



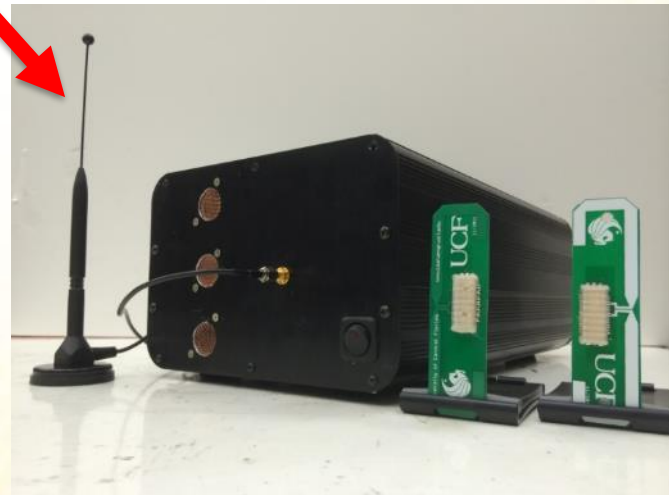
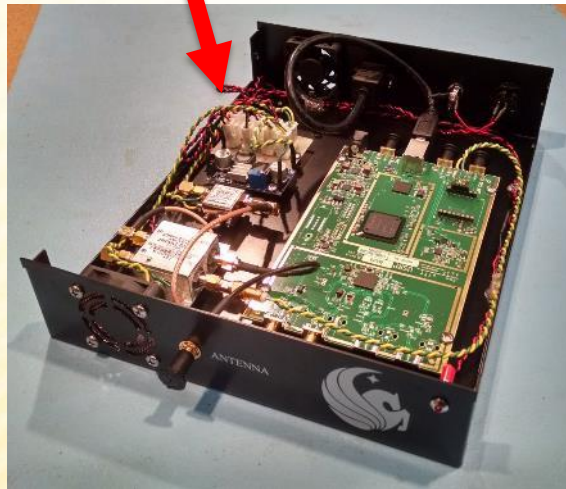
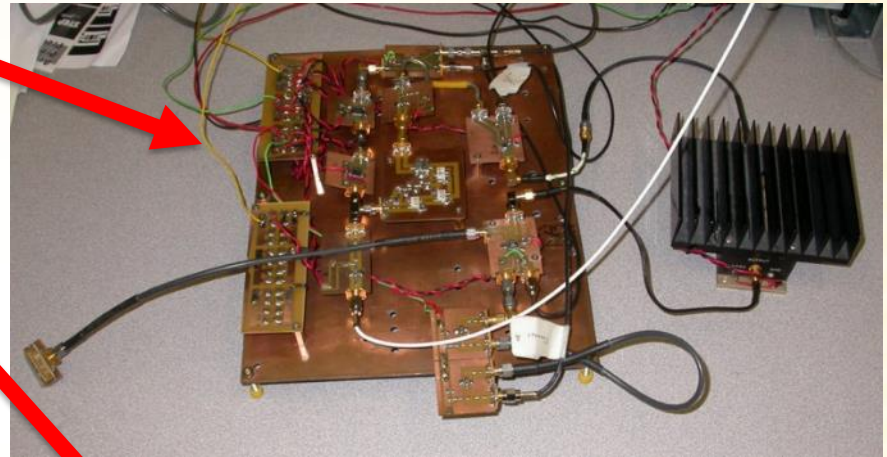
Software Defined Radio Approach for Passive, Wireless RFID Sensors

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PWS-4B: Passive Wireless SAW and RFID Sensors

UCF Interrogation System History

- 250 MHz Prototypes (2008-2009)
- 915MHz Pulsed (2011)
- 915MHz Noise Coherent (2012-2014)
- 915MHz Software Radio (2015)

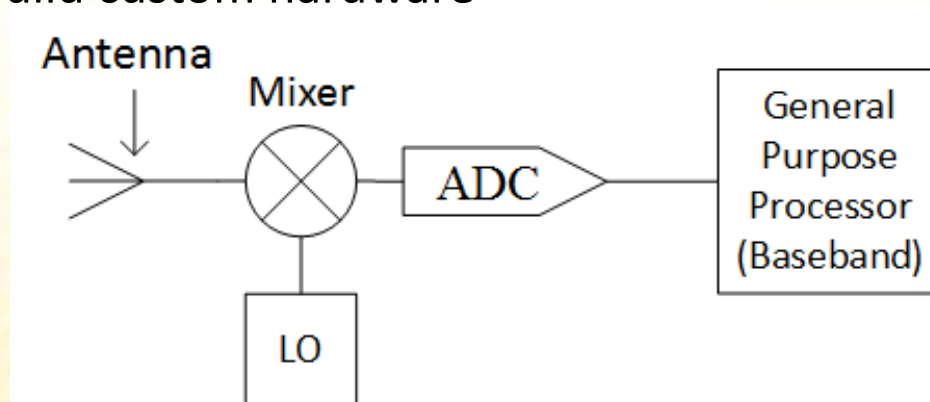


Why SDR for Passive RFID Sensing?

