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Radio Receiver Mixer Model for Event Driven Simulators to support Functional Verification of RF-SOC Wireless Links

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Agenda

- Background and Motivation
- Mixer theory
 - Ugly Math
 - Pretty result
- Model code
- Test code
- Results

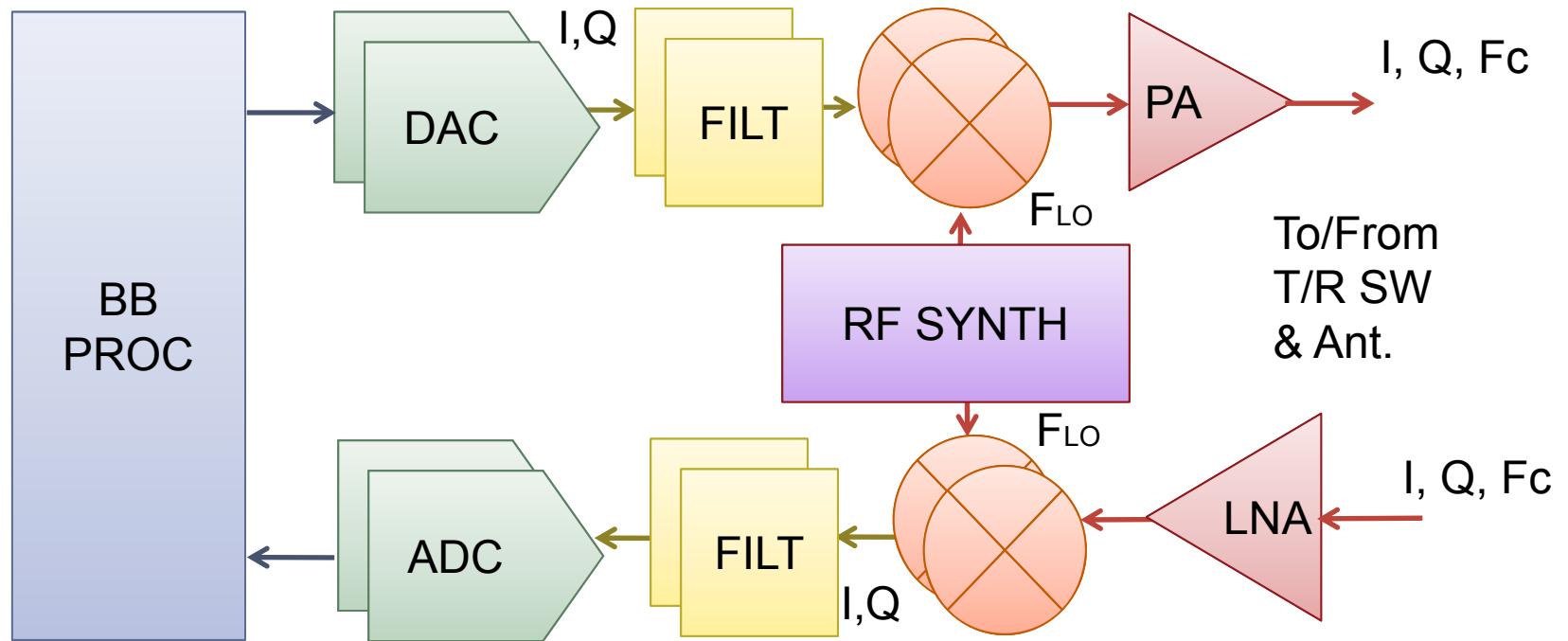


Drivers for Consumer Device IC's

- Wires – Weight – Wallet
 - Consumers like Simplicity,
 - Convenience, Affordability
 - ~~Cables~~
 - ~~Power Outlet~~
 - Batteries
- Wireless connectivity is improvement.
 - If LOW power and LOW cost.
 - Lower Power -> more digital & simpler analog[Horowitz] -> smaller process nodes
 - Lower Cost -> more integration
- More Digital More Integration -> More risk of respin for functional failure
 - RF functional verification is key enabler to success.



