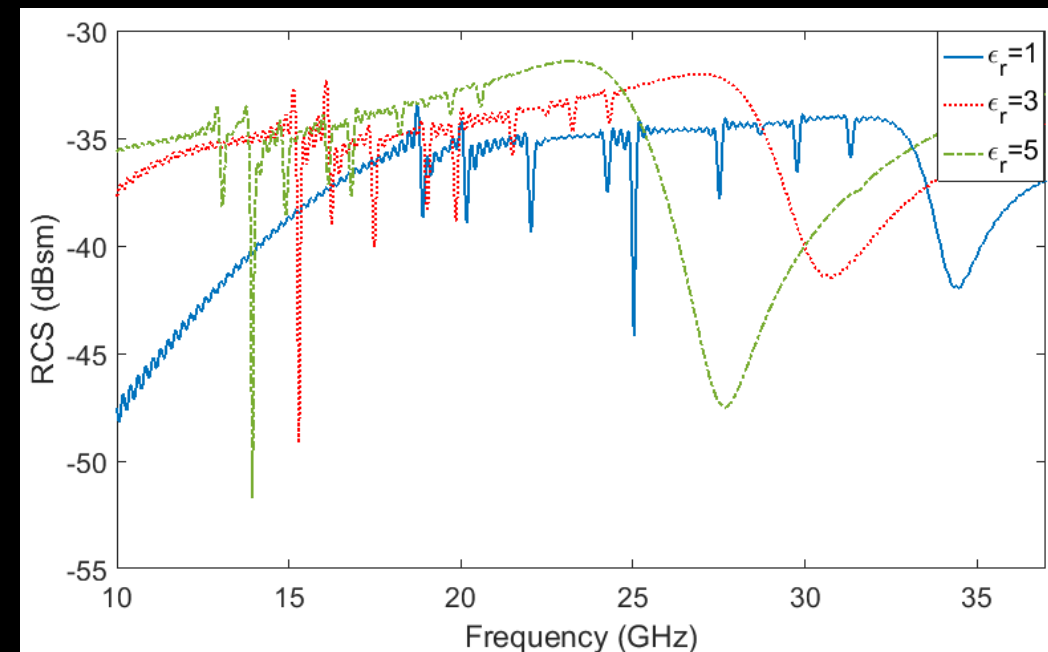
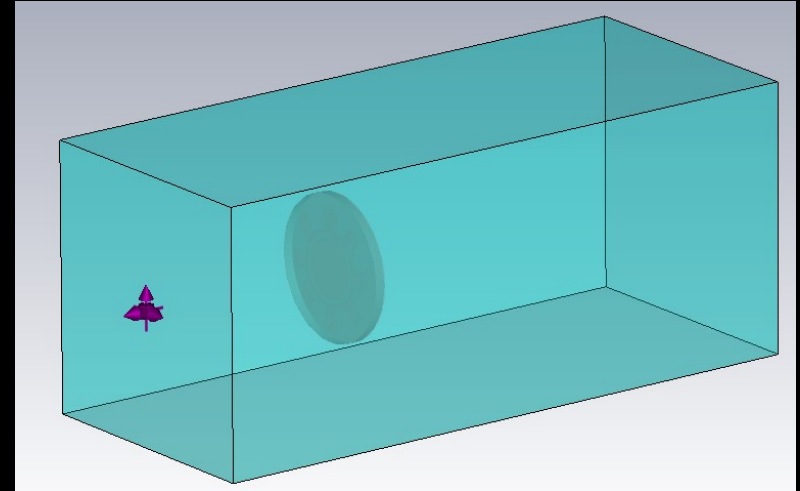


Overcoming Measurement Challenges

- Orientation independent tags
 - Mitigates z-axis rotation issues, but not x- or y-axis rotation
- Depolarizing tags
 - Isolates the response of the tag from that of the background
- Specialized reader antennas
 - Using dual or circular polarization to reduce z-axis rotation sensitivity
 - Using high gain antennas to increase the read range
 - Using antennas with narrow beams to illuminate single tags

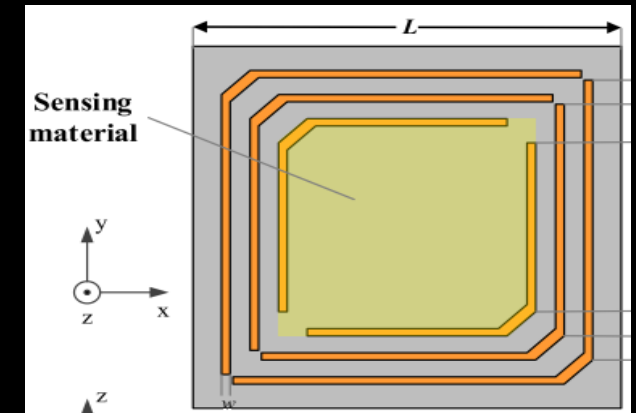
Chipless RFID for Sensing

- Tags can be designed so that changes in the environment result in changes of the tag's code
- Sensing parameter examples: dielectric constant, humidity, temperature, strain, corrosion, displacement, light intensity, etc.
- Binary codes often are not assigned to sensing tag responses, but they can be
 - Typically look at the shift or change in magnitude of 1 notch in the response
- Key challenge: isolating the effect of the sensing parameter from the effects of the measurement challenges