- ‘Universal’ software radio platforms – theoretically can be used for any application
 - Common platform for every application
 - Rapidly adapt in research environment
- Performance improvements delivered via software/firmware updates (FPGA or Software)
- Low-Cost
 - Reduce time to build and assemble interrogator unit (Time and Effort)
 - SDR platforms fabricated in high volume by external company, greatly reduce hardware cost

Software Radio - Intro

- Implement typical radio hardware functions in software (Processing on Host Computer)
 - Filters, Modulators/Demodulators, Detectors, etc.
- Single Radio -> Many Applications (Universal)
 - Communication, RADAR, ADS-B, etc.
- Commercial off-the-shelf Hardware
 - HackRF, bladeRF, USRP, sound-cards, etc.
 - No need to build custom hardware

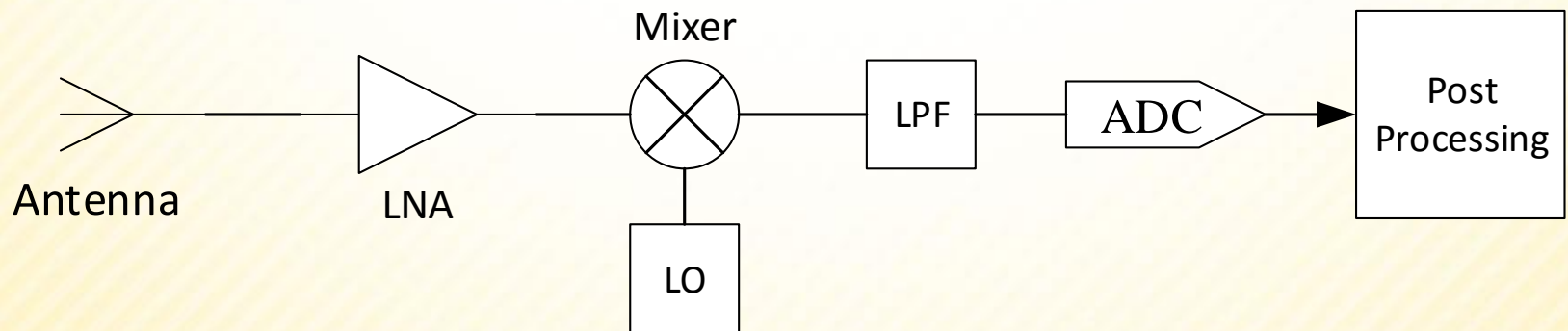


SDR Operation

- Baseband Processing
 - Transmit – Baseband \rightarrow RF (Up Conversion)
 - Receive – RF \rightarrow Baseband (Down Conversion)
 - Typically Zero IF (**Direct Conversion Transceiver**)
 - Signal processing accomplished on general purpose processor (PC) or FPGA, not special hardware or circuit
 - **In-Phase (I) and Quadrature (Q) sampling**
 - No ambiguity for positive/negative frequency ($\cos(x) = \cos(-x)$)
 - Can implement any arbitrary waveform/modulation scheme
 - BPSK, QPSK, OOK, FM, AM, etc

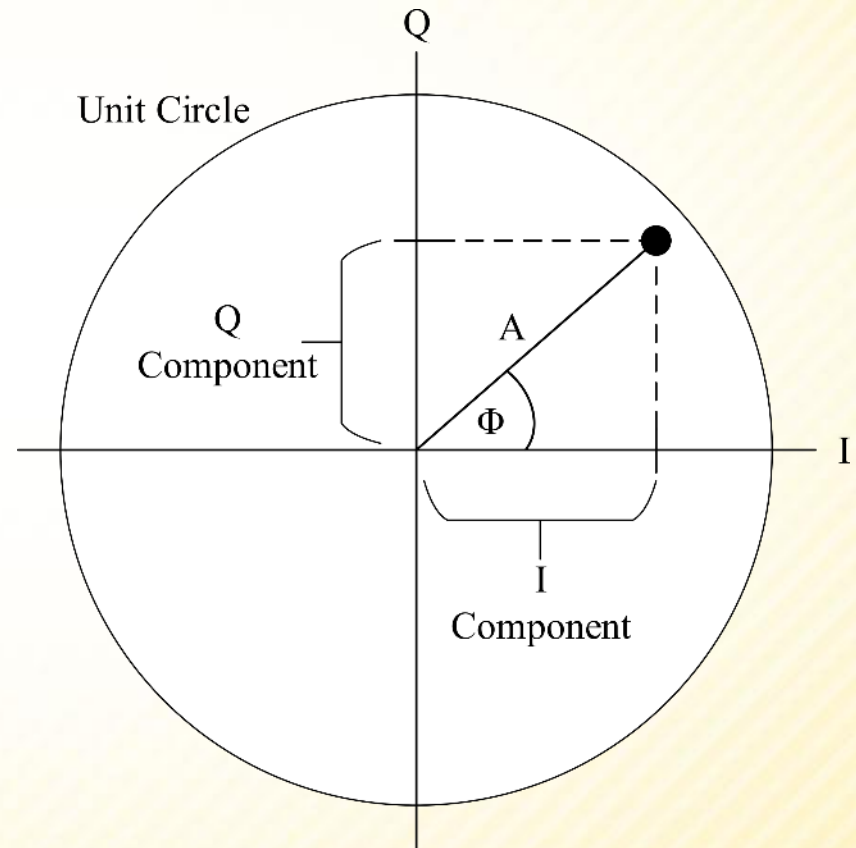
Direct Conversion Architecture

- Translate frequency band of interest to base-band (center frequency is zero)
- Advantages:
 - No image reject circuitry, No IF Stage, Simple!
- Disadvantages:
 - Requires complex calibration for: DC offset, I/Q imbalance, LO leakage
 - Non-Linear distortion will mix into bandwidth of interest



