

Passive Wireless Vibration Sensing for Measuring Aerospace Structural Flutter

W. (Cy) Wilson & Jason P. Moore
NASA Langley Research Center

IEEE Wireless for Space and Extreme Environments
(WISEE 2017)

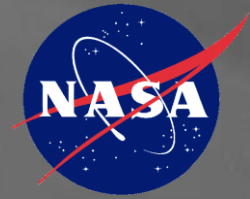
Passive Wireless Sensor Technology Workshop

Oct. 10-12, 2017

Montreal, Quebec, Canada



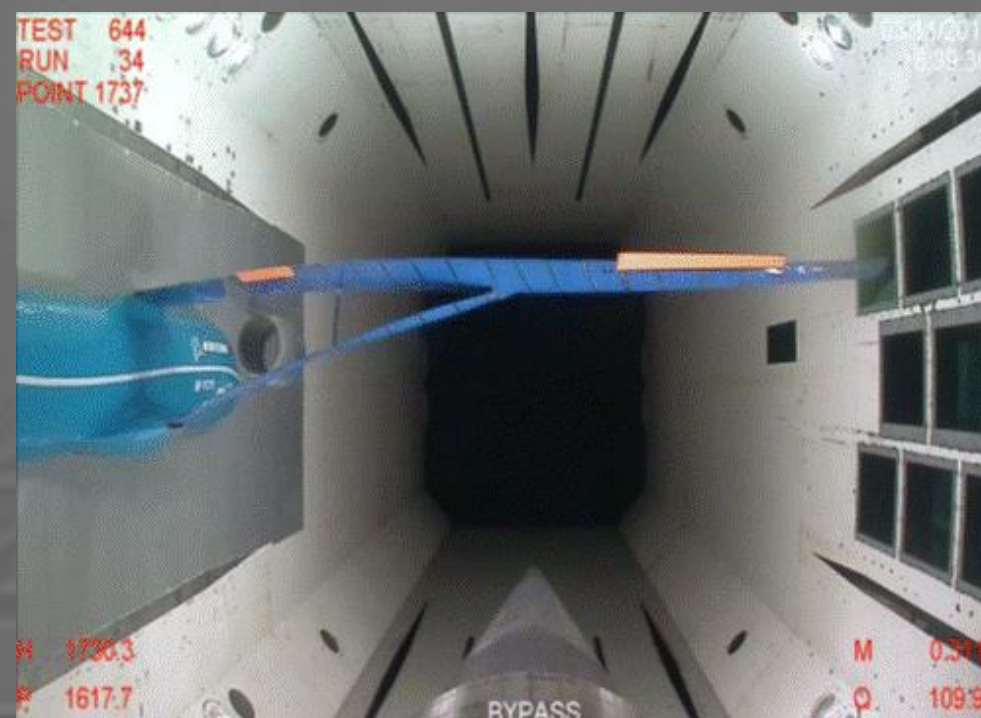
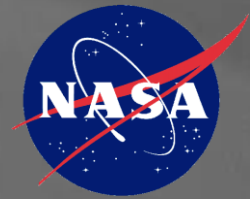
Outline



- **Motivation**
- **Previous SAW Sensor Work**
- **SAW Results**
- **Microwave Experimental Setup**
- **Results**
- **Conclusions**
- **Funding/Partnership Opportunities**



Motivation



The Advanced Air Transport Technology (AATT) Project is investigating flutter effects in aeroelastic wings.

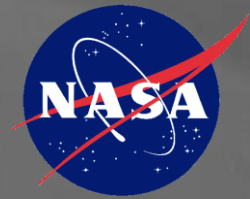
A subprogram, the Subsonic Ultra-Green Aircraft Research (SUGAR), is examining the aeroelasticity of high aspect ratio truss-braced wings, which could reduce aircraft fuel consumption by 5~10%.

NASA is also investigating the behavior of light-weight flexible aircraft structures using the X-56 Multi-Utility Technology Testbed (MUTT) an unmanned aircraft system

- Two center-bodies
- Four sets of interchangeable wings of varying aeroelasticity.



Motivation

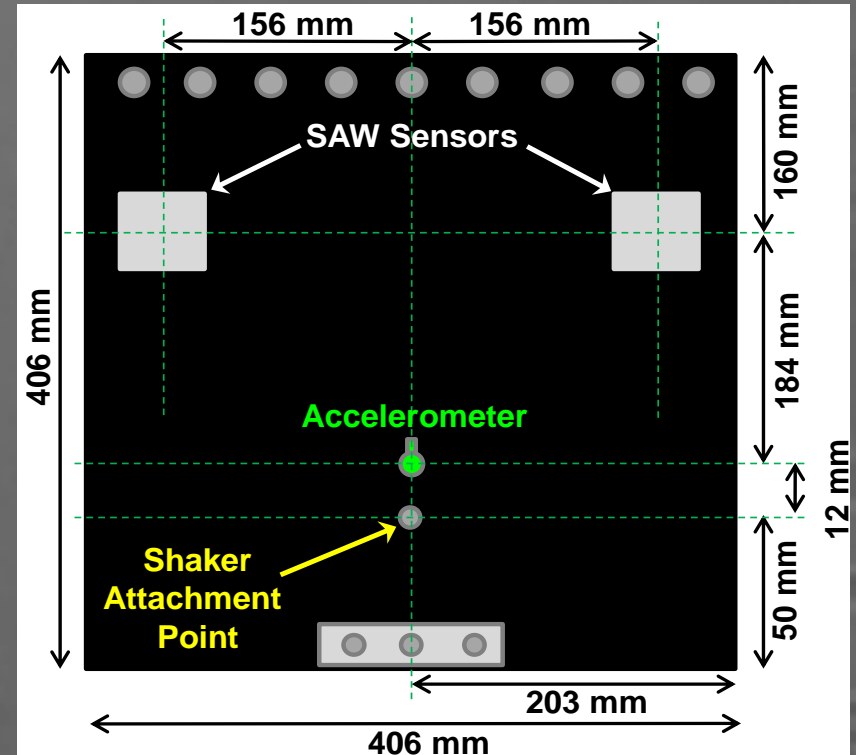
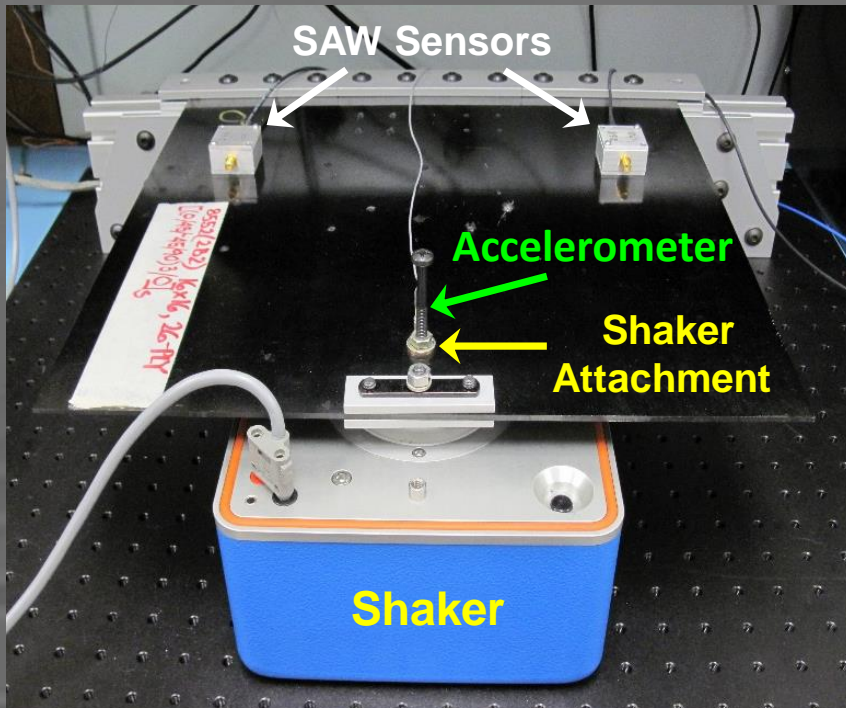
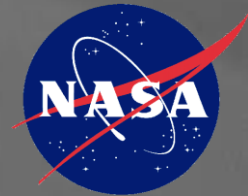


- Helios high altitude long duration aircraft.





CFRP Panel



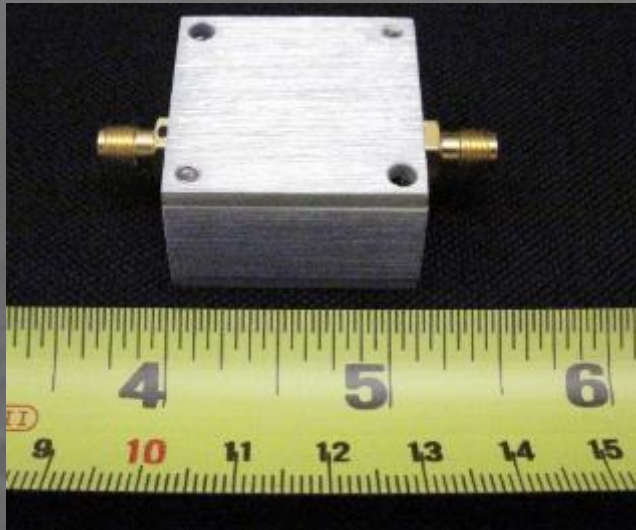
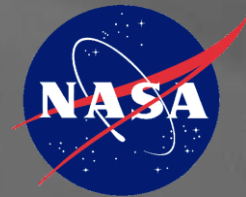
The SAW and accelerometer are mounted on top of the panel. The shaker is located at the free end of the cantilever underneath the panel.

A diagram showing the location and distances of the sensors and the shaker attachment location.

Carbon fiber–reinforced polymer (CFRP) composite panel is 2.78 mm thick and was fabricated at NASA LaRC, it is a laminate of IM7/8552 is quasi-isotropic and is made up of IM7 fibers and 8552 prepreg with a 26 ply layup of $[(0/+45/-45/90)_3 0]_s$.



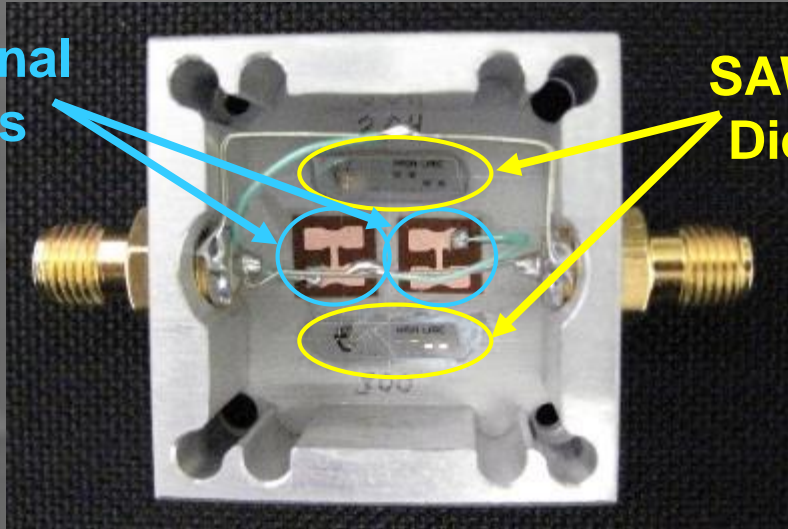
SAW Frequency Division Multiplexed (FDM) Sensor Modules



SAW sensor module
3.81cm x 3.81cm x 1.9cm
(1.5" x 1.5" x 0.75")