Block Diagram of Generic Wireless tranciever



- Using real number modeling – models for all blocks are fairly straightforward except the RX mixer.
 - RF I & Q values must be rotated to BB I & Q values based on phase difference between Carrier and Local Oscillator.

Digital

Analog

RF

Representing RF signals

$$S_{RF} = re\{ [I(t) + jQ(t)]e^{j\omega t} \}$$

$$S_{RF} = I(t)\cos(\omega t) - Q(t)\sin(\omega t)$$

- I, Q, f [= $\omega/2\pi$] are sufficient to represent most RF signals.
 - FM: I = signal Ampl Q = 0, variation in f carries signal information
 - AM: I = signal, Q = 0, f is carrier frequency
 - QAM: I & Q carry Baseband signal, f is channel frequency.
- System Level simulations (Matlab)
 - assume fixed frequency,
 - use complex number for I & Q.
 - Assumption doesn't hold for functional verification.

Mixer Theory

- “At the core of all mixers presently in use is a multiplication of two signals in the time domain. The fundamental usefulness of multiplication may be understood from examination of the following trigonometric identity:

$$(A \cos \omega_1 t)(B \cos \omega_2 t) = \frac{AB}{2} [\cos(\omega_1 - \omega_2)t + \cos(\omega_1 + \omega_2)t]$$

”

- Tom Lee [15]

The Ugly Math – Quadrature mixer

1: Get an instantaneous value for frequency(phase)

$$\omega t = \int_0^t \omega dt = \omega \int_0^t dt$$

$$\phi = \int_0^t \omega dt = 2\pi \int_0^t F dt$$

2: This makes our Mixer Equation:

$$(A \cos \phi_{RF}) (\cos \phi_{LO}) = \frac{A}{2} [\cos(\phi_{RF} - \phi_{LO}) + \cos(\phi_{RF} + \phi_{LO})]$$

4: Dropping the summing terms due to filtering
Our Quadrature receiver gives us two output signals:

$$I_{REC} = \frac{I}{2} [\cos(\Delta\phi)] - \frac{Q}{2} [\sin(\Delta\phi)]$$

$$Q_{REC} = \frac{I}{2} [\sin(\Delta\phi)] + \frac{Q}{2} [\cos(\Delta\phi)]$$

3: define a few other terms

$$\Delta\phi = \phi_{RF} - \phi_{LO} \quad \& \quad \Sigma\phi = \phi_{RF} + \phi_{LO}$$

$$(I \cos \phi_{RF} - Q \sin \phi_{RF}) (\cos \phi_{LO}) = \frac{I}{2} M'_{11} - \frac{Q}{2} M'_{12}$$

$$(I \cos \phi_{RF} - Q \sin \phi_{RF}) (-\sin \phi_{LO}) = -\frac{I}{2} M'_{21} + \frac{Q}{2} M'_{22}$$

$$M'_{11} = \cos(\Delta\phi) + \cos(\Sigma\phi)$$

$$M'_{12} = \sin(\Delta\phi) + \sin(\Sigma\phi)$$

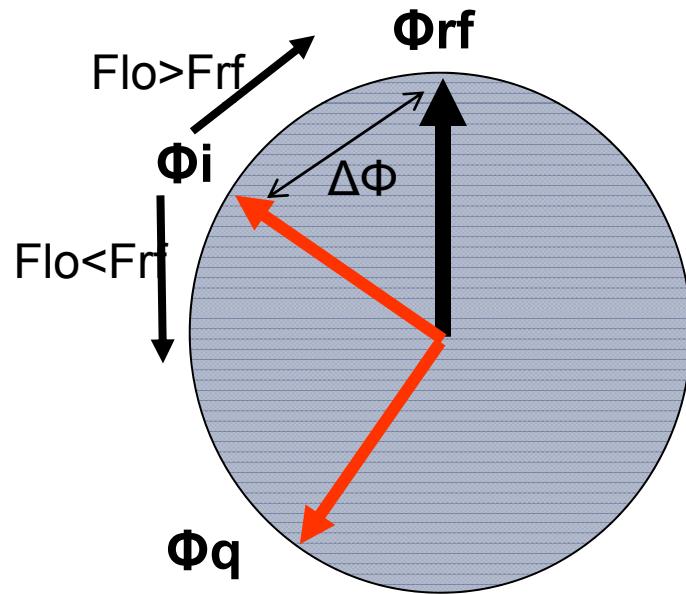
$$M'_{21} = -\sin(\Delta\phi) + \sin(\Sigma\phi)$$