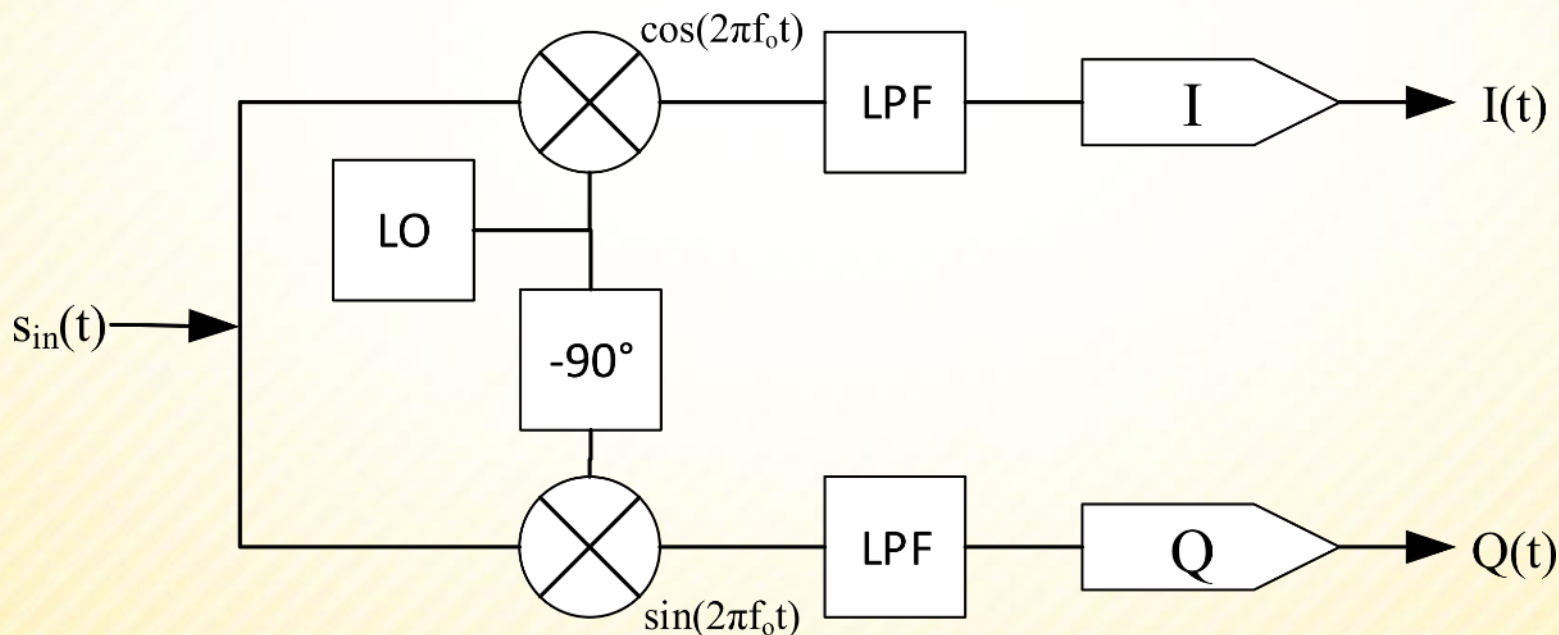
Direct Conversion – I/Q

- Need a way to generate In-Phase (I, 'Real') and Quadrature (Q, 'Imag') signal components
 - 90° out of phase
- Form phase vector
 - Remove ambiguity in +,- freq
 - Direct conversion is centered at zero!
- Complex waveforms/modulation
 - QPSK, QAM, etc
- How to do this with hardware?



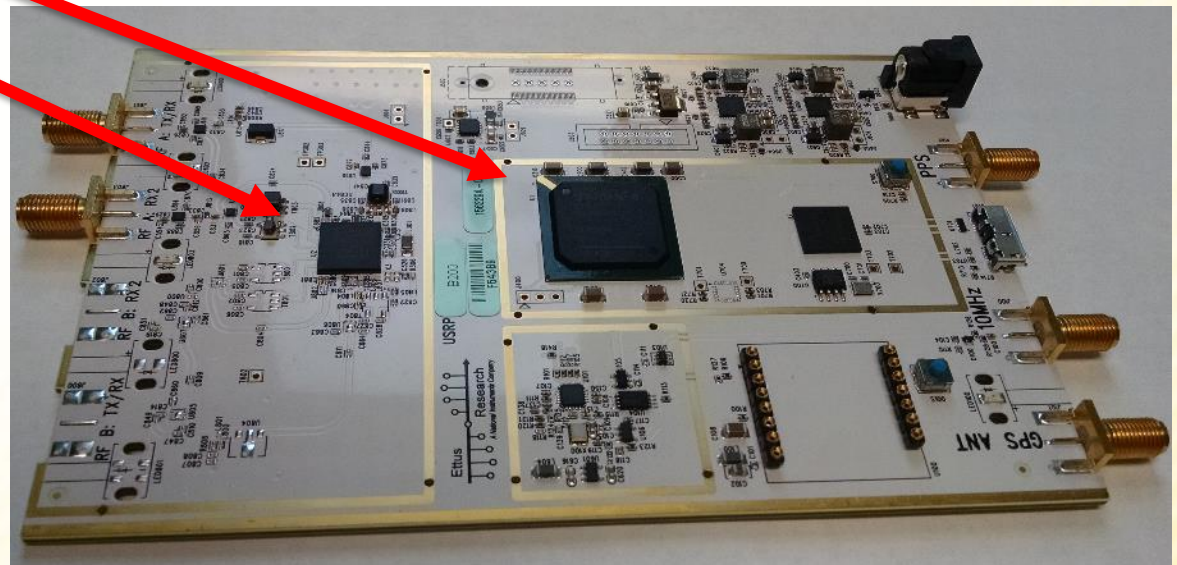
Direct Conversion – RX Chain

- Receiver has two receive paths
- Signal components are decomposed from input with LO
 - One cosine, One sine
- Transmit is just the opposite