Terminal
Pads

SAW
Die

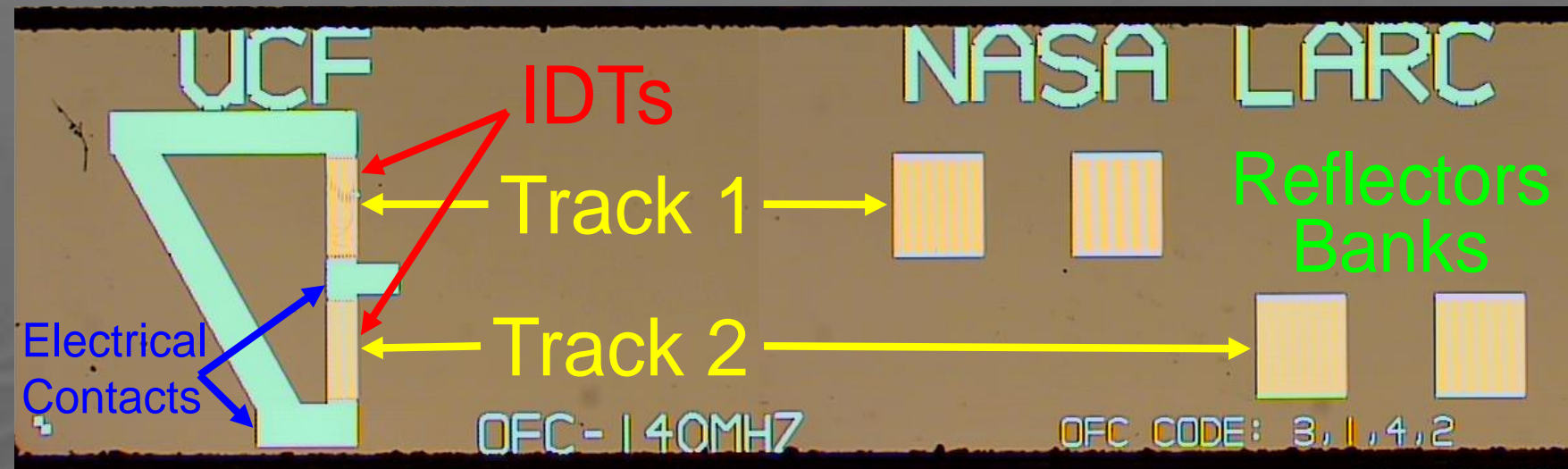


Two SAW die bonded inside, and two SMA connections.

- The prototype FDM system has six SAW sensors (140, 172, 204, 236, 268, 300 MHz) in three modules. 140/236, 172/268, 204/300.
- One SAW sensor is bonded rigidly to the bottom of the package and is used for measuring strain (236, 268, 300)
- The other SAW sensor is bonded with a flexible bonding agent such as RTV that does not transfer strain (140, 172, 204), for measuring environmental effects.



Surface Acoustic Wave Sensor

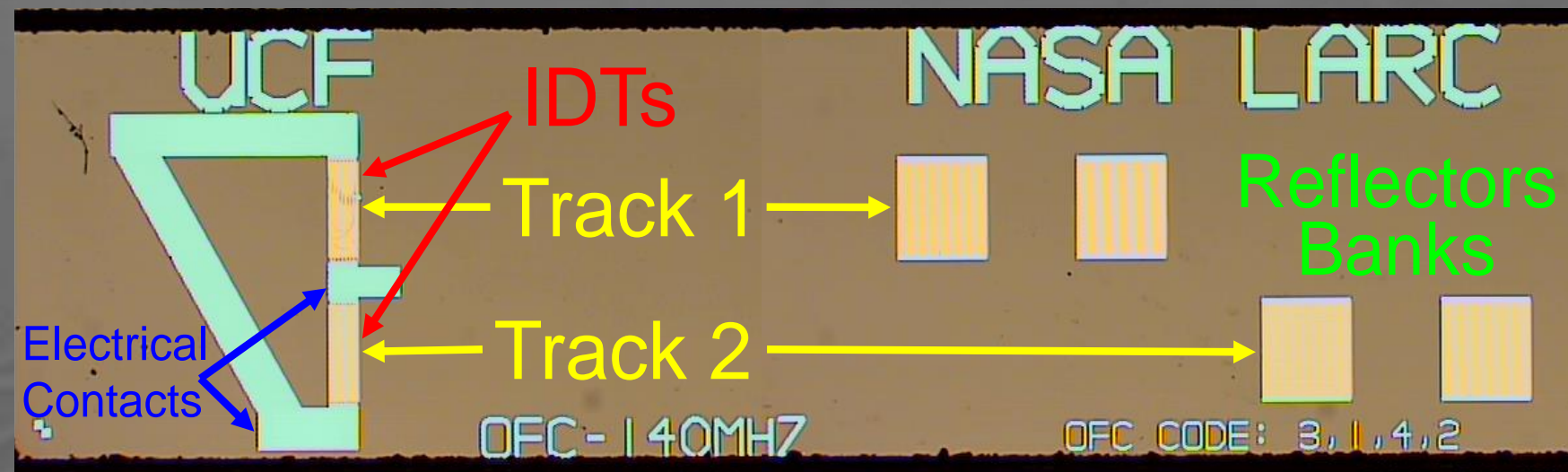
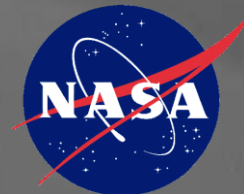


Time response of 140 MHz SAW device

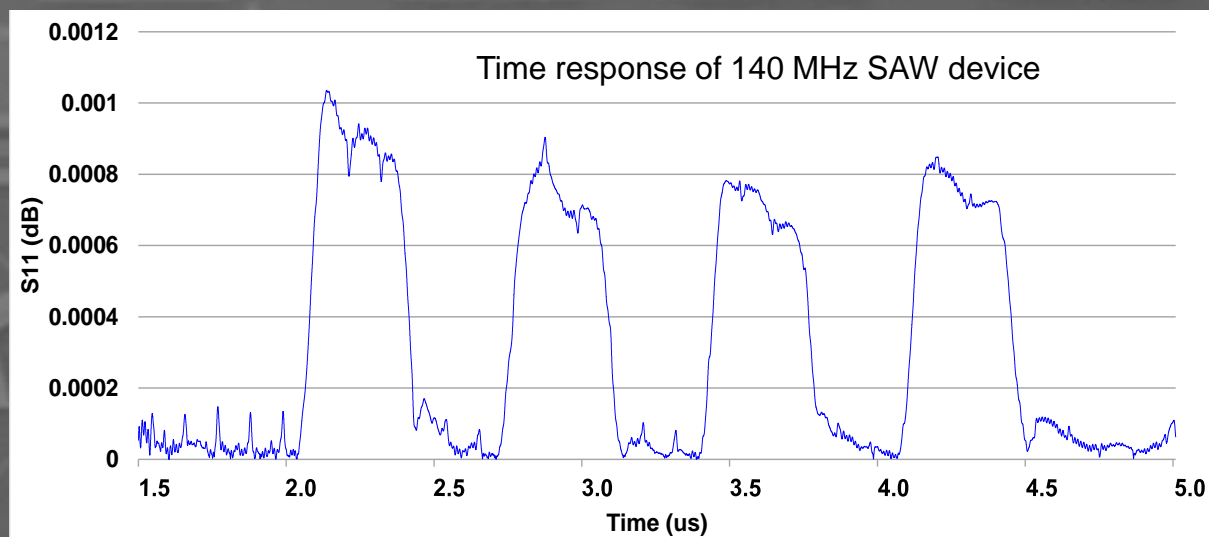
- For this work the 236MHz device was used
- The sensor has four orthogonal frequency coded (OFC) reflector banks in two tracks,
- The IDTs have a wider bandwidth of 15 MHz, while each reflector has a bandwidth of 6MHz.
- The gratings in each track reflect a different frequency with an arrangement of f_3, f_1, f_4, f_2 .
- The reflector center frequencies are $f_1=231.5$, $f_2=234.5$, $f_3=237.5$, $f_4=241.5$ MHz



Surface Acoustic Wave Sensor

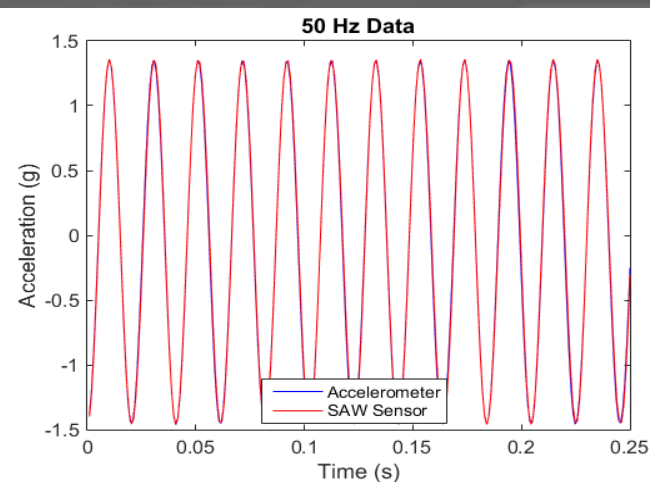
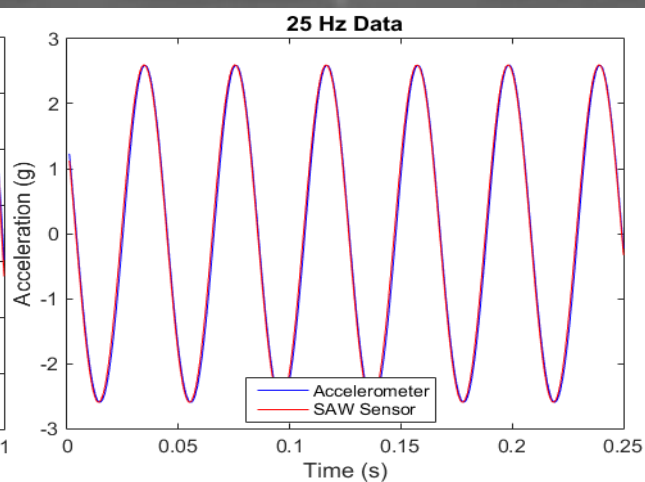
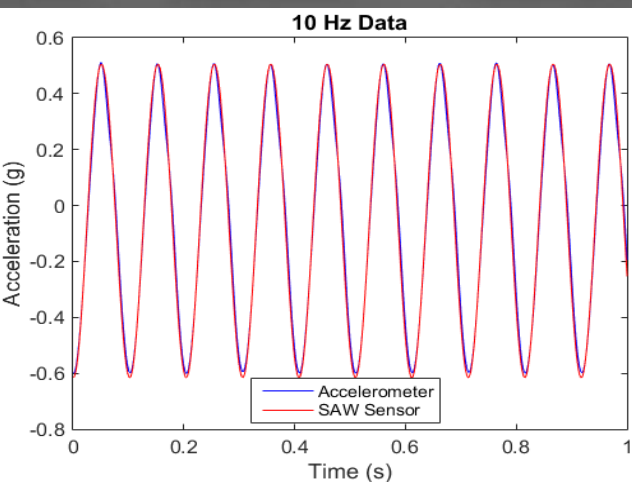
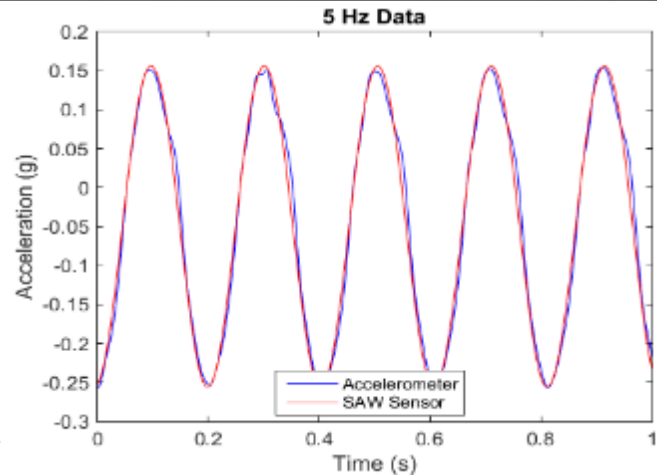
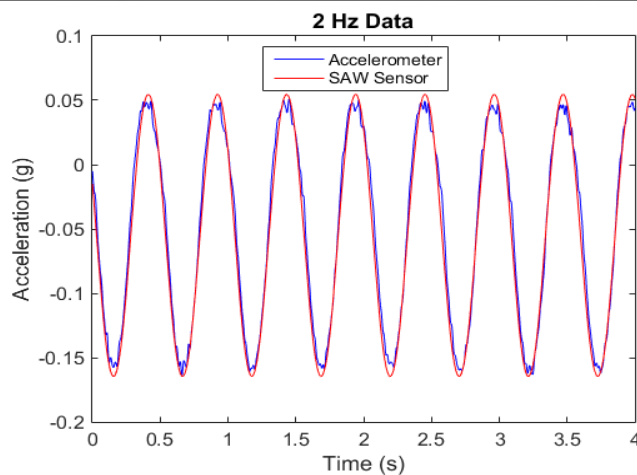
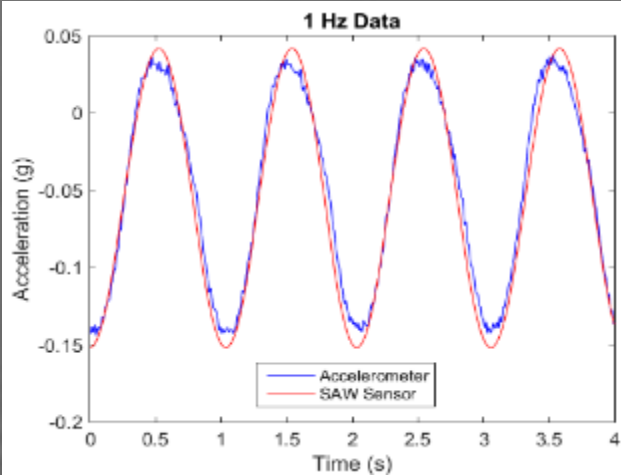
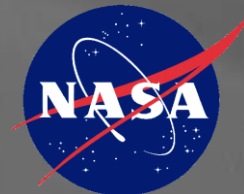