$$M'_{22} = \cos(\Delta\phi) - \cos(\Sigma\phi)$$

The Pretty Result

- The mixer model only needs to know the Difference in the phase between the RF Frequency and LO frequency to calculate the Baseband output of the mixer.
- Since integration is linear, the difference in phase can be calculated by integrating the difference in frequency.

$$R_I = G_I [I(t) \cos(\Delta\phi) - Q(t) \sin(\Delta\phi)]$$
$$R_Q = G_Q [I(t) \cos(\Delta\phi - \pi/2) - Q(t) \sin(\Delta\phi - \pi/2)]$$



Model Code – module and variable declarations

```
module rx_mixer_generic_sv ( // goes here
    input logic enable,           // only logic controls are made as pins
    input var real RXin_I_inph, RFin_I_quad, // BB equiv I and Q
    input var real RXin_freq, RFin_BW,      // Fcarrier, Signal BW
    input var real LOin_Freq_inph, LOin_Freq_quad,
    input var real Gain,          // this is the core mixer gain
    output var real BB_I_Iout,    // output is current
    output var real BB_Q_Qout,    // output is current
    output var real BB_BW );     // same bandwidth for all 4 pins
-----
reg Fi_ok, Fq_ok; //status LO input freq and sig BW
real RXin_freq_Last, LOin_Freq_inph_Last; // prior value for integration
real time_Last, dt; //time variables for integration
integer Ndel_t; // for modulo integration
real DeltaPhi; // Phase difference between RF and LO
real two_pi, pi, pi_by2, signQ; // "pi constants" & LO rot direction
real M11, M12, M21, M22; // Matrix relating <I, Q>in to <I, Q>out
real Eff_gain; // gain after BW checks
```

Model Code – module initialization

```
always @(posedge enable) begin //initialize model
    RXin_freq_Last = RXin_freq;
    L0in_Freq_inph_Last = L0in_Freq_inph;
    time_Last = $realtime;
    dt = 0;
    pi_by2 = $qc_asin(1.0);
    pi = pi_by2*2.0;
    two_pi = 2.0*pi;
    signQ = (L0in_Freq_quad>0)? 1.0 : -1.0;
    BB_I_Iout = RXin_I_inph; // at t0 M11 M22 = 1 M12 m21 = 0
    BB_Q_Iout = signQ*RFin_I_quad;
end
```

Model Code – sanity check inputs

```
always @(L0i n_Freq_i nph, L0i n_Freq_quad, RXi n_freq, RFi n_BW) begin  
    Fi_ok = $qc_abs(L0i n_Freq_i nph-RXi n_freq) < RFi n_BW;  
    Fq_ok = $qc_abs($qc_abs(L0i n_Freq_quad)-RXi n_freq) < RFi n_BW;  
    Eff_gain = (Fi_ok&&Fq_ok)?Gain: 0.0;  
    BB_BW = (Fi_ok&&Fq_ok)?RFi n_BW: 0.0;  
end  
always @(L0i n_Freq_quad) signgnQ = (L0i n_Freq_quad>0)? 1.0 : -1.0;
```

Model Code – Integration to get deltaPhi

```
always @(L0i n_Freq_i nph, RXi n_freq, RXi n_I i nph, RFi n_I quad) begin // update events
    #0 dt = ($real time - time_last)*1e-9; // timescale is in ns
    if (dt > 0.0) begin // update only if time has moved
        // - integrate Del taF to get Del taPhase
        Del taPhi = Del taPhi + (RXi n_freq_last - L0i n_Freq_i nph_last)*dt*two_pi;
        //use Prior values until next delta time
        Ndel t = Del taPhi /two_pi; // get 2*pi units
        Del taPhi = Del taPhi - Ndel t*two_pi; // subtract them
    end
    RXi n_freq_last = RXi n_freq; //update the history vars
    L0i n_Freq_i nph_last = L0i n_Freq_i nph;
    time_last = $real time;
```