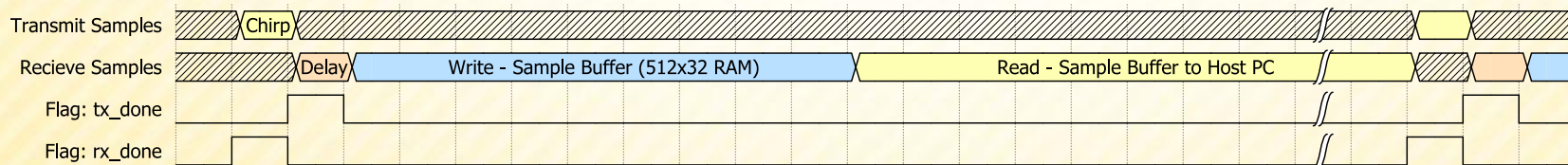
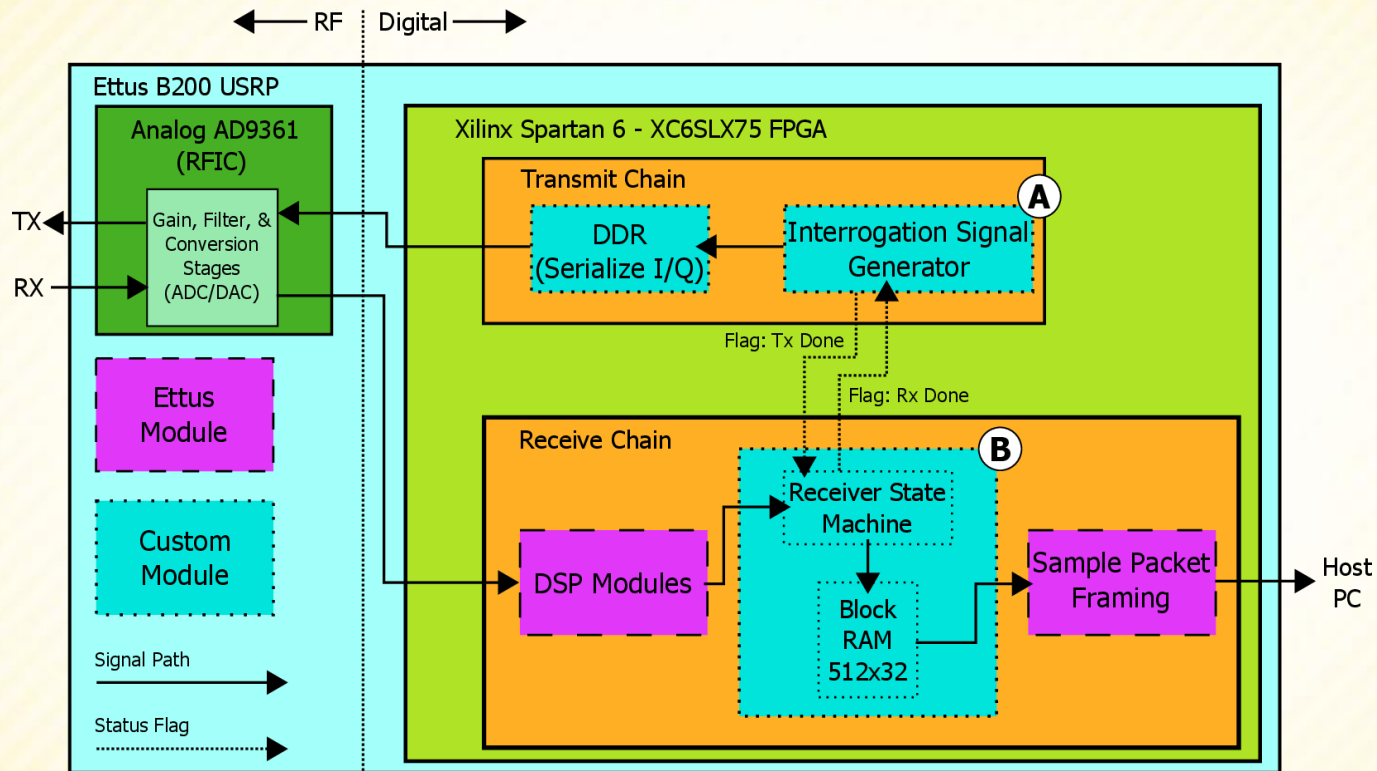


USRP B200

- Fully Integrated SDR (15 x 10 cm)
- Bandwidth: 56MHz (Max), USB 3.0
- RF Coverage: 70MHz – 6GHz
- Xilinx Spartan 6 FPGA
- Analog AD9361 RFIC
- Built in I/Q cal. routines