- Time Response for the four gratings.



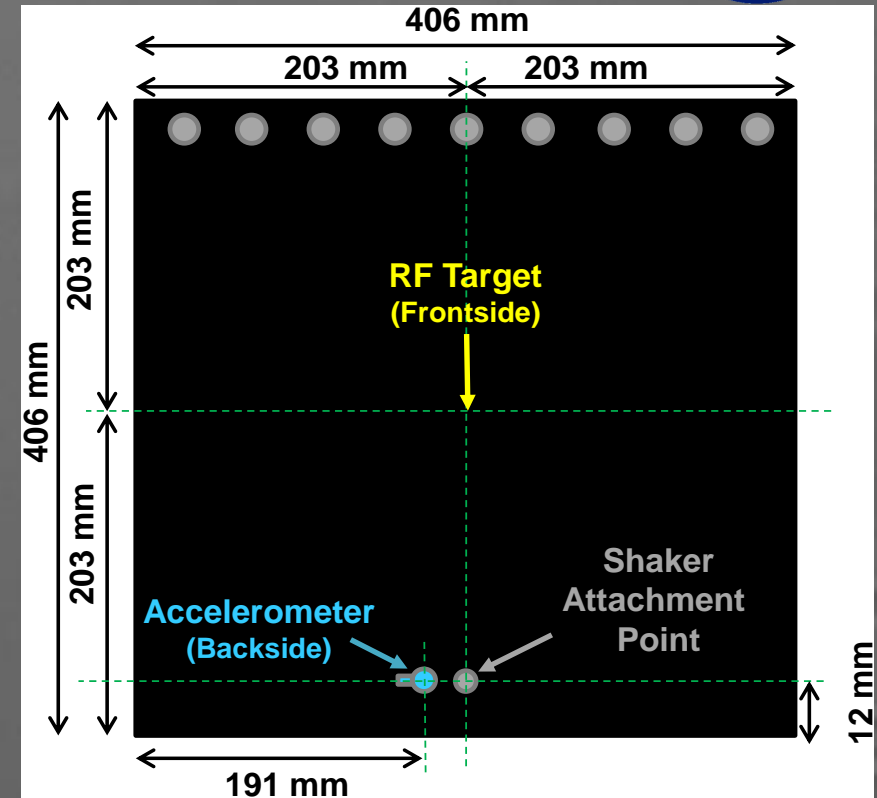
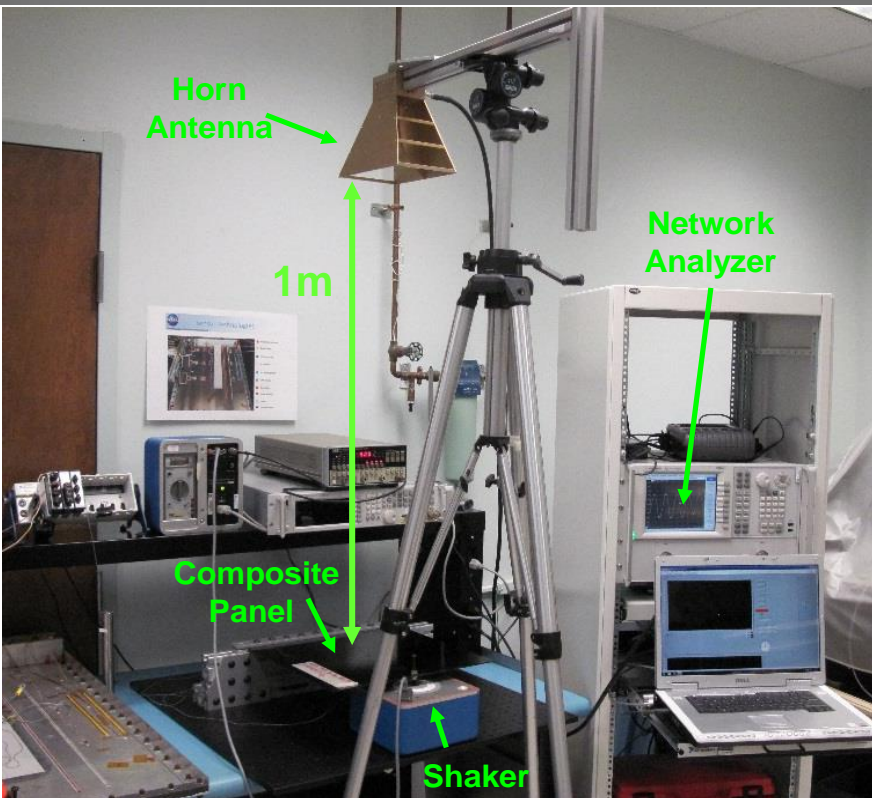
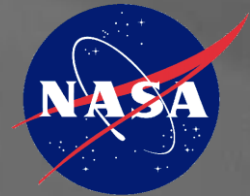


SAW Results





Microwave Test Setup

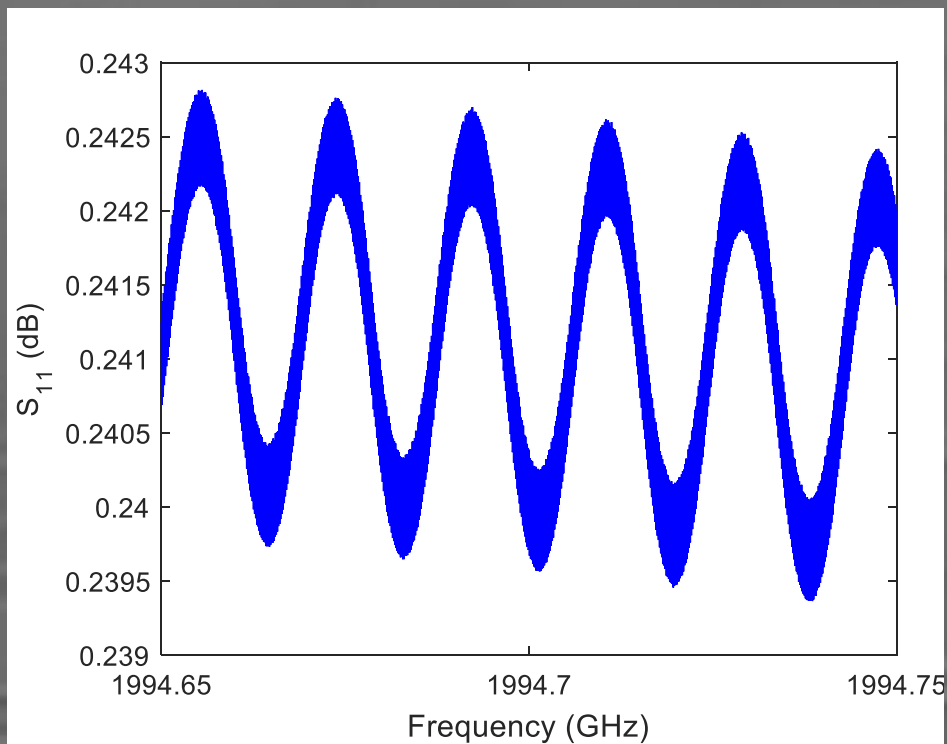
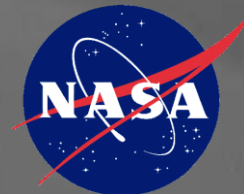


The test setup showing the network analyzer, the horn antenna, the composite test panel, and the shaker.

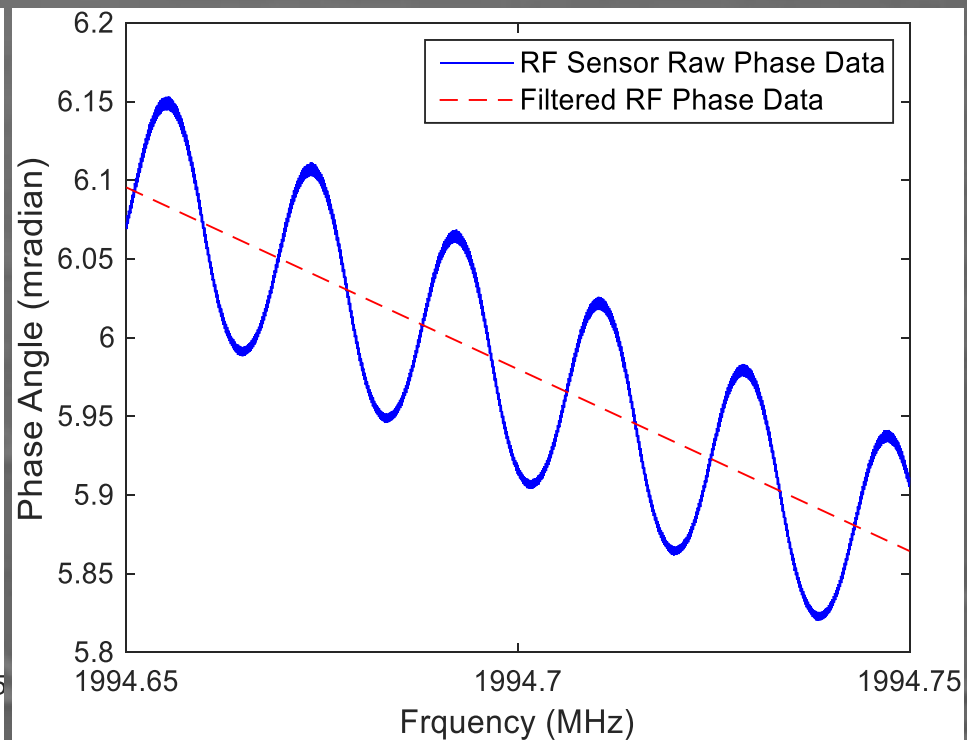
A diagram showing the location and distances of the accelerometer (underside), the RF target area and the shaker attachment location.