Model Code – core equations

```
// matrix factors
M11      = $qc_cos(Del taPhi )*Eff_gai n;
M12      = -1.0 * $qc_si n(Del taPhi )*Eff_gai n;
M21      = si gnQ * $qc_si n(Del taPhi )*Eff_gai n;
M22      = si gnQ * $qc_cos(Del taPhi )*Eff_gai n;
BB_I_I out = M11 * RXI n_I i nph + M12 * RFIn_I quad;
BB_Q_I out = M21 * RXI n_I i nph + M22 * RFIn_I quad;
end
endmodul e
```

Testing the model – 10 cases

TestID	Description	Fr _f	F _{lo}	F _{bb}	LO IlleadsQ	Gain
1	"Fr _f = F _{lo} "	2.4G	2.4G	2M	T	3dB
2	"Fr _f < F _{lo} "	2.4G	2.4005G	2M	T	3dB
3	"Fr _f << F _{lo} "	2.4G	2.404G	2M	T	3dB
4	"Fr _f > F _{lo} "	2.4005G	2.4G	2M	T	3dB
5	"Fr _f >> F _{lo} "	2.402G	2.4G	2M	T	3dB
6	"Fr _f = -F _{lo} "	2.4G	2.4G	2M	F	3dB
7	"Fr _f < -F _{lo} "	2.4G	2.4005G	2M	F	3dB
8	"Fr _f << -F _{lo} "	2.4G	2.404G	2M	F	3dB
9	"Fr _f > -F _{lo} "	2.4005G	2.4G	2M	F	3dB
10	"Fr _f >> -F _{lo} "	2.402G	2.4G	2M	F	3dB

Testing the model - expected results

```
Fexpect = $qc_abs(Frf + Fbb - Fl o);
I I eadsQexpect = L0_I I eadsQ ~^ (FrF + Fbb > Fl o);
BB_I freq = RX_BBMon. xI Freq;
BB_Qfreq = RX_BBMon. xQFreq;
IQPhasing = RX_BBMon. I_I eads_Q;
FromBBmonI = RX_BBMon. xI PeakAc;
FromBBmonQ = RX_BBMon. xQPeakAc;
PeakInput = RXsrc. peak;
Radius = $qc_sqrt(FromBBmonI * FromBBmonI +
                  FromBBmonQ * FromBBmonQ);
if(PeakInput>0.0) begin
    Actual Gain = (20.0)*$qc_log10(Radius/PeakInput); //Gain in dB.
    GainOK = ($qc_abs(Actual Gain - RxGain[TestID])<2.0);
end
```

Testing the model – Did we pass (Verilog)

```
testpassed = (I_IleadsQexpect === RX_BBMon.I_Ileads_Q)
             && ($qc_abs(BB_I freq - Fexpect) <2e3)
             && ($qc_abs(BB_Qfreq - Fexpect) <2e3)
             && GainOK;

$strobe("%s @ %t: RXTEST%02d %s Gain: %g dB, Frf: %g Hz,
        Flfo: %g L0: %s Hz, Fbb: %g Hz, BB: %s",
        testpassed?"SPECINFO": "SPECFAIL", $real time,
        TestID,
        testpassed?" Passed ":" Failed ",
        Actual Gain, $qc_abs(Frf), $qc_abs(Flfo),
        L0_I_IleadsQ? "I_Ileads_Q": "Q_Ileads_I",
        $qc_abs(Fexpect),
        IQPhasing? "I_Ileads_Q": "Q_Ileads_I");

if (!testpassed) QcAssertFailIncrement;
```