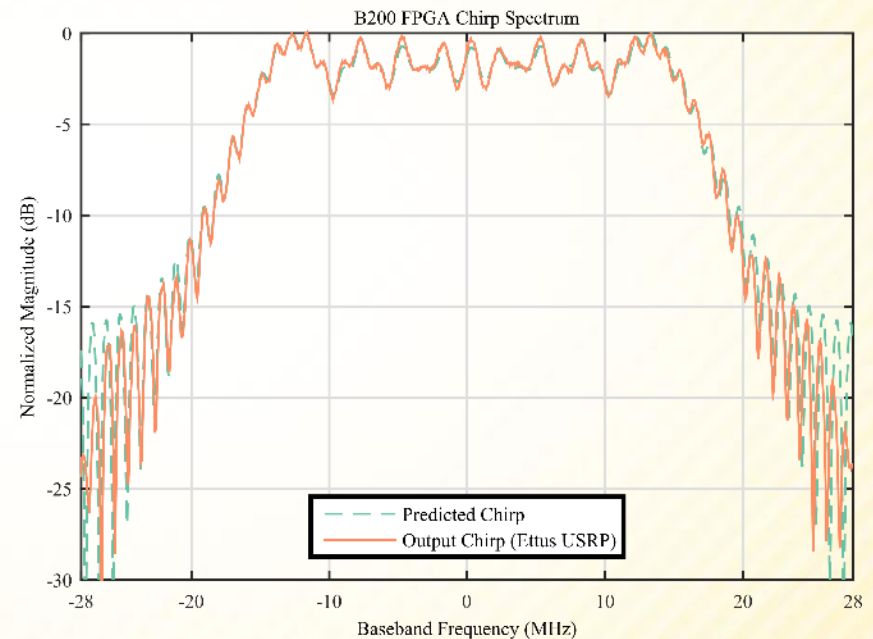
FPGA Block Diagram



Transmit – Pulsed Chirp

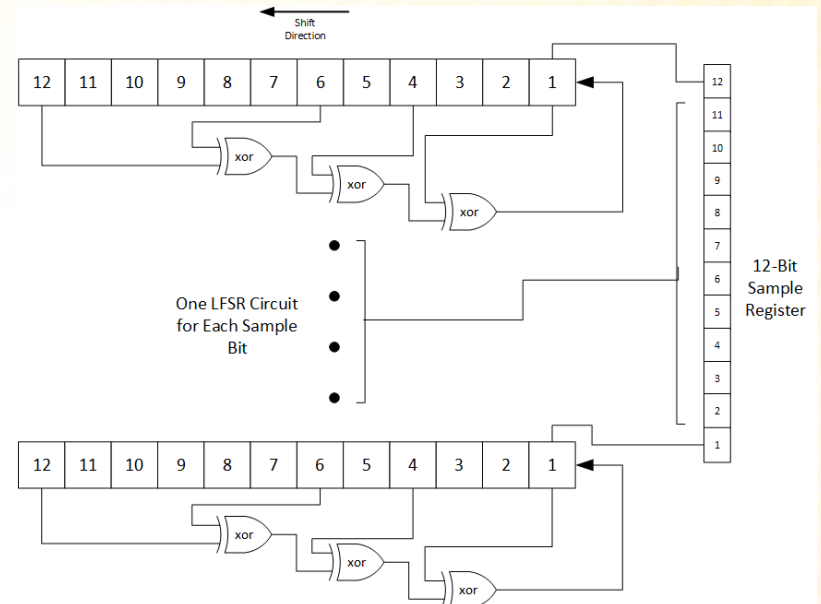
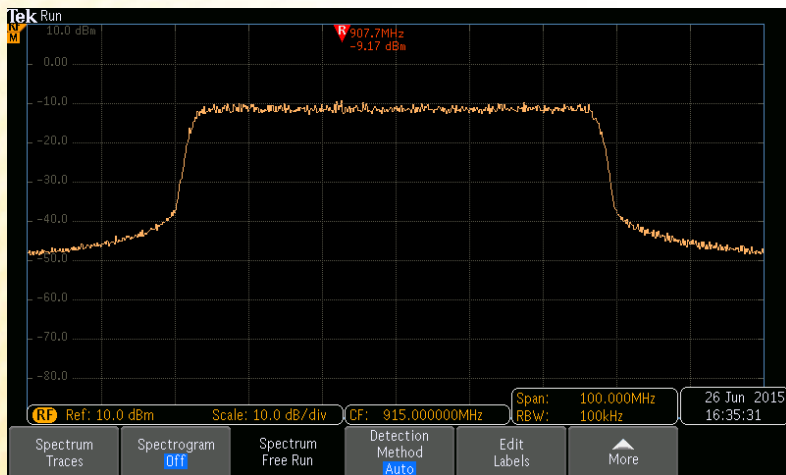
- Linear FM Sweep (Chirp)
- Time Length: $1\mu\text{s}$
- Bandwidth: 35 MHz
- Samples Pre-Calculated and Hard Coded on FPGA
 - Interrogation signal always the same
 - Matlab script to generate Verilog

- Frequency (Predicted vs USRP)