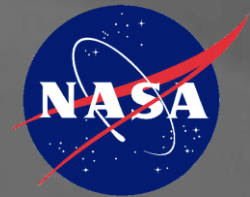
Raw Data



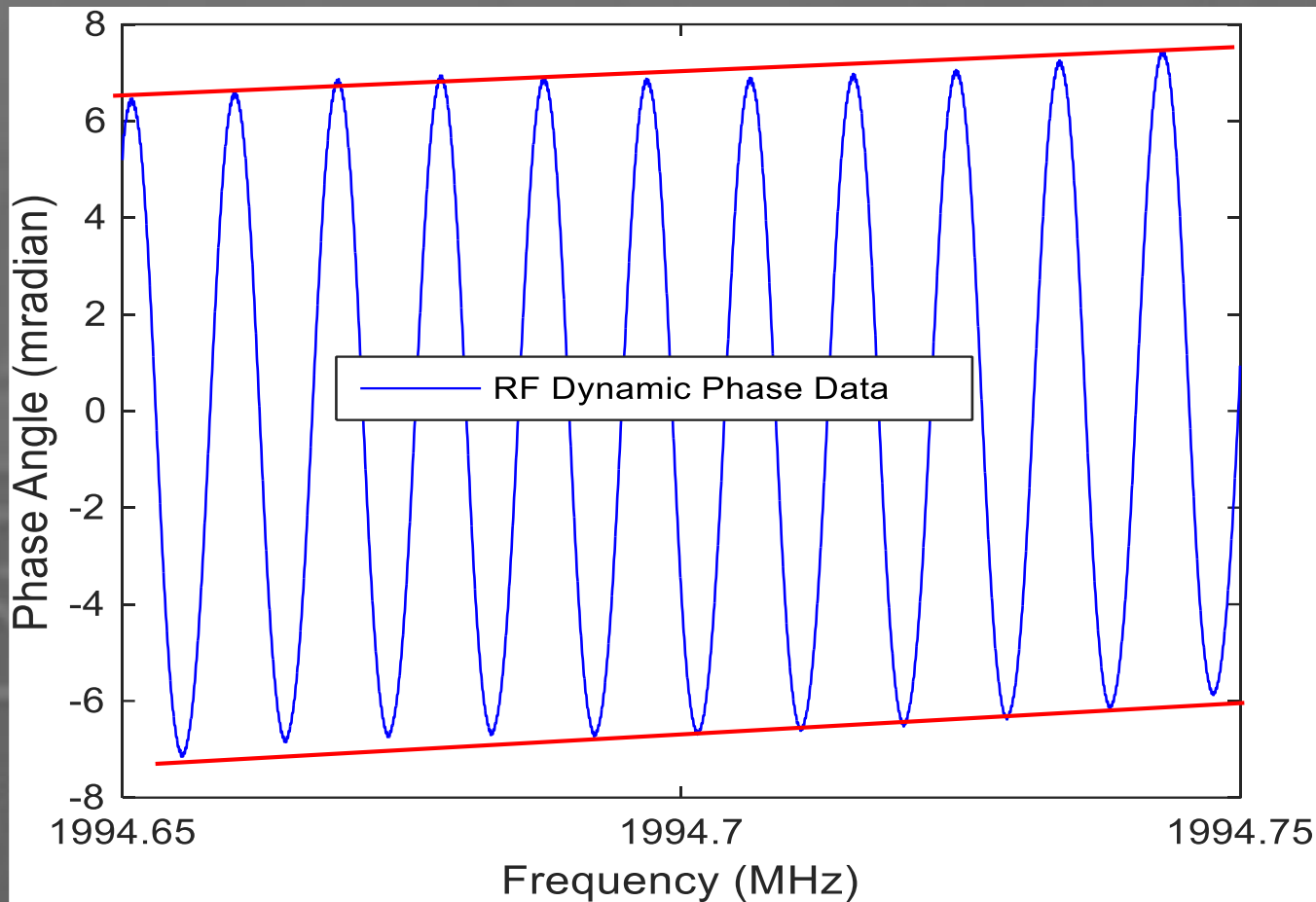
The raw S_{11} data with
a 2 Hz sine wave.



The calculated phase data
with a 2 Hz sine wave.



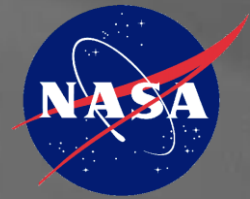
Delta Phase Response



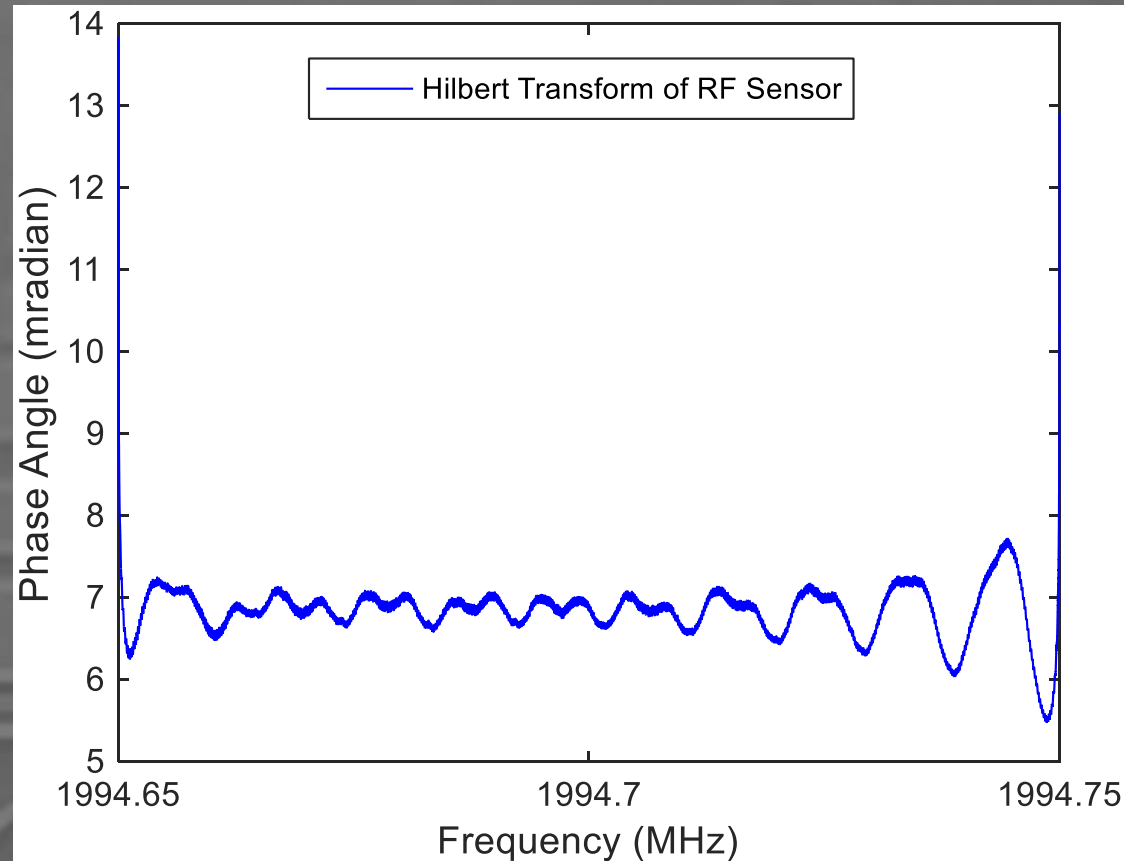
The delta-phase data resulting from subtraction of filtered phase data (in red) from the raw phase data (in blue).



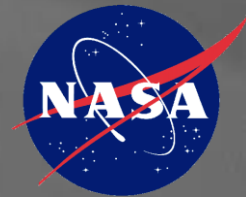
Hilbert Transform of Data



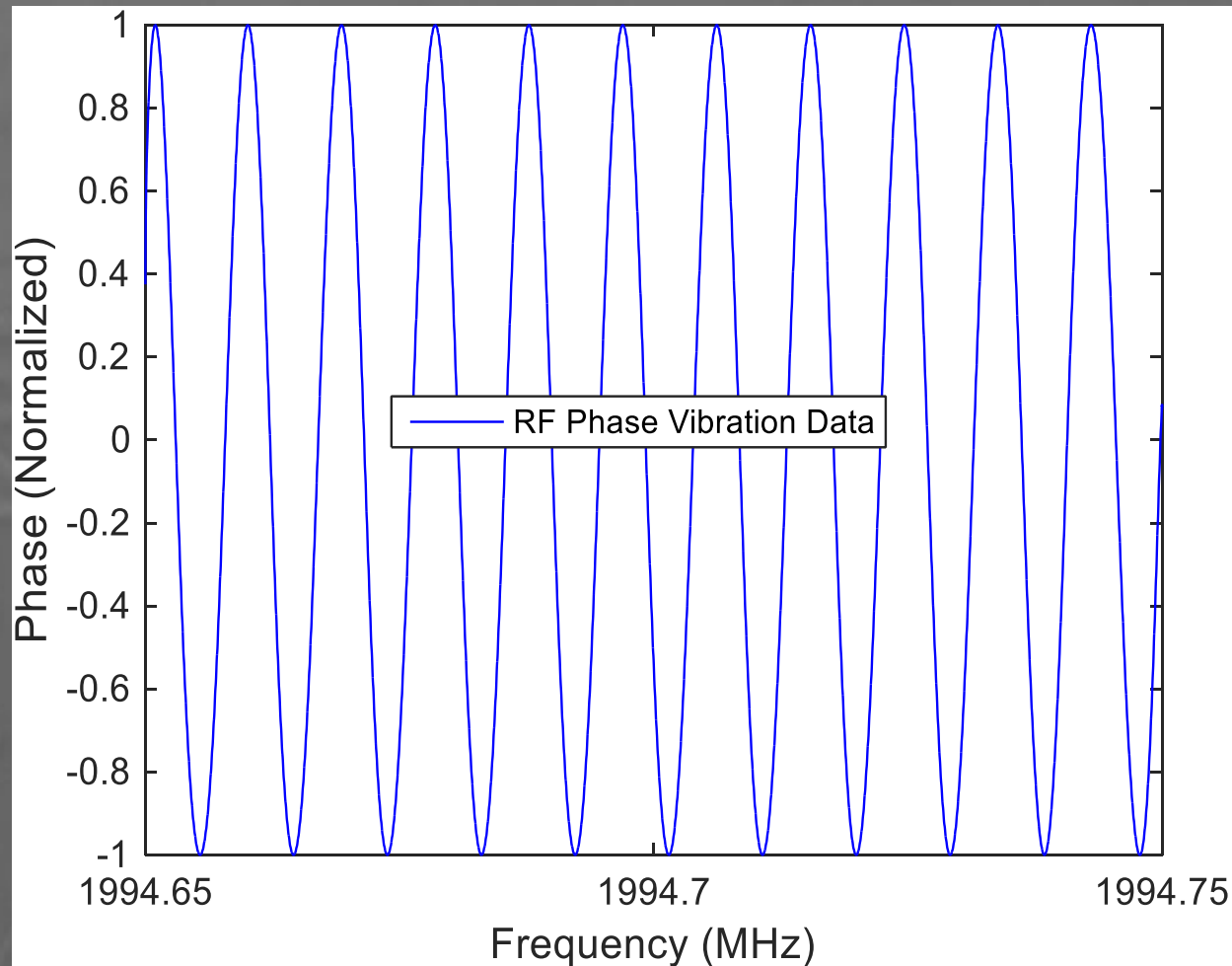
$$H[g(t)] = \frac{1}{\pi} \int_{-\infty}^{\infty} \frac{g(\tau)}{t - \tau} d\tau$$