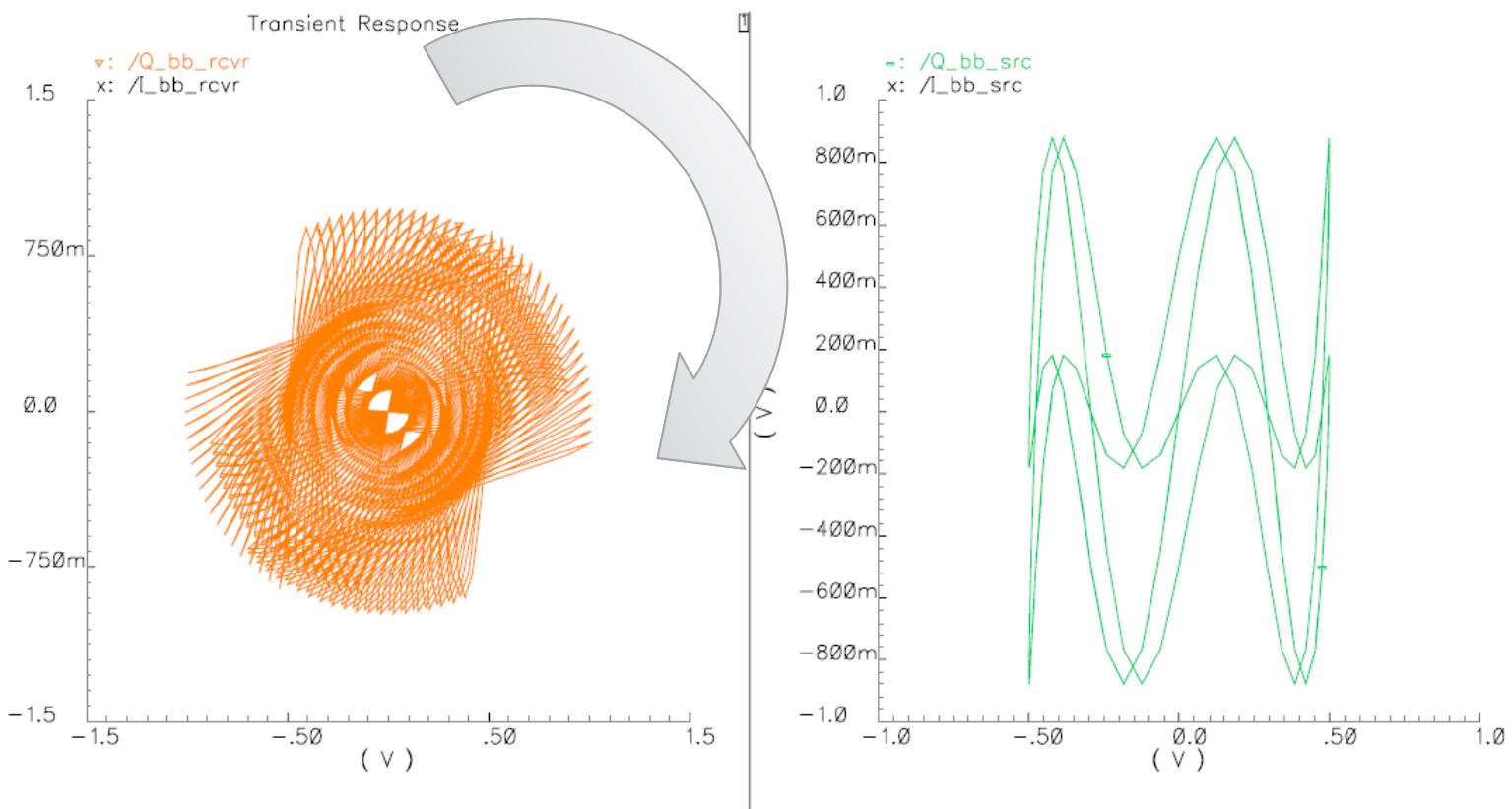
Automated Test Results

SPECINFO @ 15388.000 ns: RXTEST01 Passed : Gain:3.00487 dB, Frf: 2.4e+09 Hz, Flo: 2.4e+09 LO:I leads Q Hz, Fbb: 2e+06 Hz, BB:I leads Q
SPECINFO @ 33228.000 ns: RXTEST02 Passed : Gain:3.00867 dB, Frf: 2.4e+09 Hz, Flo: 2.4005e+09 LO:I leads Q Hz, Fbb: 1.5e+06 Hz, BB:I leads Q
SPECINFO @ 47898.000 ns: RXTEST03 Passed : Gain:3.00355 dB, Frf: 2.4e+09 Hz, Flo: 2.404e+09 LO:I leads Q Hz, Fbb: 2e+06 Hz, BB:Q leads I
SPECINFO @ 60648.000 ns: RXTEST04 Passed : Gain:2.99961 dB, Frf: 2.4005e+09 Hz, Flo: 2.4e+09 LO:I leads Q Hz, Fbb: 2.5e+06 Hz, BB:I leads Q
SPECINFO @ 70528.000 ns: RXTEST05 Passed : Gain:2.98611 dB, Frf: 2.402e+09 Hz, Flo: 2.4e+09 LO:I leads Q Hz, Fbb: 4e+06 Hz, BB:I leads Q