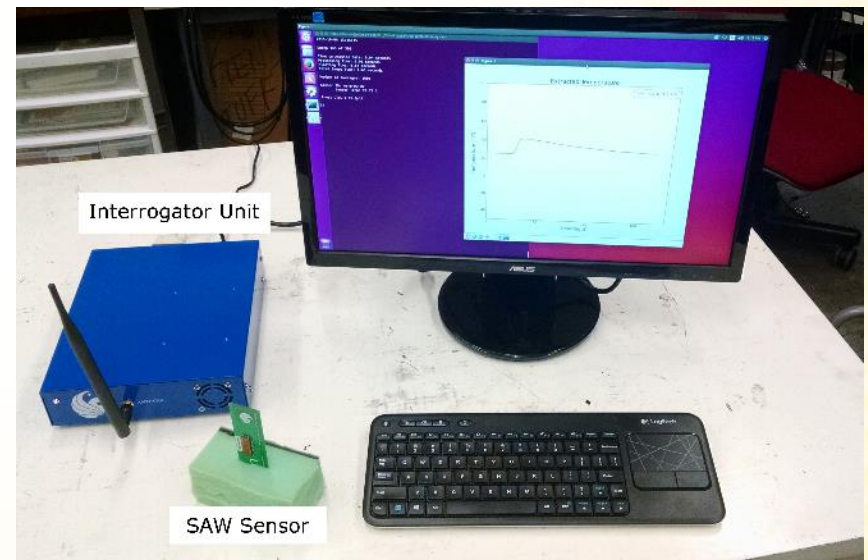
Transmit Pulse – Noise

- Linear feedback shift register (LFSR) Network
 - Generates pseudo-random bits
 - Each LFSR seeded with different random value
- 1 μ s noise pulse