The absolute value of the Hilbert transform from the filtered delta-phase data



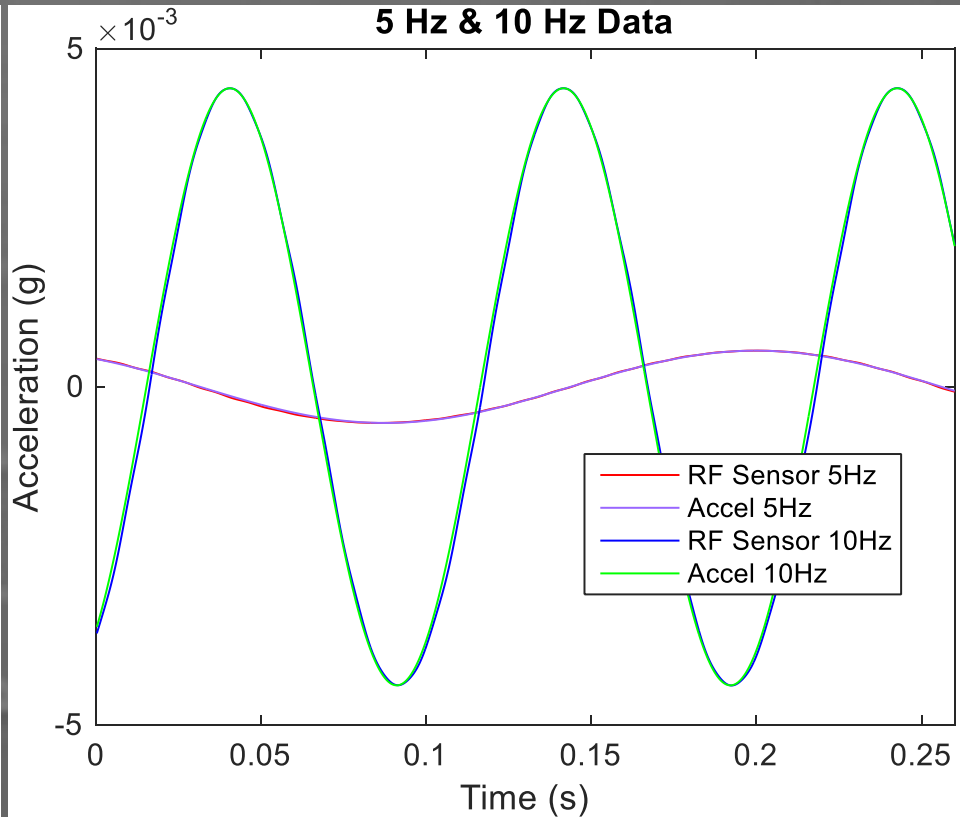
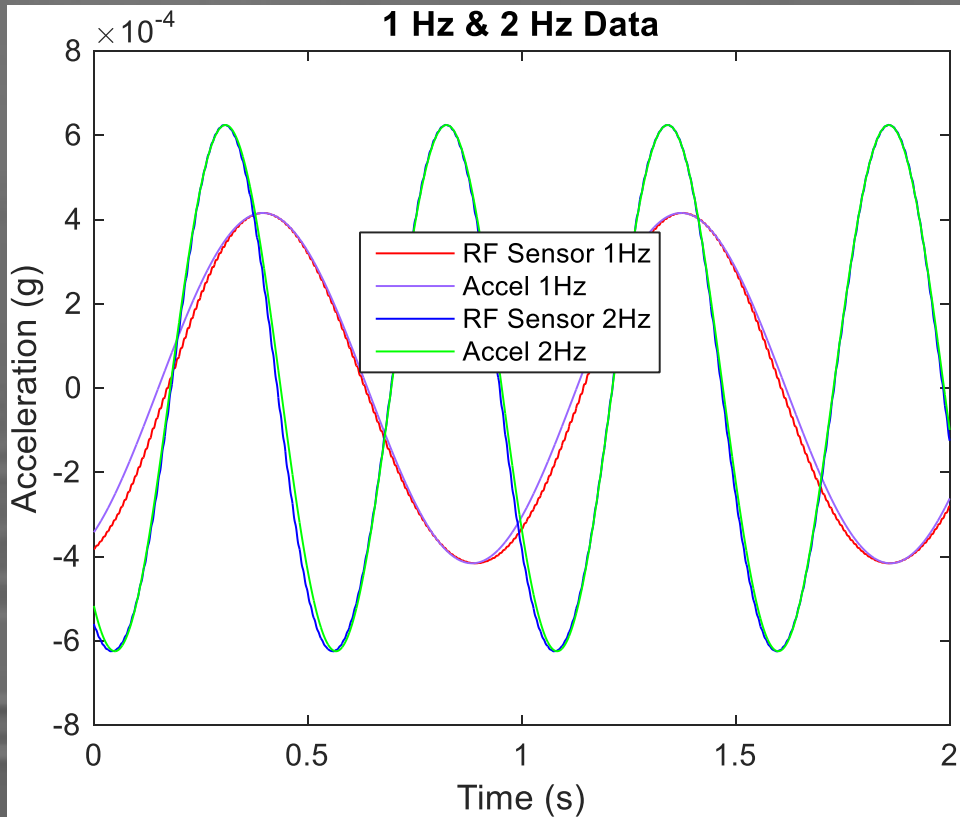
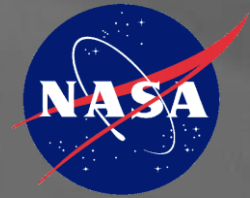
Vibration Data



The vibration data, calculated by dividing the delta-phase data by the analytic signal (Hilbert transformed) data.

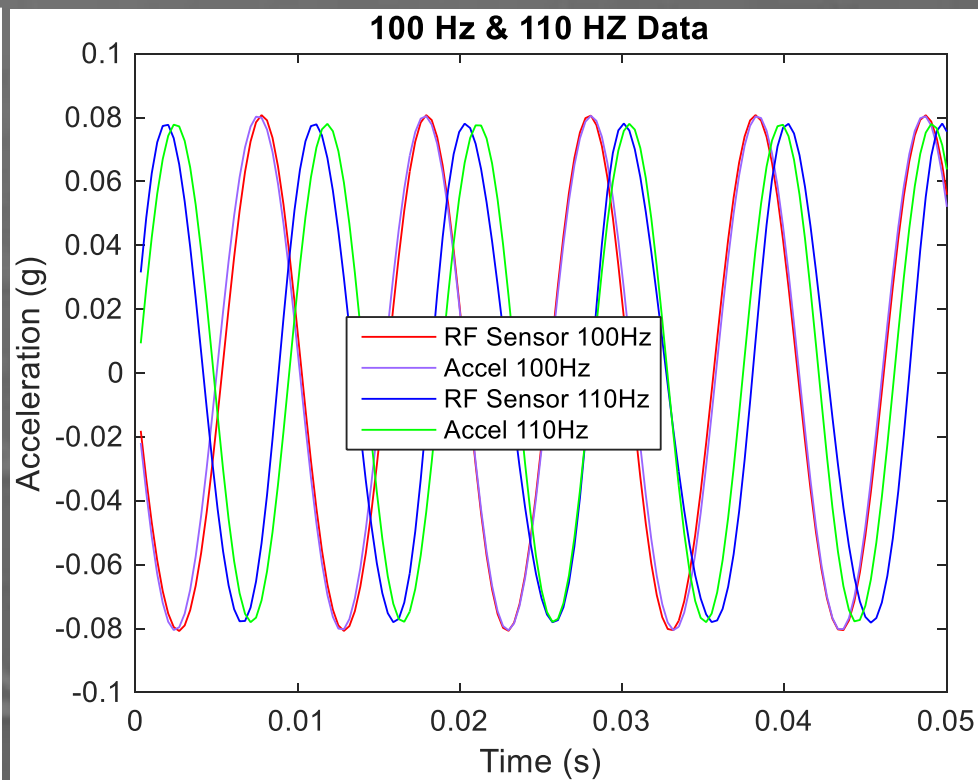
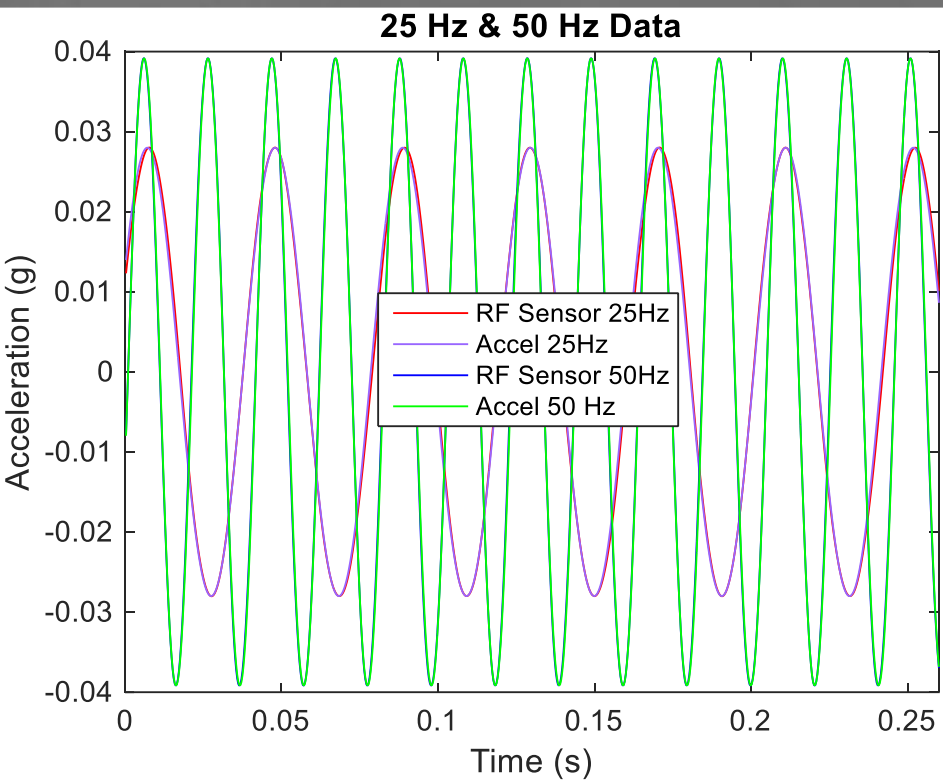
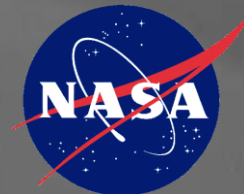