SPECINFO @ 85398.000 ns: RXTEST06 Passed : Gain:3.00598 dB, Frf: 2.4e+09 Hz, Flo: 2.4e+09 LO:Q leads I Hz, Fbb: 2e+06 Hz, BB:Q leads I
SPECINFO @ 103228.00 ns: RXTEST07 Passed : Gain:3.00735 dB, Frf: 2.4e+09 Hz, Flo: 2.4005e+09 LO:Q leads I Hz, Fbb: 1.5e+06 Hz, BB:Q leads I
SPECINFO @ 117908.00 ns: RXTEST08 Passed : Gain:3.00546 dB, Frf: 2.4e+09 Hz, Flo: 2.404e+09 LO:Q leads I Hz, Fbb: 2e+06 Hz, BB:I leads Q
SPECINFO @ 130668.00 ns: RXTEST09 Passed : Gain:3.0074 dB, Frf: 2.4005e+09 Hz, Flo: 2.4e+09 LO:Q leads I Hz, Fbb: 2.5e+06 Hz, BB:Q leads I
SPECINFO @ 140548.00 ns: RXTEST10 Passed : Gain:2.98868 dB, Frf: 2.402e+09 Hz, Flo: 2.4e+09 LO:Q leads I Hz, Fbb: 4e+06 Hz, BB:Q leads I