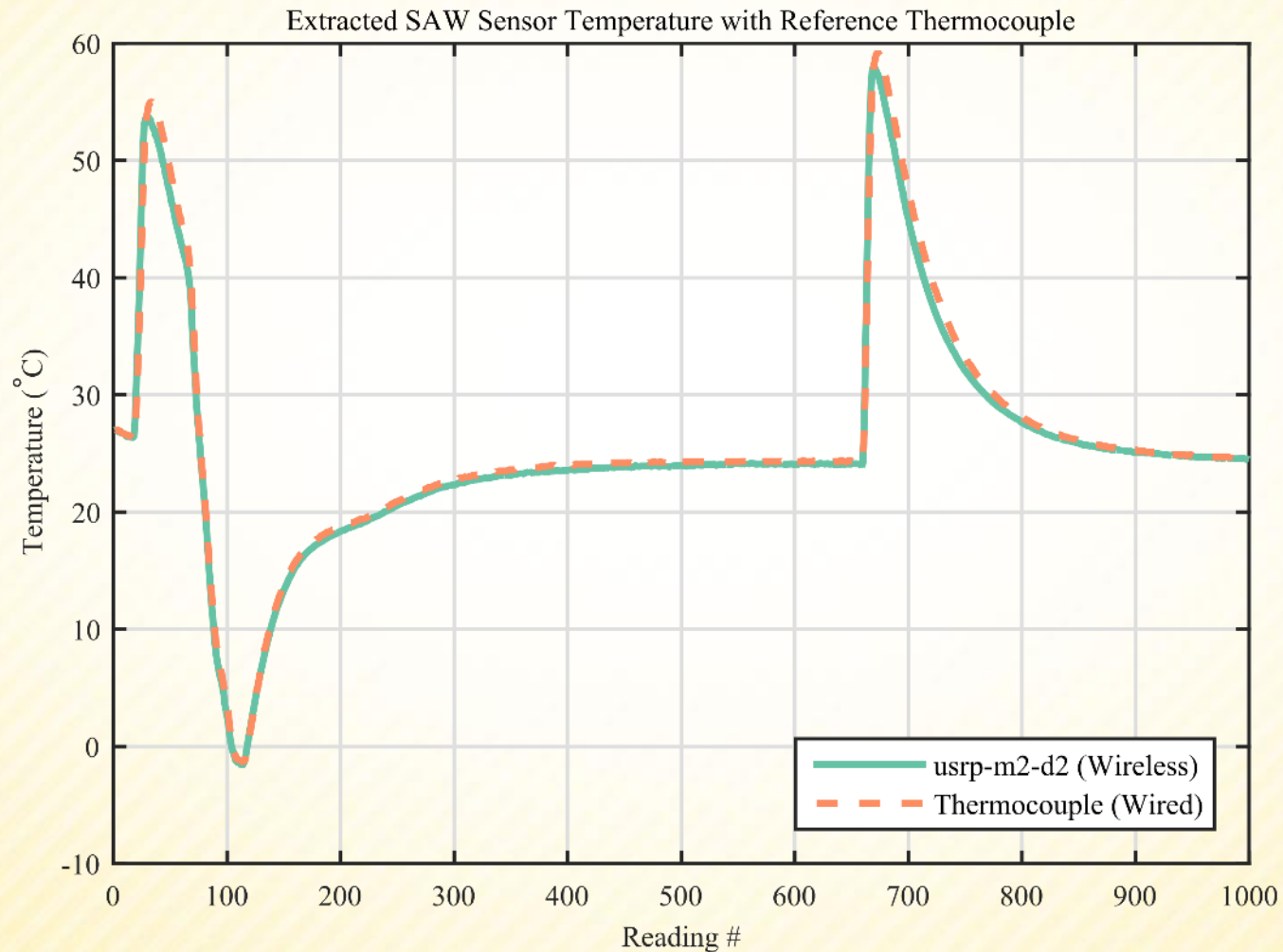


USRP SAW Sensor Interrogation Systems

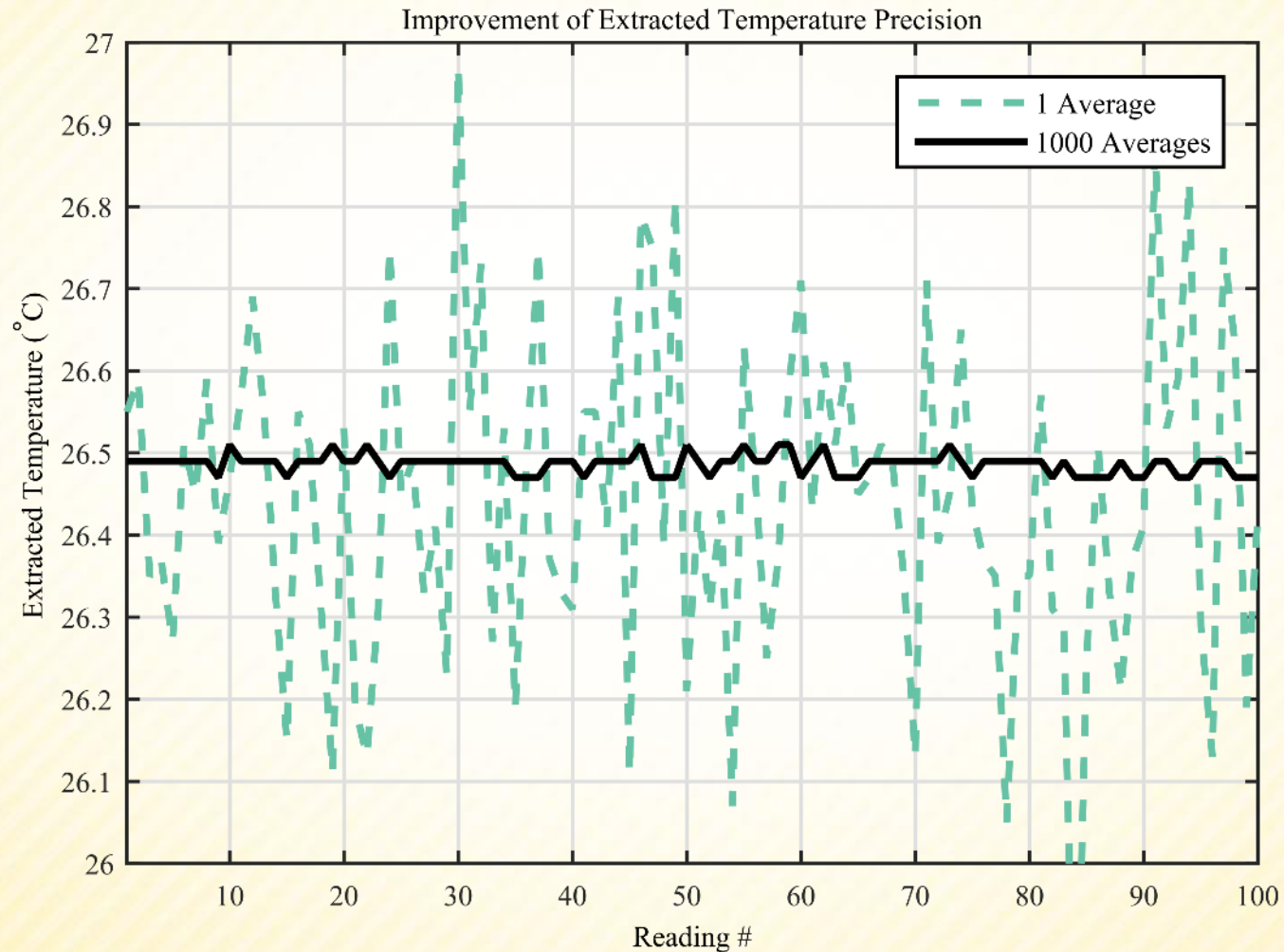
- Integrated into Custom Enclosures
 - 10"x8"x2" (25x20x5cm)
 - 2-3 lbs (~1kg)
- Two Embodiments Developed
 - USRP w/ External Host CPU
 - USRP w/ Embedded Host CPU
- Output Power: > +20dBm
- Range: Up to 7m Tested
 - Use higher gain antenna
- Reading Time:
 - 1 Average: ~70ms
 - 1000 Average: ~400ms
- Component Cost: <\$1500