Results



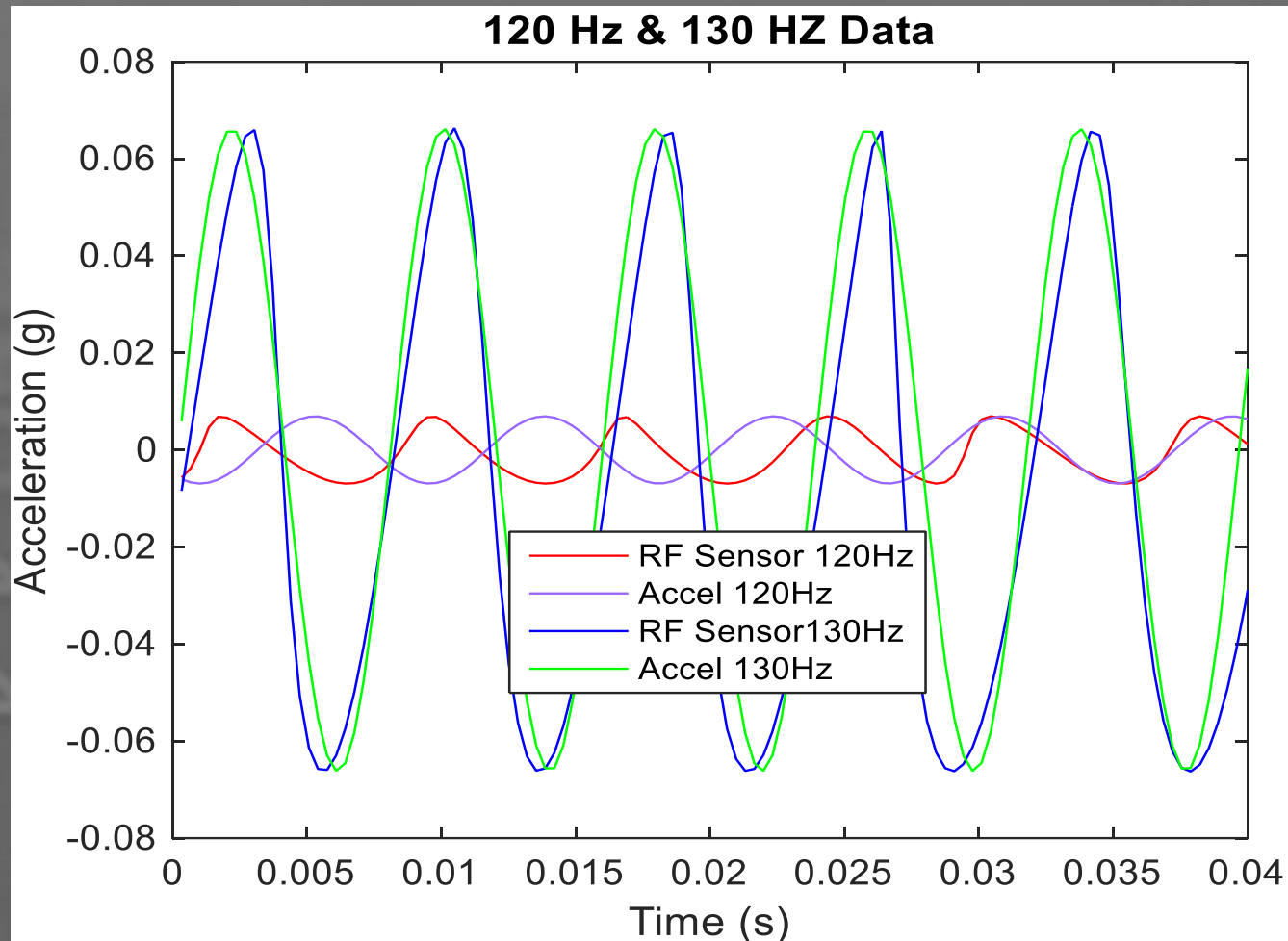
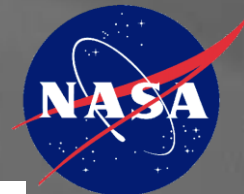


Results



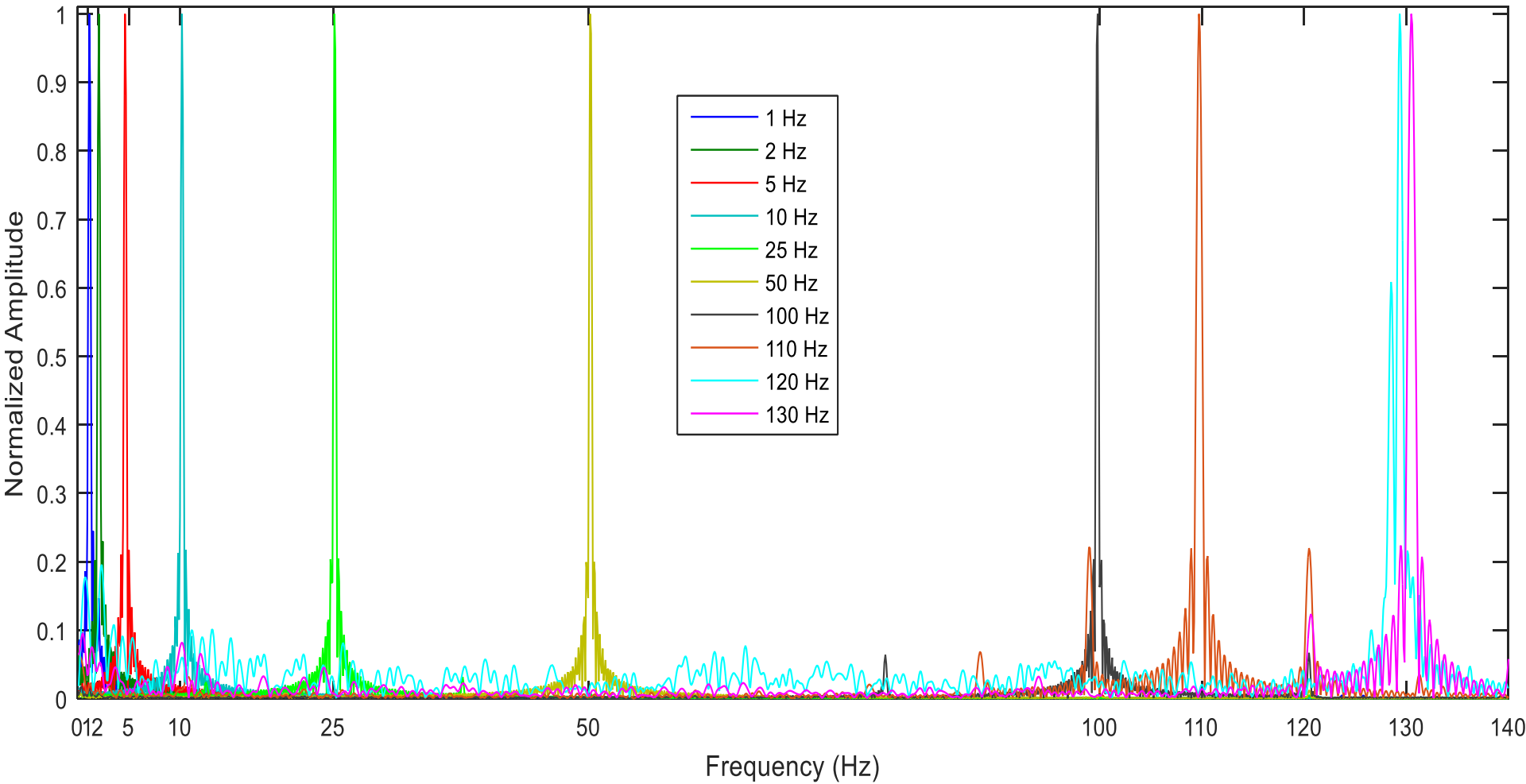
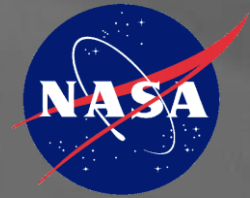


Results



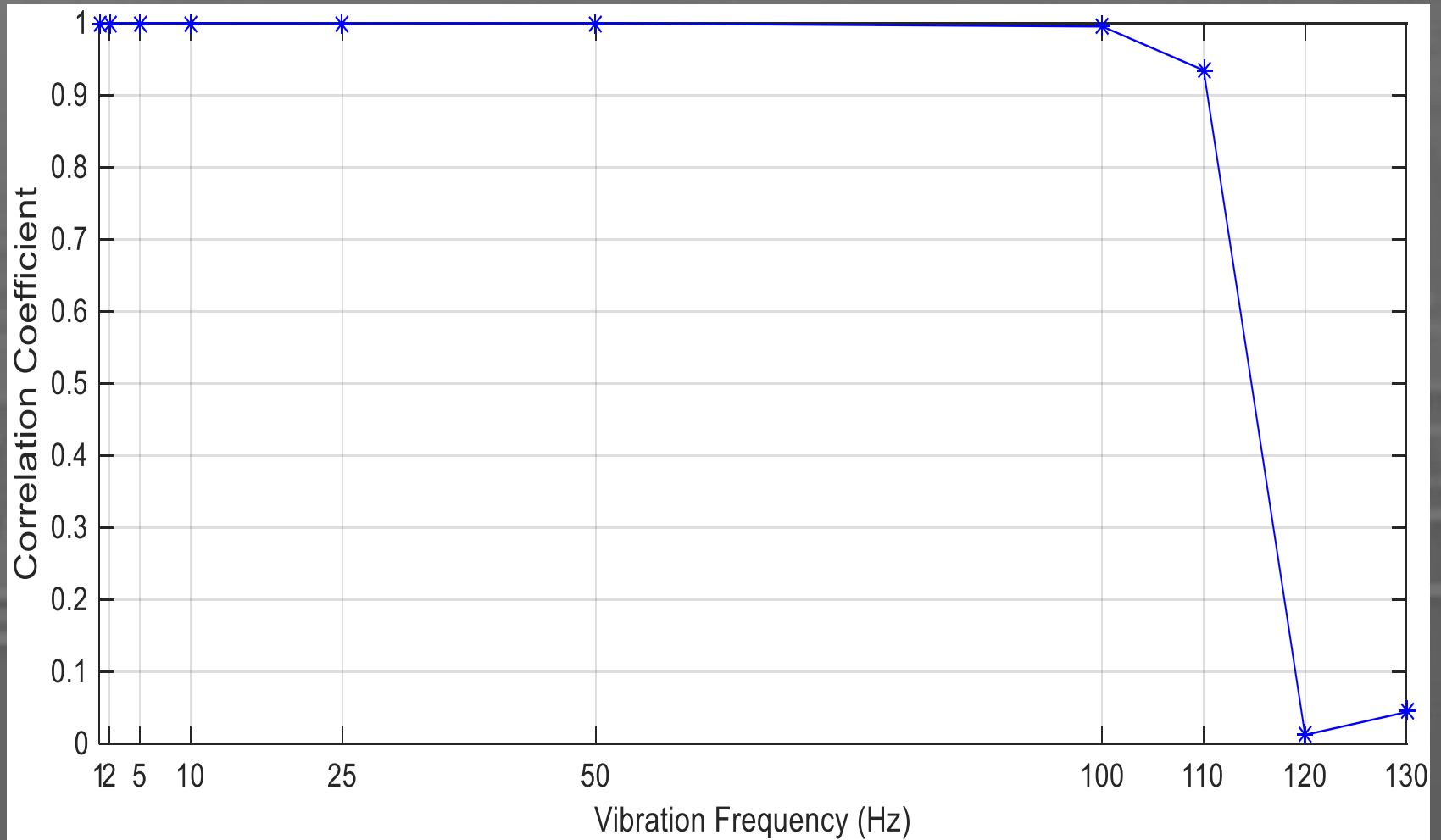
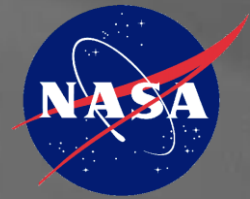


FFT Results of RF Data





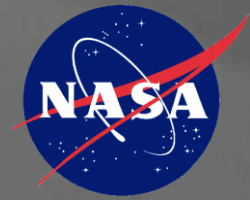
Error



Correlation coefficient of the vibration data.



Conclusions



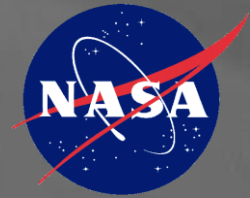
- A new method of employing microwaves to detect aeroelastic structural flutter phenomena has been presented.
- The RF sensor data was compared to accelerometer data taken from a cantilevered panel vibrating at 1 Hz, 2 Hz, 5 Hz, 10 Hz, 25 Hz, 50 Hz, 100 Hz, 110 Hz, 120 Hz, and 130 Hz.
- Up to 100 Hz, the processed RF sensor phase data yielded a vibrational behavior that qualitatively closely matches the accelerometer-measured vibrational input.
- The spectrum of the data is also closely matches the expected frequency response up to 100 Hz.