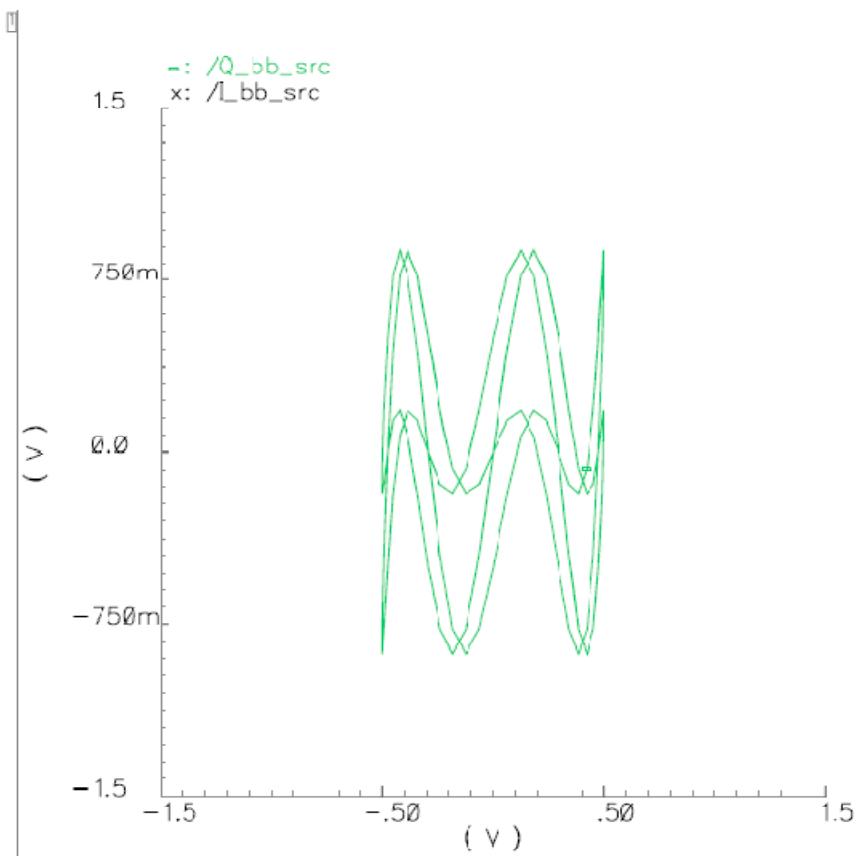
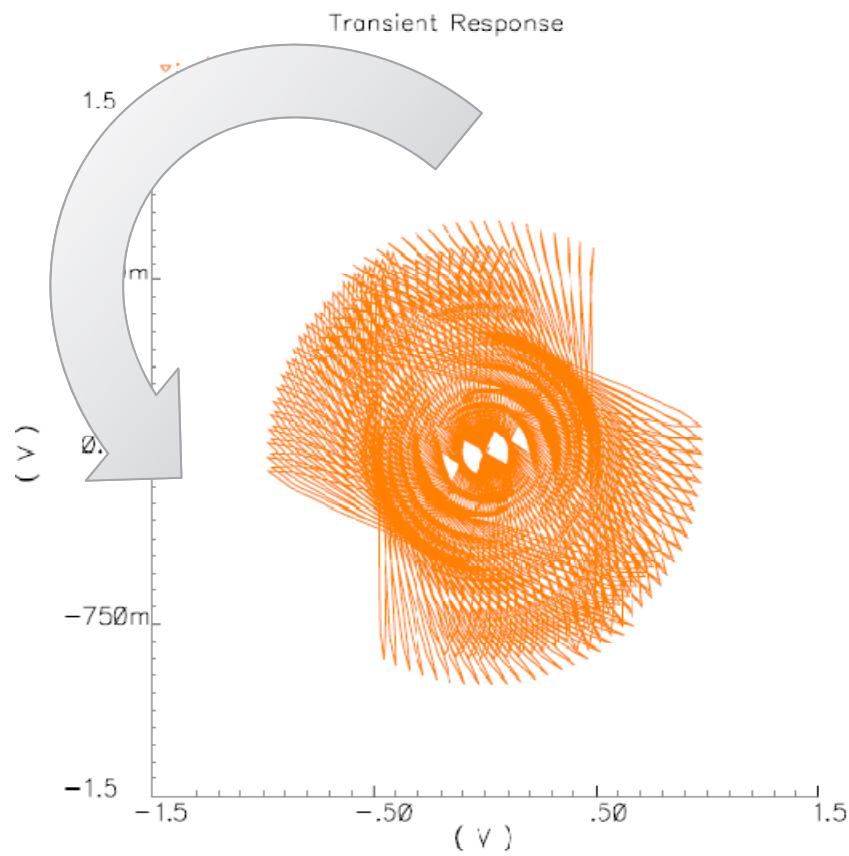
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Simulation PASSED

Example Waveforms Flo > Frf



Lissajou plot $F_{lo} < F_{rf}$



Summary

- Passband model is conceptually simpler:
 - Single real value sampled at 8-20x RF carrier
 - Mixer is simple multiplication with approx sinusoid Quad LO signal.
 - followed by 3rd or 4th order discrete time IIR filter.
- This model is approx 100x faster in simulation than Passband model
- Inserting RF signal path in chip-chip simulations is only 2-3x longer run times vs all digital signal path (with DAC->ADC channel model)
 - This Run time is acceptable given ability to check FULL functionality of Radio control and data interfaces.