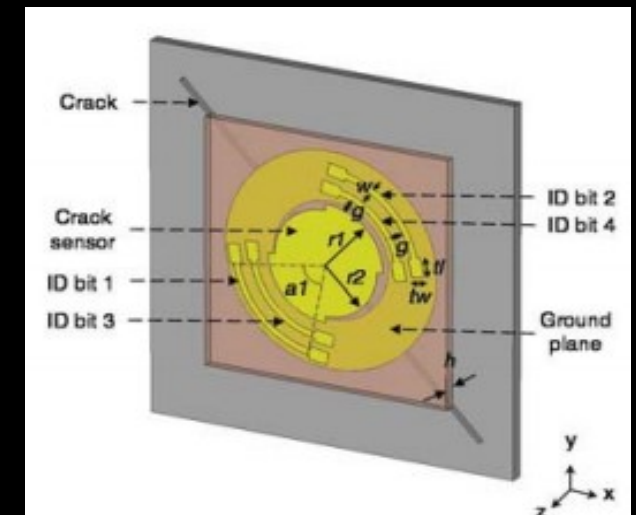


Combining Identification and Sensing

- Can have tag features in a sensing tag (code bits) that are not sensitive to the sensing parameter
 - Act as ID bits
- Can have a sensing feature (bit) that is sensitive to an environmental factor
 - Ex. Sensing the effect of the material the tag is attached to on the response for correction purposes
- Key challenge: isolating the effect of the sensing parameter from the effects of the measurement challenges



Humidity sensor with ID bits [11]



Crack sensor with ID bits [12]

Conclusions

- Chipless RFID has the potential to provide inexpensive, passive, and wireless identification and sensing capabilities
- There are still many challenges, some significant, to be overcome in the chipless RFID field, especially for bringing chipless RFID out of the lab. and into the practical applications realm

References

1. A. Ramos, A. Lazaro, and D. Girbau, "Time-coded chipless sensors to detect quality of materials in civil engineering," in *2015 9th European Conference on Antennas and Propagation (EuCAP)*, 2015, pp. 1-4.
2. S. Preradovic, I. Balbin, N. C. Karmakar, and G. Swiegers, "A Novel Chipless RFID System Based on Planar Multiresonators for Barcode Replacement," in *2008 IEEE International Conference on RFID*, 2008, pp. 289-296.
3. M. A. Islam, Y. Yap, N. Karmakar, and A. K. M. Azad, "Orientation independent compact chipless RFID tag," in *2012 IEEE International Conference on RFID-Technologies and Applications (RFID-TA)*, 2012, pp. 137-141.
4. D. H. Nguyen, M. Zomorodi, and N. C. Karmarka, "Spatial-Based Chipless RFID System," *IEEE Journal of Radio Frequency Identification*, pp. 1-1, 2019.
5. A. Habib, M. A. Afzal, H. Sadia, Y. Amin, and H. Tenhunen, "Chipless RFID tag for IoT applications," in *2016 IEEE 59th International Midwest Symposium on Circuits and Systems (MWSCAS)*, 2016, pp. 1-4.
6. S. Preradovic, I. Balbin, N. C. Karmakar, and G. Swiegers, "A Novel Chipless RFID System Based on Planar Multiresonators for Barcode Replacement," in *2008 IEEE International Conference on RFID*, 2008, pp. 289-296.
7. M. Grace, "Measurement of Radar Cross Section Using the "VNA Master" Handheld VNA: Application Note," Anritsu2011.
8. K. V. S. Rao, P. V. Nikitin, K. V. S. Rao, and P. V. Nikitin, "Theory and measurement of backscattering from RFID tags," *IEEE Antennas and Propagation Magazine*, vol. 48, pp. 212-218, 2006.

References

9. D. Hotte, R. Siragusa, Y. Duroc, and S. Tedjini, "Radar cross-section measurement in millimetre-wave for passive millimetre-wave identification tags," *IET Microwaves, Antennas & Propagation*, vol. 9, pp. 1733-1739, 2015.
10. A. Vena, "Contribution au développement de la technologie RFID sans puce à haute capacité de codage," Université de Grenoble, 2014.
11. S. Fan, T. Chang, X. Liu, Y. Fan, and M. M. Tentzeris, "A Depolarizing Chipless RFID Tag with Humidity Sensing Capability," in *2018 IEEE International Symposium on Antennas and Propagation & USNC/URSI National Radio Science Meeting*, 2018, pp. 2469-2470.
12. A. M. J. Marindra, R. Sutthaweeikul, and G. Y. Tian, "Depolarizing Chipless RFID Sensor Tag for Characterization of Metal Cracks Based on Dual Resonance Features," in *2018 10th International Conference on Information Technology and Electrical Engineering (ICITEE)*, 2018, pp. 73-78.