Funding/Partnership Opportunities



- NASA does not have the resources to develop all of the sensors it needs for its applications, therefore, we are looking for partners!
- Small Business Innovation Research (SBIR) Small Business Technology Transfer (STTR) **sbir.nasa.gov**
 - Focus Area 3 Autonomous Systems for Space Exploration
 - **T12.01 Advanced Structural Health Monitoring**
 - Wireless low power, small, sensors for structural health monitoring
 - Focus Area 15 Lightweight Materials Structures and Assembly / Construction
 - **Z11.01 NDE Sensors**
 - Wireless sensors for nondestructive testing
- NASA Research Opportunities (NRAs) Grants & Contracts
 - **nspires.nasaprs.com**
- Space Act Agreements (SAA)
 - Partnerships with and without exchange of funds

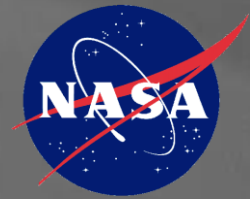


Auxiliary Slides





Correlation Coefficient



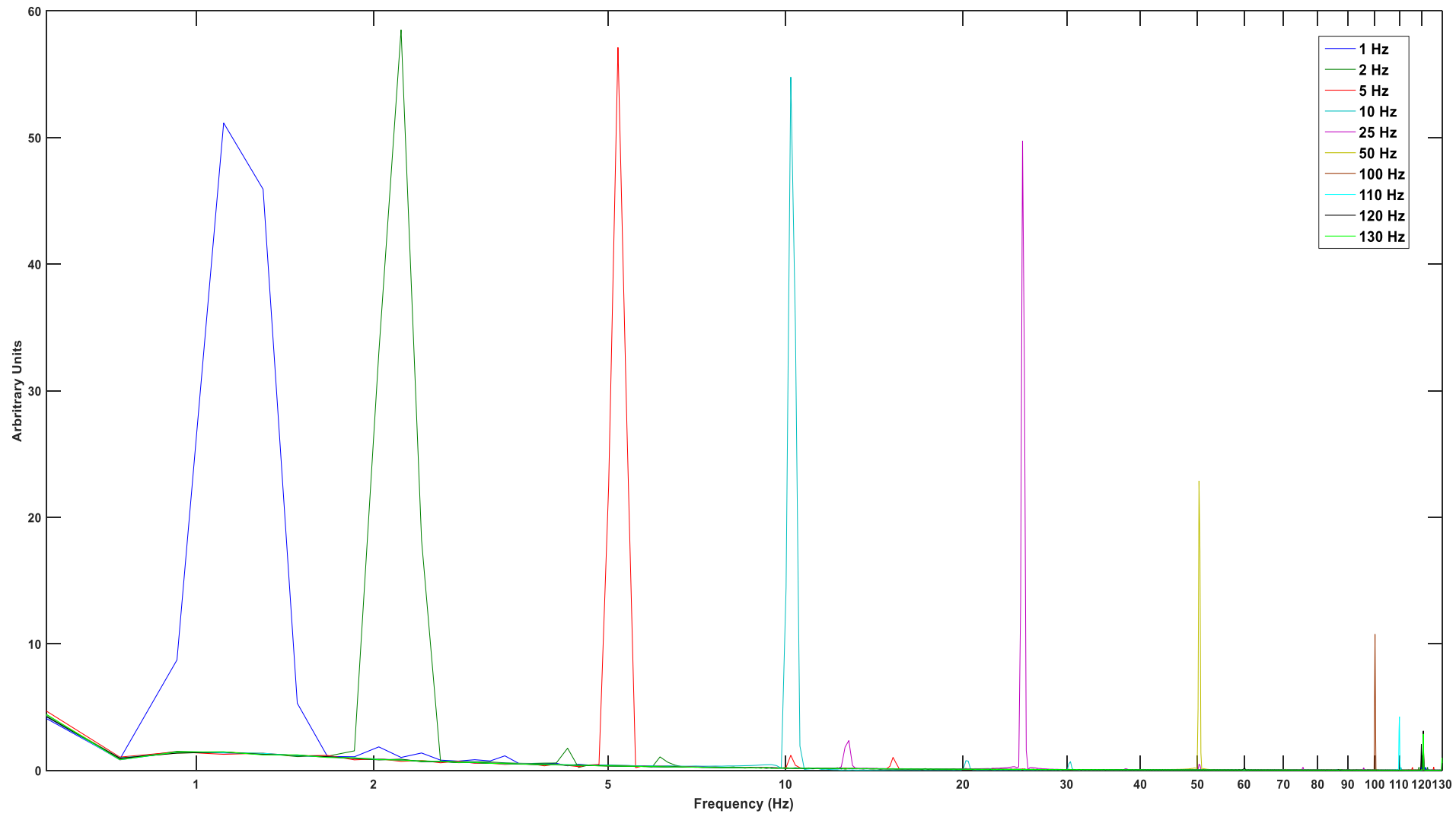
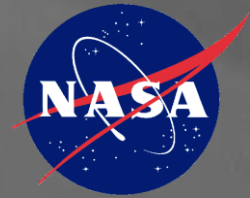
$$r = \frac{\sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})}{\sqrt{\sum_{i=1}^n (x_i - \bar{x})^2} \sqrt{\sum_{i=1}^n (y_i - \bar{y})^2}}$$

Frequency (Hz)	Correlation Coefficient
1	9.9788e-01
2	9.9920e-01
5	9.9979e-01
10	9.9971e-01
25	9.9922e-01
50	9.9959e-01
100	9.9523e-01
110	9.3451e-01
120	1.2193e-02
130	4.3864e-02

Pearson correlation coefficient was computed for each data set

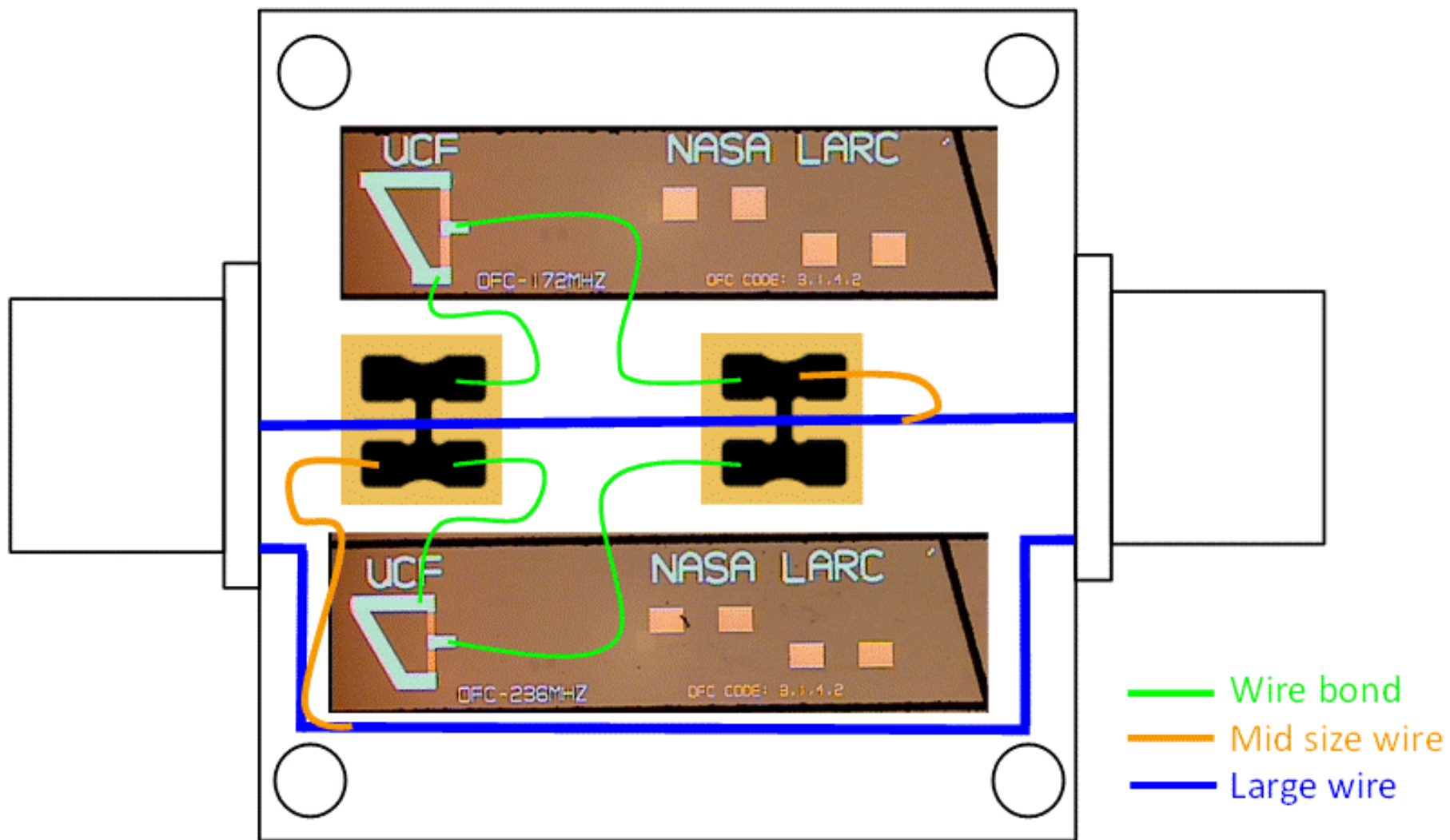
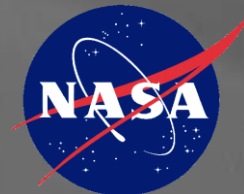