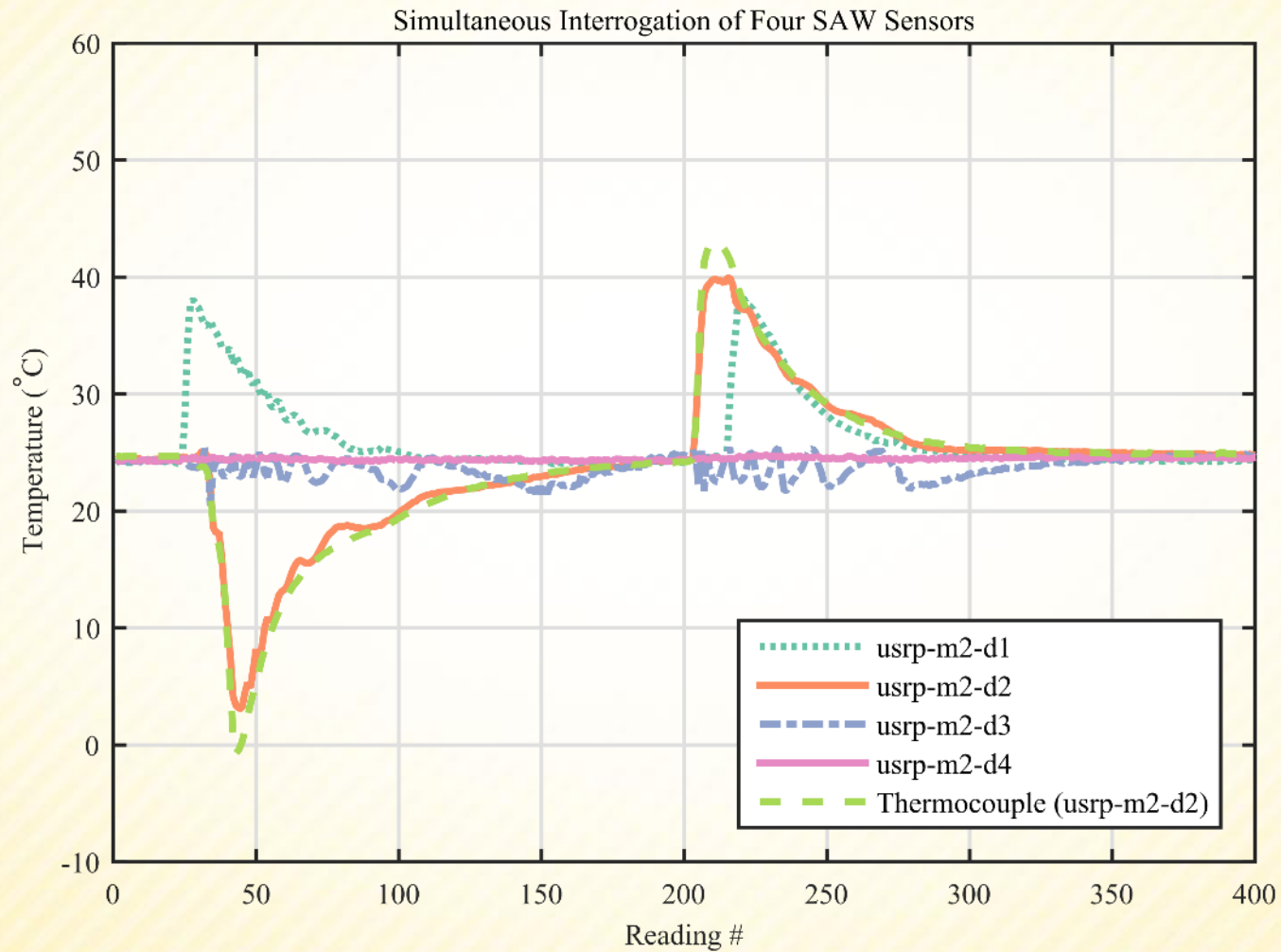
Single Sensor Temperature Run



Averaging Multiple Sweeps



SDR w/ Temperature Sensors



Application Specific Customizations

- Center Frequency
 - SDR can return for different sensor frequency, no modifications
- Custom UI
 - Based on application and need
- Headless Operation
 - Not every application will use a monitor or have operator
 - Monitor remote locations, etc.
- Antennas
 - Flexible, smaller
- Enclosure
 - Customize for integration into other application
- Output power, bandwidth, and other programmable specs

Possible Other Use Modes

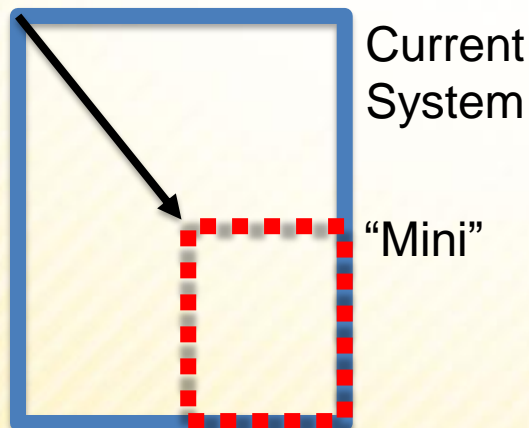
- Sensor Array Frequency Hopping
 - All sensors don't have to use the same center frequency or bandwidth
 - Reuse discrete time slots -> Greatly increase number of sensors
- Networked SDR Architecture
 - Small, zoned interrogators over large/compartmentalized areas
- SAW Sensor Interrogator + Wireless Data Link
 - SDR can reconfigure to relay SAW sensor data to centralized data collection
- Any other ideas?

Current Work

- Adding support for different SAW sensor embodiments
 - Temperature (Demonstrated), Strain, & Gas (Hydrogen, Methane and Other)
- Enhanced User Interface
 - Better facilitate testing
- Enhanced System Integration
 - Light and Rugged (And small!)
- Improved reading accuracy/precision and speed
 - Currently ~70ms per reading with Desktop host PC, aiming for 1ms
 - Off-load more tasks to FPGA!
- Real time statistics for sensors
- What are other needs?

Upcoming SDR Implementation

- Integrate B200mini into design
 - Greatly reduced footprint (3.3"x2")
 - Same performance as B200
- Improved System Integration
 - Cables take up the most space!
 - External components merged into custom PCB (Stackable add-on card for B200mini)



Conclusion

- Commercial-off-the-shelf SDR units can be purposed for interrogating passive, wireless SAW sensors
- Pulsed mode interrogator prototype demonstrated with the USRP B200
 - Chirp and Noise Interrogation Signals
 - Coherent Averaging of Multiple Sensor Responses
 - 915MHz Operation, 4 sensors interrogated simultaneously
- SDR is highly reconfigurable and can meet a wide variety of application needs with wireless SAW sensors

Funding Sources

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 - Wireless, Passive Strain Sensor for Space Applications
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