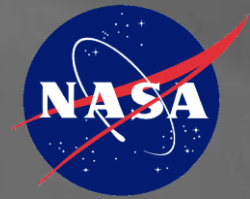
FFT of Raw Phase Data



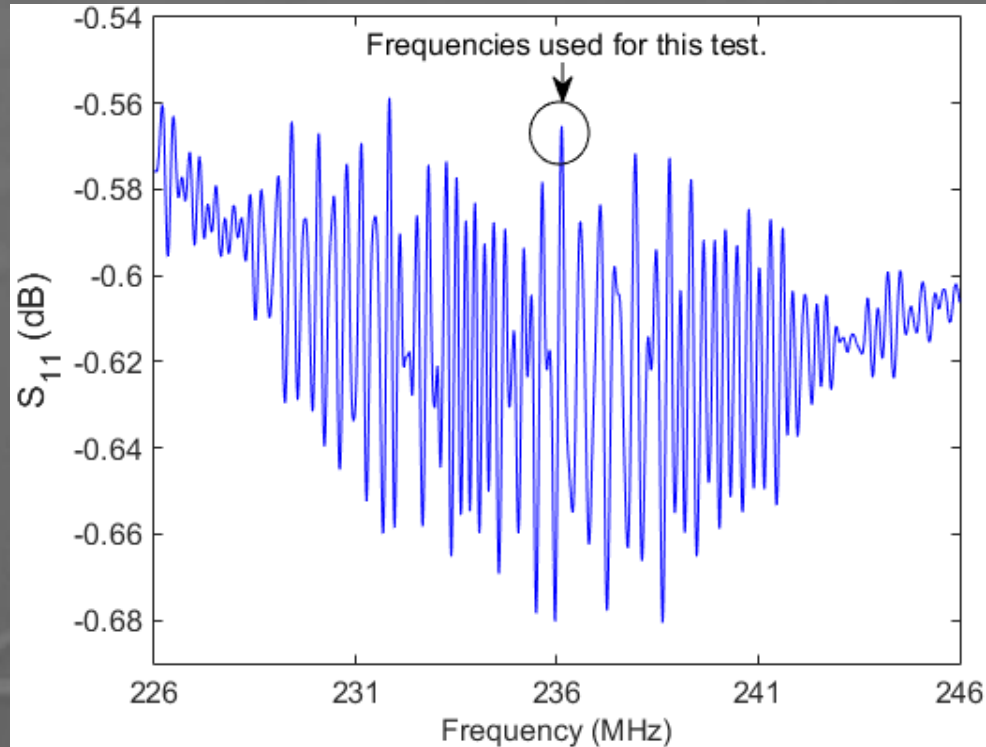


Module Wiring





SAW S_{11} Response



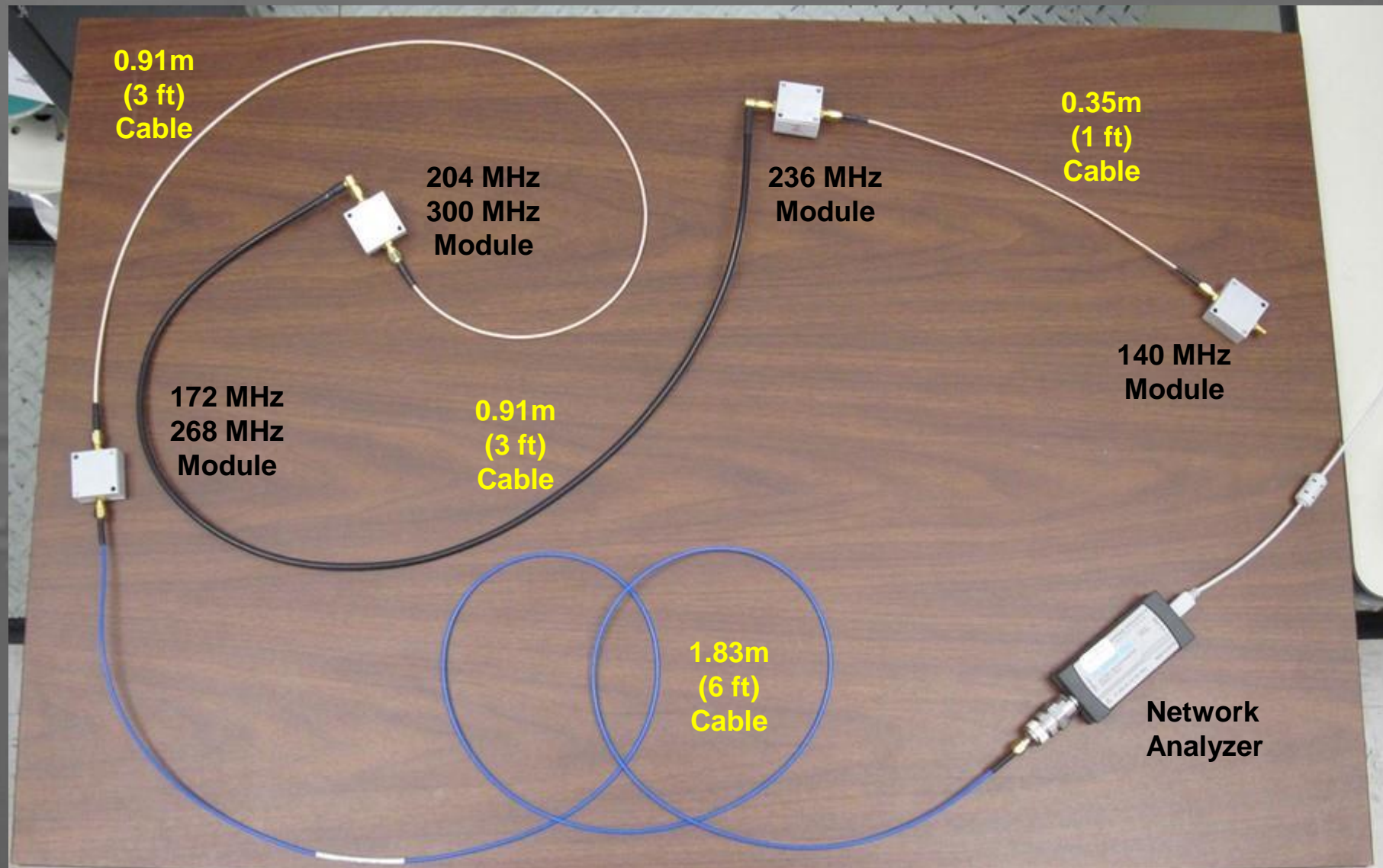
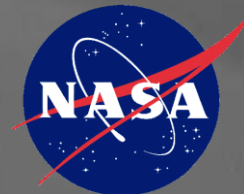
SAW S_{11} response.

The circle indicates the frequencies used for this work.

The subset of frequencies is a 100 kHz frequency window.
(236.055 MHz to 236.155 MHz)

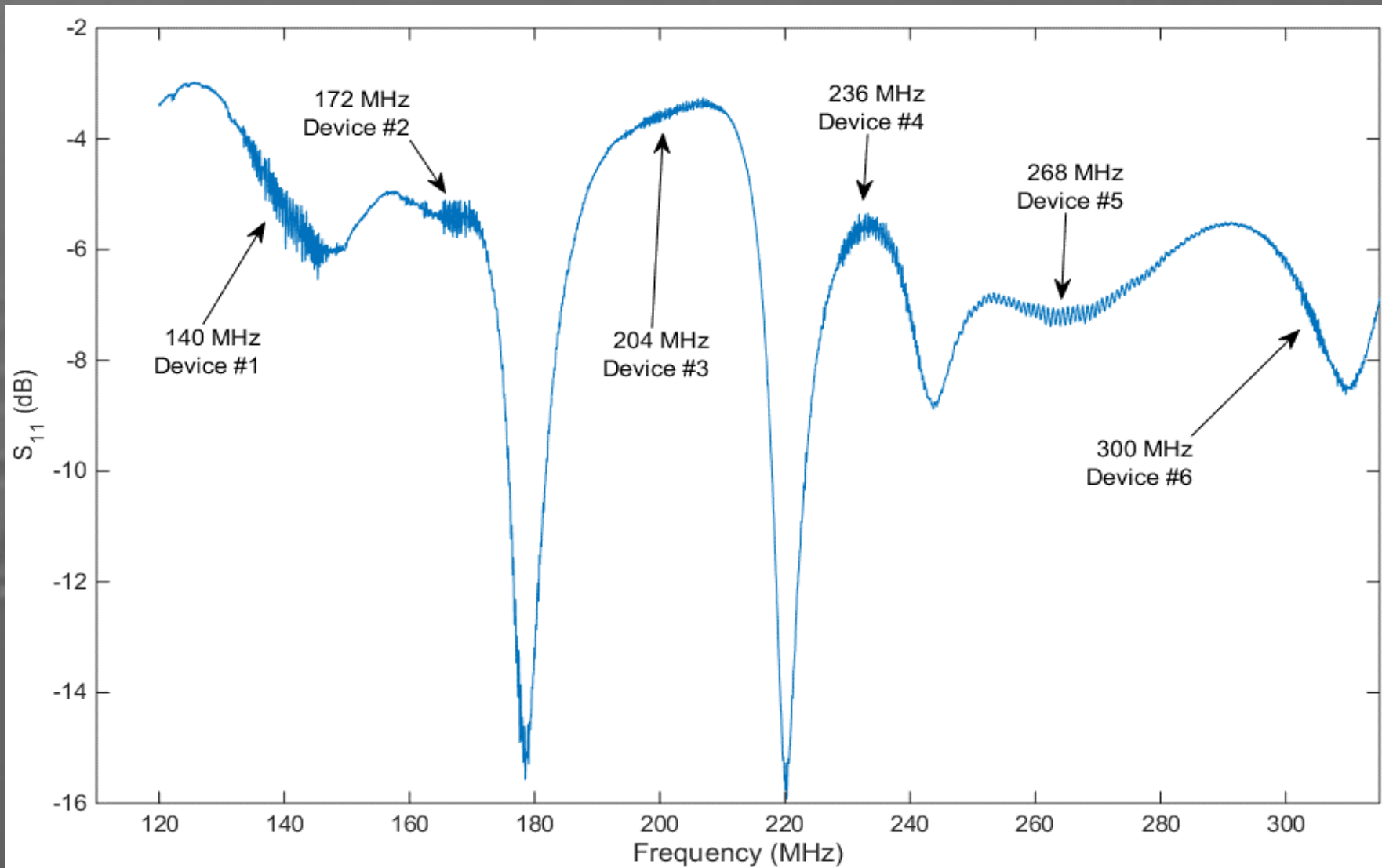
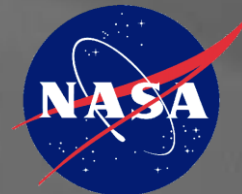


FDM SAW Sensor System



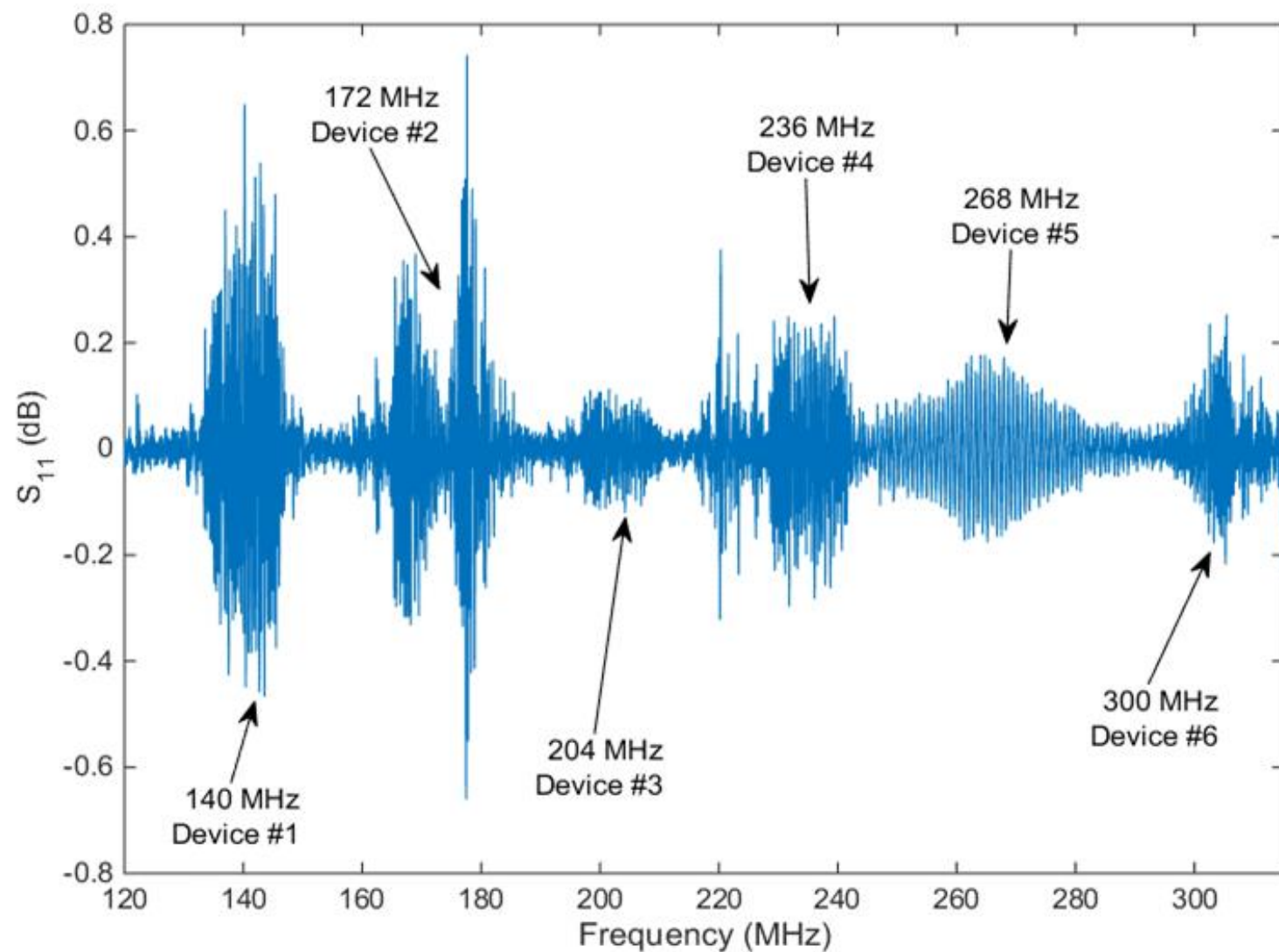
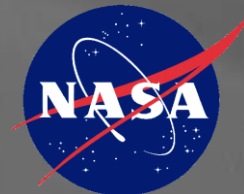


Frequency Division Multiplexed S_{11} Response





Frequency Division Multiplexed Filtered S11 Response





FDM SAW Sensor System

